A POINTWISE INEQUALITY FOR THE FOURTH ORDER LANE-EMDEN EQUATION

MOSTAFA FAZLY, JUNCHENG WEI, AND XINGWANG XU

ABSTRACT. We prove that the following pointwise inequality holds

$$-\Delta u \geq \sqrt{\frac{2}{(p+1)-c_n}} |x|^{\frac{\alpha}{2}} u^{\frac{p+1}{2}} + \frac{2}{n-4} \frac{|\nabla u|^2}{u} \ \ \text{in} \ \ \mathbb{R}^n$$

where $c_n := \frac{8}{n(n-4)}$, for positive bounded solutions of the fourth order Hénon equation that is

$$\Delta^2 u = |x|^a u^p \quad \text{ in } \quad \mathbb{R}^n$$

for some $a\geq 0$ and p>1. Motivated by the Moser's proof of the Harnack's inequality as well as Moser iteration type arguments in the regularity theory, we develop an iteration argument to prove the above pointwise inequality. As far as we know this is the first time that such an argument is applied towards constructing pointwise inequalities for partial differential equations. An interesting point is that the coefficient $\frac{2}{n-4}$ also appears in the fourth order Q-curvature and the Paneitz operator. This in particular implies that the scalar curvature of the conformal metric with conformal factor $u^{\frac{4}{n-4}}$ is positive.

1. Introduction

We are interested in proving a priori pointwise estimate for positive solutions of the following fourth order Hénon equation

(1.1)
$$\Delta^2 u = |x|^a u^p \quad \text{in} \quad \mathbb{R}^n$$

where p>1 and $a\geq 0$. Let us first mention that for the case a=0, it is known that (1.1) only admits u=0 as a nonnegative solution when p is a subcritical exponent that is $1< p<\frac{n+4}{n-4}$ when $n\geq 5$ and 1< p when $n\leq 4$. Moreover, for the critical case $p=\frac{n+4}{n-4}$ all entire positive solutions are classified. See [20, 29]. This is a counterpart of the standard Liouville theorem of Gidas-Spruck in [17, 18] for the second order Lane-Emden equation

$$(1.2) -\Delta u = u^p \text{in } \mathbb{R}^n$$

stating that u=0 is the only nonnegative solution for (1.2) when p is a subcritical exponent that is $1 when <math>n \ge 3$. Note also that for the fourth order Hénon equation, it is conjectured that u=0 is the only nonnegative solution of (1.1) when p is a subcritical exponent that is when $1 and <math>n \ge 5$, see [15]. Therefore, throughout this note, when we are dealing with (1.1), we assume

Key words and phrases. Semilinear elliptic equations, a priori pointwise estimate, Moser iteration type arguments, elliptic regularity.

The first two authors are supported by NSERC grants.

that $p > \frac{n+4+2a}{n-4}$ and $n \ge 5$. For more information, see [15, 28] and references therein.

Pointwise estimates have had tremendous impact on the theory of elliptic partial differential equations. In what follows we list some of the celebrated pointwise inequalities for certain semilinear elliptic equations and systems. These inequalities have been used to tackle well-known conjectures and open problems. The following inequality by Modica [21] has been one of the main techniques to solve the De Giorgi's conjecture (1978) for the Allen-Cahn equation and to analyze various semilinear equations and problems.

Theorem 1.1. (Modica [21], 1985) Let $F \in C^2(\mathbb{R})$ be a nonnegative function and u be a bounded entire solution of

(1.3)
$$\Delta u = F'(u) \quad in \quad \mathbb{R}^n.$$

Then

$$(1.4) |\nabla u|^2 \le 2F(u) in \mathbb{R}^n.$$

For the specific case $F(u) = \frac{1}{4}(1-u^2)^2$, equation (1.3) is known as the Allen-Cahn equation. Note also that Caffarelli et al. in [3] extended this inequality to quasilinear equations. We refer interested readers to [4, 9–13] regarding pointwise gradient estimates and certain improvements of (1.4). For the fourth order counterpart of (1.3) with an arbitrary nonlinearity, a general inequality of the form (1.4) is not known. However, for a particular nonlinearity known as the fourth order Lane-Emden equation, i.e.

