DISCRETE AND CONTINUOUS DYNAMICAL SYSTEMS Volume **36**, Number **6**, June **2016** 

pp. 2991-3009

## A DEGENERATE EDGE BIFURCATION IN THE 1D LINEARIZED NONLINEAR SCHRÖDINGER EQUATION

## MATT COLES AND STEPHEN GUSTAFSON

Department of Mathematics, University of British Columbia 1984 Mathematics Road Vancouver, British Columbia, Canada V6T 1Z2

(Communicated by Chongchun Zeng)

ABSTRACT. This work deals with the focusing Nonlinear Schrödinger Equation in one dimension with pure-power nonlinearity near cubic. We consider the spectrum of the linearized operator about the soliton solution. When the nonlinearity is exactly cubic, the linearized operator has resonances at the edges of the essential spectrum. We establish the degenerate bifurcation of these resonances to eigenvalues as the nonlinearity deviates from cubic. The leadingorder expression for these eigenvalues is consistent with previous numerical computations.

1. Introduction. The focusing, pure-power, Nonlinear Schrödinger Equation for  $\psi(x,t) \in \mathbb{C}, x \in \mathbb{R}^n, t \in \mathbb{R}$ ,

$$i\partial_t \psi = -\Delta \psi - |\psi|^{p-1} \psi \qquad (\text{NLS}_p)$$

finds applications in quantum mechanics, optics, and other areas, and has seen intensive mathematical study in recent years (eg. [25, 15]). (NLS<sub>p</sub>) famously exhibits solitary waves (sometimes called solitons), solutions which maintain a fixed spatial profile, and which are observed to play a key role in the dynamics of general solutions. One naturally asks about the stability of these waves, which leads immediately to an investigation of the spectrum of the linearized operator governing the dynamics close to the solitary wave solution. Systematic spectral analysis of the linearized operator has a long history (eg. [29, 12], and for more recent studies [9, 4, 27, 28]).

The principle motivation for the present work comes from [4] where *resonance* eigenvalues (with explicit resonance eigenfunctions) were observed to sit at the edges (or *thresholds*) of the spectrum for the 1D linearized NLS problem with focusing cubic nonlinearity. Numerically, it was observed that the same problem with power nonlinearity close to p = 3 (on both sides) has a true eigenvalue close to the threshold. In this paper we establish analytically the observed qualitative behaviour. Stated roughly, our main result is:

for  $p \approx 3$ ,  $p \neq 3$ , the linearization of the 1D (NLS<sub>p</sub>) about its soliton has purely imaginary eigenvalues, bifurcating from resonances at the edges of the essential

<sup>2010</sup> Mathematics Subject Classification. 35P15, 35Q55.

Key words and phrases. Nonlinear Schrödinger equation, linearized operator, edge bifurcation, Birman-Schwinger formulation, resolvent expansion, Lyapunov-Schmidt reduction.

spectrum of linearized (NLS<sub>3</sub>), whose distance from the thresholds is of order  $(p-3)^4$ .

The exact statement is given as Theorem 4 in Section 4, and includes the precise leading order behaviour of the eigenvalues.

The eigenvalues obtained here, being on the imaginary axis, correspond to *stable* behaviour at the linear level. A further motivation for obtaining detailed information about the spectra of linearized operators is that such information is a key ingredient in studying the *asymptotic stability* of solitary waves: see [2, 5, 6, 11, 23, 24, 1, 7] for some results of this type. Such results typically assume the absence of threshold eigenvalues or resonances. The presence of a resonance is an exceptional case which complicates the stability analysis by retarding the time-decay of perturbations. Nevertheless, the asymptotic stability of solitons in the 1D cubic focusing NLS was recently proved in [10]. The proof relies on integrable systems technology and so is only available for the cubic equation. The solitons are known to be stable in the (weaker) orbital sense for all p < 5 (the so-called mass subcritical range) while for  $p \ge 5$  they are unstable [13, 30], but the question of asymptotic stability for p < 5 and  $p \ne 3$  seems to be open. The existence (and location) of eigenvalues on the imaginary axis, which is shown here, should play a role in any attempt on this problem.

The generic bifurcation of resonances and eigenvalues from the edge of the essential spectrum was studied by [8] and [26] in three dimensions. Edge bifurcations have also been studied in one dimensional systems using the Evans function in [20] and [21] as well as in the earlier works [18], [19] and [22]. We do not follow that route, but rather adopt the approach of [8, 26] (going back also to [17], and in turn to the classical work [16]), using a *Birman-Schwinger* formulation, resolvent expansion, and *Lyapunov-Schmidt reduction*.

Our work is distinct from [8, 26] due to the unique challenges of working in one dimension, in particular the strong singularity of the free resolvent at zero energy, which among other things increases by one the dimension of the range of the projection involved in the Lyapunov-Schmidt reduction procedure.

Moreover, our work is distinct from all of [20, 21, 8, 26] in that we study the particular (and as it turns out non-generic) resonance and perturbation corresponding to the near-cubic pure-power NLS problem. Generically, a resonance is associated with the birth or death of an eigenvalue, and such is the picture obtained in [8, 26, 20, 21]: an eigenvalue approaches the essential spectrum, becomes a resonance on the threshold and then disappears. In our setting, the eigenvalue approaches the essential spectrum, sits on the threshold as a resonance, then returns as an eigenvalue. The bifurcation is degenerate in the sense that the expansion of the eigenvalue begins at higher order, and the analysis we develop to locate this eigenvalue is thus considerably more delicate.

The paper is organized as follows. The problem is set up in Section 2. In Section 3 we collect some results that are necessary for the bifurcation analysis. Section 4 is devoted to the statement and proof of the main result. The positivity of a certain (explicit) coefficient, which is crucial to the proof, is verified numerically; details of this computation are given in Section 5.

2. Mathematical setup. We consider  $(NLS_p)$  in one space dimension:

$$i\partial_t \psi = -\partial_x^2 \psi - |\psi|^{p-1} \psi.$$
 (2.1)

Here  $\psi = \psi(x,t) : \mathbb{R} \times \mathbb{R} \to \mathbb{C}$  with 1 . The NLS (2.1) admits solutions of the form

$$\psi(x,t) = Q_p(x)e^{it} \tag{2.2}$$

where  $Q_p(x) > 0$  satisfies

$$-Q_p'' - Q_p^p + Q_p = 0. (2.3)$$

In one dimension the explicit solutions

$$Q_p^{p-1}(x) = \left(\frac{p+1}{2}\right)\operatorname{sech}^2\left(\frac{p-1}{2}x\right)$$
(2.4)

of (2.3) for each  $p \in (1, \infty)$  are classically known to be the unique  $H^1$  solutions of (2.3) up to spatial translation and phase rotation (see e.g. [3]). In what follows we study the linearized NLS problem. That is, linearize (2.1) about the *solitary wave* solutions (2.2) by considering solutions of the form

$$\psi(x,t) = \left(Q_p(x) + h(x,t)\right)e^{it}.$$

Then h solves, to leading order (i.e. neglecting terms nonlinear in h)

$$i\partial_t h = (-\partial_x^2 + 1)h - Q_p^{p-1}h - (p-1)Q_p^{p-1}\operatorname{Re}(h).$$

We write the above as a matrix equation

$$\partial_t \vec{h} = J \hat{H} \vec{h}$$

with

$$\vec{h} := \begin{pmatrix} \operatorname{Re}(h) \\ \operatorname{Im}(h) \end{pmatrix} \qquad J^{-1} := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
$$\hat{H} := \begin{pmatrix} -\partial_x^2 + 1 - pQ_p^{p-1} & 0 \\ 0 & -\partial_x^2 + 1 - Q_p^{p-1} \end{pmatrix}.$$

The above  $J\hat{H}$  is the linearized operator as it appears in [4]. We now consider the system rotated

$$i\partial_t \vec{h} = iJ\hat{H}\vec{h}$$

and find U unitary so that,  $UiJ\hat{H}U^* = \sigma_3 H$ , where  $\sigma_3$  is one of the Pauli matrices and with H self-adjoint:

$$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \qquad U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ 1 & -i \end{pmatrix},$$
$$H = \begin{pmatrix} -\partial_x^2 + 1 & 0 \\ 0 & -\partial_x^2 + 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} p+1 & p-1 \\ p-1 & p+1 \end{pmatrix} Q_p^{p-1} =: \tilde{H} - V^{(p)}.$$

In this way we are consistent with the formulation of [8, 26]. We can also arrive at this system,  $i\partial_t \vec{h} = \sigma_3 H \vec{h}$ , by letting  $\vec{h} = \begin{pmatrix} h & \bar{h} \end{pmatrix}^T$  from the start.

Thus we are interested in the spectrum of

$$\mathcal{L}_p := \sigma_3 H$$

and so in what follows we consider the eigenvalue problem

$$\mathcal{L}_p u = zu, \qquad z \in \mathbb{C}, \qquad u \in L^2(\mathbb{R}, \mathbb{C}^2).$$
 (2.5)

That the essential spectrum of  $\mathcal{L}_p$  is

$$\sigma_{ess}(\mathcal{L}_p) = (-\infty, -1] \cup [1, \infty)$$

and 0 is an eigenvalue of  $\mathcal{L}_p$  are standard facts [4].

