MATH 340. Explicit Dictionaries vs. Revised Simplex Method. Richard Anstee

We display the dictionary method on the left and the corresponding revised simplex method on the right. We use B^{-1} in the revised simplex method below for convenience. In actual computation one does not explicitly compute B^{-1} . There are several possible questions about updates that can be asked. One could ask to give the new basic feasible solution after the pivot. And one could ask for the eta matrix E that updates the old B to the new B. It is rarely asked to provide the update to B^{-1} itself since it is not used in practice. The update rule is given but you can ignore if you wish. The actual revised simplex does not directly compute B^{-1} since that is numerically more unstable and so one uses a different approach.

Dictionary Format

max	5x	1 .	$+x_2$	$-2x_{3}$			
	$-4x_1$		$+x_2$	$+2x_{3}$	\leq	3	
	-x	; ₁ -	$-3x_{2}$	$+2x_{3}$	\leq	3	
	x_1		$+x_2$	$-x_3$	\leq	-1	
Phase	One	e:					
x_4	=	3	$+4x_{1}$	$-x_2$	_	$-2x_{3}$	$+x_0$
x_5	=	3	$+x_{1}$	$+3x_{2}$	2 -	$-2x_{3}$	$+x_0$
x_6	=	-1	$-x_1$	$-x_2$	-	$+x_3$	$+x_0$
w	=						$-x_0$

Revised Simplex Method

$$\begin{aligned}
x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_0 & b \\
x_4 \begin{pmatrix} -4 & 1 & 2 & 1 & 0 & 0 & -1 \\ -1 & -3 & 2 & 0 & 1 & 0 & -1 \\ 1 & 1 & -1 & 0 & 0 & 1 & -1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} \\
\text{Phase One has } w = \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix} \\
\text{basis } \{x_4, x_5, x_6\}, \ B^{-1} = \begin{pmatrix} x_4 & x_5 & x_6 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\
\text{special pivot: } B^{-1}\mathbf{b} = \mathbf{b} = \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} \quad B^{-1}A_0 = A_0 = \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix} \\
\begin{pmatrix} x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} - \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} x_0 \ge \mathbf{0}. \quad \text{So } x_0 \text{ enters } x_6 \text{ leaves}
\end{aligned}$$

new basis $\{x_4, x_5, x_0\}$

new basic feasible solution $(1, 0, 0, 0, 4, 4, 0)^T$

eta matrix update
$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix}$$

Non-standard Pivot to Feasibility: x_0 enters and x_6 leaves x_4 4 $+5x_{1}$ $-3x_{3}$ $+x_6$ = $-3x_3 + x_6$ = $4 + 2x_1 + 4x_2$ x_5 x_0 = 1 $+x_1$ $+x_{2}$ $-x_3$ $+x_6$ $= -1 -x_1$ w $-x_2$ $+x_3$ $-x_6$ new $B^{-1} = \begin{array}{c} x_4 \\ x_5 \\ x_6 \end{array} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix}$ from old B^{-1} by pivot $\begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ Now w yields $c = \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix}$ $c_N^T - c_B^T B^{-1} A_N =$ $\begin{pmatrix} x_1 & x_2 & x_3 & x_6 & x_4 & x_5 & x_0 & x_4 \\ (0 & 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 & -1 \end{pmatrix} x_5 \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ x_0 \end{pmatrix} \begin{pmatrix} x_4 & -4 & 1 & 2 & 0 \\ -1 & -3 & 2 & 0 \\ 1 & 1 & -1 & 1 \end{pmatrix}$ $\begin{array}{cccc} x_1 & x_2 & x_3 & x_6 \\ = & \begin{pmatrix} -1 & -1 & 1 & -1 \end{pmatrix} & \text{so } x_3 \text{ enters} \end{array}$ $B^{-1}A_3 = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix}, B^{-1}\mathbf{b} = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 1 \end{pmatrix}.$ $\begin{pmatrix} x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 1 \end{pmatrix} - \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} x_3 \ge \mathbf{0}.$ So x_0 leaves

new basis $\{x_4, x_5, x_3\}$

new basic feasible solution $(0, 0, 0, 1, 1, 1, 0)^T$ or $(0, 0, 1, 1, 1, 0)^T$ ignoring x_0

eta matrix update $\begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$

 $x_{3} \text{ enters and } x_{0} \text{ leaves}$ $x_{4} = 1 + 2x_{1} - 3x_{2} + 3x_{0} - 2x_{6}$ $x_{5} = 1 - x_{1} + x_{2} + 3x_{0} - 2x_{6}$ $x_{3} = 1 + x_{1} + x_{2} - x_{0} + x_{6}$ $w = -x_{0}$

$$new \ B^{-1} = \begin{array}{cc} x_4 & x_5 & x_6 \\ x_4 & \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ x_3 & \begin{pmatrix} 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \text{ from old } B^{-1} \text{ by pivot} \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} \to \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

