

Talk 1 :

What is Gromov-Witten theory?

Short answer: A (virtual) count of curves inside a smooth projective variety.

Two examples of enumerative problems:

(1) Let p_1, \dots, p_5 be five points in general position in \mathbb{P}^2 . How many conics pass through these points?

Answer: A conic in \mathbb{P}^2 is defined by a homogenous quadratic polynomial in three variables, X_0, X_1, X_2 , i.e. conics correspond to global sections $H^0(\mathbb{P}^2, \mathcal{O}_{\mathbb{P}^2}(2)) = V$ upto multiplication by scalars.

Conics in $\mathbb{P}^2 \longleftrightarrow \mathbb{P}(V) = \text{Proj}(\text{Sym}^\bullet V^\vee)$
(Projective space of lines in V)

For any point $p = (p_0, p_1, p_2) \in \mathbb{C}^3$ there is an evaluation morphism

$$e_p : V \longrightarrow \mathbb{C}$$

$$e_p(f) = f(p)$$

so that $e_p \in V^\vee$ defines a global section $s_p \in H^0(\mathbb{P}(V), \mathcal{O}_{\mathbb{P}(V)}(1))$.

The zero locus of s_p is precisely the hyperplane $H_p := \{[f] \in \mathbb{P}(V) \mid f(p) = 0\} \subseteq \mathbb{P}(V)$.

Then the conics we want are in the intersection

$$\bigcap_{i=1}^5 H_{p_i}$$

and if the points p_i are in general position, the intersection is exactly one point. So there is exactly one conic passing through all p_i .

In this example, there is a vector bundle

$$\mathcal{O}_{\mathbb{P}(V)}(1)^{\oplus 5} \longrightarrow \mathbb{P}(V)$$

rank 5
dim 5

and a global section $(e_{p_1}, \dots, e_{p_5})$ of $\mathcal{O}_{\mathbb{P}(V)}(1)^{\oplus 5}$ whose zero locus is the answer to the problem.

(2) Let $Z \subset \mathbb{P}^3$ be a smooth cubic surface. One knows that Z contains exactly 27 lines. Let us try to see this fact for a general cubic surface.

Let $G = \text{Gr}(2, 4)$ be the Grassmannian of lines in \mathbb{P}^3 , with tautological bundle \mathcal{S} . Similar to (1) there is a correspondence

$$\begin{array}{ccc} \text{Homogeneous degree 3} & & \text{Global sections} \\ \text{polynomials in } x_0, x_1, x_2, x_3 & \longleftrightarrow & H^0(G, \text{Sym}^3(\mathcal{S}^\vee)) \end{array}$$

i.e. cubic surfaces in \mathbb{P}^3 correspond to sections of $\text{Sym}^3(\mathcal{S}^\vee)$ and the zero locus in G of a

section f is precisely the lines $L \subseteq \mathbb{P}^3$ on which f vanishes, i.e. $L \subset Z(f)$.

So we are reduced to computing

$$\int_{G_r(2,4)} c_4(\text{Sym}^3(S^V))$$

(Top Chern class of a complex v.b. is the Euler class)

The splitting principle shows that

$$c_4(\text{Sym}^3(S^V)) = 9c_2(S^V)(2c_1^2(S^V) + c_2(S^V))$$

and the Chern classes of S^V are represented by Schubert varieties

$$c_1(S^V) = \Pi_\ell := \{L \subseteq \mathbb{P}^3 \mid L \cap \ell \neq \emptyset\} \quad \ell \subseteq \mathbb{P}^3 \text{ a line}$$

$$c_2(S^V) = \Pi_h := \{L \subseteq \mathbb{P}^3 \mid L \subseteq h\} \quad h \subseteq \mathbb{P}^3 \text{ a plane}$$

with computations

$$\begin{aligned} \Pi_\ell^2 &= \Pi_h + \Pi_p \quad (:= \{L \subseteq \mathbb{P}^3 \mid p \in L\}) \quad p \in \mathbb{P}^3 \text{ a point} \\ \Pi_h \Pi_p &= 0 \quad , \quad \Pi_h^2 = 1 \end{aligned}$$

$$\begin{aligned} \text{So } c_4(\text{Sym}^3(S^V)) &= 9\Pi_h(2\Pi_\ell^2 + \Pi_h) \\ &= 9\Pi_h(3\Pi_h + 2\Pi_p) \\ &= 27\Pi_h^2 + 18\Pi_h\Pi_p \\ &= \underline{\underline{27}} \end{aligned}$$

In this example too, there is a vector bundle

$$\begin{array}{ccc} \text{Sym}^3(\mathcal{S}^\vee) & \longrightarrow & \text{Gr}(2,4) \\ \text{rank } 4 & & \text{dim } 4 \end{array}$$

the zero locus of a general section giving the answer.