$$(1.5) \Delta^2 u = u^p in \mathbb{R}^n$$

it is shown by Wei and Xu, as Theorem 3.1 in [29], that the negative Laplacian of the positive solutions is non-negative that is $-\Delta u \geq 0$ in \mathbb{R}^n . Set $v = -\Delta u$ and from the fact that $-\Delta u \geq 0$ we can consider (1.5) as a special case (when q = 1) of the Lane-Emden system that is

(1.6)
$$\begin{cases} -\Delta u = v^q \text{ in } \mathbb{R}^n, \\ -\Delta v = u^p \text{ in } \mathbb{R}^n, \end{cases}$$

where $p \geq q \geq 1$. Note that there is a significance difference between system (1.6) and equation (1.5) in the sense that this system has Hamiltonian structure while the equation has gradient structure, see [6, 7, 27] and references therein. This system has been of great interest at least in the past two decades. In particular, the Lane-Emden conjecture stating that u=v=0 is the only nonnegative solution for this system where $\frac{1}{p+1}+\frac{1}{q+1}>\frac{n-2}{n}$ has been studied extensively and various methods and techniques are developed to tackle this conjecture. Among these methods, Souplet [28] proved the following pointwise inequality for solutions of (1.6) and then used it to prove the Lane-Emden conjecture in four dimensions. Note that the particular case 1 is done by Phan in [25].

Theorem 1.2. (Souplet [28], 2009) Let u and v be nonnegative solutions of (1.6). Then the following inequality holds

(1.7)
$$\frac{u^{p+1}}{p+1} \le \frac{v^{q+1}}{q+1} \quad in \ \mathbb{R}^n.$$

Applying this theorem, the following pointwise inequality holds for nonnegative solutions of (1.5)

$$(1.8) -\Delta u \ge \sqrt{\frac{2}{p+1}} u^{\frac{p+1}{2}} \text{ in } \mathbb{R}^n.$$

Note also that Phan in [25], with similar methods provided in [28], extended the pointwise inequality (1.7) to nonnegative solutions of the Hénon-Lane-Emden system that is

(1.9)
$$\begin{cases} -\Delta u = |x|^b v^q & \text{in } \mathbb{R}^n, \\ -\Delta v = |x|^a u^p & \text{in } \mathbb{R}^n, \end{cases}$$

where $p \ge q \ge 1$. Suppose that $0 \le a - b \le (n-2)(p-q)$ then

(1.10)
$$|x|^a \frac{u^{p+1}}{p+1} \le |x|^b \frac{v^{q+1}}{q+1} \text{ in } \mathbb{R}^n.$$

The standard method to prove a pointwise inequality, as it is used to prove (1.7) and (1.4), is to derive an appropriate equation, call it an auxiliary equation, for the difference function of the right-hand and the left-hand sides of the inequality. Then, whenever we have enough decay estimates on solutions of the auxiliary equation, maximum principles can be applied to prove that the difference function has a fixed sign. So, the key point here is to manipulate a suitable auxiliary equation.

In a more technical framework, to construct an auxiliary equation to prove (1.7) and (1.8) a few positive terms including a gradient term of the form $|\nabla u|^2 u^{t-2}$ for some number t are not considered in [28]. To be more explicit, in order to prove (1.8), that is a particular case of (1.7), the difference function $w(x) := \Delta u + \sqrt{\frac{2}{p+1}} u^{\frac{p+1}{2}}$ is considered. Straightforward calculations show that the following auxiliary equation holds

(1.11)
$$\left(\sqrt{\frac{2}{p+1}}u^{\frac{1-p}{2}}\right)\Delta w = \Delta u + \sqrt{\frac{2}{p+1}}u^{\frac{p+1}{2}} + \frac{p-1}{2}\frac{|\nabla u|^2}{u}.$$

In order to show that Δw is nonnegative when w is nonnegative, via maximum principles for the above equation, the gradient term $\frac{|\nabla u|^2}{u}$ is not considered in [28]. Note that the above equation (1.11) implies, in the spirit, that the gradient term $\frac{|\nabla u|^2}{u}$ should have an impact on the inequality just like the Laplacian operator and the power term $u^{\frac{p+1}{2}}$. This is our motivation to attempt to include the gradient term in the inequality (1.8) that gives a lower bound on the Laplacian operator. Let us briefly mention that Modica in his proof of (1.4) took advantage of similar gradient terms to construct an auxiliary equation. Following ideas provided by Modica [21] and Souplet [28], as we shall see in the proof of Proposition 3.1, we manage to keep most of the positive terms when looking for an auxiliary equation.

