

Outline

Week 12: Application of vector differential equations to electrical networks

Course Notes: 6.4

Goals: determine behaviour of LCR networks using vector differential equations

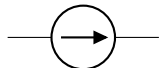
Circuit Components



Resistor



Voltage Source



Current Source

Circuit Components



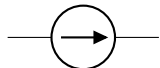
Resistor



Voltage Source



Capacitor



Current Source

Circuit Components



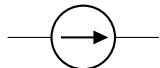
Resistor



Voltage Source



Capacitor



Current Source



Inductor

Circuit Components



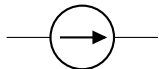
Resistor



Voltage Source



Capacitor
acts like a changing voltage source



Current Source



Inductor

Circuit Components



Resistor

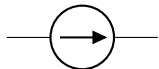


Voltage Source



Capacitor

acts like a changing voltage source



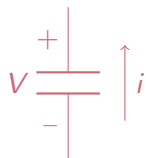
Current Source



Inductor

acts like a changing current source

Differential Equations

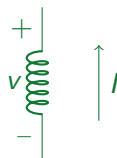


V : Voltage drop

i : current

C : capacitance

$$\frac{dV}{dt} = \frac{-i}{C}$$



v : voltage drop

I : current

L : inductance

$$\frac{dI}{dt} = \frac{-v}{L}$$

Changing:

V , v : voltage drops

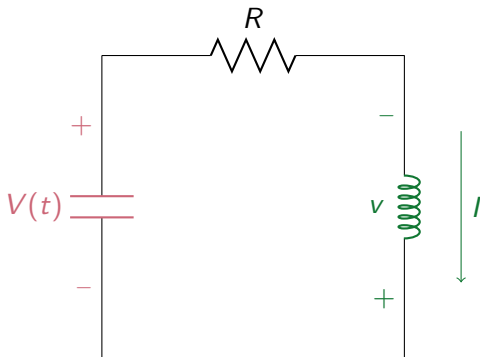
I : current

Constant:

R : resistance

C : capacitance

L : inductance



Changing:

V , v : voltage drops

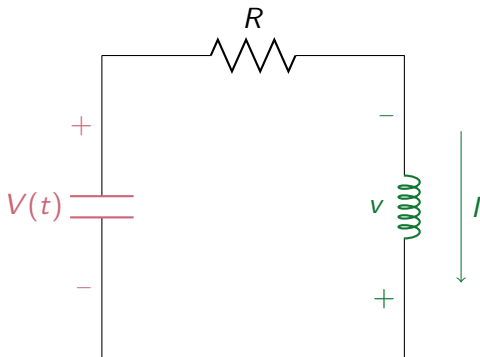
I : current

Constant:

R : resistance

C : capacitance

L : inductance



Goal: find equations for $V(t)$ (voltage across capacitor)
and $I(t)$ (current through inductor).

Changing:

V , v : voltage drops

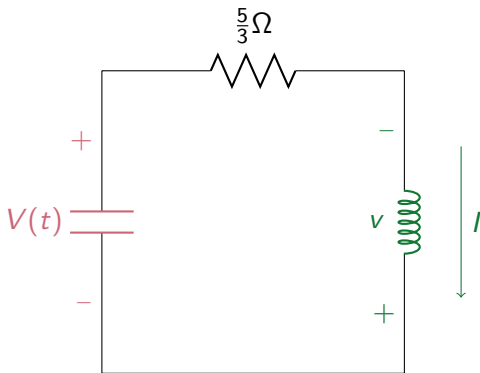
I : current

Constant:

$R = \frac{5}{3}$: resistance

$C = \frac{1}{2}$: capacitance

$L = \frac{1}{3}$: inductance



Goal: find equations for $V(t)$ (voltage across capacitor) and $I(t)$ (current through inductor).

Changing:

V , v : voltage drops

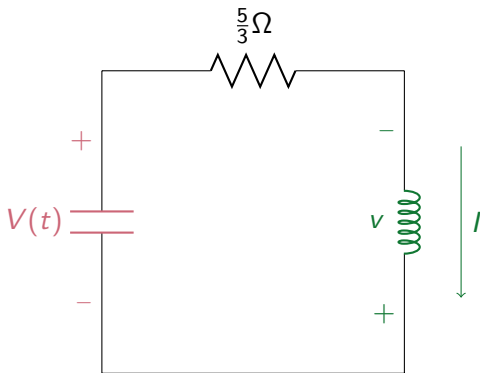
I : current

Constant:

$R = \frac{5}{3}$: resistance

$C = \frac{1}{2}$: capacitance

$L = \frac{1}{3}$: inductance



Goal: find equations for $V(t)$ (voltage across capacitor) and $I(t)$ (current through inductor).

