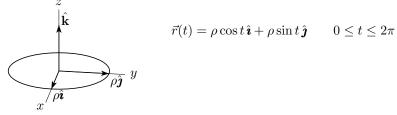
Parametrizing Circles

These notes discuss a simple strategy for parametrizing circles in three dimensions. We start with the circle in the xy-plane that has radius ρ and is centred on the origin. This is easy to parametrize:

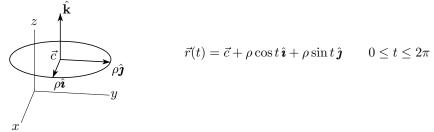


Note that we can check that $\vec{r}(t)$ lies on the desired circle by checking, firstly, that $\vec{r}(t)$ lies in the correct plane (in this case, the *xy*-plane) and, secondly, that the distance from $\vec{r}(t)$ to the centre of the circle is ρ :

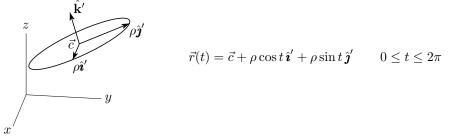
$$\vec{r}(t) - \vec{0} = \left| \rho \cos t \,\hat{\boldsymbol{\imath}} + \rho \sin t \,\hat{\boldsymbol{\jmath}} \right| = \sqrt{(\rho \cos t)^2 + (\rho \sin t)^2} = \rho$$

since $\sin^2 t + \cos^2 t = 1$.

Now let's move the circle so that its centre is at some general point \vec{c} . To parametrize this new circle, which still has radius ρ and which is still parallel to the xy-plane, we just translate by \vec{c} :



Finally, let's consider a circle in general position. The secret to parametrizing a general circle is to replace \hat{i} and \hat{j} by two new vectors \hat{i}' and \hat{j}' which (a) are unit vectors, (b) are parallel to the plane of the desired circle and (c) are mutually perpendicular.



To check that this is correct, observe that

• $\vec{r}(t) - \vec{c}$ is parallel to the plane of the desired circle because $\vec{r}(t) - \vec{c} = \rho \cos t \, \hat{\imath}' + \rho \sin t \, \hat{\jmath}'$ and both $\hat{\imath}'$ and $\hat{\jmath}'$ are parallel to the plane of the desired circle

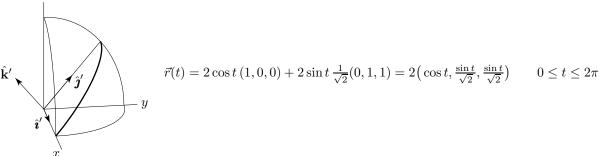
 $\circ \vec{r}(t) - \vec{c}$ is of length ρ for all t because

$$\begin{aligned} |\vec{r}(t) - \vec{c}|^2 &= (\vec{r}(t) - \vec{c}) \cdot (\vec{r}(t) - \vec{c}) \\ &= (\rho \cos t \, \hat{\imath}' + \rho \sin t \, \hat{\jmath}') \cdot (\rho \cos t \, \hat{\imath}' + \rho \sin t \, \hat{\jmath}') \\ &= \rho^2 \cos^2 t \, \hat{\imath}' \cdot \hat{\imath}' + \rho^2 \sin^2 t \, \hat{\jmath}' \cdot \hat{\jmath}' + 2\rho \cos t \sin t \, \hat{\imath}' \cdot \hat{\jmath}' \\ &= \rho^2 (\cos^2 t + \sin^2 t) = \rho^2 \end{aligned}$$

since $\hat{\boldsymbol{i}}' \cdot \hat{\boldsymbol{j}}' = \hat{\boldsymbol{j}}' \cdot \hat{\boldsymbol{j}}' = 1$ ($\hat{\boldsymbol{i}}'$ and $\hat{\boldsymbol{j}}'$ are both unit vectors) and $\hat{\boldsymbol{i}}' \cdot \hat{\boldsymbol{j}}' = 0$ ($\hat{\boldsymbol{i}}'$ and $\hat{\boldsymbol{j}}'$ are perpendicular).

To find such a parametrization in practice, we need to find the centre \vec{c} of the circle, the radius ρ of the circle and two mutually perpendicular unit vectors, \hat{i}' and \hat{j}' , in the plane of the circle. It is often easy to find at least one point \vec{p} on the circle. Then we can take $\hat{i}' = \frac{\vec{p} - \vec{c}}{|\vec{p} - \vec{c}|}$. It is also often easy to find a unit vector, \hat{k}' , that is normal to the plane of the circle. Then we can choose $\hat{j}' = \hat{k}' \times \hat{i}'$.