Vague moral: Moduli spaces should be obtained, at least locally, by the following recipe -

X : a smooth scheme

E : a vector bundle on X

$s \neq 0 \in \Gamma(X, E)$ a nonzero global section

$\mathcal{M} = \text{zero locus of } s$, the moduli space.

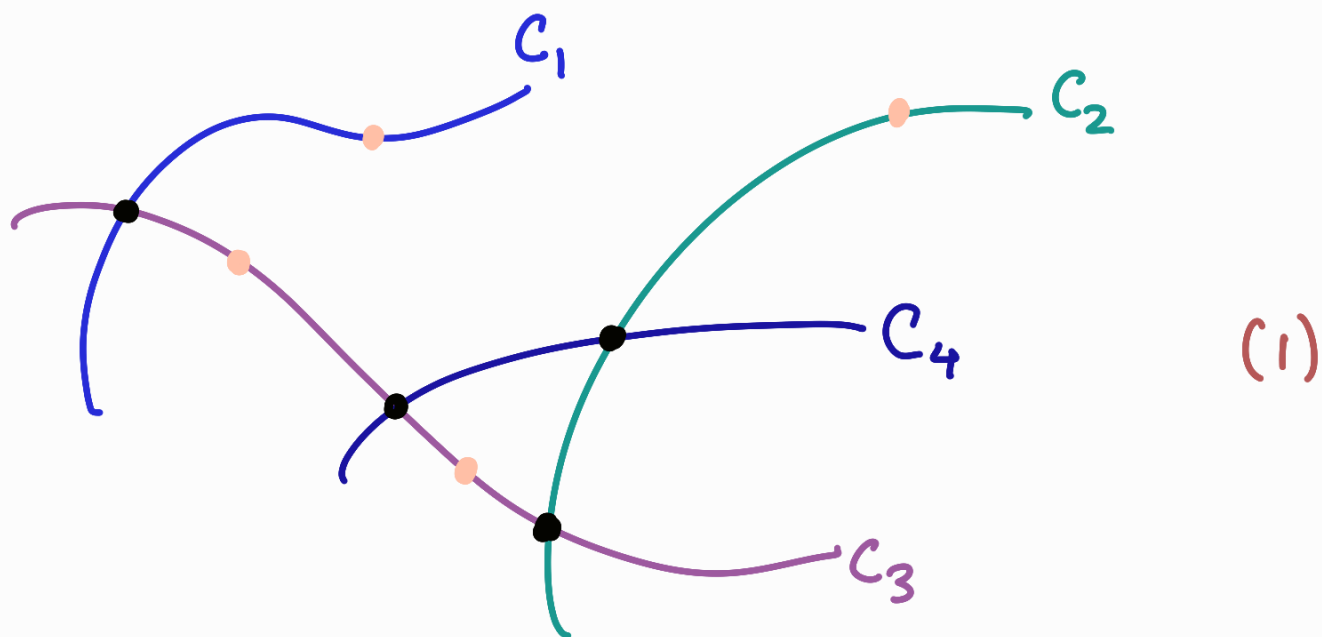
$$\mathcal{M} = s^{-1}(0) \hookrightarrow X$$

(Here will arise transversality issues: $\text{codim}(\mathcal{M}, X)$ need not be equal to $\text{rank } E$. An easy example is taking two functions $xz, yz \in \mathbb{C}[x, y, z]$ whose zero locus isn't equidimensional)

Counting curves in a projective variety X :
 Embedded curves in X have as bad singularities as possible. Kontsevich's idea is to redefine a 'curve' as (the image of) a map $f: C \rightarrow X$ where C is now a curve with prescribed singularities only + extra conditions to have nice moduli spaces.

Moduli spaces of stable maps

- Definition: A n -pointed genus g quasi-stable curve $(C, \{p_i\}_{i=1}^n)$ is a projective, connected, reduced curve C of arithmetic genus g with at worst nodal singularities and n distinct nonsingular marked points $p_1, \dots, p_n \in C$.



- : marked points
- : nodes

Picture of a quasi-stable curve.

Important example: Ignoring marked points, C is a quasi-stable curve of genus 0 iff C is a tree of smooth rational curves.

Proof is an exercise! (Hint - Normalization)

For genus 1, there are several possibilities: Smooth cubic curve in \mathbb{P}^2 (elliptic curve), nodal cubic curve, a cycle of rational curves etc.

