

# Limits

## Notation.

- $\mathbb{N}$  is the set  $\{1, 2, 3, \dots\}$  of all natural numbers
- $\mathbb{R}$  is the set of all real numbers
- $\forall$  is read “for all”
- $\exists$  is read “there exists”
- $\in$  is read “element of”
- $\notin$  is read “not an element of”
- $\{ A \mid B \}$  is read “the set of all  $A$  such that  $B$ ”
- If  $S$  is a set and  $T$  is a subset of  $S$ , then  $S \setminus T$  is  $\{ x \in S \mid x \notin T \}$ , the set  $S$  with the elements of  $T$  removed.
- if  $n$  is a natural number,  $\mathbb{R}^n$  is used for both the set of  $n$ -component vectors  $\langle x_1, x_2, \dots, x_n \rangle$  and the set of points  $(x_1, x_2, \dots, x_n)$  with  $n$ -coordinates.
- If  $S$  and  $T$  are sets, then  $f : S \rightarrow T$  means that  $f$  is a function which assigns to each element of  $S$  an element of  $T$ .
- $[a, b] = \{ x \in \mathbb{R} \mid a \leq x \leq b \}$   
 $(a, b) = \{ x \in \mathbb{R} \mid a < x < b \}$   
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Roughly speaking,  $\lim_{\vec{x} \rightarrow \vec{a}} \vec{f}(\vec{x}) = \vec{L}$  means that  $\vec{f}(\vec{x})$  approaches  $\vec{L}$  as  $\vec{x}$  approaches  $\vec{a}$ . Here is the precise definition of limit, and a couple of related definitions.

**Definition 1** Let  $m, n \in \mathbb{N}$ .

(a) Let  $\vec{a} \in \mathbb{R}^n$  and  $\vec{L} \in \mathbb{R}^m$ , and let  $\vec{f} : \mathbb{R}^n \setminus \{\vec{a}\} \rightarrow \mathbb{R}^m$ . Then  $\lim_{\vec{x} \rightarrow \vec{a}} \vec{f}(\vec{x}) = \vec{L}$  if

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \text{such that} \quad |\vec{f}(\vec{x}) - \vec{L}| < \varepsilon \quad \text{whenever} \quad 0 < |\vec{x} - \vec{a}| < \delta$$

(b) Let  $\vec{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ . Then  $f$  is continuous at  $\vec{a} \in \mathbb{R}^n$  if  $\lim_{\vec{x} \rightarrow \vec{a}} \vec{f}(\vec{x}) = \vec{f}(\vec{a})$  and  $\vec{f}$  is continuous on  $\mathbb{R}^n$  if it is continuous at every  $\vec{a} \in \mathbb{R}^n$ .

## Remark 2

(a) Here is what that definition of limit says. Suppose you have a magic microscope whose magnification can be set as high as you like. Suppose that when the magnification is set to  $\frac{1}{\varepsilon}$ , you can only see those points whose distance from  $\vec{L}$  is less than  $\varepsilon$ . The definition

says that no matter how high you set the magnification, (i.e. no matter how small you set  $\varepsilon > 0$ ), you will be able to see  $\vec{f}(\vec{x})$  whenever  $\vec{x}$  is close enough to  $\vec{a}$  (if the distance from  $\vec{x}$  to  $\vec{a}$  is less than  $\delta$ , then you will certainly see  $\vec{f}(\vec{x})$ ).

(b) Definition 1.a, of  $\lim_{\vec{x} \rightarrow \vec{a}} \vec{f}(\vec{x})$ , is set up so that the function  $\vec{f}(\vec{x})$  is never evaluated at  $\vec{x} = \vec{a}$ . Indeed  $\vec{f}(\vec{x})$  need not even be defined at  $\vec{x} = \vec{a}$ . This is exactly what happens in the definition of the derivative  $h'(a) = \lim_{x \rightarrow a} \frac{h(x) - h(a)}{x - a}$ . (In this case  $f(x) = \frac{h(x) - h(a)}{x - a}$ .)

We'll first do a couple of examples with  $m = n = 1$ . We'll do higher dimensional examples later.

