

# Lecture 1: Review of methods to solve Ordinary Differential Equations

(Compiled 4 January 2019)

In this lecture we will briefly review some of the techniques for solving First Order ODE and Second Order Linear ODE, including Cauchy-Euler/Equidimensional Equations

**Key Concepts:** First order ODEs: Separable and Linear equations; Second Order Linear ODEs: Constant Coefficient Linear ODE, Cauchy-Euler/Equidimensional Equations.

## 1 First Order ordinary Differential Equations:

### 1.1 Separable Equations:

$$\begin{aligned}\frac{dy}{dx} &= P(x)Q(y) \\ \int \frac{dy}{Q(y)} &= \int P(x) dx + C\end{aligned}\tag{1.1}$$

Example 1:

$$\begin{aligned}\frac{dy}{dx} &= \frac{4y}{x(y-3)} \\ \left(\frac{y-3}{y}\right) dy &= \frac{4}{x} dx \\ y - 3 \ln|y| &= 4 \ln|x| + C \\ y &= \ln(x^4 y^3) + C \\ Ax^4 y^3 &= e^y\end{aligned}\tag{1.2}$$

### 1.2 Linear First Order equations - The Integrating Factor:

$$y'(x) + P(x)y = Q(x)\tag{1.3}$$

Can we find a function  $F(x)$  to multiply (4.3) by in order to turn the left hand side into a derivative of a product:

$$Fy' + FPy = FQ\tag{1.4}$$

$$(Fy)' = Fy' + F'y = FQ\tag{1.5}$$

So let  $F' = FP$  which is a separable Eq.

$$\frac{dF}{F(x)} = P(x) dx \Rightarrow \int \frac{dF}{F} = \int P(x) dx + C$$

$$\text{Therefore } \ln F = \int P(x) dx + C \quad (1.6)$$

$$\text{or } F = Ae^{\int P(x) dx} \quad \text{choose } A = 1$$

$$F = e^{\int P(x) dx} \quad \text{integrating factor}$$

Therefore

$$\begin{aligned} e^{\int P(x) dx} y' + e^{\int P(x) dx} P(x)y &= e^{\int P(x) dx} Q(x) \\ (e^{\int P(x) dx} y)' &= e^{\int P(x) dx} Q(x) \\ y(x) &= e^{-\int P(x) dx} \left\{ \int e^{\int P(x) dx} Q(x) dx + C \right\} \end{aligned} \quad (1.7)$$

Example 2:

$$y' + 2y = 0 \quad (1.8)$$

$$\begin{aligned} F(x) = e^{2x} \Rightarrow e^{2x} y' + e^{2x} 2y &= (e^{2x} y)' = 0 \\ e^{2x} y &= c \\ y(x) &= Ce^{-2x} \end{aligned}$$

Example 3: Solve

$$\frac{dy}{dx} + \cot(x)y = 5e^{\cos x}, \quad y(\pi/2) = -4 \quad (1.9)$$

$$\begin{aligned} P(x) &= \cot x & Q(x) &= 5e^{\cos x} \\ F(x) &= e^{\int \cot x dx} & &= e^{\ln(\sin x)} = \sin x \end{aligned} \quad (1.10)$$

$$\text{Therefore } \sin(x)y' + \cos(x)y = (\sin(x)y)' = 5e^{\cos x} \sin x$$

$$\sin(x)y = -5e^{\cos x} + C$$

$$y(x) = -\frac{5e^{\cos x} - C}{\sin x} \quad (1.11)$$

$$-4 = y(\pi/2) = -\frac{5-C}{1} \Rightarrow C = 1$$

$$\text{Therefore } y(x) = \frac{1-5e^{\cos x}}{\sin x}$$

## 2 Second Order Constant Coefficient Linear Equations:

$$Ly = ay'' + by' + cy = 0$$

$$\begin{aligned} \text{Guess } y &= e^{rx} & y' &= re^{rx} & y'' &= r^2 e^{rx} \\ Ly &= [ar^2 + br + c]e^{rx} = 0 \text{ provided } [] = 0 \end{aligned}$$