$$\text{Kirkhoff: } -v - V + \frac{5}{3}I = 0 \quad \Rightarrow \quad v = \frac{5}{3}I - V$$

Differential Equations:

$$\frac{dV}{dt} = \frac{-I}{C} = -2I \quad \frac{dI}{dt} = \frac{-v}{L} = 3\left(V - \frac{5}{3}I\right) = 3V - 5I$$

Differential Equations: $\frac{dV}{dt} = -2I$, $\frac{dI}{dt} = 3V - 5I$

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Find: $\begin{bmatrix} V(t) \\ I(t) \end{bmatrix}$

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$$\begin{bmatrix} V(t) \\ I(t) \end{bmatrix}' = \begin{bmatrix} -2I \\ 3V - 5I \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ 3 & -5 \end{bmatrix} \begin{bmatrix} V(t) \\ I(t) \end{bmatrix}$$

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$$\lambda_1 = -2, \mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -3, \mathbf{x}_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

Differential Equations: $\frac{dV}{dt} = -2I$, $\frac{dI}{dt} = 3V - 5I$

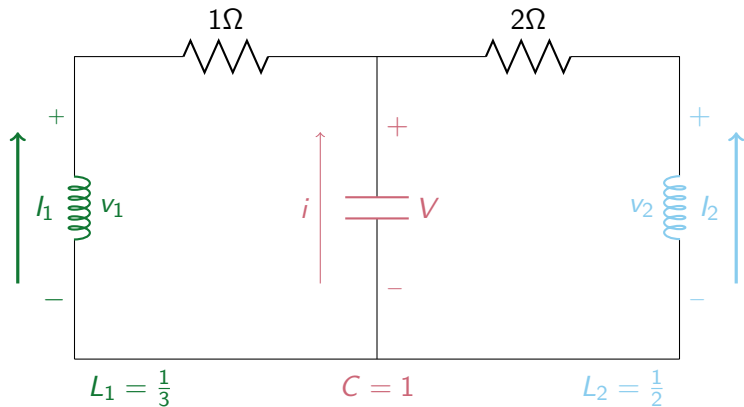
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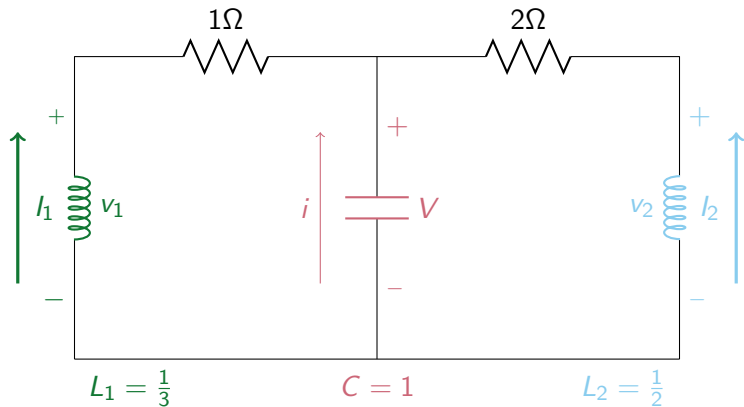
$$\lambda_1 = -2, \mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -3, \mathbf{x}_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} V(t) \\ I(t) \end{bmatrix} = c_1 e^{-2t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} c_1 e^{-2t} + 2c_2 e^{-3t} \\ c_1 e^{-2t} + 3c_2 e^{-3t} \end{bmatrix}$$



Want to find: $i_1(t)$, $i_2(t)$, and $V(t)$.



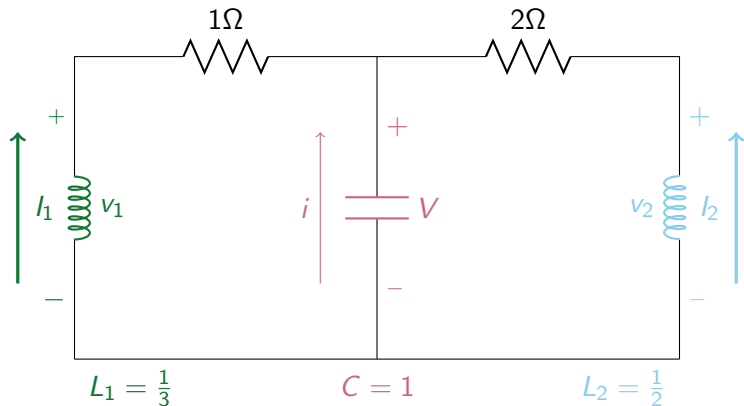
Want to find: $i_1(t)$, $i_2(t)$, and $V(t)$.

