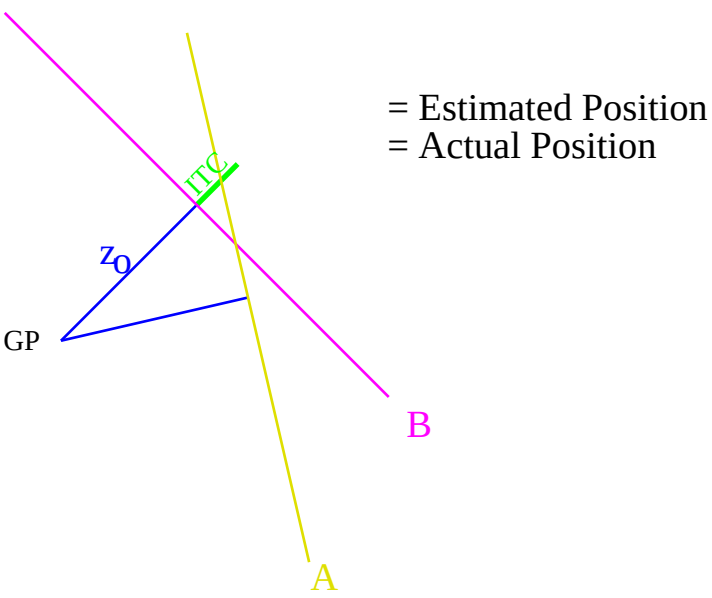
= Estimated Position
= Actual Position
TTC
z_0
GP
B
A