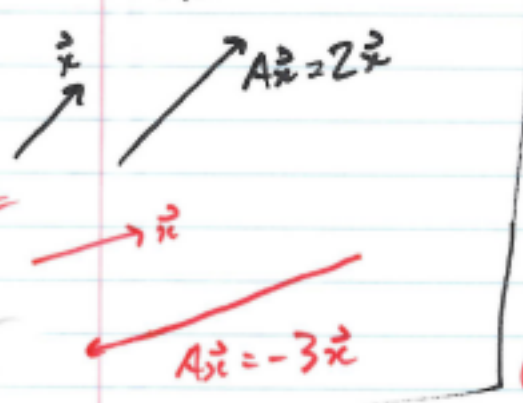


Math 152 Lecture 21 Complex Eigenvalues

Ex $R_{\mathbb{R}^2}$ in \mathbb{R}^2 , let $R = Rot_{\theta}$, $\theta \neq 0, \pi$

$R\vec{x}$ rotates \vec{x} by $\theta \Rightarrow R\vec{x} \neq \lambda\vec{x}$, $\vec{x} \neq 0$
 $\lambda \in \mathbb{R}$
 \hookrightarrow no real eigenvals

Aside
 $A\vec{x} = \lambda\vec{x}$



Geometric argument

Algebra: $R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

$\det(R - \lambda I) = \det \begin{bmatrix} \cos \theta - \lambda & -\sin \theta \\ \sin \theta & \cos \theta - \lambda \end{bmatrix}$

$= (\lambda - \cos \theta)^2 + \sin^2 \theta = 0$

$(\lambda - \cos \theta)^2 = -\sin^2 \theta \Rightarrow \lambda - \cos \theta = \pm \sqrt{-1} \sin \theta$

$\lambda = \cos \theta \pm i \sin \theta$

$\lambda_1 = \cos \theta + i \sin \theta$: $A - \lambda_1 I = \begin{bmatrix} -i \sin \theta & -\sin \theta \\ \sin \theta & -i \sin \theta \end{bmatrix} \sim \begin{bmatrix} -i \sin \theta & -\sin \theta \\ 0 & 0 \end{bmatrix}$

(div by $\sin \theta \neq 0$) $\sim \begin{bmatrix} i & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow x_2 = s$ (free)
 $i x_1 + 1 = 0$
 $x_1 = -1/i = -i/1 = i$

$\vec{v}_1 = \begin{bmatrix} i \\ 1 \end{bmatrix}$

Could repeat for $\lambda_2 = \cos \theta - i \sin \theta$ or use $\lambda_2 = \bar{\lambda}_1$

* Note: for real matrix $A\vec{v} = \lambda\vec{v} \Rightarrow \overline{A\vec{v}} = \overline{\lambda\vec{v}} \Rightarrow A\vec{v} = \bar{\lambda}\vec{v} \Rightarrow A\vec{v} = \bar{\lambda}\vec{v}$
so $\bar{\lambda}$ and \vec{v} also an eval/evec.

In our case $\lambda_2 = \cos \theta - i \sin \theta$, $\vec{v}_2 = \bar{\vec{v}}_1 = \begin{bmatrix} -i \\ 1 \end{bmatrix}$

Ex $A = \begin{bmatrix} 0 & 0 & 3 \\ 1 & 0 & -1 \\ 0 & 1 & 3 \end{bmatrix}$, find evals/evecs, hint: $\lambda_1 = 3$

$$\det(A - \lambda I) = \det \begin{bmatrix} -\lambda & 0 & 3 \\ 1 & -\lambda & -1 \\ 0 & 1 & 3-\lambda \end{bmatrix} = -\lambda(-\lambda(3-\lambda)+1) + 0 + 3(1) = -\lambda^3 + 3\lambda^2 - \lambda + 3 = 0^*$$

hint $\lambda_1 = 3$ is a root: divide ~~the~~ my polynomial by $\lambda - 3$

$$\begin{array}{r} -\lambda^2 \quad -1 \\ \lambda - 3 \overline{) -\lambda^3 + 3\lambda^2 - \lambda + 3} \\ \ominus -\lambda^3 + 3\lambda^2 \\ \hline -\lambda + 3 \\ \ominus -\lambda + 3 \\ \hline 0 \end{array}$$

polynomial long div

$$\Rightarrow (\lambda - 3)(-\lambda^2 - 1) = 0^*$$

$$\lambda_1 = 3 \quad \lambda^2 + 1 = 0 \quad \lambda_{2,3} = \pm i$$

$$\lambda_1 = 3: A - \lambda I: \begin{bmatrix} } \sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\lambda_2 = i: A - iI = \begin{bmatrix} -i & 0 & 3 \\ 1 & -i & -1 \\ 0 & 1 & 3-i \end{bmatrix} \begin{array}{l} i(1) \\ (2) \leftrightarrow (3) \end{array} \sim \begin{bmatrix} 1 & 0 & 3i \\ 0 & 1 & 3-i \\ 1 & -i & -1 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} -3i \\ -3+i \\ 1 \end{bmatrix} \quad \begin{array}{l} x_1 = -3i(1) \\ x_2 = -(3-i)(1) \\ x_3 = \text{free} = 1 \end{array} \sim \begin{bmatrix} 1 & 0 & 3i \\ 0 & 1 & 3-i \\ 0 & 0 & 0 \end{bmatrix}$$

will eventually go to 0 row

$$\lambda_3 = -i = \bar{\lambda}_2 \quad \text{so } \vec{v}_3 = \overline{\vec{v}_2} = \begin{bmatrix} -3i \\ -3+i \\ 1 \end{bmatrix} = \begin{bmatrix} 3i \\ -3-i \\ 1 \end{bmatrix}$$