• Definition (Family of quasi-stable curves)

Let S be a scheme. A family of n -pointed quasi-stable curves of genus g over S is a flat, projective morphism $\pi: \mathcal{C} \rightarrow S$ such that for every geometric point $s: \text{spec } \Omega \rightarrow S$ the geometric fiber \mathcal{C}_s is a genus g quasi-stable curve and there are n disjoint sections $p_i: S \rightarrow \mathcal{C}$ of π , $i=1, \dots, n$.

So for every s as above, $(\mathcal{C}_s, p_1(s), \dots, p_n(s))$ is a n -pointed genus g quasi-stable curve, varying as $s \in S$ varies in the base.

One is interested in morphisms (or families of morphisms) of a quasi-stable curve to a target scheme X , in line with the idea.

• Definition (Family of morphisms)

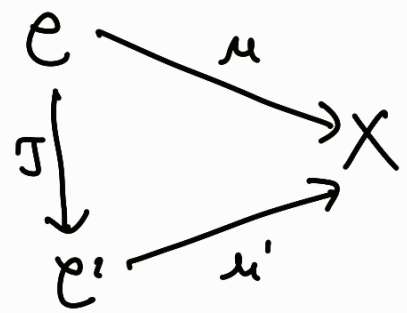
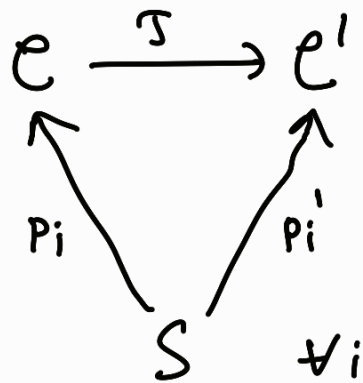
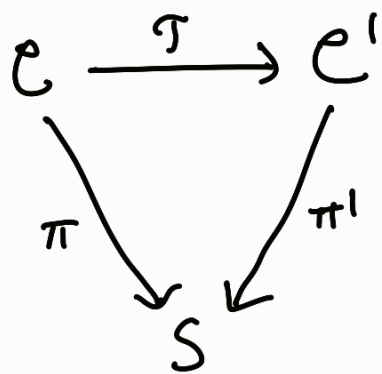
Let S be a scheme and X a target scheme. A family of morphisms of n -pointed genus g quasi-stable curves to X is the data

$$\left(\pi: \mathcal{C} \rightarrow S, \{p_i: S \rightarrow \mathcal{C}\}_{i=1}^n, \mu: \mathcal{C} \rightarrow X \right)$$

with $(\pi: \mathcal{C} \rightarrow S, \{p_i\}_{i=1}^n)$ being a family of n -pointed genus g quasi-stable curves over S and μ a morphism.

There is an obvious notion of 'isomorphism of families of morphisms' - in which the obvious diagrams commute for a second S -family

$$\left(\pi': \mathcal{C}' \rightarrow S, \{p'_i\}_{i=1}^n, \mu': \mathcal{C}' \rightarrow X \right)$$



where $T: \mathcal{C} \rightarrow \mathcal{C}'$ is an isomorphism over S .

One would like to have conditions ensuring 'stability' as in the case of moduli of pointed curves $\overline{\mathcal{M}}_{g,n}$. For a quasi-stable curve (C, p_1, \dots, p_n) and an irreducible component $E \subset C$, the special points on E are the marked points on E and the nodal points of intersection $E \cap E'$ for $E' \subset C$ another irreducible component.

- Definition: Let (C, p_1, \dots, p_n) be a quasi-stable curve and $\mu: C \rightarrow X$ a map. The map μ is called stable if for an irreducible component $E \subset C$, the following hold
 - (a) If $\delta_a(E) = 0$ and $\mu(E) = \text{point}$, then E has at least three special points.
 - (b) If $\delta_a(E) = 1$ and $\mu(E) = \text{point}$, then E has at least one special point.

The stability condition ensures that the morphisms $\mu: C \rightarrow X$ have only finitely many automorphisms.

• Definition: A family of stable maps parametrized by S

$$\{ \pi: \mathcal{C} \rightarrow S, (p_i)_{i=1}^n, \mu: \mathcal{C} \rightarrow X \}$$

is a family of maps such that for every geometric fiber $s: \text{spec } \Omega \rightarrow S$, the map

$$\mu_s: (\mathcal{C}_s, p_1(s), \dots, p_n(s)) \rightarrow X$$

is stable.

• Describing the moduli functor $\overline{\mathcal{M}}_{g,n}(X, \beta)$:

Let X be a target scheme and $\beta \in A_1(X)$ be a cycle class. A stable map $\mu: (\mathcal{C}, (p_i)_{i=1}^n) \rightarrow X$ is said to represent β if $\mu_*[C] = \beta$.