When p = 3 we have the following *resonance* at the threshold z = 1 [4]

$$u_0 = \begin{pmatrix} 2 - Q_3^2 \\ -Q_3^2 \end{pmatrix} = 2 \begin{pmatrix} \tanh^2 x \\ -\operatorname{sech}^2 x \end{pmatrix}$$
(2.6)

in the sense that

$$\mathcal{L}_3 u_0 = u_0, \qquad u_0 \in L^{\infty}, \qquad u_0 \notin L^q, \text{ for } q < \infty.$$
(2.7)

Our main interest is how this resonance bifurcates when  $p \neq 3$  but |p-3| is small. We now seek an eigenvalue of (2.5) in the following form

$$z = 1 - \alpha^2, \qquad \alpha > 0. \tag{2.8}$$

We note that the spectrum of  $\mathcal{L}_p$  for the soliton (2.4) may only be located on the Real or Imaginary axes [4], and so any eigenvalues in the neighbourhood of z = 1 must be real. There is also a resonance at z = -1 which we do not mention further; symmetry of the spectrum of  $\mathcal{L}_p$  ensures the two resonances bifurcate in the same way.

We now recast the problem in accordance with the *Birman-Schwinger formula*tion (pp. 85 of [14]), as in [8, 26]. For (2.8), (2.5) becomes

$$(\sigma_3 \tilde{H} - 1 + \alpha^2)u = \sigma_3 V^{(p)}u$$

The constant-coefficient operator on the left is now invertible so we can write

$$u = (\sigma_3 \tilde{H} - 1 + \alpha^2)^{-1} \sigma_3 V^{(p)} u =: R^{(\alpha)} V^{(p)} u.$$

After noting that  $V^{(p)}$  is positive we set

$$w := V_0^{1/2} u, \quad V_0 := V^{(p=3)}$$

and apply  $V_0^{1/2}$  to arrive at the problem

$$w = -K_{\alpha,p}w, \qquad K_{\alpha,p} := -V_0^{1/2} R^{(\alpha)} V_0^{(p)} V_0^{-1/2}$$
(2.9)

with

$$R^{(\alpha)} = \begin{pmatrix} (-\partial_x^2 + \alpha^2)^{-1} & 0\\ 0 & (-\partial_x^2 + 2 - \alpha^2)^{-1} \end{pmatrix}.$$
 (2.10)

We now seek solutions  $(\alpha, w)$  of (2.9) which correspond to eigenvalues  $1 - \alpha^2$  and eigenfunctions  $V_0^{-1/2} w$  of (2.5). The decay of the potential  $V^{(p)}$  and hence  $V_0^{\frac{1}{2}}$  now allows us to work in the space  $L^2 = L^2(\mathbb{R}, \mathbb{C}^2)$ , whose standard inner product we denote by  $\langle \cdot, \cdot \rangle$ .

The resolvent  $R^{(\alpha)}$  has integral kernel

$$R^{(\alpha)}(x,y) = \begin{pmatrix} \frac{1}{2\alpha} e^{-\alpha|x-y|} & 0\\ 0 & \frac{1}{2\sqrt{2-\alpha^2}} e^{-\sqrt{2-\alpha^2}|x-y|} \end{pmatrix}$$

for  $\alpha > 0$ . We expand  $R^{(\alpha)}$  as

$$R^{(\alpha)} = \frac{1}{\alpha} R_{-1} + R_0 + \alpha R_1 + \alpha^2 R_R.$$
 (2.11)

These operators have the following integral kernels

$$R_{-1}(x,y) = \begin{pmatrix} \frac{1}{2} & 0\\ 0 & 0 \end{pmatrix}, R_0(x,y) = \begin{pmatrix} -\frac{|x-y|}{2} & 0\\ 0 & \frac{e^{-\sqrt{2}|x-y|}}{2\sqrt{2}} \end{pmatrix}, R_1(x,y) = \begin{pmatrix} \frac{|x-y|^2}{4} & 0\\ 0 & 0 \end{pmatrix}$$

and for  $\alpha > 0$  the remainder term  $R_R$  is continuous in  $\alpha$  and uniformly bounded as an operator from a weighted  $L^2$  space (with sufficiently strong polynomial weight) to its dual. Moreover, since the entries of the full integral kernel  $R^{(\alpha)}(x, y)$  are bounded functions of |x - y|, we see that the entries of

$$R_R(x,y) = \frac{1}{\alpha^2} \left( R^{(\alpha)}(x,y) - \left(\frac{1}{\alpha}R_{-1}(x,y) + R_0(x,y) + \alpha R_1(x,y)\right) \right)$$

grow at most quadratically in |x - y| as  $|x - y| \to \infty$ . We also expand the potential  $V^{(p)}$  in  $\varepsilon$  where  $\varepsilon := p - 3$ 

$$V^{(p)} = V_0 + \varepsilon V_1 + \varepsilon^2 V_2 + \varepsilon^3 V_R, \qquad \varepsilon := p - 3$$
(2.12)

and

$$V_{0} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} Q_{3}^{2} \qquad V_{1} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} Q_{3}^{2} + \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} q_{1}$$
$$V_{2} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} q_{1} + \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} q_{2} \qquad V_{R} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} q_{2} + \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} q_{R}$$
$$V_{0}^{1/2} = \frac{1}{2} \begin{pmatrix} \sqrt{3} + 1 & \sqrt{3} - 1 \\ \sqrt{3} - 1 & \sqrt{3} + 1 \end{pmatrix} Q_{3}.$$

Here we have expanded

$$Q_p^{p-1}(x) = Q_3^2(x) + \varepsilon q_1(x) + \varepsilon^2 q_2(x) + \varepsilon^3 q_R(x)$$

and the computation gives

$$Q_3^2(x) = 2 \operatorname{sech}^2 x, \qquad q_1(x) = \operatorname{sech}^2 x \left(\frac{1}{2} - 2x \tanh x\right)$$
$$q_2(x) = \frac{1}{2} \left(2x^2 \tanh^2 x \operatorname{sech}^2 x - x^2 \operatorname{sech}^4 x - x \tanh x \operatorname{sech}^2 x\right).$$

By Taylor's theorem, the remainder term  $q_R(x)$  satisfies an estimate of the form  $|q_R(x)| \leq C(1+|x|^3) \operatorname{sech}^2(x/2)$  for some constant C which is uniform in x and  $\varepsilon \in (-1, 1)$ . We will henceforth write

Q for  $Q_3$  and  $K_{\alpha,\varepsilon}$  for  $K_{\alpha,p}$ .

## 3. Some preliminaries. We study (2.9), that is:

$$(K_{\alpha,\varepsilon} + 1)w = 0. \tag{3.1}$$

Using the expansions (2.11) and (2.12) for  $R^{(\alpha)}$  and  $V^{(p)}$  we make the following expansion

$$K_{\alpha,\varepsilon} = \frac{1}{\alpha} \left( K_{-10} + \varepsilon K_{-11} + \varepsilon^2 K_{-12} + \varepsilon^3 K_{R1} \right) + K_{00} + \varepsilon K_{01} + \varepsilon^2 K_{02} + \varepsilon^3 K_{R2} + \alpha K_{10} + \alpha \varepsilon K_{R3} + \alpha^2 K_{R4}$$

$$(3.2)$$

where  $K_{R4}$  is uniformly bounded and continuous in  $\alpha > 0$  and  $\varepsilon$  in a neighbourhood of 0, as an operator on  $L^2(\mathbb{R}, \mathbb{C}^2)$ .

Before stating the main theorem we assemble some necessary facts about the above operators.

**Lemma 1.** Each operator appearing in the expansion (3.2) for  $K_{\alpha,\varepsilon}$  is a Hilbert-Schmidt (so in particular bounded and compact) operator from  $L^2(\mathbb{R}, \mathbb{C}^2)$  to itself.

*Proof.* This is a straightforward consequence of the spatial decay of the weights which surround the resolvent. The facts that  $||V_0^{-1/2}|| \leq Ce^{|x|}$ , and that  $||V_0^{1/2}|| \leq Ce^{-|x|}$ , while each of  $||V_0||$ ,  $||V_1||$ ,  $||V_2||$  and  $||V_R||$  can be bounded by  $Ce^{-3|x|/2}$  (say if we restrict to  $|\varepsilon| < \frac{1}{2}$ ) imply easily that these operators all have square integrable integral kernels.

**Remark 2.** The same decay estimates for the potentials used in the proof of Lemma 1 show that for  $\alpha > 0$  and  $w \in L^2$  solving (2.9) the corresponding eigenfunction of (2.5)  $u = V_0^{-1/2} w$  lies in  $L^2$  and so the eigenvalue  $z = 1 - \alpha^2$  is in fact a true eigenvalue. Indeed  $w \in L^2 \implies V^{(p)} V_0^{-1/2} w \in L^2$  and so  $u = -R^{(\alpha)} V^{(p)} V_0^{-1/2} w \in L^2$ , since the free resolvent  $R^{(\alpha)}$  preserves  $L^2$  for  $\alpha > 0$ .