**Example 3** In Example 2 of the notes "A Little Logic" we saw that the statement

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that if } |x| < \delta \text{ then } x^2 < \varepsilon$$

is true. Consequently

$$\lim_{x \rightarrow 0} x^2 = 0$$

**Example 4** In this example, we consider  $\lim_{x \rightarrow 0} \sin \frac{1}{x}$ . So fix any real number  $L$  and let

- $S(\delta, \varepsilon)$  be the statement " $|\sin \frac{1}{x} - L| < \varepsilon$  whenever  $0 < |x| < \delta$ ",
- $T(\varepsilon)$  be the statement " $\exists \delta > 0$  such that  $S(\delta, \varepsilon)$ " or

$$\exists \delta > 0 \text{ such that } |\sin \frac{1}{x} - L| < \varepsilon \text{ whenever } 0 < |x| < \delta$$

- $U$  be the statement " $\forall \varepsilon > 0 T(\varepsilon)$ " or

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that } |\sin \frac{1}{x} - L| < \varepsilon \text{ whenever } 0 < |x| < \delta$$

Then

- Fix any  $\varepsilon > 0$  and any  $\delta > 0$ . The statement  $S(\delta, \varepsilon)$  is true if all values of  $\sin \frac{1}{x}$ , with  $0 < |x| < \delta$ , lie in the interval  $(L - \varepsilon, L + \varepsilon)$ . As  $x$  runs over the interval  $(0, \delta)$ , (so that, in particular,  $0 < |x| < \delta$ )  $\frac{1}{x}$  covers the set  $(\frac{1}{\delta}, \infty)$ . This contains many intervals of length  $2\pi$  and hence many periods of  $\sin$ . So, as  $x$  runs over the interval  $(0, \delta)$ ,  $\sin \frac{1}{x}$  covers all of  $[-1, 1]$ . So  $S(\delta, \varepsilon)$  is true if and only if the interval  $[-1, 1]$  is contained in the interval  $(L - \varepsilon, L + \varepsilon)$ . In particular, when  $\varepsilon < 1$ , the interval  $(L - \varepsilon, L + \varepsilon)$ , which has length  $2\varepsilon$ , is shorter than  $[-1, 1]$  and cannot contain it, so that  $S(\delta, \varepsilon)$  is false.
- Because  $S(\delta, \varepsilon)$  is false for all  $\delta > 0$  when  $\varepsilon < 1$ ,  $T(\varepsilon)$  is false for all  $\varepsilon < 1$ .
- $U$  is false since, as we have just seen,  $T(\varepsilon)$  is false for at least one  $\varepsilon > 0$ . For example  $T(\frac{1}{2})$  is false.

In conclusion,  $\sin \frac{1}{x}$  has no limit as  $x \rightarrow 0$ .

**Theorem 5** Let  $n \in \mathbb{N}$ ,  $\vec{a}, \vec{b} \in \mathbb{R}^n$ ,  $F, G \in \mathbb{R}$  and

$$f, g : \mathbb{R}^n \setminus \{\vec{a}\} \rightarrow \mathbb{R} \quad \vec{X} : \mathbb{R}^n \setminus \{\vec{b}\} \rightarrow \mathbb{R}^n \setminus \{\vec{a}\} \quad \gamma : \mathbb{R} \rightarrow \mathbb{R}$$

Assume that

$$\lim_{\vec{x} \rightarrow \vec{a}} f(\vec{x}) = F \quad \lim_{\vec{x} \rightarrow \vec{a}} g(\vec{x}) = G \quad \lim_{\vec{y} \rightarrow \vec{b}} \vec{X}(\vec{y}) = \vec{a} \quad \lim_{t \rightarrow F} \gamma(t) = \gamma(F) = \Gamma$$

Then

- (a)  $\lim_{\vec{x} \rightarrow \vec{a}} [f(\vec{x}) + g(\vec{x})] = F + G$
- (b)  $\lim_{\vec{x} \rightarrow \vec{a}} f(\vec{x})g(\vec{x}) = FG$
- (c)  $\lim_{\vec{x} \rightarrow \vec{a}} \frac{f(\vec{x})}{g(\vec{x})} = \frac{F}{G}$  if  $G \neq 0$
- (d)  $\lim_{\vec{y} \rightarrow \vec{b}} f(\vec{X}(\vec{y})) = F$
- (e)  $\lim_{\vec{x} \rightarrow \vec{a}} \gamma(f(\vec{x})) = \Gamma$