Indicial Eq.:

$$\begin{aligned} g(r) &= ar^2 + br + c = 0 & r_{1,2} &= -\frac{b \pm \sqrt{b^2 - 4ac}}{2a} \\ \text{or } g(r) &= a(r - r_1)(r - r_2) = 0 \end{aligned} \quad (2.1)$$

Case I:  $\Delta = b^2 - 4ac > 0, r_1 \neq r_2, y(x) = c_1 e^{r_1 x} + c_2 e^{r_2 x}$  is the general solution.

Case II:  $\Delta = 0$ ,  $r_1 = r_2$ , repeated roots  $Ly = a(r - r_1)^2 e^{rx} = 0$ . In this case obtain only *one* solution  $y(x) = e^{r_1 x}$ . How do we get a second solution?

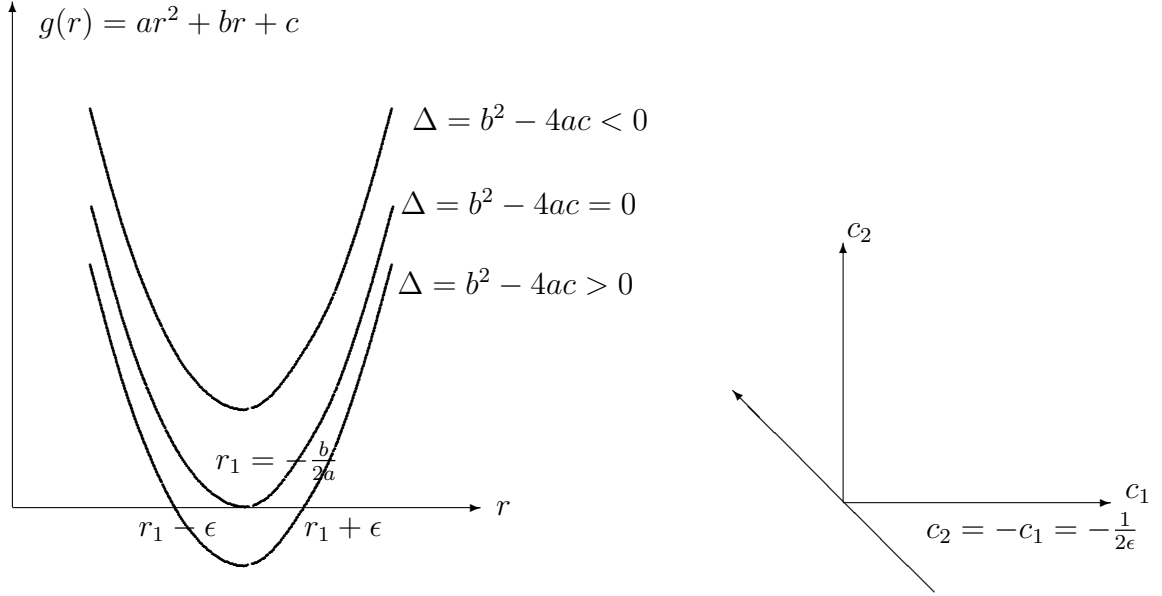


FIGURE 1. Left Figure: Roots of the characteristic polynomial  $g(r) = ar^2 + br + c$  for the different cases of the discriminant  $\Delta = b^2 - 4ac$ . We consider special solution, in which  $g(r) = a(r - (r_1 - \epsilon))(r - (r_1 + \epsilon)) = a[(r - r_1)^2 - \epsilon^2] \approx a(r - r_1)^2$ . Right Figure: We consider the special solution (2.3) for the case in which the two parameters  $c_1$  and  $c_2$  have been chosen to be  $c_2 = -c_1 = -\frac{1}{2\epsilon}$ , which represents a straight line in the two-parameter  $c_1 - c_2$  space