We will also need the projections P and  $\overline{P}$  which are defined as follows: for  $f\in L^2$  let

$$Pf := \frac{\langle v, f \rangle v}{\|v\|^2}, \quad v := V_0^{1/2} \left( \begin{array}{c} 1\\ 0 \end{array} \right)$$

as well as the complementary  $\overline{P} := 1 - P$ . A direct computation shows that for any  $f \in L^2$  we have

$$K_{-10}f = -4Pf. (3.3)$$

Note that all operators in the expansion containing  $R_{-1}$  return outputs in the direction of v.

**Lemma 3.** The operator  $\overline{P}(K_{00}+1)\overline{P}$  has a one dimensional kernel spanned by

$$w_0 := V_0^{1/2} u_0$$

as an operator from  $\operatorname{Ran}(\overline{P})$  to  $\operatorname{Ran}(\overline{P})$ .

*Proof.* First note that by (2.7)

$$-V_0 u_0 = \sigma_3 u_0 - \tilde{H} u_0, \qquad [-V_0 u_0]_1 = [u_0]_1'' \tag{3.4}$$

from which it follows that

$$Pw_0 = 0$$
, i.e.  $w_0 \in \operatorname{Ran}(\overline{P})$ .

Then a direct computation using (3.4), the expansion (3.2), the expression for  $R_0$ , and integration by parts, shows that

$$(K_{00}+1)w_0 = 2v$$

and so indeed  $\overline{P}(K_{00}+1)\overline{P}w_0=0$ .

Theorem 5.2 in [17] shows that the kernel of the analogous scalar operator can be at most one dimensional. We will use this argument, adapted to the vector structure, to show that any two non-zero elements of the kernel must be multiples of each other. Take  $w \in L^2$  with  $\langle w, v \rangle = 0$  and  $\overline{P}(K_{00} + 1)w = 0$ . That is  $(K_{00} + 1)w = cv$  for some constant c. This means

$$-V_0^{1/2}R_0V_0V_0^{-1/2}w + w = cV_0^{1/2} \begin{pmatrix} 1\\ 0 \end{pmatrix}.$$

Let  $w = V_0^{1/2} u$  where  $u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ . We then obtain, after rearranging and expanding

$$\left(\begin{array}{c}u_1\\u_2\end{array}\right) = \left(\begin{array}{c}c-\frac{1}{2}\int_{\mathbb{R}}|x-y|Q^2(y)\left(2u_1(y)+u_2(y)\right)dy\\\frac{1}{2\sqrt{2}}\int_{\mathbb{R}}\exp\left(-\sqrt{2}|x-y|\right)Q^2(y)(u_1(y)+2u_2(y))dy\end{array}\right).$$

We now rearrange the first component. Expand

$$\begin{aligned} -\frac{1}{2} \int_{\mathbb{R}} |x-y| Q^2(y) (2u_1(y) + u_2(y)) dy \\ &= -\frac{1}{2} \int_{-\infty}^x (x-y) Q^2(y) (2u_1(y) + u_2(y)) dy \\ &- \frac{1}{2} \int_x^\infty (y-x) Q^2(y) (2u_1(y) + u_2(y)) dy \end{aligned}$$

and rewrite the first term as

$$-\frac{x}{2}\int_{-\infty}^{x}Q^{2}(y)(2u_{1}(y)+u_{2}(y))dy + \frac{1}{2}\int_{-\infty}^{x}yQ^{2}(y)(2u_{1}(y)+u_{2}(y))dy$$
$$=\frac{x}{2}\int_{x}^{\infty}Q^{2}(y)(2u_{1}(y)+u_{2}(y))dy + b - \frac{1}{2}\int_{x}^{\infty}yQ^{2}(y)(2u_{1}(y)+u_{2}(y))dy$$

where

$$b := \frac{1}{2} \int_{\mathbb{R}} y Q^2(y) (2u_1(y) + u_2(y)) dy$$

and where we used  $\int_{\mathbb{R}} 2Q^2 u_1 + Q^2 u_2 = 0$  since  $\langle w, v \rangle = 0$ . So putting everything back together we see

$$\begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} c+b+\int_x^\infty (x-y)Q^2(y)\left(2u_1(y)+u_2(y)\right)dy\\ \frac{1}{2\sqrt{2}}\int_{\mathbb{R}}\exp\left(-\sqrt{2}|x-y|\right)Q^2(y)(u_1(y)+2u_2(y))dy \end{pmatrix}.$$
 (3.5)

We claim that as  $x \to \infty$ 

$$\left(\begin{array}{c} u_1\\ u_2 \end{array}\right) \to \left(\begin{array}{c} c+b\\ 0 \end{array}\right).$$

Observe

$$\left| \int_{x}^{\infty} (x-y)Q^{2}(y) \left( 2u_{1}(y) + u_{2}(y) \right) dy \right| \leq \int_{x}^{\infty} |y-x|Q^{2}(y)| 2u_{1}(y) + u_{2}(y)| dy$$
$$\leq \int_{x}^{\infty} |y|Q^{2}(y)| 2u_{1}(y) + u_{2}(y)| dy$$
$$\to 0$$

as  $x \to \infty$ . Here we have used the fact that  $w \in L^2$  implies  $Q|2u_1 + u_2| \in L^2$  and that  $|y|Q \in L^2$ . As well, in the second component

$$\begin{split} \int_{\mathbb{R}} e^{-\sqrt{2}|x-y|} Q^2(y)(u_1(y) + 2u_2(y)) dy \\ = & e^{-\sqrt{2}x} \int_{-\infty}^x e^{\sqrt{2}y} Q^2(y)(u_1(y) + 2u_2(y)) dy \\ & + e^{\sqrt{2}x} \int_x^\infty e^{-\sqrt{2}y} Q^2(y)(u_1(y) + 2u_2(y)) dy \end{split}$$

$$\begin{aligned} \left| e^{-\sqrt{2}x} \int_{-\infty}^{x} e^{\sqrt{2}y} Q^{2}(y)(u_{1}(y) + 2u_{2}(y))dy \right| \\ &\leq e^{-\sqrt{2}x} \int_{-\infty}^{x} e^{\sqrt{2}y} Q^{2}(y)|u_{1}(y) + 2u_{2}(y)|dy \\ &\leq e^{-\sqrt{2}x} \left( \int_{-\infty}^{x} e^{2\sqrt{2}y} Q^{2}(y)dy \right)^{1/2} \left( \int_{-\infty}^{x} Q^{2}(y)|u_{1}(y) + 2u_{2}(y)|^{2}dy \right)^{1/2} \\ &\leq C e^{-\sqrt{2}x} \left( \int_{-\infty}^{x} e^{2\sqrt{2}y} Q^{2}(y)dy \right)^{1/2} \\ &\leq C e^{-\sqrt{2}x} \left( \int_{-\infty}^{x} e^{2\sqrt{2}y} e^{-2y}dy \right)^{1/2} \\ &\leq C e^{-\sqrt{2}x} \left( e^{-2\sqrt{2}x} e^{-2x} \right)^{1/2} \leq C e^{-x} \to 0, \quad x \to \infty \end{aligned}$$

where we again used  $Q|u_1 + 2u_2| \in L^2$ . Similarly,

l

$$\left| e^{\sqrt{2}x} \int_x^\infty e^{-\sqrt{2}y} Q^2(y) (u_1(y) + 2u_2(y)) dy \right| \to 0$$

as  $x \to \infty$  which addresses the claim.

Next we claim that if c + b = 0 in (3.5) then  $u \equiv 0$ . To address the claim we first note that if c + b = 0 then  $u \equiv 0$  for all  $x \ge X$  for some X, by estimates similar to those just done. Finally, we appeal to ODE theory. Differentiating (3.5) in x twice returns the system

$$u_1'' = -2Q^2 u_1 - Q^2 u_2 \tag{3.6}$$

$$u_2'' - 2u_2 = -Q^2 u_1 - 2Q^2 u_2. aga{3.7}$$

Any solution u to the above with  $u \equiv 0$  for all large enough x must be identically zero.

With the claim in hand we finish the argument. Given two non-zero elements of the kernel, say u and  $\tilde{u}$  with limits as  $x \to \infty$  (written as above) c + b and  $\tilde{c} + \tilde{b}$  respectively, the combination

$$u^* = u - \frac{c+b}{\tilde{c}+\tilde{b}}\tilde{u}$$

satisfies (3.5) but with  $u^*(x) \to 0$  as  $x \to \infty$ , and so  $u^* \equiv 0$ . Therefore, u and  $\tilde{u}$  are linearly dependent, as required.

Note that  $K_{00}$ , and hence  $\overline{P}(K_{00}+1)\overline{P}$ , is self-adjoint. Indeed

$$K_{00} = -V_0^{1/2} R_0 V_0 V_0^{-1/2}$$
  
=  $-V_0^{-1/2} V_0 R_0 V_0^{1/2}$   
=  $(K_{00})^*$ .