In this paper, we develop a Moser iteration type argument to prove a lower bound for the negative Laplacian of positive bounded solutions of (1.1) that involves powers of u and the new term $\frac{|\nabla u|^2}{u}$ with $\frac{2}{n-4}$ as the coefficient. The remarkable point is that the coefficient $\frac{2}{n-4}$ is what we exactly need in the estimate of the scalar curvature for the conformal metric $g = u^{\frac{2}{n-4}}g_0$.

Here is our main result.

Theorem 1.3. Let u be a bounded positive solution of (1.1). Then the following pointwise inequality holds

$$(1.12) -\Delta u \ge \sqrt{\frac{2}{(p+1)-c_n}} |x|^{\frac{\alpha}{2}} u^{\frac{p+1}{2}} + \frac{2}{n-4} \frac{|\nabla u|^2}{u} \quad in \ \mathbb{R}^n$$

where $c_n := \frac{8}{n(n-4)}$ and $0 \le a \le \inf_{k \ge 0} A_k$ (defined at (4.28)).

Remark 1.1. A natural question here is that what are the best constants in the inequality (1.12)?

Let us now put the inequality (1.12) in a more geometric text. By the conformal change $g = u^{\frac{4}{n-4}}g_0$ where g_0 is the usual Euclidean metric, the new scalar curvature becomes

$$S_g = -\frac{4(n-1)}{n-2} u^{-\frac{n+2}{n-4}} \Delta\left(u^{\frac{n-2}{n-4}}\right).$$

An immediate consequence of (1.12) is that the conformal scalar curvature is positive. Note that this can not be deduced from the inequality (1.8).

The idea of proving a lower bound for the negative of Laplacian operator is also used in the context of nonlinear eigenvalue problems to prove certain regularity results, e.g. see [5]. Similar pointwise inequalities are used to prove Liouville theorems in the notion of stability in [30, 31] and references therein as well. We would like to mention that Gui in [19] proved a very interesting Hamiltonian identity for elliptic systems that may be regarded as a generalization of the Modica's inequality. He used this identity to rigorously analyze the structure of level curves of saddle solutions of the Allen-Cahn equation as well as Young's Law for the contact angles in triple junction formation. Note also that as it is shown by Farina in [8] for the Ginzburg-Landau system, the analog of Modica's estimate is false for systems in general. We refer interested readers to [1] for a review of this topic and to [16] for De Giorgi type results for systems.

Here is the organization of the paper. In Section 2, we provide certain standard elliptic estimates that are consequences of Sobolev embeddings and the regularity theory. Then, in Section 3 we develop a Moser iteration type argument, following ideas provided by Modica [21] and Souplet in [28]. Finally, in Section 4, we first give a certain maximum principle type argument for a quasilinear equation that arises in the Moser iteration process. Then we apply the estimates and methods developed in former sections. We suggest to ignore the weight function $|x|^a$ in (1.1) when reading the paper for the first time.

2. Technical elliptic estimates

In this section, we provide some elliptic decay estimates that we use frequently later in the proofs. Deriving the right decay estimates for solutions of (1.1) play a fundamental role in the most our proofs. Similar estimates have been also used in the literature to construct Liouville theorems and regularity results. We refer the interested readers to [14, 15, 25, 26, 28]. We start with the following standard estimate.

Lemma 2.1. (L^p -estimate on B_R) Suppose that u is a nonnegative solution of (1.1) then for any R > 1 we have

$$\int_{B_R} |x|^a u^p \le C \ R^{n - \frac{4p + a}{p - 1}},$$

where C = C(n, p, a) > 0 is independent from R.