*First Method: Perturbation of the double root:* Consider a small perturbation (see figure 1 a) to the double root case, such that  $g(r) = a(r - (r_1 - \epsilon))(r - (r_1 + \epsilon)) = a[(r - r_1)^2 - \epsilon^2] \approx a(r - r_1)^2$ . In this case the two, very close but distinct, roots of  $g(r) = 0$  are given by:

$$r = r_1 + \epsilon \text{ and } r = r_1 - \epsilon \quad (2.2)$$

Now since we still have two distinct roots in this perturbed case, the general solution is:

$$y(x) = c_1 e^{(r_1 + \epsilon)x} + c_2 e^{(r_1 - \epsilon)x} \quad (2.3)$$

Now choosing a special solution by selecting  $c_1 = \frac{1}{2\epsilon} = -c_2$ , and we obtain a family of solutions that depend on the small parameter  $\epsilon$  (see figure 1 b):

$$y(x, \epsilon) = \frac{e^{(r_1 + \epsilon)x} - e^{(r_1 - \epsilon)x}}{2\epsilon} \approx \left. \frac{\partial}{\partial r} e^{rx} \right|_{r=r_1} \quad (2.4)$$

Now taking the limit as  $\epsilon \rightarrow 0$  by making use of L'Hospital's Rule, we obtain the following limiting solution:

$$y(x, \epsilon) = e^{r_1 x} \left( \frac{e^{\epsilon x} - e^{-\epsilon x}}{2\epsilon} \right) \xrightarrow{\epsilon \rightarrow 0} x e^{r_1 x} = \left. \frac{\partial}{\partial r} e^{rx} \right|_{r=r_1} \quad (2.5)$$

*Second Method: taking the derivative with respect to  $r$ :* From (2.4) and (2.5) we see that the new solution  $x e^{r_1 x}$  was obtained by taking the derivative of  $y(x, r) = e^{rx}$  with respect to  $r$  and then making the substitution  $r = r_1$ . This

is, in fact, a general procedure that we will use later in the course. To see why this procedure works, let

$$\begin{aligned} y(r, x) &= e^{rx} \\ Ly(r, x) &= a(r - r_1)^2 e^{rx} \\ L \left[ \frac{\partial y}{\partial r}(r, x) \right]_{r=r_1} &= [2a(r - r_1)e^{rx} + a(r - r_1)^2 x e^{rx}]_{r=r_1} = 0 \end{aligned} \quad (2.6)$$

Therefore  $\left[ \frac{\partial y}{\partial r}(r, x) \right]_{r=r_1} = x e^{r_1 x}$  is also a solution.

Thus, to summarize, the general solution for the case of a double root is:

$$y(x) = c_1 e^{r_1 x} + c_2 x e^{r_1 x} \quad (2.7)$$

Case III: Complex Conjugate Roots:  $\Delta = b^2 - 4ac < 0$

$$\begin{aligned} r_{\pm} &= -\frac{b}{2a} \pm \frac{i\sqrt{4ac - b^2}}{2a} = \lambda \pm i\mu \\ y(x) &= c_1 e^{(\lambda+i\mu)x} + c_2 e^{(\lambda-i\mu)x} \\ &= e^{\lambda x} [A \cos \mu x + B \sin \mu x]. \end{aligned} \quad (2.8)$$

Example 4:

$$\begin{aligned} Ly &= y'' + y' - 6y = 0 \\ y &= e^{rx}(r^2 + r - 6) = (r + 3)(r - 2) = 0 \\ y(x) &= c_1 e^{-3x} + c_2 e^{2x} \end{aligned} \quad (2.9)$$

Example 5:

$$\begin{aligned} Ly &= y'' + 6y' + 9y = 0 \\ y &= e^{rx}(r + 3)^2 = 0 \\ y(x) &= c_1 e^{-3x} + c_2 x e^{-3x} \end{aligned} \quad (2.10)$$