As we have seen above in Lemma 1, thanks to the decay of the potential,  $\overline{P}K_{00}\overline{P}$  is a compact operator. Therefore, the simple eigenvalue -1 of  $\overline{P}K_{00}\overline{P}$  is isolated and so

$$(\overline{P}(K_{00}+1)\overline{P})^{-1}: \{v, w_0\}^{\perp} \to \{v, w_0\}^{\perp}$$
 (3.8)

exists and is bounded.

With the above preliminary facts assembled, we proceed to the bifurcation analysis.

4. Bifurcation analysis. This section is devoted to the proof of the main result:

**Theorem 4.** There exists  $\varepsilon_0 > 0$  such that for  $-\varepsilon_0 \le \varepsilon \le \varepsilon_0$  the eigenvalue problem (3.1) has a solution  $(\alpha, w)$  of the form

$$w = w_0 + \varepsilon w_1 + \varepsilon^2 w_2 + \tilde{w}$$
  

$$\alpha = \varepsilon^2 \alpha_2 + \tilde{\alpha}$$
(4.1)

where  $\alpha_2 > 0$ ,  $w_0$ ,  $w_1$ ,  $w_2$  are known (given below), and  $|\tilde{\alpha}| < C|\varepsilon|^3$  and  $\|\tilde{w}\|_{L^2} < C|\varepsilon|^3$  for some C > 0.

**Remark 5.** This theorem confirms the behaviour observed numerically in [4]: for  $p \neq 3$  but close to 3, the linearized operator  $J\hat{H}$  (which is unitarily equivalent to  $iL_p$ ) has true, purely imaginary eigenvalues in the gap between the branches of essential spectrum, which approach the thresholds as  $p \to 3$ . Note Remark 2 to see that  $u = V_0^{-1/2}w$  is a true  $L^2$  eigenfunction of (2.5). In addition, the eigenfunction approaches the resonance eigenfunction in some weighted  $L^2$  space. Furthermore, we have found that  $\alpha^2$ , the distance of the eigenvalues from the thresholds, is to leading order proportional to  $(p-3)^4$ . Finally, note that  $\alpha = \varepsilon^2 \alpha_2 + O(\varepsilon^3)$  with  $\alpha_2 > 0$  gives  $\alpha > 0$  for both  $\varepsilon > 0$  and  $\varepsilon < 0$ , ensuring the eigenvalues appear on both sides of p = 3.

The quantities in (4.1) are defined as follows:

$$\begin{split} w_{0} &:= V_{0}^{1/2} u_{0} \\ Pw_{1} &:= \frac{1}{4} K_{-11} w_{0} \\ \overline{P}w_{1} &:= -\left(\overline{P}(K_{00}+1)\overline{P}\right)^{-1} \left(\frac{1}{4} \overline{P} K_{00} K_{-11} w_{0} + \overline{P} K_{01} w_{0}\right) \\ Pw_{2} &:= \frac{1}{4} \left(K_{-11} w_{1} + K_{-12} w_{0} + \alpha_{2} (K_{00}+1) w_{0}\right) \\ \overline{P}w_{2} &:= -\left(\overline{P}(K_{00}+1)\overline{P}\right)^{-1} \left(\frac{1}{4} \overline{P} K_{00} K_{-11} w_{1} + \frac{1}{4} \overline{P} K_{00} K_{-12} w_{0} \right. \\ &\left. + \frac{\alpha_{2}}{4} \overline{P} K_{00} (K_{00}+1) w_{0} + \overline{P} K_{01} w_{1} + \overline{P} K_{02} w_{0} + \alpha_{2} \overline{P} K_{10} w_{0}\right) \\ \alpha_{2} &:= \frac{-\frac{1}{4} \langle w_{0}, K_{00} K_{-11} w_{1} \rangle - \frac{1}{4} \langle w_{0}, K_{00} K_{-12} w_{0} \rangle - \langle w_{0}, K_{01} w_{1} \rangle - \langle w_{0}, K_{02} w_{0} \rangle}{\langle w_{0}, K_{10} w_{0} \rangle + \frac{1}{4} \langle w_{0}, K_{00} (K_{00}+1) w_{0} \rangle} \end{split}$$

Remark 6. A numerical computation shows

$$\alpha_2 \approx 2.52/8 > 0.$$

Since the positivity of  $\alpha_2$  is crucial to the main result, details of this computation are described in Section 5.

Note that the functions on which  $\overline{P}(K_{00}+1)\overline{P}$  is being inverted in the expressions for  $\overline{P}w_1$  and  $\overline{P}w_2$  are orthogonal to both  $w_0$  and v, and so these quantities are well-defined by (3.8). The projections to v are zero by the presence of  $\overline{P}$ . As for the

projections to  $w_0$ , the identity

$$\langle w_0, \frac{1}{4}K_{00}K_{-11}w_0 + K_{01}w_0 \rangle = 0$$
 (4.2)

has been verified analytically. It is because of this identity that the  $O(\varepsilon)$  term is absent in the expansion of  $\alpha$  in (4.1). The fact that

$$0 = \langle w_0, \frac{1}{4}K_{00}K_{-11}w_1 + \frac{1}{4}K_{00}K_{-12}w_0 + \frac{\alpha_2}{4}K_{00}(K_{00}+1)w_0 + K_{01}w_1 + K_{02}w_0 + \alpha_2K_{10}w_0 \rangle$$

comes from our definition of  $\alpha_2$ .

The above definitions, along with (3.3), imply the relationships below

$$0 = K_{-10} w_0 \tag{4.3}$$

$$0 = K_{-11}w_0 + K_{-10}w_1 \tag{4.4}$$

$$0 = K_{-10}w_2 + K_{-11}w_1 + K_{-12}w_0 + \alpha_2(K_{00} + 1)w_0$$
(4.5)

$$0 = \overline{P}(K_{00} + 1)w_1 + \overline{P}K_{01}w_0 \tag{4.6}$$

$$0 = \overline{P}(K_{00} + 1)w_2 + \overline{P}K_{01}w_1 + \overline{P}K_{02}w_0 + \alpha_2\overline{P}K_{10}w_0$$
(4.7)

which we will use in what follows.

Using the expression for  $\alpha$  in (4.1), our expansion (3.2) for  $K_{\alpha,\varepsilon}$  now takes the form

$$K_{\alpha,\varepsilon} = \frac{1}{\alpha} \left( K_{-10} + \varepsilon K_{-11} + \varepsilon^2 K_{-12} + \varepsilon^3 K_{R1} \right) + K_{00} + \varepsilon K_{01} + \varepsilon^2 K_{02} + \varepsilon^3 K_{R2} + (\alpha_2 \varepsilon^2 + \tilde{\alpha}) K_{10} + (\alpha_2 \varepsilon^2 + \tilde{\alpha}) \varepsilon K_{R3} + (\alpha_2 \varepsilon^2 + \tilde{\alpha})^2 K_{R4} =: \frac{1}{\alpha} \left( K_{-10} + \varepsilon K_{-11} + \varepsilon^2 K_{-12} + \varepsilon^3 K_{R1} \right) + K_{00} + \varepsilon \overline{K}_1 + \tilde{\alpha} \overline{K}_2$$

where  $\overline{K}_1$  is a bounded (uniformly in  $\varepsilon$ ) operator depending on  $\varepsilon$  but not  $\tilde{\alpha}$ , while  $\overline{K}_2$  is a bounded (uniformly in  $\varepsilon$  and  $\tilde{\alpha}$ ) operator depending on both  $\varepsilon$  and  $\tilde{\alpha}$ .

Further decomposing

$$\tilde{w} = \beta v + W, \qquad \langle W, v \rangle = 0,$$

we aim to show existence of a solution with the remainder terms  $\tilde{\alpha}$ ,  $\beta$  and W small. We do so via a Lyapunov-Schmidt reduction.

