

~~Errata~~ Errata last day:  $\frac{1}{10}$  missing for  $c_1$   
see also lec21\_...m

Last day: apply eigenanalysis to random walk

Ex  $P = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$  by (4) has an equilibrium prob  $\vec{p}$

Eigenanalysis: evalues:  $\det(A - \lambda I) = 0$  scalar eqn  
 $= \det \begin{bmatrix} \frac{1}{2} - \lambda & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} - \lambda \end{bmatrix} = 0$   
 $\Rightarrow (\frac{1}{2} - \lambda)(\frac{1}{2} - \lambda) - \frac{1}{4} = 0$   
 $\Rightarrow \lambda^2 - \lambda = 0$

$\lambda_1 = 1$  now solve  $(A - \lambda I)\vec{x} = \vec{0}$  (vector eqn)  
 $P - I = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \sim \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} \rightarrow$  evec is  $\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \vec{v}_1$

$\lambda_2 = 0$   $P - 0I = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \sim \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$  the equil. prob.  $\vec{p} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$   
 $\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$  note: property (3)  
 by property (2)

Intuition behind this: let  $\vec{x}^{(0)} = [a, 1-a]^T$  for some  $0 \leq a \leq 1$   
 Solve  $T\vec{c} = \vec{x}^{(0)}$  for  $\vec{c} \Rightarrow \begin{bmatrix} \frac{1}{2} & -1 & \vdots & a \\ \frac{1}{2} & 1 & \vdots & 1-a \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & \vdots & 1 \\ 0 & 1 & \vdots & \frac{1}{2}-a \end{bmatrix}$   
 evecs as cols

$\vec{x}^{(0)} = c_1 \vec{v}_1 + c_2 \vec{v}_2 = 1\vec{p} + (\frac{1}{2}-a)\vec{v}_2$

So  $P^n \vec{x}^{(0)} = c_1 \lambda_1^n \vec{v}_1 + c_2 \lambda_2^n \vec{v}_2 = \vec{p}$  for  $n \geq 1$

Ex  $P = \begin{bmatrix} 1/2 & 2/3 \\ 1/2 & 1/3 \end{bmatrix}$

Again by (4) we must have equilb prob.

Eigen analysis: ...  $\lambda_1 = 1$ ,  $\vec{v}_1 = \begin{bmatrix} 4/3 \\ 1 \end{bmatrix}$

$\lambda_2 = -1/6$ ,  $\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Rescale  $\vec{v}_1$  to get  $\vec{p} = \frac{1}{4/3+1} \begin{bmatrix} 4/3 \\ 1 \end{bmatrix} = \frac{1}{7/3} \begin{bmatrix} 4/3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4/7 \\ 3/7 \end{bmatrix} = \vec{p}$

Ex Same  $P$ , consider the walk $\vec{x}$  from  $\vec{x}(0)$

$\vec{x}(0) = c_1 \vec{p} + c_2 \vec{v}_2$

Sum entries gives 1

$\vec{v}_2$  entries sum to 0 by prop (3)

Trick: Sum entries in the eqn:  $1 = c_1 \cdot 1 + c_2 \cdot 0 \Rightarrow \boxed{c_1 = 1}$

So  $\vec{x}(0) = \vec{p} + c_2 \vec{v}_2$  depends on exactly which  $\vec{x}(0)$

equilib prob + "perturbation" away from equilibrium

$P^n \vec{x}(0) = \vec{p} + c_2 \left(-\frac{1}{6}\right)^n \vec{v}_2$

oscillating and shrinking as  $n$  increases

So  $\lim_{n \rightarrow \infty} P^n \vec{x}(0) = \vec{p}$

Ex: 
$$P = \begin{bmatrix} 0 & 1/4 & 1/2 & 0 \\ 1/2 & 1/4 & 0 & 1/2 \\ 1/2 & 1/4 & 0 & 0 \\ 0 & 1/4 & 1/2 & 1/2 \end{bmatrix}$$

note: some entries = 0  
cannot use prop (4)

↳ Octave:  $\lambda_1 = 1$       $\vec{v}_1 = [1 \ 2 \ 1 \ 2]^T$

$\lambda_2 = -1/2$       $\vec{v}_2 = [2 \ -2 \ -1 \ 1]^T$

$\lambda_3 = 0$       $\vec{v}_3 = [1 \ -2 \ 1 \ 0]^T$

$\lambda_4 = 1/4$       $\vec{v}_4 = [-1 \ 1 \ -1 \ 1]^T$

$$\vec{p} = \frac{1}{\sum_i v_i} \vec{v}_1 = \frac{1}{6} \vec{v}_1 = [1/6 \ 1/3 \ 1/6 \ 1/3]^T$$