Example 6:

$$\begin{aligned} Ly &= y'' - 4y' + 13y = 0 \\ y &= e^{rx} : r^2 - 4r + 13 = 0 \\ & \quad r = \frac{4 \pm \sqrt{16 - 52}}{2} = 2 \pm 3i \\ \text{Therefore } y(x) &= e^{2x} [A \cos 3x + B \sin 3x]. \end{aligned} \quad (2.11)$$

### 3 Cauchy/Euler/Equidimensional Equations:

$$Ly = x^2 y'' + \alpha x y' + \beta y = 0. \quad (3.1)$$

Aside: Note if we let  $t = \ln x$  or  $x = e^t$  then  $\frac{d}{dx} = \frac{d}{dt} \frac{dt}{dx} \Rightarrow \frac{d}{dt} = x \frac{d}{dx}$ .

$$\frac{d^2}{dt^2} = x \frac{d}{dx} \left( x \frac{d}{dx} \right) = x^2 \frac{d^2}{dx^2} + x \frac{d}{dx} \Rightarrow x^2 \frac{d^2}{dx^2} = \frac{d^2}{dt^2} - \frac{d}{dt} \quad (3.2)$$

$$\begin{aligned} \text{Therefore } \ddot{y} - \dot{y} + \alpha \dot{y} + \beta y &= 0 \\ \ddot{y} + (\alpha - 1)\dot{y} + \beta y &= 0 \end{aligned} \quad (3.3)$$

$$y = e^{rt} \Rightarrow r^2 + (\alpha - 1)r + \beta = 0 \quad \text{Characteristic Eq.}$$

Back to (3.1): Guess  $y = x^r$ ,  $y' = rx^{r-1}$ , and  $y'' = r(r-1)x^{r-2}$ .

$$\begin{aligned} \text{Therefore } \{r(r-1) + \alpha r + \beta\} x^r &= 0 \\ f(r) = r^2 + (\alpha-1)r + \beta &= 0 \quad \text{as above.} \end{aligned} \quad (3.4)$$

$$r_{\pm} = \frac{1 - \alpha \pm \sqrt{(\alpha-1)^2 - 4\beta}}{2} \quad (3.5)$$

Case 1:  $\Delta = (\alpha-1)^2 - 4\beta > 0$  Two Distinct Real Roots  $r_1, r_2$ .

$$y = c_1 x^{r_1} + c_2 x^{r_2} \quad (3.6)$$

If  $r_1$  or  $r_2 < 0$  then  $|y| \rightarrow \infty$  as  $x \rightarrow 0$ .

Case 2:  $\Delta = 0$  Double Root  $(r - r_1)^2 = 0$ .

We obtain only one solution in this case:

$$y = c_1 x^{r_1} \quad (3.7)$$

To get a second solution we use second method introduced above, in which we differentiate with respect to the parameter  $r$ :

$$\begin{aligned} \frac{\partial}{\partial r} L[x^r] &= L\left[\frac{\partial}{\partial r} x^r\right] = L[x^r \log x] \\ \frac{\partial}{\partial r} \{f(r)x^r\} &= f'(r)x^r + f(r)x^r \log x = 0 \quad \text{since } f(r) = (r - r_1)^2. \end{aligned} \quad (3.8)$$

General Solution:  $y(x) = (c_1 + c_2 \log x)x^{r_1}$ .