First substitute (4.1) to (3.1) and apply the projection  $\overline{P}$  to obtain

$$0 = \overline{P}(K_{\alpha,\varepsilon} + 1)w$$

$$= \overline{P}(K_{\alpha,\varepsilon} + 1)(w_{0} + \varepsilon w_{1} + \varepsilon^{2}w_{2} + \beta v + W)$$

$$= \overline{P}(K_{00} + 1)w_{0} + \varepsilon \overline{P}(K_{00} + 1)w_{1} + \varepsilon \overline{P}K_{01}w_{0}$$

$$+ \varepsilon^{2}\overline{P}(K_{00} + 1)w_{2} + \varepsilon^{2}\overline{P}K_{01}w_{1} + \varepsilon^{2}\overline{P}K_{02}w_{0} + \varepsilon^{2}\alpha_{2}\overline{P}K_{10}w_{0}$$

$$+ \overline{P}(K_{00} + 1)(\beta v + W) + \tilde{\alpha}\overline{P}K_{10}w_{0} + \overline{P}(\varepsilon \overline{K}_{1} + \tilde{\alpha}\overline{K}_{2})(\beta v + W)$$

$$+ \varepsilon^{3}\overline{P}(K_{R2}w_{0} + K_{02}w_{1} + K_{01}w_{2} + \varepsilon K_{02}w_{2} + \varepsilon K_{R2}w_{1} + \varepsilon^{2}K_{R2}w_{2})$$

$$+ (\alpha_{2}\varepsilon^{2} + \tilde{\alpha})\overline{P}K_{10}(\varepsilon w_{1} + \varepsilon^{2}w_{2}) + (\alpha_{2}\varepsilon^{2} + \tilde{\alpha})\varepsilon\overline{P}K_{R3}(w_{0} + \varepsilon w_{1} + \varepsilon^{2}w_{2})$$

$$+ (\alpha_{2}\varepsilon^{2} + \tilde{\alpha})^{2}\overline{P}K_{R4}(w_{0} + \varepsilon w_{1} + \varepsilon^{2}w_{2}).$$
(4.8)

Making some cancellations coming from Lemma 3, (4.6) and (4.7) leads to

$$\begin{aligned} -P(K_{00}+1)PW &= \\ \beta \overline{P}K_{00}v + \tilde{\alpha}\overline{P}K_{10}w_0 + \overline{P}\left(\varepsilon\overline{K}_1 + \tilde{\alpha}\overline{K}_2\right)(\beta v + W) \\ &+ \varepsilon^3\overline{P}\left(K_{R2}w_0 + K_{02}w_1 + K_{01}w_2 + \varepsilon K_{02}w_2 + \varepsilon K_{R2}w_1 + \varepsilon^2 K_{R2}w_2\right) \\ &+ (\alpha_2\varepsilon^2 + \tilde{\alpha})\overline{P}K_{10}(\varepsilon w_1 + \varepsilon^2 w_2) + (\alpha_2\varepsilon^2 + \tilde{\alpha})\varepsilon\overline{P}K_{R3}(w_0 + \varepsilon w_1 + \varepsilon^2 w_2) \\ &+ (\alpha_2\varepsilon^2 + \tilde{\alpha})^2\overline{P}K_{R4}(w_0 + \varepsilon w_1 + \varepsilon^2 w_2) \\ &=: \mathcal{F}(W; \varepsilon, \tilde{\alpha}, \beta). \end{aligned}$$

According to (3.8), inversion of  $\overline{P}(K_{00}+1)\overline{P}$  on  $\mathcal{F}$  requires the solvability condition

$$P_0 \mathcal{F} = 0, \qquad P_0 := \frac{1}{\|w_0\|_2^2} \langle w_0, \cdot \rangle w_0, \quad \overline{P}_0 := 1 - P_0$$

$$(4.9)$$

which we solve together with the fixed point problem

$$W = \left(-\overline{P}(K_{00}+1)\overline{P}\right)^{-1}\overline{P}_{0}\mathcal{F}(W;\varepsilon,\tilde{\alpha},\beta) =: \mathcal{G}(W;\varepsilon,\tilde{\alpha},\beta)$$
(4.10)

in order to solve (4.8).

Write

$$F := \overline{P} \left( \beta K_{00} v + \tilde{\alpha} K_{10} w_0 + \left( \varepsilon \overline{K}_1 + \tilde{\alpha} \overline{K}_2 \right) \left( \beta v + W \right) + \varepsilon^3 f_1 + \varepsilon \tilde{\alpha} f_2 + \tilde{\alpha}^2 h_1 \right)$$

where  $f_1$  and  $f_2$  denote functions depending on (and  $L^2$  bounded uniformly in)  $\varepsilon$  but not  $\tilde{\alpha}$ , while  $h_1$  denotes an  $L^2$  function depending on (and uniformly  $L^2$  bounded in) both  $\varepsilon$  and  $\tilde{\alpha}$ .

**Lemma 7.** For any M > 0 there exists  $\varepsilon_0 > 0$  and R > 0 such that for all  $-\varepsilon_0 \leq \varepsilon \leq \varepsilon_0$  and for all  $\tilde{\alpha}$  and  $\beta$  with  $|\tilde{\alpha}| \leq M|\varepsilon|^3$  and  $|\beta| \leq M|\varepsilon|^3$  there exists a unique solution  $W \in L^2 \cap \{v, w_0\}^{\perp}$  of (4.10) satisfying  $||W||_{L^2} \leq R|\varepsilon|^3$ .

*Proof.* We prove this by means of Banach Fixed Point Theorem. We must show that  $\mathcal{G}(W)$  maps the closed ball of radius  $R|\varepsilon|^3$  into itself and that  $\mathcal{G}(W)$  is a contraction mapping. Taking  $W \in L^2$  orthogonal to v and  $w_0$  such that  $||W||_{L^2} \leq R|\varepsilon|^3$  and given M > 0 where  $|\tilde{\alpha}| \leq M|\varepsilon|^3$  and  $|\beta| \leq M|\varepsilon|^3$ , we have, using the boundedness of  $(-\overline{P}(K_{00}+1)\overline{P})^{-1}\overline{P}_0$ ,

$$\begin{split} \|\mathcal{G}\|_{L^{2}} &\leq C|\beta| \|\overline{P}K_{00}v + \overline{P}\left(\varepsilon\overline{K}_{1} + \tilde{\alpha}\overline{K}_{2}\right)v\|_{L^{2}} + C|\tilde{\alpha}| \|\overline{P}\left(K_{10}w_{0} + \varepsilon f_{2} + \tilde{\alpha}h_{1}\right)\|_{L^{2}} \\ &+ C\|\overline{P}\left(\varepsilon\overline{K}_{1} + \tilde{\alpha}\overline{K}_{2}\right)W\|_{L^{2}} + |\varepsilon|^{3}C\|\overline{P}f_{1}\|_{L^{2}} \\ &\leq CM|\varepsilon|^{3} + CM|\varepsilon|^{3} + C|\varepsilon|\|W\|_{L^{2}} + C|\tilde{\alpha}|\|W\|_{L^{2}} + C|\varepsilon|^{3} \\ &\leq C|\varepsilon|^{3} + CR|\varepsilon|^{4} \\ &\leq R|\varepsilon|^{3} \end{split}$$

for some appropriately chosen R with  $|\varepsilon|$  small enough. Here C is a positive, finite constant whose value changes at each appearance. Next consider

$$\begin{aligned} \|\mathcal{G}(W_{1}) - \mathcal{G}(W_{2})\|_{L^{2}} \\ &\leq C \|\overline{P}\left(\varepsilon\overline{K}_{1} + \tilde{\alpha}\overline{K}_{2}\right)\|_{L^{2} \to L^{2}} \|W_{1} - W_{2}\|_{L^{2}} \\ &\leq C |\varepsilon|\|\overline{P}\ \overline{K}_{1}\|_{L^{2} \to L^{2}} \|W_{1} - W_{2}\|_{L^{2}} + C |\tilde{\alpha}|\|\overline{P}\ \overline{K}_{2}\|_{L^{2} \to L^{2}} \|W_{1} - W_{2}\|_{L^{2}} \\ &\leq C |\varepsilon|\|W_{1} - W_{2}\|_{L^{2}} \leq \kappa \|W_{1} - W_{2}\|_{L^{2}} \end{aligned}$$

with  $0 < \kappa < 1$  by taking  $|\varepsilon|$  sufficiently small. Hence  $\mathcal{G}(W)$  is a contraction, and we obtain the desired result.

Lemma 7 provides W as a function of  $\tilde{\alpha}$  and  $\beta$ , which we may then substitute into (4.9) to get

$$0 = \langle w_0, \mathcal{F} \rangle$$
  
=  $\beta \langle w_0, K_{00}v \rangle + \tilde{\alpha} \langle w_0, K_{10}w_0 \rangle + \varepsilon \beta \langle w_0, \overline{K}_1v \rangle + \tilde{\alpha}\beta \langle w_0, \overline{K}_2v \rangle$   
+  $\varepsilon^3 \langle w_0, f_1 \rangle + \varepsilon \tilde{\alpha} \langle w_0, f_2 \rangle + \tilde{\alpha}^2 \langle w_0, h_1 \rangle + \varepsilon \langle w_0, \overline{K}_1W \rangle + \tilde{\alpha} \langle w_0, \overline{K}_2W \rangle$   
=:  $\beta \langle w_0, K_{00}v \rangle + \tilde{\alpha} \langle w_0, K_{10}w_0 \rangle + \mathcal{F}_1$  (4.11)

which is the first of two equations relating  $\tilde{\alpha}$  and  $\beta$ .