Differential:

$$\frac{di_1}{dt} = \frac{-v_1}{L_1} = -3v_1$$

$$\frac{di_2}{dt} = \frac{-v_2}{L_2} = -2v_2$$

$$\frac{dV}{dt} = \frac{-i}{C} = -i$$



Want to find: $i_1(t)$, $i_2(t)$, and $V(t)$.

Differential:

$$\frac{di_1}{dt} = \frac{-v_1}{L_1} = -3v_1$$

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$$\frac{dV}{dt} = \frac{-i}{C} = -i$$

Kirkhoff:

$$-v_1 + 1i_1 + V = 0$$

$$-v_2 + 2i_2 + V = 0$$

$$i = -i_1 - i_2$$

Differential:

$$\frac{dl_1}{dt} = \frac{-v_1}{L_1} = -3v_1$$

$$\frac{dl_2}{dt} = \frac{-v_2}{L_2} = -2v_2$$

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Kirkhoff:

$$-v_1 + 1l_1 + V = 0$$

$$-v_2 + 2l_2 + V = 0$$

$$i = -l_1 - l_2$$

Combined:

$$\frac{dl_1}{dt} = -3v_1 = -3(l_1 + V) = -3l_1 - 3V$$

$$\frac{dl_2}{dt} = -2v_2 = -2(2l_1 + V) = -4l_2 - 2V$$

$$\frac{dV}{dt} = -i = l_1 + l_2$$

$$\begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}' = \begin{bmatrix} -3 & 0 & -3 \\ 0 & -4 & -2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}$$

Now we need the eigenvalues and eigenvectors of the matrix.

$$\begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}' = \begin{bmatrix} -3 & 0 & -3 \\ 0 & -4 & -2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}$$

$$\lambda_1 \approx -1.6 - 1.5i, \quad \mathbf{x}_1 \approx \begin{bmatrix} 1 \\ 0.46 - 0.13i \\ -.46 + .49i \end{bmatrix}$$

$$\lambda_2 \approx -1.6 + 1.5i, \quad \mathbf{x}_2 \approx \begin{bmatrix} 1 \\ 0.46 + 0.13i \\ -.46 - .49i \end{bmatrix}$$

$$\lambda_3 \approx -3.7, \quad \mathbf{x}_3 \approx \begin{bmatrix} 1 \\ -1.9 \\ 0.25 \end{bmatrix}$$

$$\begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}' = \begin{bmatrix} -3 & 0 & -3 \\ 0 & -4 & -2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}$$

$$\lambda_1 \approx -1.6 - 1.5i, \quad \mathbf{x}_1 \approx \begin{bmatrix} 1 \\ 0.46 - 0.13i \\ -.46 + .49i \end{bmatrix}$$

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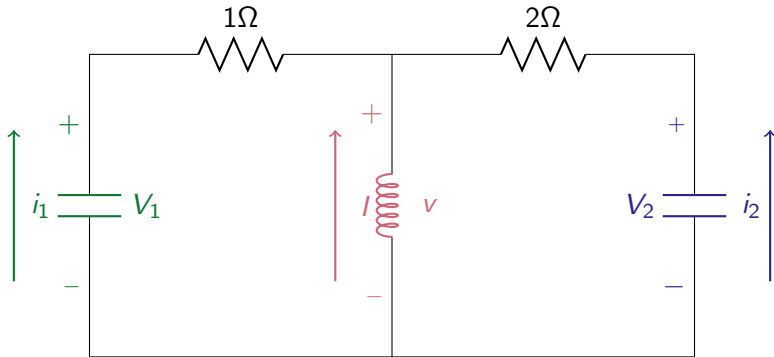
$$c_1 e^{-1.6t} e^{-1.5it} \mathbf{x}_1 + c_2 e^{-1.6t} e^{1.5it} \mathbf{x}_2 + c_3 e^{-3.7t} \mathbf{x}_3$$

$$\begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}' = \begin{bmatrix} -3 & 0 & -3 \\ 0 & -4 & -2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ V \end{bmatrix}$$

$$\begin{aligned} \lambda_1 &\approx -1.6 - 1.5i, & \mathbf{x}_1 &\approx \begin{bmatrix} 1 \\ 0.46 - 0.13i \\ -.46 + .49i \end{bmatrix} \\ \lambda_2 &\approx -1.6 + 1.5i, & \mathbf{x}_2 &\approx \begin{bmatrix} 1 \\ 0.46 + 0.13i \\ -.46 - .49i \end{bmatrix} \\ \lambda_3 &\approx -3.7, & \mathbf{x}_3 &\approx \begin{bmatrix} 1 \\ -1.9 \\ 0.25 \end{bmatrix} \end{aligned}$$

$$c_1 e^{-1.6t} e^{-1.5it} \mathbf{x}_1 + c_2 e^{-1.6t} e^{1.5it} \mathbf{x}_2 + c_3 e^{-3.7t} \mathbf{x}_3$$