The (contravariant) functor $\overline{\mathcal{M}}_{g,n}(X, \beta)$ maps a scheme S to S -families of stable maps to X representing β , i.e.

$$\overline{\mathcal{M}}_{g,n}(X, \beta) : (\text{Sch}/\mathbb{C})^{\text{op}} \longrightarrow (\text{Groupoids})$$

$$\overline{\mathcal{M}}_{g,n}(X, \beta)(S) := \left. \begin{array}{l} \pi: \mathcal{C} \rightarrow S, (p_i)_{i=1}^n, \mu: \mathcal{C} \rightarrow X \\ \text{families of stable maps} \\ \text{such that } \mu_s \text{ represents } \beta \\ \text{for every geometric pt } s \in S \end{array} \right\}$$

and the morphisms in $\overline{\mathcal{M}}_{g,n}(X, \beta)(S)$ are S -isomorphisms of families of maps

Note that the points of this 'space' $\overline{\mathcal{M}}_{g,n}(X, \beta)(\mathbb{C})$ are just stable maps along with an extra finite

group attached to it - the automorphism group of the stable map.

A detour - heuristic computation of the expected dimension of $\overline{\mathcal{M}}_{g,n}(X,\beta)$: We're looking at a space whose points correspond to stable maps $\mu: C \rightarrow X$. By a little deformation theory, deformations of the map μ are given by

$$H^0(C, \mu^* \text{Hom}(\Omega_X, \mathcal{O}_X))$$

(this is the tangent space at μ in the scheme of morphisms $\text{Hom}(C, X)$)

and the obstruction space is

$$H^1(C, \mu^* \text{Hom}(\Omega_X, \mathcal{O}_X))$$

So if X is smooth, which we assume from now, the expected dimension of deformations of μ is

$$h^0(C, \mu^* TX) - h^1(C, \mu^* TX)$$

$$= \chi(C, \mu^* TX) = \deg(\mu^* TX) + rk(\mu^* TX)(1-g)$$

by Riemann-Roch ($g = g_a(C)$)

$$\begin{aligned} \text{The last number is } & \deg(\mu^* TX) + \dim X (1-g) \\ & = -K_X \cdot \beta + \dim X (1-g) \end{aligned}$$

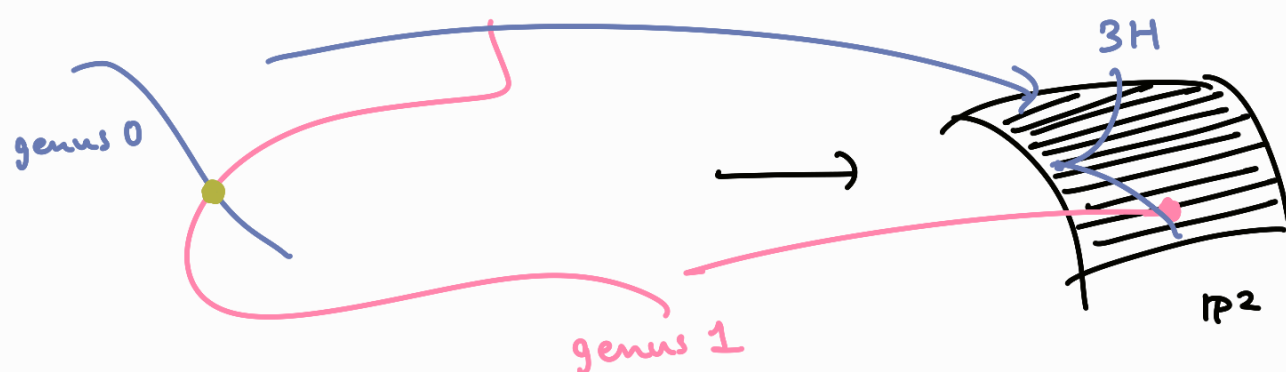
Accounting for deformations of the original curve C adds an extra $3g-3+n$ to the above, so the expected dim (also virtual dimension) is

$$vdim \overline{\mathcal{M}}_{g,n}(X,\beta) = (\dim X - 3)(1-g) + n - K_X \cdot \beta$$

Some examples to show that $\overline{\mathcal{M}}_{g,n}(X, \beta)$ is badly behaved.