The second equation is the complementary one to (4.8): substitute (4.1) to (3.1) but this time multiply by  $\alpha$  and take projection P to see

$$0 = \alpha P(K_{\alpha,\varepsilon} + 1)w$$
  

$$= K_{-10}w_0 + \varepsilon (K_{-11}w_0 + K_{-10}w_1)$$
  

$$+ \varepsilon^2 (K_{-10}w_2 + K_{-11}w_1 + K_{-12}w_0) + \varepsilon^2 \alpha_2 (K_{00} + 1)w_0$$
  

$$+ \varepsilon^3 (K_{-11}w_2 + K_{-12}w_1 + K_{R1}w_0 + \varepsilon K_{-12}w_2 + \varepsilon K_{R1}w_1 + \varepsilon^2 K_{R1}w_2)$$
  

$$+ \beta K_{-10}v + K_{-10}W + \varepsilon (K_{-11} + \varepsilon K_{-12} + \varepsilon^2 K_{R1})(\beta v + W)$$
  

$$+ \tilde{\alpha} (K_{00} + 1)w_0 + \varepsilon^3 \alpha_2 P(K_{00} + 1)(w_1 + \varepsilon w_2) + \varepsilon \tilde{\alpha} P(K_{00} + 1)(w_1 + \varepsilon w_2)$$
  

$$+ \varepsilon^2 \alpha_2 P(K_{00} + 1)(\beta v + W) + \tilde{\alpha} P(K_{00} + 1)(\beta v + W)$$
  

$$+ \alpha P(\varepsilon K_{01} + \varepsilon^2 K_{02} + \varepsilon^3 K_{R2} + \alpha K_{10} + \alpha \varepsilon K_{R3} + \alpha^2 K_{R4})$$
  

$$\times (w_0 + \varepsilon w_1 + \varepsilon^2 w_2 + \beta v + W).$$
  
(4.12)

After using known information about  $w_0, w_1, w_2, \alpha_2$  coming from (4.3), (4.4), (4.5) and noting that  $K_{-10}W = -4PW = 0$  from (3.3) we have

$$0 = \beta K_{-10}v + \tilde{\alpha}(K_{00} + 1)w_0 + \varepsilon^3 (K_{-11}w_2 + K_{-12}w_1 + K_{R1}w_0 + \varepsilon K_{-12}w_2 + \varepsilon K_{R1}w_1 + \varepsilon^2 K_{R1}w_2) + \varepsilon (K_{-11} + \varepsilon K_{-12} + \varepsilon^2 K_{R1})(\beta v + W) + \varepsilon^3 \alpha_2 P(K_{00} + 1)(w_1 + \varepsilon w_2) + \varepsilon \tilde{\alpha} P(K_{00} + 1)(w_1 + \varepsilon w_2) + \varepsilon^2 \alpha_2 P(K_{00} + 1)(\beta v + W) + \tilde{\alpha} P(K_{00} + 1)(\beta v + W) + \alpha P(\varepsilon K_{01} + \varepsilon^2 K_{02} + \varepsilon^3 K_{R2} + \alpha K_{10} + \alpha \varepsilon K_{R3} + \alpha^2 K_{R4}) \times (w_0 + \varepsilon w_1 + \varepsilon^2 w_2 + \beta v + W).$$

Written more compactly, this is

$$0 = \beta K_{-10}v + \tilde{\alpha}(K_{00} + 1)w_0 + \varepsilon^3 f_4 + \varepsilon \overline{K}_3(\beta v + W) + \tilde{\alpha}\varepsilon f_5 + \tilde{\alpha}\overline{K}_4(\beta v + W) + \tilde{\alpha}^2 h_2$$

where  $\overline{K}_3$  is a bounded (uniformly in  $\varepsilon$ ) operator containing  $\varepsilon$  but not  $\tilde{\alpha}$ , while  $\overline{K}_4$ is a bounded (uniformly in  $\varepsilon$  and  $\tilde{\alpha}$ ) operator containing both  $\varepsilon$  and  $\tilde{\alpha}$ . Functions  $f_4$ and  $f_5$  depend on  $\varepsilon$  (and are uniformly  $L^2$ -bounded) but not  $\tilde{\alpha}$ , while the function  $h_2$ depends on both  $\varepsilon$  and  $\tilde{\alpha}$  (and is uniformly  $L^2$ -bounded). To make the relationship

between  $\tilde{\alpha}$  and  $\beta$  more explicit we take inner product with v

$$0 = \beta \langle v, K_{-10}v \rangle + \tilde{\alpha} \langle v, (K_{00} + 1)w_0 \rangle + \varepsilon^3 \langle v, f_4 \rangle + \varepsilon \langle v, \overline{K}_3(\beta v + W) \rangle + \tilde{\alpha} \varepsilon \langle v, f_5 \rangle + \tilde{\alpha} \langle v, \overline{K}_4(\beta v + W) \rangle + \tilde{\alpha}^2 \langle v, h_2 \rangle =: \beta \langle v, K_{-10}v \rangle + \tilde{\alpha} \langle v, (K_{00} + 1)w_0 \rangle + \mathcal{F}_2.$$
(4.13)

Now let

$$\vec{\zeta} = \begin{pmatrix} \tilde{\alpha} \\ \beta \end{pmatrix}$$

and rewrite (4.11) and (4.13) in the following way

$$A\vec{\zeta} := \begin{pmatrix} \langle w_0, K_{10}w_0 \rangle & \langle w_0, K_{00}v \rangle \\ \langle v, (K_{00}+1)w_0 \rangle & \langle v, K_{-10}v \rangle \end{pmatrix} \begin{pmatrix} \tilde{\alpha} \\ \beta \end{pmatrix} = \begin{pmatrix} \mathcal{F}_1 \\ \mathcal{F}_2 \end{pmatrix}$$

which we recast as a fixed point problem

$$\vec{\zeta} = A^{-1} \begin{pmatrix} \mathcal{F}_1 \\ \mathcal{F}_2 \end{pmatrix} =: \vec{F}(\tilde{\alpha}, \beta; \varepsilon).$$
(4.14)

We have computed

$$A = \begin{pmatrix} 0 & 16\\ 16 & -32 \end{pmatrix}$$

so in particular, A is invertible. We wish to show there is a solution  $(\tilde{\alpha}, \beta)$  of (4.14) of the appropriate size. We establish this fact in the following Lemmas. Lemmas 8 and 9 are accessory to Lemma 10.

**Lemma 8.** The operators and functions  $\overline{K}_2$ ,  $\overline{K}_4$  and  $h_1$ ,  $h_2$  are continuous in  $\tilde{\alpha} > 0$ .

*Proof.* The operators and function in question are compositions of continuous functions of  $\tilde{\alpha}$ .

**Lemma 9.** The W given by Lemma  $\vec{\gamma}$  is continuous in  $\vec{\zeta}$  for sufficiently small  $|\varepsilon|$ .

*Proof.* Let  $(\tilde{\alpha}_1, \beta_1)$  give rise to  $W_1$  and let  $(\tilde{\alpha}_2, \beta_2)$  give rise to  $W_2$  via Lemma 7. Take  $|\tilde{\alpha}_1 - \tilde{\alpha}_2| < \delta$  and  $|\beta_1 - \beta_2| < \delta$ . We show that  $||W_1 - W_2||_{L^2} < C\delta$  for some constant C > 0. Observing  $\overline{K}_2$  depends on  $\tilde{\alpha}$ , we see

$$\begin{split} \|W_1 - W_2\|_{L^2} &= \|\left(\overline{P}(K_{00} + 1)\overline{P}\right)^{-1}\overline{P}_0\|_{L^2 \to L^2} \|\mathcal{F}(W_1, \vec{\zeta_1}; \varepsilon) - \mathcal{F}(W_2, \vec{\zeta_2}; \varepsilon)\|_{L^2} \\ &\leq C \left\| (\beta_1 - \beta_2)K_{00}v + (\tilde{\alpha}_1 - \tilde{\alpha}_2)K_{10}w_0 + \varepsilon(\beta_1 - \beta_2)\overline{K}_1v \right. \\ &\quad + \varepsilon\overline{K}_1(W_1 - W_2) + \tilde{\alpha}_1\beta_1\overline{K}_2(\tilde{\alpha}_1)v - \tilde{\alpha}_2\beta_2\overline{K}_2(\tilde{\alpha}_2)v + \tilde{\alpha}_1\overline{K}_2(\tilde{\alpha}_1)W_1 \\ &\quad - \tilde{\alpha}_2\overline{K}_2(\tilde{\alpha}_2)W_2 + \varepsilon(\tilde{\alpha}_1 - \tilde{\alpha}_2)f_2 + \tilde{\alpha}_1^2h_1(\tilde{\alpha}_1) - \tilde{\alpha}_2^2h_1(\tilde{\alpha}_2) \right\|_{L^2} \\ &\leq C\delta + C|\varepsilon| \|W_1 - W_2\|_{L^2} \end{split}$$

$$+ \|\tilde{\alpha}_1 \overline{K}_2(\tilde{\alpha}_1)(W_1 - W_2) + (\tilde{\alpha}_1 \overline{K}_2(\tilde{\alpha}_1) - \tilde{\alpha}_2 \overline{K}_2(\tilde{\alpha}_2)) W_2\|_{L^2}$$
  
$$\leq C\delta + C|\varepsilon| \|W_1 - W_2\|_{L^2}$$

noting that  $|\tilde{\alpha}_1| \leq M |\varepsilon|^3$ . Rearranging the above gives

$$||W_1 - W_2||_{L^2} < C\delta$$

for small enough  $|\varepsilon|$ .

**Lemma 10.** There exists  $\varepsilon_0 > 0$  such that for all  $-\varepsilon_0 \leq \varepsilon \leq \varepsilon_0$  the equation (4.14) has a fixed point with  $|\tilde{\alpha}|, |\beta| \leq M |\varepsilon|^3$  for some M > 0.