**Proof:** Note that the  $\varepsilon$  and  $\delta$  in “ $\forall \varepsilon > 0 \exists \delta > 0$  such that  $S(\delta, \varepsilon)$ ” are dummy variables, just as  $x$  is a dummy variable in  $\int_0^1 x dx$ . You may replace  $\varepsilon$  and  $\delta$  by whatever symbols you like. The hypotheses of this theorem say that

$$\forall \varepsilon_f > 0 \exists \delta_f > 0 \text{ such that } |f(\vec{x}) - F| < \varepsilon_f \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_f \quad (1)$$

$$\forall \varepsilon_g > 0 \exists \delta_g > 0 \text{ such that } |g(\vec{x}) - G| < \varepsilon_g \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_g \quad (2)$$

$$\forall \varepsilon_X > 0 \exists \delta_X > 0 \text{ such that } |\vec{X}(\vec{y}) - \vec{a}| < \varepsilon_X \text{ whenever } 0 < |\vec{y} - \vec{b}| < \delta_X \quad (3)$$

$$\forall \varepsilon_\gamma > 0 \exists \delta_\gamma > 0 \text{ such that } |\gamma(t) - \Gamma| < \varepsilon_\gamma \text{ whenever } 0 < |t - F| < \delta_\gamma \quad (4)$$

(a) We are to prove that

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that } |f(\vec{x}) + g(\vec{x}) - F - G| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

So pick any  $\varepsilon > 0$ . We must prove that there is a  $\delta > 0$  such that

$$|f(\vec{x}) + g(\vec{x}) - F - G| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

Observe that

$$|f(\vec{x}) + g(\vec{x}) - F - G| = |[f(\vec{x}) - F] + [g(\vec{x}) - G]| \leq |f(\vec{x}) - F| + |g(\vec{x}) - G|$$

Set  $\varepsilon_1 = \frac{\varepsilon}{2}$  and  $\varepsilon_2 = \frac{\varepsilon}{2}$ . By (1) with  $\varepsilon_f = \varepsilon_1$  and (2) with  $\varepsilon_g = \varepsilon_2$ ,

$$\exists \delta_1 > 0 \text{ such that } |f(\vec{x}) - F| < \varepsilon_1 \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_1$$

$$\exists \delta_2 > 0 \text{ such that } |g(\vec{x}) - G| < \varepsilon_2 \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_2$$

Choose  $\delta = \min\{\delta_1, \delta_2\}$ . Then whenever  $0 < |\vec{x} - \vec{a}| < \delta$  we also have  $0 < |\vec{x} - \vec{a}| < \delta_1$  and  $0 < |\vec{x} - \vec{a}| < \delta_2$  so that

$$|f(\vec{x}) + g(\vec{x}) - F - G| \leq |f(\vec{x}) - F| + |g(\vec{x}) - G| < \varepsilon_1 + \varepsilon_2 = \varepsilon$$

(b) is a homework assignment.

(c) We are to prove that

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that } \left| \frac{f(\vec{x})}{g(\vec{x})} - \frac{F}{G} \right| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

So pick any  $\varepsilon > 0$ . We must prove that there is a  $\delta > 0$  such that

$$\left| \frac{f(\vec{x})}{g(\vec{x})} - \frac{F}{G} \right| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

Set  $\varepsilon_1 = \frac{1}{6}|G|\varepsilon$  and  $\varepsilon_2 = \frac{G^2}{6(|F|+1)}\varepsilon$ . By (1) with  $\varepsilon_f = \varepsilon_1$ , (2) with  $\varepsilon_g = \varepsilon_2$  and (2) with  $\varepsilon_g = \frac{1}{2}|G|$ ,

$$\exists \delta_1 > 0 \text{ such that } |f(\vec{x}) - F| < \varepsilon_1 \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_1$$

$$\exists \delta_2 > 0 \text{ such that } |g(\vec{x}) - G| < \varepsilon_2 \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_2$$

$$\exists \delta_3 > 0 \text{ such that } |g(\vec{x}) - G| < \frac{1}{2}|G| \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_3$$