Proof: Consider the following test function $\phi_R \in C_c^4(\mathbb{R}^n)$ with $0 \le \phi_R \le 1$;

$$\phi_R(x) = \begin{cases} 1, & \text{if } |x| < R; \\ 0, & \text{if } |x| > 2R; \end{cases}$$

where $||D^i\phi_R||_{\infty} \leq \frac{C}{R^i}$ where $1 \leq i \leq 4$. For fixed $m \geq 2$, we have

$$|\Delta^2 \phi_R^m(x)| \le \begin{cases} 0, & \text{if } |x| < R \text{ or } |x| > 2R; \\ CR^{-4} \phi_R^{m-4}, & \text{if } R < |x| < 2R; \end{cases}$$

where C > 0 is independent from R. For $m \ge 2$, multiply the equation by ϕ_R^m and integrate to get

$$\int_{B_{2R}} |x|^a u^p \phi_R^m = \int_{B_{2R}} \Delta^2 u \phi_R^m
= \int_{B_{2R}} u \Delta^2 \phi_R^m \le C R^{-4} \int_{B_{2R} \setminus B_R} u \phi_R^{m-4}.$$

Applying Hölder's inequality we get

$$\int_{B_{2R}} |x|^a u^p \phi_R^m \leq C R^{-4} \left(\int_{B_{2R} \setminus B_R} |x|^{\frac{-a}{p}p'} \right)^{\frac{1}{p'}} \left(\int_{B_{2R} \setminus B_R} |x|^a u^p \phi_R^{(m-4)p} \right)^{1/p} \\
\leq C R^{(n-\frac{a}{p}p')\frac{1}{p'}-4} \left(\int_{B_{2R} \setminus B_R} |x|^a u^p \phi_R^{(m-4)p} \right)^{1/p},$$

where $p' = \frac{p}{p-1}$. Set m = (m-4)p that gives $m = \frac{4p}{p-1}$ to get

$$\int_{B_{2R}} |x|^a u^p \phi_R^m \le C R^{(n-\frac{a}{p}p')\frac{1}{p'}-4} \left(\int_{B_{2R}} |x|^a u^p \phi_R^m \right)^{1/p}.$$

Therefore,

$$\int_{B_{2R}} |x|^a u^p \phi_R^m \le C \ R^{(n - \frac{a}{p}p') - 4p'}.$$

This finishes the proof.

From the Hölder's inequality we get the following.

Corollary 2.1. Under the same assumptions as Lemma 2.1. The following estimate holds

$$\int_{B_R \setminus B_{R/2}} u \le CR^{n - \frac{a+4}{p-1}}$$

where C = C(n, p, a) > 0 is independent from R.

We now show that the operator $-\Delta u$ has a sign. Then, we apply this to provide various elliptic estimates for derivatives of u. In addition, later on this helps us to start an iteration argument.

Proposition 2.1. Let u be a positive solution of (1.1). Then, $-\Delta u \geq 0$ in \mathbb{R}^n .

Proof: Let $v = -\Delta u$. Ideas and methods applied in this proof are strongly motivated by the ones given in [29]. Suppose that there is $x_0 \in \mathbb{R}^n$ such that $v(x_0) < 0$. Without loss of generality we take $x_0 = 0$, i. e. in case of $x_0 \neq 0$ set $\omega(x) = v(x + x_0)$ and apply the same argument. We use the notation $\bar{f}(r) = \frac{1}{|\partial B_r|} \int_{\partial B_r} f dS$ as the average of function f(x) on the boundary of B_r . We refer interested readers to [23] regarding the average function. Applying the Hölder's inequality

(2.1)
$$\begin{cases} -\Delta_r \bar{u}(r) = \bar{v}(r) \text{ in } \mathbb{R}, \\ -\Delta_r \bar{v}(r) \geq r^a (\bar{u})^p \text{ in } \mathbb{R}, \end{cases}$$

where Δ_r is the Laplacian operator in the polar coordinates, i.e.

$$\Delta_r \bar{f}(r) = r^{1-n} (r^{n-1} \bar{f}'(r))'.$$

It is straightforward to see that

$$\bar{v}'(r) = \frac{1}{|\partial B_r|} \int_{B_r} \Delta v = -\frac{1}{|\partial B_r|} \int_{B_r} |x|^a u^p \le 0.$$

Therefore, $\bar{v}(r) \leq \bar{v}(0) < 0$ for r > 0. Similarly for $\bar{u}'(r)$ we have

$$\bar{u}'(r) = -\frac{1}{|\partial B_r|} \int_{B_r} v = -r^{1-n} \int_0^r s^{n-1} \bar{v}(s) ds$$

$$\geq -\bar{v}(0) r^{1-n} \int_0^r s^{n-1} ds = -\frac{\bar{v}(0)}{n} r.$$

From this for any $r \geq r_0$ we get

$$(2.2) \bar{u}(r) \ge \alpha r^2,$$

where $\alpha = -\frac{\bar{v}(0)}{2n} > 0$. We now have a lower bound on $\bar{u}(r)$. Instead suppose that the following more general lower bound holds on $\bar{u}(r)$,