Check:

$$\begin{aligned} L(x^{r_1} \log x) &= x^2 (x^r \log x)'' + \alpha x (x^r \log x)' + \beta (x^r \log x) - \\ &= x^2 [r(r-1)x^r \log x + rx^{r-2} + (r-1)x^{r-2}] \\ &\quad + \alpha x [rx^{r-1} \log x + x^{r-1}] + \beta (x^r \log x) \\ &= \{r^2 + (\alpha-1)r + \beta\} x^r \log x + \{2r-1+\alpha\} x^r = 0 \end{aligned} \quad (3.9)$$

Case 3:  $\Delta = (\alpha-1)^2 - 4\beta < 0$ .

$$\begin{aligned} r_{\pm} &= \frac{(1-\alpha)}{2} \pm i \frac{[4\beta - (\alpha-1)^2]^{1/2}}{2} = \lambda \pm i\mu \\ y(x) &= c_1 x^{(\lambda+i\mu)} + c_2 x^{(\lambda-i\mu)} \quad x^r = e^{r \ln x} \\ &= c_1 e^{(\lambda+i\mu) \ln x} + c_2 e^{(\lambda-i\mu) \ln x} \\ &= x^{\lambda} \{c_1 e^{i\mu \ln x} + c_2 e^{-i\mu \ln x}\} \\ &= A_1 x^{\lambda} \cos(\mu \ln x) + A_2 x^{\lambda} \sin(\mu \ln x) \end{aligned} \quad (3.10)$$

*Observations:*

- If  $x < 0$  replace by  $|x|$ .

- The two solutions are linearly independent as we can verify by applying the Wronskian test, as follows:

$$\begin{aligned}
w(y_1, y_2) &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_1' y_2 \quad (\text{look up the definition of the Wronskian}) \\
&= \{x^\lambda \cos(\mu \ln x)\} \{\log x x^\lambda \sin(\mu \ln x) + x^{\lambda-1} \cos(\mu \ln x)\mu\} \\
&\quad - \{x^\lambda \log x \cos(\mu \ln x) - x^{\lambda-1} \sin(\mu \ln x)\mu\} \{x^\lambda \sin(\mu \ln x)\} \\
&= \mu x^{2\lambda-1} \quad \text{independent for } x \neq 0.
\end{aligned}$$

Example 7:

$$\begin{aligned}
x^2 y'' - x y' - 2y &= 0, & y(1) &= 0, & y'(1) &= 1 \\
y = x^r & \quad r(r-1) - r - 2 = 0 & \quad r^2 - 2r - 2 &= 0 & & \\
& \quad (r-1)^2 = 3 & \quad r &= 1 \pm \sqrt{3} & & 
\end{aligned} \tag{3.11}$$

$$\begin{aligned}
y &= c_1 x^{1+\sqrt{3}} + c_2 x^{1-\sqrt{3}} \\
y(1) &= c_1 + c_2 = 0 \quad c_2 = -c_1 \\
y(x) &= c_1 \left( x^{1+\sqrt{3}} - x^{1-\sqrt{3}} \right)
\end{aligned} \tag{3.12}$$

$$y'(x) = c_1 \left[ (1+\sqrt{3})x^{\sqrt{3}} - (1-\sqrt{3})x^{-\sqrt{3}} \right] \Big|_{x=1} = c_1 2\sqrt{3} = 1$$

$$\text{Therefore } y(x) = \frac{1}{2\sqrt{3}} \left( x^{1+\sqrt{3}} - x^{1-\sqrt{3}} \right). \tag{3.13}$$

Example 8:

$$\begin{aligned}
x^2 y'' - 3x y' + 4y &= 0 & y(1) &= 1 & y'(1) &= 0 \\
y = x^r & \implies r(r-1) - 3r + 4 = r^2 - 4r + 4 = 0 & (r-2)^2 &= 0 & & 
\end{aligned} \tag{3.14}$$

$$\begin{aligned}
y(x) &= c_1 x^2 + c_2 x^2 \log x \\
y(1) &= c_1 = 1 & y'(1) &= [2x + c_2(2x \log x + x)]_{x=1} \\
&= 2 + c_2 = 0
\end{aligned} \tag{3.15}$$

$$\text{Therefore } y(x) = x^2 - 2x^2 \log x.$$