Example 1 Let *C* be the intersection of the sphere $x^2 + y^2 + z^2 = 4$ and the plane z = y. The intersection of any plane with any sphere is a circle. The plane in question passes through the centre of the sphere, so *C* has the same centre and same radius as the sphere. So *C* has radius 2 and centre (0,0,0). The point (2,0,0) satisfies both $x^2 + y^2 + z^2 = 4$ and z = y and so is on *C*. We may choose \hat{i}' to be the unit vector in the direction from the centre (0,0,0) of the circle towards (2,0,0). Namely $\hat{i}' = (1,0,0)$. Since the plane of the circle is z - y = 0, the vector $\vec{\nabla}(z - y) = (0, -1, 1)$ is perpendicular to the plane of *C*. So we may take $\hat{k}' = \frac{1}{\sqrt{2}}(0, -1, 1)$. Then $\hat{j}' = \hat{k}' \times \hat{i}' = \frac{1}{\sqrt{2}}(0, -1, 1) \times (1, 0, 0) = \frac{1}{\sqrt{2}}(0, 1, 1)$. Subbing in $\vec{c} = (0, 0, 0)$, $\rho = 2$, $\hat{i}' = (1, 0, 0)$ and $\hat{j}' = \frac{1}{\sqrt{2}}(0, 1, 1)$ gives



To check this, note that $x = 2\cos t$, $y = \sqrt{2}\sin t$, $z = \sqrt{2}\sin t$ satisfies both $x^2 + y^2 + z^2 = 4$ and z = y.

Example 2 Let C be the circle that passes through the three points (3, 0, 0), (0, 3, 0) and (0, 0, 3). All three points obey x + y + z = 3. So the circle lies in the plane x + y + z = 3. We guess, by symmetry, or by looking at the figure below, that the centre of the circle is at the centre of mass of the three points, which is $\frac{1}{3}[(3, 0, 0) + (0, 3, 0) + (0, 0, 3)] = (1, 1, 1)$. We can check this by checking that (1, 1, 1) is equidistant from the three points:

$$|(3,0,0) - (1,1,1)| = |(2,-1,-1)| = \sqrt{6}$$
$$|(0,3,0) - (1,1,1)| = |(-1,2,-1)| = \sqrt{6}$$
$$|(0,0,3) - (1,1,1)| = |(-1,-1,2)| = \sqrt{6}$$

This tells us both that (1, 1, 1) is indeed the centre and that the radius of C is $\sqrt{6}$. We may choose \hat{i}' to be the unit vector in the direction from the centre (1, 1, 1) of the circle towards (3, 0, 0). Namely $\hat{i}' = \frac{1}{\sqrt{6}}(2, -1, -1)$. Since the plane of the circle is x+y+z=3, the vector $\vec{\nabla}(x+y+z) = (1, 1, 1)$ is perpendicular to the plane of C. So we may take $\hat{k}' = \frac{1}{\sqrt{3}}(1, 1, 1)$. Then $\hat{j}' = \hat{k}' \times \hat{i}' = \frac{1}{\sqrt{18}}(1, 1, 1) \times (2, -1, -1) = \frac{1}{\sqrt{18}}(0, 3, -3) = \frac{1}{\sqrt{2}}(0, 1, -1)$. Subbing in $\vec{c} = (1, 1, 1)$, $\rho = \sqrt{6}$, $\hat{i}' = \frac{1}{\sqrt{6}}(2, -1, -1)$ and $\hat{j}' = \frac{1}{\sqrt{2}}(0, 1, -1)$ gives

$$\vec{r}(t) = (1,1,1) + \sqrt{6}\cos t \,\frac{1}{\sqrt{6}}(2,-1,-1) + \sqrt{6}\sin t \,\frac{1}{\sqrt{2}}(0,1,-1) \\ = \left(1 + 2\cos t, 1 - \cos t + \sqrt{3}\sin t, 1 - \cos t - \sqrt{3}\sin t\right) \quad 0 \le t \le 2\pi$$

To check this, note that $\vec{r}(0) = (3,0,0)$, $\vec{r}(\frac{2\pi}{3}) = (0,3,0)$ and $\vec{r}(\frac{4\pi}{3}) = (0,0,3)$ since $\cos\frac{2\pi}{3} = \cos\frac{4\pi}{3} = -\frac{1}{2}$, $\sin\frac{2\pi}{3} = \frac{\sqrt{3}}{2}$ and $\sin\frac{4\pi}{3} = -\frac{\sqrt{3}}{2}$.

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