(2.3)
$$\bar{u}(r) \ge \frac{\alpha^{p^k}}{\beta^{s_k}} r^{t_k} \text{ for } r \ge r_k,$$

where $s_0 := 0$, $t_0 := 2$, $\alpha := -\frac{\bar{v}(0)}{2n} > 0$ and $\beta := 2p + a + n + 4 > 0$. Note that system (2.1) makes a relation between two functions $\bar{u}(r)$ and $\bar{v}(r)$. Therefore, the lower bound on $\bar{u}(r)$ forces an upper bound on $\bar{v}(r)$ and vice versa. In the light of this fact, we can construct an iteration argument to improve the bound (2.3). Integrating the second equation of (2.1) over $[r_k, r]$ when $r \geq r_k$ we get

$$r^{n-1}\bar{v}'(r) \leq r_k^{n-1}\bar{v}'(r_k) - \frac{\alpha^{p^{k+1}}}{\beta^{ps_k}} \int_{r_k}^r s^{n-1+a+pt_k} ds$$

$$\leq -\frac{\alpha^{p^{k+1}}}{\beta^{ps_k}(pt_k+n+a)} (r^{pt_k+n+a} - r_k^{pt_k+n+a}) \text{ since } \bar{v}' < 0.$$

Therefore $\bar{v}'(r) \leq -\frac{\alpha^{p^{k+1}}}{\beta^{ps_k}(pt_k+n+a)}(r^{pt_k+a+1}-r_k^{pt_k+a+1})$ for all $r \geq r_k$ that is

$$\bar{v}'(r) \le -\frac{\alpha^{p^{k+1}}}{2\beta^{ps_k}(pt_k+n+a)}r^{pt_k+a+1} \text{ for all } r \ge 2^{\frac{1}{pt_k+a+1}}r_k.$$

Integrating the last inequality over $\left[2^{\frac{1}{pt_k+a+1}}r_k,r\right]$ when $r\geq 2^{\frac{1}{pt_k+a+1}}r_k=\tilde{r}_k$, we obtain

$$\bar{v}(r) \leq \bar{v}(\tilde{r}_k) - \frac{\alpha^{p^{k+1}}}{2\beta^{ps_k} T_{k,n,a,p}} (r^{pt_k+a+2} - \tilde{r}_k^{pt_k+a+2}),$$

where $T_{k,n,a,p} := (pt_k + n + a)(pt_k + 2 + a)$. By similar discussions and by taking r large enough, that is $r \ge 2^{\frac{1}{pt_k+a+1}} 2^{\frac{1}{pt_k+a+2}} r_k = \tilde{\tilde{r}}_k$, we end up with

(2.4)
$$\bar{v}(r) \le -\frac{\alpha^{p^{k+1}}}{4\beta^{ps_k} T_{k,n,a,p}} r^{pt_k + a + 2}.$$

Applying (2.4) and integrating equation (2.1) again over $[\tilde{\tilde{r}}_k, r]$ when $r \geq \tilde{\tilde{r}}_k$, we have

$$r^{n-1}\bar{u}'(r) = \tilde{r}_k^{n-1}\bar{u}'(\tilde{r}_k) - \int_{\tilde{r}_k}^r s^{n-1}\bar{v}(s)ds$$
$$\geq \frac{\alpha^{p^{k+1}}}{4\beta^{ps_k}T_{k,n,a,p}} \int_{\tilde{r}_k}^r s^{pt_k+a+n+1}ds.$$

Therefore, the following new lower bound on $\bar{u}(r)$ holds

$$\bar{u}(r) \geq \frac{\alpha^{p^{k+1}}}{2^4 \beta^{ps_k} \tilde{T}_{k,n,a,p}} r^{pt_k+a+n+4},$$

where

$$r \ge 2^{\frac{1}{pt_k + a + 3}} 2^{\frac{1}{pt_k + a + 4}} \tilde{\tilde{r}}_k = 2^{\sum_{i=1}^4 \frac{1}{pt_k + a + i}} r_k,$$

and

$$\tilde{T}_{k,n,a,p} = (pt_k + n + a + 2)(pt_k + 4 + a)T_{k,n,a,p}
= (pt_k + n + a)(pt_k + 2 + a)(pt_k + n + a + 2)(pt_k + 4 + a)
< (pt_k + n + a + 4)^4.$$