Choose  $\delta = \min\{\delta_1, \delta_2, \delta_3\}$ . Then whenever  $0 < |\vec{x} - \vec{a}| < \delta$  we also have  $0 < |\vec{x} - \vec{a}| < \delta_1$  and  $0 < |\vec{x} - \vec{a}| < \delta_2$  and  $0 < |\vec{x} - \vec{a}| < \delta_3$  so that

$$\begin{aligned} \left| \frac{f(\vec{x})}{g(\vec{x})} - \frac{F}{G} \right| &= \frac{|f(\vec{x})G - Fg(\vec{x})|}{|g(\vec{x})G|} = \frac{|(f(\vec{x}) - F)G - F(g(\vec{x}) - G)|}{|g(\vec{x})G|} \\ &\leq \frac{|f(\vec{x}) - F||G| + |F||g(\vec{x}) - G|}{|g(\vec{x})||G|} \\ &\leq \frac{\varepsilon_1|G| + |F|\varepsilon_2}{\frac{1}{2}|G||G|} \quad \text{since } |g(\vec{x})| = |g(\vec{x}) - G + G| \geq |G| - |g(\vec{x}) - G| \geq \frac{1}{2}|G| \\ &= \frac{1}{6}|G|\varepsilon \frac{|G|}{G^2/2} + \frac{|F|}{G^2/2} \frac{G^2}{6(|F|+1)}\varepsilon = \frac{\varepsilon}{3} + \frac{1}{3} \frac{|F|}{|F|+1} \varepsilon \\ &< \varepsilon \end{aligned}$$

(d) We are to prove that

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that } |f(\vec{X}(\vec{y})) - F| < \varepsilon \text{ whenever } 0 < |\vec{y} - \vec{b}| < \delta$$

So pick any  $\varepsilon > 0$ . We must prove that there is a  $\delta > 0$  such that

$$|f(\vec{X}(\vec{y})) - F| < \varepsilon \text{ whenever } 0 < |\vec{y} - \vec{b}| < \delta$$

By (1) with  $\varepsilon_f = \varepsilon$

$$\exists \delta_f > 0 \text{ such that } |f(\vec{x}) - F| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_f$$

and (3) with  $\varepsilon_X = \delta_f$ ,

$$\exists \delta_X > 0 \text{ such that } |\vec{X}(\vec{y}) - \vec{a}| < \delta_f \text{ whenever } 0 < |\vec{y} - \vec{b}| < \delta_X$$

Choosing  $\delta = \delta_X$ , we have

$$0 < |\vec{y} - \vec{b}| < \delta = \delta_X \implies 0 < |\vec{X}(\vec{y}) - \vec{a}| < \delta_f \implies |f(\vec{X}(\vec{y})) - F| < \varepsilon$$

(e) has essentially the same proof as part (d). We are to prove that

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ such that } |\gamma(f(\vec{x})) - \Gamma| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

So pick any  $\varepsilon > 0$ . We must prove that there is a  $\delta > 0$  such that

$$|\gamma(f(\vec{x})) - \Gamma| < \varepsilon \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta$$

By (4) with  $\varepsilon_\gamma = \varepsilon$  and the hypothesis that  $\gamma(F) = \Gamma$

$$\exists \delta_\gamma > 0 \text{ such that } |\gamma(t) - \Gamma| < \varepsilon \text{ whenever } |t - F| < \delta_\gamma$$

By (1) with  $\varepsilon_f = \delta_\gamma$

$$\exists \delta_f > 0 \text{ such that } |f(\vec{x}) - F| < \delta_\gamma \text{ whenever } 0 < |\vec{x} - \vec{a}| < \delta_f$$

Choosing  $\delta = \delta_f$ , we have

$$0 < |\vec{x} - \vec{a}| < \delta = \delta_f \implies |f(\vec{x}) - F| < \delta_\gamma \implies |\gamma(f(\vec{x})) - \Gamma| < \varepsilon$$

■

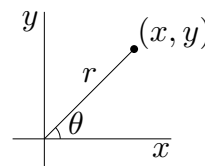
**Example 6** There is a typical application of Theorem 5. Here “ $\stackrel{a}{=}$ ” means that Theorem 5.a justifies that equality.