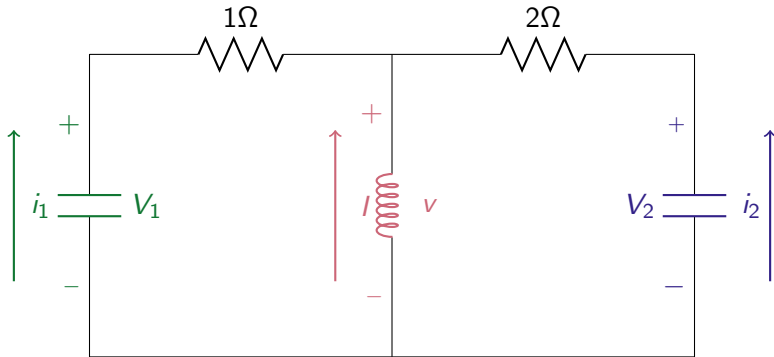
Regardless of initial conditions, the solutions will decay.
They may or may not oscillate while decaying.



Capacitances: $C_1 = \frac{1}{6}$, $C_2 = \frac{1}{3}$

Inductance: $L = \frac{1}{3}$

Find $V_1(t)$, $V_2(t)$, and $I(t)$.



Capacitances: $C_1 = \frac{1}{6}$, $C_2 = \frac{1}{3}$

Inductance: $L = \frac{1}{3}$

Find $V_1(t)$, $V_2(t)$, and $I(t)$.

Differential Equations:

$$\frac{dV_1}{dt} = -\frac{i_1}{C_1} \quad \frac{dV_2}{dt} = -\frac{i_2}{C_2} \quad \frac{dI}{dt} = -\frac{v}{L}$$

We use Kirkhoff's Laws to solve for i_1 , i_2 , and v in terms of V_1 , V_2 , and I .

Left Loop: $-V_1 + i_1 + v = 0$

Right Loop: $-V_2 + 2i_2 + v = 0$

Inductor (like a current source): $i_1 + i_2 = -I$

$$\overbrace{\begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 1 \\ 1 & 1 & 0 \end{bmatrix}}^{i_1 \quad i_2 \quad v} \left| \begin{array}{c} V_1 \\ V_2 \\ -I \end{array} \right. \xrightarrow{\text{row reduce}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & \frac{1}{3}(V_1 - V_2 - 2I) \\ 0 & 1 & 0 & \frac{1}{3}(-V_1 + V_2 - I) \\ 0 & 0 & 1 & \frac{1}{3}(2V_1 + V_2 + 2I) \end{array} \right]$$

$$\frac{dV_1}{dt} = -\frac{i_1}{C_1} = -6 \left(\frac{1}{3} \right) (V_1 - V_2 - 2I) = -2V_1 + 2V_2 + 4I$$

$$\frac{dV_2}{dt} = -\frac{i_2}{C_2} = -3 \left(\frac{1}{3} \right) (-V_1 + V_2 - I) = V_1 - V_2 + I$$

$$\frac{dI}{dt} = -\frac{v}{L} = -3 \left(\frac{1}{3} \right) (2V_1 + V_2 + 2I) = -2V_1 - V_2 - 2I$$

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$$\frac{dI}{dt} = -\frac{v}{L} = -3 \left(\frac{1}{3} \right) (2V_1 + V_2 + 2I) = -2V_1 - V_2 - 2I$$

In vector differential equation form:

$$\begin{bmatrix} V_1 \\ V_2 \\ I \end{bmatrix}' = \begin{bmatrix} -2 & 2 & 4 \\ 1 & -1 & 1 \\ -2 & -1 & -2 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ I \end{bmatrix}$$

Eigenvalues and Eigenvectors:

$$\lambda_1 = -2, \mathbf{x}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \quad \lambda_2 = \overline{\lambda}_3 = \frac{-3 + 3\sqrt{3}i}{2}, \quad \mathbf{x}_2 = \overline{\mathbf{x}}_3 = \begin{bmatrix} 4 \\ 1 - \sqrt{3}i \\ 2\sqrt{3}i \end{bmatrix}$$

Solutions all decay; some oscillate.

