## Extra credit assignment: review problems. Part 1.

Part 2 will be posted soon. The whole assignment is worth $5 \%$ and can be done instead of the computer project, or in addition to it for extra credit.

1. Lines and planes in $\mathbb{R}^{3}$ and in higher dimension. Remember from multivariable calculus that a line in $\mathbb{R}^{3}$ can be given by a parametric equation, or by "symmetric equation"

$$
\frac{x-x_{0}}{a}=\frac{y-y_{0}}{b}=\frac{z-z_{0}}{c}
$$

. Note that the "symmetric equation" is, in fact, two equations, and together they represent your line as an intersection of two planes, one vertical, one horizontal.

A plane in $\mathbb{R}^{3}$ (if it contains the origin) is a linear subspace of co-dimension 1 (so it is given by a single equation on $x, y, z$ ). Note that the way the equation for a plane is introduced in multivariable calculus uses the dot product: it is given via a normal vector $(a, b, c)$ (then the equation for a plane containing 0 is

$$
(x, y, z) \cdot(a, b, c)=0
$$

which gives $a x+b y+c z=0$ ). However, in the end we do not need the dot product to think of a plane, it is just a linear subspace of $\mathbb{R}^{3}$ defined by one linear relation on its coordinates (in other words, it is a space of solutions of a single linear equation). Before proceeding, make sure you understand these statements.

In this problem, solve all the parts without using cross product (in $\mathbb{R}^{3}$, the cross product simplifies some of the calculations, but it does not generalize to higher-dimensional spaces; here the goal is to illustrate what happens in $\mathbb{R}^{n}$, so we do not want to be distracted by the cross product).
(a) Write down a general vector form of a parametric equation for a line in $\mathbb{R}^{3}$ that passes through the origin (namely, a 1-dimensional linear subspace of $\mathbb{R}^{3}$ ).
(b) Write down a general form of a parametric equation for a line in $\mathbb{R}^{n}$ that passes through the origin (namely, a 1-dimensional linear subspace of $\mathbb{R}^{n}$ ).
(c) Write down a general form of the "symmetric equation" for a line in $\mathbb{R}^{4}$. How many equations does it really consist of?
(d) If you take a "system" of linear equations that consists of a single equation $x+3 y+2 z=0$ and "solve" it using the methods from our course, what do you get? (I claim that you should get a parametric equation for your plane, and it will use two parametrs). Interpret this solution in terms of a basis. Namely, find a basis for the plane $x+3 y+2 z=0$.
(e) How many equations do you need to define a plane in $\mathbb{R}^{4}$ ? Why? Can you use rank-nullity theorem to give a rigorous proof?
(f) Find a basis for the plane $W$ in $\mathbb{R}^{4}$ defined by the equations

$$
\begin{aligned}
& x+2 y+3 z+w=0 \\
& y-z-5 w=0
\end{aligned}
$$

(g) Interpret your result in the previous part as " The kernel of the linear map ... is the linear subspace $W$ with basis ..." (Fill in the blanks in the above sentence).
(h) Write down a linear equation that defines the plane (call it $W$ ) with basis $\{(1,1,1),(2,3,1)\}$ in $\mathbb{R}^{3}$ (without using cross product!) I claim that I can interpret your result in the following language: "Find a linear functional $f: \mathbb{R}^{3} \rightarrow \mathbb{R}$ such that $\operatorname{Ker}(f)=W$." Write down this linear functional.
(i) Write down a system of linear equations in $\mathbb{R}^{4}$ that define the plane $W$ with basis $\{(1,1,1,1),(2,3,0,1)\}$ and interpret your result as " $W=$ $\operatorname{Ker}(A)$, where $A$ is a linear map ....".
(j) Let $f_{1}: \mathbb{R}^{3} \rightarrow \mathbb{R}$ be the linear functional $f_{1}(x, y, z)=x+2 y+3 z$, and let $f_{2}: \mathbb{R}^{3} \rightarrow \mathbb{R}$ be the linear functional $f_{2}(x, y, z)=x-y-z$. Give a complete description of $\operatorname{Ker}\left(f_{1}\right) \cap \operatorname{Ker}\left(f_{2}\right)$ in as many ways as you can, as precisely as you can.
(k) How many linear equations do you need to define a plane in $\mathbb{R}^{n}$ ? Why?
(l) Decide whether the line with parametric equation $(x, y, z)=(t, 2 t, 3 t)$ is contained in the plane given by the equation $x+y-z=0$.
Now I am going to ask this question in a different way: "Let $v=(1,2,3)$, and let $w_{1}$ and $w_{2}$ be a basis for the plane $x+y-z=0$. Is the collection of vectors $\left\{v, w_{1}, w_{2}\right\}$ linearly independent?"
(m) Let $W_{1}$ be the subspace of $\mathbb{R}^{5}$ defined by the equation $x_{1}+x_{2}+x_{3}+$ $x_{4}+x_{5}=0$, and let $W_{2}$ be defined by the equations $x_{1}-x_{2}+x_{3}=0$ and $x_{2}-2 x_{3}+x_{5}=0$. Find the dimensions of $W_{1}$ and $W_{2}$, and find a basis for $W_{1} \cap W_{2}$.
II. Linear maps and their matrices. The fundamental idea is that if you have a basis in $V$ and a basis in $W$, you can define a linear map from $V$ to $W$ using a matrix. In the matrix, the columns are the coordinates of the images (in $W$ ) of the basis vectors of $V$. In doing this, you have complete freedom as to where your map sends the basis vectors.

1. Let $P_{n}$ be the space of polynomials of degree not greater than $n$, and let $D: P_{n} \rightarrow P_{n}$ be the linear map given by $D(p)=p^{\prime}$ (the derivative of $p$ ). Write down the matrix for $D$ with respect to the basis $\left\{1, x, x^{2}, \ldots, x^{n}\right\}$. What is the size of this matrix? Find the kernel and image of $D$. Find the eigenvalues and eigenvectors of $D$ in $P_{n}$. Prove that $D^{n}=0$ (so $D$ is a so-called nilpotent linear operator).
2. Curtis, Section 13, Problem 1 (p.107)
3. Curtis, Section 13, Problem 2 (p.107)
4. Explain whether there exists a linear transformation $T: \mathbb{R}^{4} \rightarrow \mathbb{R}^{2}$ such that $T(0,1,1,1)=(2,0), T(1,2,1,1)=(1,2), T(1,1,1,2)=(3,1)$, $T(2,1,0,1)=(2,3)$. (This is problem 11 in Curtis).
5. Let $C^{\infty}((0,1))$ be the space of all infinitely-differentiable functions on the interval $(0,1)$ (it is infinite-dimensional).
(a) Prove that $e^{\lambda x}$ is an eigenvector of the differentiation operator $D: C^{\infty}((0,1)) \rightarrow C^{\infty}((0,1))$ defined by $D(f)=f^{\prime}$. Conclude that the functions $e^{\lambda x}$ form a linearly independent set of vectors in $C^{\infty}((0,1))$.
(b) Consider the linear subspace $W$ of $C^{\infty}((0,1))$ spanned by $\left\{e^{x}, e^{2 x}, e^{3 x}\right\}$ (by the previous part, you know that they are linearly independent, so $W$ is 3 -dimensional). Let $A_{1}: W \rightarrow \mathbb{R}^{3}$ be defined by $A_{1}(f)=\left(f(1), 3 f^{\prime}(2), f^{\prime \prime}(3)\right)$. Find the matrix for the linear map $A_{1}$ with respect to the given basis of $W$ and the standard basis of $\mathbb{R}^{3}$.