EXAMPLE (1): Consider $\overline{\mathcal{M}}_{1,0}(\mathbb{P}^2, 3H)$ where H is the class of a line in \mathbb{P}^2 . The expected dim of $\overline{\mathcal{M}}_{1,0}(\mathbb{P}^2, 3H)$ is $3H \cdot 3H = 9$ but there is a 'boundary component' with bigger dimension described as follows -

Consider source curves to be a genus 1 curve with a genus 0 tail and the morphism to \mathbb{P}^2 contracts the genus 1 curve (and maps the genus 0 curve to the class $3H$ necessarily)



Then these maps are parametrized by

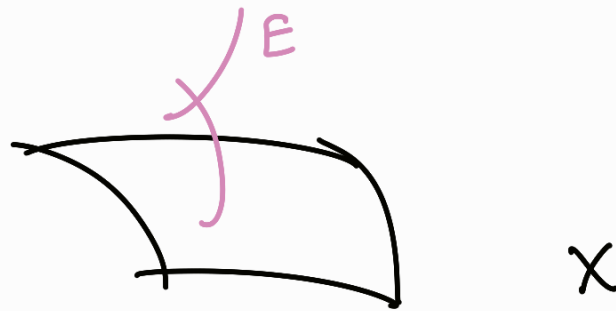
$$\overline{\mathcal{M}}_{0,1}(\mathbb{P}^2, 3H) \times \mathcal{M}_{1,1}$$

the marked point in each factor being the point of intersection. The above space has dimension = expected dimension (this is a fact, coming later) and equals 10 by the formula.

So the boundary is badly behaved.

EXAMPLE (2) : It is not even obvious if $\overline{\mathcal{M}}_{g,n}(X, \beta)$ has nonempty interior, i.e. maps with irreducible source curves. The following 'stupid' example shows that an empty interior may be the case.

Take \mathbb{P}^2 , blow up a point and then blow up a point on the exceptional divisor to get X .



Let β be the class of the exceptional divisor in X . (Here E is two rational curves intersecting in a node) Then $\mathcal{M}_{0,n}(X, \beta)$ (the interior) is empty as irreducible source curves cannot map to E and E is the only curve representing β . The compactification $\overline{\mathcal{M}}_{0,n}(X, \beta)$ is obviously nonempty.

EXAMPLE (3) : (Calabi-Yau threefolds) Let X be a CY3, i.e. a simply connected Kähler threefold with trivial canonical bundle (such an X is automatically projective). The virtual dimension formula shows that $\text{vdim } \overline{\mathcal{M}}_{g,0}(X, \beta) = 0$ so we may expect a moduli space being a finite set of points.

If Q is a general quintic threefold in \mathbb{P}^4 (famously CY3 by the adjunction formula) the homology $H_2(Q, \mathbb{Z}) \cong \mathbb{Z}$ with a line in Q being a generator.

It is also famously known that for a general Q , there are exactly 2875 lines in Q . Then the moduli space $\overline{\mathcal{M}}_{0,0}(Q, 2)$ has those many components of dimension 2 corresponding to

$$\mathbb{P}^1 \xrightarrow{(\cdot)^2} \mathbb{P}^1 \hookrightarrow Q$$

the first map being a double cover - the dimension of $\overline{\mathcal{M}}_{0,0}(\mathbb{P}^1, 2)$ is 2, computing this obviously doesn't need any formula and the second map embedding \mathbb{P}^1 as a line in Q - 2875 possible ways.

• The main theorems

Theorem (Kontsevich) For X a projective scheme and $\beta \in A_1(X)$, $\overline{\mathcal{M}}_{g,n}(X, \beta)$ is a Deligne-Mumford stack and admits a projective coarse moduli space $\mathcal{M}_{g,n}(X, \beta)$

The situation for GW theory in genus 0 is better than higher genera.

Assume that X is nonsingular and convex (in addition to being projective).

By convexity is meant that for any morphism $\mu: \mathbb{P}^1 \rightarrow X$, $H^1(\mathbb{P}^1, \mu^*TX) = 0$ (no obstructions). The reason for naming the property 'convex' is probably this -

The vector bundle μ^*TX on \mathbb{P}^1 splits into a sum of line bundles $\bigoplus_{i=1}^{\dim X} \mathcal{O}(a_i)$

The vanishing of H^1 implies that $H^1(X, \mathcal{O}(a_i)) = 0 \forall i$ i.e. $a_i \geq -1 \forall i$. But if $a_i = -1$ for some i then one can apply the double cover precomposition trick (see EXAMPLE 3) to in fact conclude $a_i = -1$ is not possible so $a_i \geq 0 \forall i$.

Theorem (Behrend - Manin) Under the above assumptions on X , $\overline{M}_{0,n}(X, \beta)$ is a normal pure dimensional variety with dimension equal to the expected dimension $\dim X - 3 + n - K_X \cdot \beta$