$$\begin{aligned} \lim_{(x,y) \rightarrow (2,3)} (x + \sin y) &\stackrel{a}{=} \lim_{(x,y) \rightarrow (2,3)} x + \lim_{(x,y) \rightarrow (2,3)} \sin y \\ &\stackrel{e}{=} \lim_{(x,y) \rightarrow (2,3)} x + \sin \left( \lim_{(x,y) \rightarrow (2,3)} y \right) \\ &= 2 + \sin 3 \\ \lim_{(x,y) \rightarrow (2,3)} (x^2 y^2 + 1) &\stackrel{a}{=} \lim_{(x,y) \rightarrow (2,3)} x^2 y^2 + \lim_{(x,y) \rightarrow (2,3)} 1 \\ &\stackrel{b}{=} \left( \lim_{(x,y) \rightarrow (2,3)} x \right) \left( \lim_{(x,y) \rightarrow (2,3)} x \right) \left( \lim_{(x,y) \rightarrow (2,3)} y \right) \left( \lim_{(x,y) \rightarrow (2,3)} y \right) + 1 \\ &= 2^2 3^2 + 1 \\ \lim_{(x,y) \rightarrow (2,3)} \frac{x + \sin y}{x^2 y^2 + 1} &\stackrel{c}{=} \frac{\lim_{(x,y) \rightarrow (2,3)} (x + \sin y)}{\lim_{(x,y) \rightarrow (2,3)} (x^2 y^2 + 1)} \\ &= \frac{2 + \sin 3}{37} \end{aligned}$$

Here we have used that  $\sin x$  is a continuous function. In this course we shall assume that we already know that “standard single variable calculus functions” like  $\sin x$ ,  $\cos x$ ,  $e^x$  and so on are continuous.

**Example 7** As a second example, we consider  $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y}{x^2 + y^2}$ . In this example, both the numerator,  $x^2 y$ , and the denominator  $x^2 + y^2$  tend to zero as  $(x, y)$  approaches  $(0, 0)$ , so we have to be more careful. A good way to see the behaviour of a function  $f(x, y)$  when  $(x, y)$  is close to  $(0, 0)$  is to switch to the polar coordinates  $r, \theta$  using

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$



Recall that the definition of  $\lim_{(x,y) \rightarrow (0,0)} f(x, y) = L$  is

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \text{such that } |f(x, y) - L| < \varepsilon \text{ whenever } 0 < |(x, y)| < \delta \quad (5)$$

The condition  $0 < |(x, y)| < \delta$  says that  $0 < r < \delta$  and no restriction on  $\theta$ . So substituting  $x = r \cos \theta$ ,  $y = r \sin \theta$  into (5) gives

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \quad \text{such that } |f(r \cos \theta, r \sin \theta) - L| < \varepsilon \text{ whenever } 0 < r < \delta, 0 \leq \theta \leq 2\pi \quad (6)$$

For our current example

$$\frac{x^2 y}{x^2 + y^2} = \frac{(r \cos \theta)^2 (r \sin \theta)}{r^2} = r \cos^2 \theta \sin \theta$$

As  $|r \cos^2 \theta \sin \theta| \leq r \rightarrow 0$  when  $r \rightarrow 0$ , we have

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y}{x^2 + y^2} = 0$$

**Example 8** As a third example, we consider  $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 - y^2}{x^2 + y^2}$ . Once again, the best way to see the behaviour of  $\frac{x^2 - y^2}{x^2 + y^2}$  for  $(x, y)$  close to  $(0, 0)$  is to switch to polar coordinates.

$$\frac{x^2 - y^2}{x^2 + y^2} = \frac{(r \cos \theta)^2 - (r \sin \theta)^2}{r^2} = \cos^2 \theta - \sin^2 \theta = \cos(2\theta)$$

No matter how small you make  $\delta > 0$ , as  $(x, y)$  runs over those points with  $r = |(x, y)| < \delta$ ,  $\frac{x^2 - y^2}{x^2 + y^2}$  takes all values in the interval  $[-1, 1]$ . So  $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 - y^2}{x^2 + y^2}$  does not exist.