We now modify this estimate to make the coefficients similar to (2.3). After simplifying we get

(2.5)
$$\bar{u}(r) \ge \frac{\alpha^{p^{k+1}}}{\beta^{ps_k} M_{\iota}} r^{pt_k + a + 4} \quad \text{for } r \ge 2^{\frac{4}{pt_k + a + 1}} r_k,$$

where $M_k := 2^4 (pt_k + n + a + 4)^4$. In what follows, we put an upper bound on M_k that is expressed as a power of β . Note that

$$\frac{1}{2}\sqrt[4]{M_{k+1}} = pt_{k+1} + n + a + 4 = p(pt_k + n + a + 4) + n + a + 4$$

$$\leq (pt_k + n + a + 4)(p+1) = \frac{p+1}{2}\sqrt[4]{M_k}.$$

From this we have $M_{k+1} \leq (p+1)^4 M_k$ and therefore $M_k \leq (p+1)^{4k} M_0$ where $M_0 = 2^4 (2p+n+a+4)^4$ because $t_0 = 2$. Since the constant β is defined as $\beta = 2p+n+a+4$, we get the following bound

$$(2.6) M_k < \beta^{4k+4}.$$

From this, (2.3) and (2.5) and to complete the iteration process, we set

$$(2.7) t_{k+1} := pt_k + a + 4 \text{ for } t_0 = 2,$$

$$(2.8) s_{k+1} := ps_k + 4k + 4 \text{ for } s_0 = 0,$$

and therefore,

(2.9)
$$\bar{u}(r) \ge \frac{\alpha^{p^{k+1}}}{\beta^{s_{k+1}}} r^{t_{k+1}} \text{ for } r \ge r_{k+1},$$

where $r_{k+1} := 2^{\frac{4}{pt_k + a + 1}} r_k \ge 2^{\sum_{i=1}^4 \frac{1}{pt_k + a + i}} r_k$. By direct calculations on these recursive sequences we get the explicit sequences

$$\begin{array}{rcl} t_k & = & \frac{2p^{k+1} + (a+2)p^k - (a+4)}{p-1}, \\ \\ s_k & = & \frac{4p^{k+1} - 4p(k+1) + 4k}{(p-1)^2}, \\ \\ r_k & = & 2^{\sum_{i=0}^{k-1} \frac{4}{p^{t_i+a+1}}} r_0 < 2^{\sum_{i=0}^{\infty} \frac{4}{p^{t_i+a+1}}} r_0 =: r^* < \infty. \end{array}$$

Set $R := \beta^{\frac{2}{p-1}} M$ where $M = \max\{\alpha^{-1}, m\}$ when m > 1 is large enough to make sure $m\beta^{\frac{2}{p-1}} \ge r^*$. Therefore, $R \ge r^* \ge r_k$ for any k and we have

$$\bar{u}(R) \ge M^{t_k - p^k} \beta^{\frac{2t_k}{p-1} - s_k}.$$

If we take k large enough, e.g. $k \ge \frac{\ln(a+4)-\ln(a+2)}{\ln p}$, then $t_k > p^k$. The fact that M > 1, gives us

$$\bar{u}(R) \ge \beta^{\frac{2t_k}{p-1} - s_k} = \beta^{\frac{2(a+2)p^k + 4k(p-1) + 4p - 2(a+4)}{(p-1)^2}}.$$

Since we have assumed that a+2>0 and $\beta>1$, we get $\bar{u}(R)\to\infty$ as $k\to\infty$. Note that $0< R<\infty$ is independent from k. This finishes the proof.

We now apply Proposition 2.1 to conclude that $-\Delta u \ge 0$ and therefore we can consider equation (1.1) as a special case of the Hénon-Lane-Emden equation.