*Proof.* We prove this by means of the Brouwer Fixed Point Theorem. We show that  $\vec{F}$  maps a closed square into itself and that  $\vec{F}$  is a continuous function. Take  $|\tilde{\alpha}|, |\beta| \leq M |\varepsilon|^3$  and and so by Lemma 7 we have  $||W||_{L^2} \leq |\varepsilon|^3 R$  for some R > 0. Consider now

$$\begin{split} \|A^{-1}\| \, |\mathcal{F}_1| \\ &\leq \|A^{-1}\| \left( |\varepsilon||\beta||\langle w_0, \overline{K}_1 v\rangle| + |\tilde{\alpha}||\beta||\langle w_0, \overline{K}_2 v\rangle| + |\varepsilon|^3|\langle w_0, f_1\rangle| \\ &+ |\varepsilon||\tilde{\alpha}||\langle w_0, f_2\rangle| + |\tilde{\alpha}|^2|\langle w_0, h_1\rangle| + |\varepsilon||\langle w_0, \overline{K}_1 W\rangle| + |\tilde{\alpha}||\langle w_0, \overline{K}_2 W\rangle| \right) \\ &\leq CM|\varepsilon|^4 + CM^2|\varepsilon|^6 + C|\varepsilon|^3 + CM|\varepsilon|^4 + CM^2|\varepsilon|^6 + CR|\varepsilon|^4 \\ &\leq C|\varepsilon|^3 + CM|\varepsilon|^4 \leq M|\varepsilon|^3 \end{split}$$

and

$$\begin{split} \|A^{-1}\| \, |\mathcal{F}_2| \\ &\leq \|A^{-1}\| \left( |\varepsilon|^3 |\langle v, f_4 \rangle| + |\varepsilon|| \langle v, \overline{K}_3(\beta v + W) \rangle| + |\tilde{\alpha}||\varepsilon|| \langle v, f_5 \rangle| \\ &\quad + |\tilde{\alpha}|| \langle v, \overline{K}_4(\beta v + W) \rangle| + |\tilde{\alpha}|^2 |\langle v, h_2 \rangle| \right) \\ &\leq C |\varepsilon|^3 + CM |\varepsilon|^4 + CR |\varepsilon|^4 + CM |\varepsilon|^4 + CM^2 |\varepsilon|^6 + CMR |\varepsilon|^6 + CM^2 |\varepsilon|^6 \\ &\leq C |\varepsilon|^3 + CM |\varepsilon|^4 \leq M |\varepsilon|^3 \end{split}$$

for some choice of M > 0 and sufficiently small  $|\varepsilon| > 0$ . Here C > 0 is a constant that is different at each instant. So  $\vec{F}$  maps the closed square to itself.

It is left to show that  $\vec{F}$  is continuous. Given  $\eta > 0$  take  $|\tilde{\alpha}_1 - \tilde{\alpha}_2| < \delta$  and  $|\beta_1 - \beta_2| < \delta$ . Let  $(\tilde{\alpha}_1, \beta_1)$  give rise to  $W_1$  and let  $(\tilde{\alpha}_2, \beta_2)$  give rise to  $W_2$  via Lemma 7. We will also use Lemma 8 and Lemma 9. Now consider

$$\begin{split} |\mathcal{F}_{1}(\tilde{\alpha}_{1},\beta_{1}) - \mathcal{F}_{1}(\tilde{\alpha}_{2},\beta_{2})| \\ &= \left| \varepsilon(\beta_{1} - \beta_{2}) \langle w_{0}, \overline{K}_{1}v \rangle + \tilde{\alpha}_{1}\beta_{1} \langle w_{0}, \overline{K}_{2}(\tilde{\alpha}_{1})v \rangle - \tilde{\alpha}_{2}\beta_{2} \langle w_{0}, \overline{K}_{2}(\tilde{\alpha}_{2})v \rangle \right. \\ &+ \varepsilon(\tilde{\alpha}_{1} - \tilde{\alpha}_{2}) \langle w_{0}, f_{2} \rangle + \tilde{\alpha}_{1}^{2} \langle w_{0}, h_{1}(\tilde{\alpha}_{1}) \rangle - \tilde{\alpha}_{2}^{2} \langle w_{0}, h_{1}(\tilde{\alpha}_{2}) \rangle \\ &+ \varepsilon \langle w_{0}, \overline{K}_{1}(W_{1} - W_{2}) \rangle + \tilde{\alpha}_{1} \langle w_{0}, \overline{K}_{2}(\tilde{\alpha}_{1})W_{1} \rangle - \tilde{\alpha}_{2} \langle w_{0}, \overline{K}_{2}(\tilde{\alpha}_{2})W_{2} \rangle \right| \\ &\leq C\delta + C \|h_{1}(\tilde{\alpha}_{1}) - h_{1}(\tilde{\alpha}_{2})\|_{L^{2}} \\ &+ C \|W_{1} - W_{2}\|_{L^{2}} + C \|\overline{K}_{2}(\tilde{\alpha}_{1}) - \overline{K}_{2}(\tilde{\alpha}_{2})\|_{L^{2} \to L^{2}} \\ &\leq C\delta < \frac{\eta}{\|A^{-1}\|\sqrt{2}} \end{split}$$

for small enough  $\delta$ . Similarly we can show

$$|\mathcal{F}_2(\tilde{\alpha}_1,\beta_1) - \mathcal{F}_2(\tilde{\alpha}_2,\beta_2)| \le C\delta < \frac{\eta}{\|A^{-1}\|\sqrt{2}}$$

for  $\delta$  small enough. Putting everything together gives  $|\vec{F}(\vec{\zeta}_1) - \vec{F}(\vec{\zeta}_2)| < \eta$  as required. Hence  $\vec{F}$  is continuous.

So finally we have solved both (4.8) and (4.12), and hence (3.1), and so have proved Theorem 4.

5. Comments on the computations. Analytical and numerical computations were used in the above to compute inner products such as the ones appearing in the definition of  $\alpha_2$  (4.1). It was critical to establish that  $\alpha_2 > 0$  since the expansion of the resolvent  $R^{(\alpha)}$  (2.10) requires  $\alpha > 0$ . Inner products containing  $w_0$  but not  $w_1$  can be written as an explicit single integral and then evaluated analytically or numerically with good accuracy. For example

$$\begin{split} \langle w_0, K_{02}w_0 \rangle &+ \frac{1}{4} \langle w_0, K_{00}K_{-12}w_0 \rangle \\ = &- \frac{1}{2} \int_{\mathbb{R}^2} |x - y| (4Q^2(x) - 3Q^4(x)) \\ &\times (Q^2(y)q_1(y) - q_1(y) + 3Q^2(y)q_2(y) - 4q_2(y) - \frac{c_2}{2}Q^2(y)) dy dx \\ &+ \frac{1}{2\sqrt{2}} \int_{\mathbb{R}^2} e^{-\sqrt{2}|x - y|} (2Q^2(x) - 3Q^4(x)) \\ &\times (Q^2(y)q_1(y) - q_1(y) + 3Q^2(y)q_2(y) - 2q_2(y) - \frac{c_2}{4}Q^2(y)) dy dx \\ = &- \int_{\mathbb{R}} Q^2(y) (Q^2(y)q_1(y) - q_1(y) + 3Q^2(y)q_2(y) - 4q_2(y) - \frac{c_2}{2}Q^2(y)) dy \\ &- \int_{\mathbb{R}} Q^2(y) (Q^2(y)q_1(y) - q_1(y) + 3Q^2(y)q_2(y) - 2q_2(y) - \frac{c_2}{4}Q^2(y)) dy \\ \approx &- 2.9369 \end{split}$$

where

$$c_2 = \frac{1}{2} \int_{\mathbb{R}} Q^2 q_1 - q_1 + 3Q^2 q_2 - 4q_2$$

To reduce the double integral to a single integral we recall some facts about the integral kernels. Let

$$h(y) = -\frac{1}{2} \int_{\mathbb{R}} |x - y| (4Q^2(x) - 3Q^4(x)) dx.$$

Then h solves the equation

$$h'' = -4Q^2 + 3Q^4.$$

Notice that  $-4Q^2 + 3Q^4 = -2Q^2u_1 - Q^2u_2$  where  $u_1$  and  $u_2$  are the components of the resonance  $u_0$  (2.6). Observing the equation (3.6) we see that  $h = u_1 + c =$  $2 - Q^2 + c$  for some constant c. We can directly compute h(0) = -2 to find c = -2and so  $h = -Q^2$ . A similar argument involving (3.7) gives

$$\frac{1}{2\sqrt{2}} \int_{\mathbb{R}} e^{-\sqrt{2}|x-y|} \left( 2Q^2(x) - 3Q^4(x) \right) dx = u_2(y) = -Q^2(y).$$

Many of the inner products can be computed analytically. These include the identity (4.2), the entires in the matrix A in (4.14) and the denominator appearing

in the expression for  $\alpha_2$ . As an example we evaluate the denominator of  $\alpha_2$ :

$$\begin{aligned} \langle w_0, K_{10}w_0 \rangle &+ \frac{1}{4} \langle w_0, K_{00}(K_{00} + 1)w_0 \rangle \\ &= -\int_{\mathbb{R}^2} \left( 3Q^4(x) - 4Q^2(x) \right) \frac{(x - y)^2}{4} \left( 3Q^4(y) - 4Q^2(y) \right) dy dx \\ &+ \frac{1}{2} \int_{\mathbb{R}^2} \left( 4Q^2(x) - 3Q^4(x) \right) |x - y| Q^2(y) dy dx \\ &- \frac{1}{4\sqrt{2}} \int_{\mathbb{R}^2} \left( 4Q^2(x) - 3Q^4(x) \right) e^{-\sqrt{2}|x - y|} Q^2(y) dy dx \\ &= \frac{3}{2} \int_{\mathbb{R}} Q^4(y) dy \\ &= 8 \end{aligned}$$

where the first integral is zero by a direct computation and the remaining double integrals are converted to single integrals as above.