Walk: state  $x^{(0)} = \vec{p} + c_2 \vec{v}_2 + c_3 \vec{v}_3 + c_4 \vec{v}_4$       $d_3 = 0$

$$P^n x^{(0)} = \vec{p} + c_2 (-1/2)^n \vec{v}_2 + c_4 (1/4)^n \vec{v}_4 + 0$$

more interesting than  $c_4$  term  
b/c shrinks slower

Ex 
$$P = \begin{bmatrix} 1/2 & 0 & 1/3 \\ 1/4 & 3/4 & 1/3 \\ 1/4 & 1/4 & 1/3 \end{bmatrix}$$

$$= \frac{1}{6 \cdot 12 \cdot 12} \det \begin{bmatrix} 1/2 - \lambda & 0 & 1/3 \\ 1/4 & 3/4 - \lambda & 1/3 \\ 1/4 & 1/4 & 1/3 - \lambda \end{bmatrix} = 0$$

$$= \det \begin{bmatrix} 3-6\lambda & 0 & 2 \\ 3 & 9-12\lambda & 4 \\ 3 & 3 & 4-12\lambda \end{bmatrix} = 0$$

$f(\lambda)$

$f(\lambda) = -864\lambda^3 + 1368\lambda^2 - 540\lambda + 36$

But  $\lambda_1 = 1$  should be a root.  $f(1) = 0 \checkmark$

poly long div

$$\begin{array}{r}
 -864\lambda^2 + 504\lambda - 36 \\
 \hline
 \lambda - 1 \quad -864\lambda^3 + 1368\lambda^2 - 540\lambda + 36 \\
 \ominus -864\lambda^2 + 864\lambda^2 \\
 \hline
 504\lambda^2 - 540\lambda + 36 \\
 \ominus 504\lambda^2 - 504\lambda \\
 \hline
 -36\lambda + 36 \\
 \ominus -36\lambda + 36 \\
 \hline
 0 \quad \checkmark
 \end{array}$$

So roots are ... use the quadratic formula:

$$\lambda_1 = 1, \quad \lambda_2 = 1/2, \quad \lambda_3 = 1/12$$

Ex Find the equilib prob in previous:

$$\vec{v}_1 = \begin{bmatrix} 2/3 \\ 2 \\ 1 \end{bmatrix} \Rightarrow \sum_i v_i = \frac{11}{3} \Rightarrow \vec{p} = \begin{bmatrix} 2/11 \\ 6/11 \\ 3/11 \end{bmatrix}$$

Application of eigen analysis: differential eqns.

Review:  $x(t)$  is an unknown function that satisfies a differential eqn: (DE)

$$\frac{dx}{dt} = f(x, t) \quad \text{for all } t. \quad (1)$$

↑  
given

Common in physics, biology, economics, etc

(1) is first-order, nonlinear (b/c we know nothing about  $f$ )

If an "initial condition" <sup>IC</sup>  $x(0) = x_0$  is given, then  $x(t)$  is uniquely determined (at least for many fens  $f$ ), at least "near"  $t=0$ .

DE & IC = "initial value problem" (IVP)

Simplest IVP:  $\frac{dx}{dt} = ax, \quad x(0) = x_0 \quad (2)$

↑  
given constant, not  $a(t)$

first-order,  
linear, Scalar — relax this in 152  
homogeneous, and  
constant coeff.

↳ see math 101  
math 255

Review: sol'n to this IVP (2) is

$$x(t) = x_0 e^{at} \quad (3)$$

How?

(1) so find a sol'n:  $x(t) = e^{at}$

(2) "general sol'n" of the DE is  $x(t) = C e^{at}$  for any  $C$  (linearity)

(3) plug general sol'n into IC, solve for  $C$ :  
 $x(0) = C e^0 = \boxed{C = x_0}$

Note:  $a$  could be complex  $a = \alpha + i\beta$   
and (3) is still a sol'n:

$$x_0 e^{at} = x_0 e^{(\alpha + i\beta)t} = x_0 e^{\alpha t} e^{i\beta t} = x_0 e^{\alpha t} (\cos \beta t + i \sin \beta t)$$

$\text{Re}(a) = \alpha$  corresponds to:  
 $\alpha > 0$  exponential growth  
 $\alpha < 0$  " decay  
 $\alpha = 0$  neither

$\text{Im}(a) = \beta$   
gives oscillation

Next: look at  $\frac{d\vec{x}}{dt} = A\vec{x}$

↓  
the skeletal  
linear vector  
IVP.

$\vec{x}(0) = \vec{x}_0$   
 $n \times n$  matrix  
vector of fens