

# Math 253 Notes on Moments of Inertia

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Colin B. Macdonald, CC-BY 2016. Supplementary notes for Math 253, to follow Section 13.4 “Center of Mass” of our text APEX Calculus 3, version 3.0.

## 1 Moments of Inertia

We’ve previously seen *moments* when calculating centre of mass of a lamina. This involved two double integrals:

$$M_y = \iint_D x\rho(x, y)dA$$
$$M_x = \iint_D y\rho(x, y)dA$$

These can also be called the “first moments”; here we look at the “second moments” or “moments of inertia”.

### 1.1 Kinetic Energy of a spinning lamina

Suppose our lamina (which lies in the  $x$ - $y$  plane) is rotating around the  $z$ -axis (note this is orthogonal to the lamina) at a constant angular rotational speed  $\omega$  radians/s. (E.g., 60 rpm = 1 rev/s =  $2\pi$  rad/s). Find the *Kinetic Energy* of the lamina. [Draw diagram!]

Riemann sum idea: as before, we consider a small rectangular piece  $R_{ij}$  with area  $\Delta x\Delta y$ . The kinetic energy of a point mass is  $\frac{1}{2}mv^2$ . Its going to be small in the limit so we use this to get:

$$\frac{1}{2}\rho(x_i, y_j)\Delta x\Delta y|\vec{v}_{ij}|^2.$$

The piece  $R_{ij}$  moves faster the further it is from the axis of rotation ( $z$ -axis,  $(x, y) = (0, 0)$ ). Different pieces move at different speeds. Our piece has kinetic energy:

$$\frac{1}{2}\rho(x_i, y_j)\Delta x\Delta y\omega^2(x_i^2 + y_j^2).$$

So take the Riemann sum over all pieces of the lamina and we get:

$$K = \frac{1}{2}\omega^2 \iint_D (x^2 + y^2)\rho(x, y)dA.$$

We define  $I_0$  the **moment of inertia** about the  $z$ -axis as just the integral part:

$$I_0 = \iint_D (x^2 + y^2)\rho(x, y)dA.$$

Larger  $I_0$  means more energy (work) to rotate the lamina about the  $z$ -axis.

## 1.2 About some other axis?

A similar argument shows how to compute the moment of inertia about some other axis parallel to the  $z$ -axis, centred at  $(x, y) = (a, b)$ :

$$I_0 = \int \int_D ((x - a)^2 + (y - b)^2) \rho(x, y) dA.$$

And in particular about the centre of mass  $(x, y) = (\bar{x}, \bar{y})$ , this would be:

$$I_{0,c} =$$

## 1.3 $x$ and $y$ axes of rotation

What about rotating around the  $x$ -axis and  $y$ -axis? This gives the moment of inertia about the  $y$ -axis denoted  $I_y$  and the moment of inertia about the  $x$ -axis denoted  $I_x$ . [Draw diagrams]

$$I_y =$$

$$I_x =$$

Note relationship to previous,  $I_0 =$

## 1.4 Changing the axis of rotation

Suppose we have  $I_{0,c}$  and want rotation around  $z$ -axis? Let  $M$  be overall mass of lamina. We get:

$$I_0 =$$

## 1.5 Examples

1. Find moment of inertia about the  $z$ -axis of a uniform circular disc of radius  $R$  and total mass  $M$ , centred at the origin.
2. Find same, but with disc centred at point  $(a, b)$ .
3. Find same, for a uniform rectangular plate, mass  $M$ , axis through centre, size  $a \times b$ .