FIGURE 1. The two components of  $\overline{P}w_1$  computed numerically with 32 basis terms.

Computing inner products containing  $w_1$  is harder. We have an explicit expression for  $Pw_1$  but lack an explicit expression for  $\overline{P}w_1$ . Therefore we approximate



FIGURE 2. The two components of function g with the computed  $\overline{P}(K_{00} + 1)\overline{P}w_1$  on top. Again 32 basis terms were used in this computation. At this scale the difference can only be seen around zero and at the endpoints.

 $\overline{P}w_1$  by numerically inverting  $\overline{P}(K_{00}+1)\overline{P}$  in

$$\overline{P}(K_{00}+1)\overline{P}w_1 = -\left(\frac{1}{4}\overline{P}K_{00}K_{-11}w_0 + \overline{P}K_{01}w_0\right) =: g.$$

Note that  $\langle g, v \rangle = \langle g, w_0 \rangle = 0$ . We represent  $\overline{P}(K_{00} + 1)\overline{P}$  as a matrix with respect to a basis  $\{\phi_j\}_{j=1}^N$ . The basis is formed by taking terms from the typical Fourier basis and projecting out the components of each function in the direction of v and  $w_0$ . Some basis functions were removed to ensure linear independence of the basis. Let  $\overline{P}w_1 = \sum_{j=1}^N a_j \phi_j$ . Then

$$B\vec{a} = \vec{b}$$

where  $B_{j,k} = \langle \phi_j, (K_{00}+1)\phi_k \rangle$  and  $b_j = \langle \phi_j, g \rangle$ . So we can solve for  $\vec{a}$  by inverting the matrix B. Once we have an approximation for  $\overline{P}w_1$  we can compute  $\overline{P}(K_{00} + 1)\overline{P}w_1$  directly to observe agreement with the function g. With this agreement we are confident in our numerical algorithm and that our numerical approximation for  $\overline{P}w_1$  is accurate. In Figure 1 we show the two components of  $\overline{P}w_1$  as computed numerically. Figure 2 shows the components of the function g with the computed  $\overline{P}(K_{00} + 1)\overline{P}w_1$  on top. With an approximation for  $\overline{P}w_1$  in hand we can combine it with our explicit expression for  $Pw_1$  and compute inner products containing  $w_1$  in the same way as the previous inner product containing  $w_0$ . In this way we establish that  $\alpha_2 > 0$ . We list computed values for the numerator of  $\alpha_2$  against the number of basis terms used in Table 1.

Number of Basis Terms	$8\alpha_2$
20	2.4992
24	2.5137
28	2.5189
30	2.5201
32	2.5207

TABLE 1. Numerical values for  $8\alpha_2$  for the number of basis terms used in the computation.

Acknowledgments. The authors thank T.P. Tsai for suggesting the problem and for helpful discussions. MC is supported by an NSERC CGS. SG is supported by an NSERC Discovery Grant.

## REFERENCES

- D. Bambusi, Asymptotic stability of ground states in some hamiltonian pde with symmetry, Comm. Math. Phys., 320 (2013), 499–542.
- [2] V. S. Buslaev and C. Sulem, On asymptotic stability of solitary waves for nonlinear Schrödinger equations, Ann. Inst. H. Poincare Anal. Non Lineaire, 20 (2003), 419–475.
- [3] T. Cazenave, Semilinear Schrödginer Equations, American Mathematical Soc., Providence, RI, 2003.
- [4] S. Chang, S. Gustafson, K. Nakanishi and T. Tsai, Spectra of linearized operators for NLS solitary waves, SIAM J. Math Anal., 39 (2007), 1070–1111.
- [5] S. Cuccagna, Stabilization of solutions to nonlinear Schrödinger equations, Comm. Pure Appl. Math., 54 (2001), 1110–1145.
- [6] S. Cuccagna, On asymptotic stability of ground states of NLS, Rev. Math. Phys., 15 (2003), 877–903.
- [7] S. Cuccagna, On asymptotic stability of moving ground states of the nonlinear Schrödinger equation, Trans. Amer. Math. Soc., 366 (2014), 2827–2888.
- [8] S. Cuccagna and D. Pelinovsky, Bifurcations from the endpoints of the essential spectrum in the linearized nonlinear Schrödinger problem, J. Math. Phys., 46 (2005), 053520, 15pp.
- [9] S. Cuccagna, D. Pelinovsky and V. Vougalter, Spectra of positive and negative energies in the linearized NLS problem, Comm. Pure Appl. Math., 58 (2005), 1–29.
- [10] S. Cuccagna and D. Pelinovsky, The asymptotic stability of solitons in the cubic NLS equation on the line, Applicable Analysis, 93 (2014), 791–822.
- [11] Z. Gang and I. M. Sigal, Asymptotic stability of nonlinear Schrödinger equations with potential, Rev. Math. Phys., 17 (2005), 1143–1207.
- [12] M. Grillakis, Linearized instability for nonlinear Schrödinger and Klein-Gordon equations, Comm. Pure Appl. Anal., 41 (1988), 747–774.
- [13] M. Grillakis, J. Shatah and W. Strauss, Stability theory of solitary waves in the presence of symmetry I, J. Funct. Anal., 74 (1987), 160–197.
- [14] S. Gustafson and I. M. Sigal, *Mathematical Concepts of Quantum Mechanics* (2nd ed.), Springer-Verlag Berlin Heidelberg, 2011.
- [15] G. Fibich, The Nonlinear Schrödinger Equation: Singular Solutions and Optical Collapse, Springer, 2015.
- [16] A. Jensen and T. Kato, Spectral properties of Schrödinger operators and time-decay of the wave functions, Duke Math. J., 46 (1979), 583–611.
- [17] A. Jensen and G. Nenciu, A unified approach to resolvent expansions at thresholds, *Rev. Math. Phys.*, 13 (2001), 717–754.

- [18] T. Kapitula, Stability criterion for bright solitary waves of the perturbed cubic-quintic Schrödinger equation, *Physica D*, **116** (1998), 95–120.
- [19] T. Kapitula and B. Sandstede, Stability of bright solitary-wave solutions to perturbed nonlinear Schrödinger equations, *Physica D*, **124** (1998), 58–103.
- [20] T. Kapitula and B. Sandstede, Edge bifurcations for near integrable systems via Evans functions, SIAM J. Math. Anal., 33 (2002), 1117–1143.
- [21] T. Kapitula and B. Sandstede, Eigenvalues and resonances using the Evans functions, Discrete Contin. Dyn. Syst., 10 (2004), 857–869.
- [22] D. Pelinovsky, Y. Kivshar and V. Afanasjev, Internal modes of envelope solitons, *Physica D*, 116 (1998), 121–142.
- [23] G. Perelman, Asymptotic stability of multi-soliton solutions for nonlinear Schrödinger equations, Comm. Partial Differential Equations, 29 (2004), 1051–1095.
- [24] W. Schlag, Stabile manifolds for an orbitally unstable nonlinear Schrödinger equation, Ann. of Math., 169 (2009), 139–227.
- [25] C. Sulem and P.-L. Sulem, The Nonlinear Schrödinger Equation, Springer, 1999.
- [26] V. Vougalter, On threshold eigenvalues and resonances for the linearized NLS equation, Math. Model. Nat. Phenom., 5 (2010), 448–469.
- [27] V. Vougalter, On the negative index theorem for the linearized NLS problem, Canad. Math. Bull., 53 (2010), 737–745.
- [28] V. Vougalter and D. Pelinovsky, Eigenvalues of zero energy in the linearized NLS problem, Journal of Mathematical Physics, 47 (2006), 062701, 13pp.
- [29] M. I. Weinstein, Modulational stability of ground states of nonlinear Schrödinger equations, SIAM J. Math Anal., 16 (1985), 472–491.
- [30] M. I. Weinstein, Lyapunov stability of ground states of nonlinear dispersive evolutions equations, Comm. Pure Appl. Math., 39 (1986), 51–68.

Received July 2015; revised September 2015.

*E-mail address*: colesmp@math.ubc.ca *E-mail address*: gustaf@math.ubc.ca