End of Phase One

Phase Two Begins

$$z = 5x_1 + x_2 - 2x_3 = -2 + 3x_1 - x_2 - 2x_6.$$

 $x_4 = 1 + 2x_1 - 3x_2 - 2x_6$
 $x_5 = 1 - x_1 + x_2 - 2x_6$
 $x_3 = 1 + x_1 + x_2 + x_6$
 $z = -2 + 3x_1 - x_2 - 2x_6$

$$\begin{aligned} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \\ (c & 0) &= \begin{pmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \\ 5 & 1 & -2 & 0 & 0 & 0 \end{pmatrix} \\ x_4 & x_5 & x_6 & x_1 & x_2 & x_6 \\ x_4 & x_5 & x_6 & x_1 & x_2 & x_6 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_4 & x_5 & x_6 & x_1 & x_2 & x_6 \\ -1 & -3 & 0 \\ 1 & 1 & 1 \end{pmatrix} \\ &= \begin{pmatrix} x_1 & x_2 & x_6 & x_1 & x_2 & x_6 & x_1 & x_2 & x_6 \\ 5 & 1 & 0 \end{pmatrix} - \begin{pmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \end{pmatrix} = \begin{pmatrix} 3 & -1 & -2 \end{pmatrix} \text{ so } x_1 \text{ enters} \\ B^{-1}A_1 &= \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} -4 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ -1 \end{pmatrix}, B^{-1}\mathbf{b} = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ \begin{pmatrix} x_4 \\ x_5 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} - \begin{pmatrix} -2 \\ 1 \\ -1 \end{pmatrix} x_1 \ge \mathbf{0}. \quad \text{So } x_5 \text{ leaves} \end{aligned}$$

new basis $\{x_4, x_1, x_3\}$

new basic feasible solution $(1, 0, 2, 3, 0, 0)^T$

eta matrix update
$$\begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$$

 x_1 enters and x_5 leaves $x_4 = 3 - 2x_5 - x_2$ $-6x_{6}$ $-x_5$ $+x_2 -2x_6$ x_1 = 1 $x_3 = 2$ $-x_5 + 2x_2 - x_6$ $= 1 -3x_5 +2x_2 -8x_6$ z

$$\operatorname{new} B^{-1} = \begin{array}{cc} x_4 & x_5 & x_6 \\ x_4 & \begin{pmatrix} 1 & 2 & 6 \\ 0 & 1 & 2 \\ x_3 & \begin{pmatrix} 0 & 1 & 2 \\ 0 & 1 & 1 \end{pmatrix} \text{ from old } B^{-1} \text{ by pivot} \begin{pmatrix} -2 \\ 1 \\ -1 \end{pmatrix} \to \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \operatorname{new \ basis} \{x_4, x_1, x_3\}$$

$$c_{N}^{T} - c_{B}^{T}B^{-1}A_{N} = \begin{pmatrix} x_{2} & x_{5} & x_{6} & x_{4} & x_{1} & x_{3} & x_{4} \\ 1 & 0 & 0 \end{pmatrix} - \begin{pmatrix} x_{4} & x_{1} & x_{3} & x_{4} \\ 0 & 5 & -2 \end{pmatrix} \begin{pmatrix} x_{1} & 2 & 6 \\ 0 & 1 & 2 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_{4} & \begin{pmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} x_2 & x_5 & x_6 & x_2 & x_5 & x_6 & x_2 & x_5 & x_6 \\ 1 & 0 & 0 \end{pmatrix} - \begin{pmatrix} -1 & 3 & 8 \end{pmatrix} = \begin{pmatrix} x_2 & x_5 & x_6 \\ 2 & -3 & -8 \end{pmatrix} \text{ so } x_2 \text{ enters}$$

$$B^{-1}A_2 = \begin{pmatrix} 1 & 2 & 6 \\ 0 & 1 & 2 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}, B^{-1}\mathbf{b} = \begin{pmatrix} 1 & 2 & 6 \\ 0 & 1 & 2 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix}.$$

$$\begin{pmatrix} x_4 \\ x_1 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} x_2 \ge \mathbf{0}. \text{ So } x_4 \text{ leaves}$$

$$\text{new basis } \{x_2 & x_3 & x_6 \} = x_3 + x_5 + x_6$$

new basis $\{x_2, x_1, x_3\}$

new basic feasible solution $(4, 3, 8, 0, 0, 0)^T$

eta matrix update
$$\begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

Optimal solution: (4, 3, 8, 0, 0, 0) with z = 7.

$$new \ B^{-1} = \begin{array}{cc} x_4 & x_5 & x_6 \\ x_2 & \begin{pmatrix} 1 & 2 & 6 \\ 1 & 3 & 8 \\ x_3 & 2 & 5 & 13 \end{array} \right) \text{ from old } B^{-1} \text{ by pivot} \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \to \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad new \text{ basis } \{x_2, x_1, x_3\}$$

$$c_{N}^{T} - c_{B}^{T}B^{-1}A_{N} = \begin{pmatrix} x_{4} & x_{5} & x_{6} & x_{2} & x_{1} & x_{3} & x_{2} \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} x_{2} & x_{1} & x_{3} & x_{2} \\ 1 & 5 & -2 \end{pmatrix} \begin{pmatrix} x_{1} & 2 & 6 \\ 1 & 3 & 8 \\ x_{3} \end{pmatrix} \begin{pmatrix} x_{4} & x_{5} & x_{6} \\ 2 & 5 & 13 \end{pmatrix} \begin{pmatrix} x_{4} & x_{5} & x_{6} \\ x_{5} & x_{6} \end{pmatrix} \begin{pmatrix} x_{4} & x_{5} & x_{6} \\ 0 & 0 & 1 \end{pmatrix}$$
$$= \begin{pmatrix} x_{4} & x_{5} & x_{6} & x_{4} & x_{5} & x_{6} \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 2 & 7 & 20 \end{pmatrix} = \begin{pmatrix} -2 & -7 & -20 \\ -2 & -7 & -20 \end{pmatrix}$$

So we are at optimality with:

$$\begin{pmatrix} x_4 & x_5 & x_6 & b \\ x_1 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_1 \\ x_3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 6 \\ 1 & 3 & 8 \\ 2 & 5 & 13 \end{pmatrix} \begin{pmatrix} 3 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \\ 8 \end{pmatrix}, \quad z = c_B^T B^{-1} \mathbf{b} = \begin{pmatrix} 1 & 5 & -2 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \\ 8 \end{pmatrix} = 7.$$