Ex with previous A, evaluate $A^{13} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

step 1: find evals/evecs

step 2: $T\vec{c} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ solve for lin. comb. of evecs

$$\begin{bmatrix} 1 & -3i & 3i \\ 0 & -3+i & -3-i \\ 1 & 1 & 1 \end{bmatrix} \vec{c} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & -3i & 3i & | & 1 \\ 0 & -3+i & -3-i & | & 0 \\ 1 & 1 & 1 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & 1 \\ 0 & 1 & 0 & | & -\frac{1}{20} + \frac{3}{20}i \\ 0 & 0 & 1 & | & -\frac{1}{20} - \frac{3}{20}i \end{bmatrix}$$

so $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \vec{v}_1 + \left(-\frac{1}{20} + \frac{3}{20}i\right) \vec{v}_2 + \left(-\frac{1}{20} - \frac{3}{20}i\right) \vec{v}_3$

c_2, c_3
complex
conj

$$A^{13} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = c_1 \lambda_1^{13} \vec{v}_1 + c_2 \lambda_2^{13} \vec{v}_2 + c_3 \lambda_3^{13} \vec{v}_3$$

$$= \lambda^3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + \underbrace{\left(-\frac{1}{20} + \frac{3}{20}i\right)^{13} \begin{bmatrix} -3i \\ -3+i \\ 1 \end{bmatrix}}_{\vec{U} + \vec{V}} + \underbrace{\left(-\frac{1}{20} - \frac{3}{20}i\right)^{13} \begin{bmatrix} 3i \\ -3-i \\ 1 \end{bmatrix}}_{\vec{U} - \vec{V}}$$

note:
 $i^{13} = i^{12}i = (-1)^6 i = i$

$2 \operatorname{Re}\{2^{\text{nd}} \text{ term}\}$

$$\operatorname{Re} \left\{ i \left(-\frac{1}{20} + \frac{3}{20}i\right) \begin{bmatrix} -3i \\ -3+i \\ 1 \end{bmatrix} \right\}$$

$$= \operatorname{Re} \left\{ \left(-\frac{3}{20} - \frac{1}{20}i\right) \begin{bmatrix} -3i \\ -3+i \\ 1 \end{bmatrix} \right\} = \begin{bmatrix} -3/20 \\ 1/2 \\ -3/20 \end{bmatrix}$$

todo:
check on
computer!

should be $\frac{1}{10}$

missing $\frac{1}{10}$ last day

$$A^{13} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0.1 \\ 0.1 \\ 0.1 \end{bmatrix} - \frac{6}{20} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

(4)

Note: λ^{13} was easy here b/c $\lambda = i$, more generally you may want use polar form.
eg. $\lambda = 1+i = \sqrt{2} e^{i\pi/4}$

$$\begin{aligned}\lambda^{13} &= (\sqrt{2} e^{i\pi/4})^{13} = 2^{13/2} e^{i13\pi/4} \\ &= 2^{13/2} e^{i5\pi/4} \\ &= 2^{13/2} \left[\frac{-1}{\sqrt{2}} - \frac{i}{\sqrt{2}} \right] \\ &= 2^6 (-1-i) = -64 - 64i\end{aligned}$$

Theory on complex evals/evecs of real matrices

(λ, \vec{v})

come in complex conj pairs

$(\bar{\lambda}, \bar{\vec{v}})$

examples last day.

the dimension of space eigenvectors corresponding to λ is at least one and at most the multiplicity of the root λ of $\det(A - \lambda I)$

if $C = \{v_1, \dots, v_m\}$ is a set of evecs corresponding to different evals then C is l.i. \rightarrow "a basis of eigenvectors"

\hookrightarrow if A has no repeated evals, it has a basis of eigenvectors
 \hookrightarrow if A has repeated eval, then may or may not be a basis of evecs.

\hookrightarrow possible to modify recipe for $A^n \vec{x}$ but not in this course.

Common in many applications

if A is symmetric then it always has real eigenvalues and it always has a basis of eigenvectors (even if there are repeated roots).

Random walks

recall: problem $P^n \vec{x}^{(0)}$

- non-negative P_{ij}
 - columns sum to 1
- prob. transition matrix
- initial prob. vec.

def'n

If $\lim_{n \rightarrow \infty} P^n \vec{x}^{(0)} = \vec{p}$ for every initial $\vec{x}^{(0)}$, prob vec

then we say the random walk has an equilibrium probability vector \vec{p}

Theory: for transition matrix P :

- (1) eigenvalues satisfy $|\lambda| \leq 1$
- (2) always at least one eigenvalue $\lambda_1 = 1$. If this is the only eigenvalue with $|\lambda| = 1$ then \vec{v}_1 (evec with $\lambda_1 = 1$) is (after scaling) the equilibrium probability.
- (3) if $|\lambda| < 1$, then the corresponding evec has entries that sum to zero.
- (4) if P (or power of P) is matrix with strictly positive entries, the random walk has an equilibrium probability.

Ex $P = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$

by (4) it has
an equilibrium
prob.