Lemma 2.2. (L^1 -estimates on B_R) Suppose that u is a nonnegative solution of (1.1) then for any R > 1 we have

$$\int_{B_R} |\Delta u| \le C R^{n - \frac{2p + 2 + a}{p - 1}},$$

where C = C(n, p, a) > 0 is independent from R.

Proof: Set $v = -\Delta u$. From Proposition 2.1 we know that $v \ge 0$. Therefore the pair (u, v) satisfies the following system

(2.10)
$$\begin{cases} -\Delta u = v \text{ in } \mathbb{R}^n, \\ -\Delta v = |x|^a u^p \text{ in } \mathbb{R}^n, \end{cases}$$

that is a particular case of the Hénon-Lane-Emden system. From the estimates provided in [15] as Lemma 2.1 we get the desired result.

Lemma 2.3. (An interpolation inequality on B_R) Let R > 1 and $z \in W^{2,1}(B_{2R})$. Then

$$\int_{B_R \backslash B_{R/2}} |Dz| \leq CR \int_{B_{2R} \backslash B_{R/4}} |\Delta z| + CR^{-1} \int_{B_{2R} \backslash B_{R/4}} |z|,$$

where C = C(n) > 0 is independent from R.

Corollary 2.2. Under the same assumptions as Lemma 2.1. The following estimate holds.

$$\int_{B_R \setminus B_{R/2}} |Du| \le CR^{n - \frac{p+3+a}{p-1}},$$

where C = C(n, p, a) > 0 is independent from R.

Lemma 2.4. $(L^{\tau}$ -estimate on $B_R)$ Let $1 < \tau < \infty$ and $z \in W^{2,\tau}(B_{2R})$. Then,

$$\int_{B_R \setminus B_{R/2}} |D^2 z|^{\tau} \le C \int_{B_{2R} \setminus B_{R/4}} |\Delta z|^{\tau} + C R^{-2\tau} \int_{B_{2R} \setminus B_{R/4}} |z|^{\tau},$$

where $C = C(n, \tau) > 0$ does not depend on R.

Lemma 2.5. (L^2 -estimates on B_R) Suppose that u is a bounded nonnegative solution of (1.1) then for any R > 1 we have

(2.11)
$$\int_{B_R} |\Delta u|^2 \le C \int_{B_{2R}} |x|^a u^{p+1} + CR^{-2} \int_{B_{2R}} |\Delta u| + CR^{-4} \int_{B_{2R} \setminus B_R} u,$$

where C = C(n, p, a) > 0 does not depend on R.

Proof: We proceed in two steps.

Step 1. Multiply the both sides of equation (1.1) with $u\phi^2$ where $\phi \in C_c^{\infty}(\mathbb{R}^n) \cap [0,1]$ is a test function. Then, doing the integration by parts, we get

$$\int_{\mathbb{R}^{n}} |\Delta u|^{2} \phi^{2} = \int_{\mathbb{R}^{n}} |x|^{a} u^{p+1} \phi^{2} - 4 \int_{\mathbb{R}^{n}} \Delta u \nabla u \cdot \nabla \phi \phi - \int_{\mathbb{R}^{n}} u \Delta u \left(2|\nabla \phi|^{2} + 2\phi \Delta \phi \right) \\
\leq \int_{\mathbb{R}^{n}} |x|^{a} u^{p+1} \phi^{2} + \delta \int_{\mathbb{R}^{n}} |\Delta u|^{2} \phi^{2} + C(\delta) \int_{\mathbb{R}^{n}} |\nabla u|^{2} |\nabla \phi|^{2} \\
+ C \int_{\mathbb{R}^{n}} |\Delta u| \left(|\nabla \phi|^{2} + |\Delta \phi| \right),$$

for some constant C > 0. Here, we have used the Cauchy's inequality for $0 < \delta < 1$. Therefore, if we set ϕ to be the standard test function that is $\phi = 1$ in B_R and $\phi = 0$ in $\mathbb{R}^n \setminus B_{2R}$ when $||D_x^i \phi||_{L^{\infty}(B_{2R} \setminus B_R)} \leq CR^{-i}$ for i = 1, 2, then we get

$$(2.12) \ \int_{B_R} |\Delta u|^2 \leq \int_{B_{2R}} |x|^a u^{p+1} + C R^{-2} \int_{B_{2R} \backslash B_R} |\nabla u|^2 + C R^{-2} \int_{B_{2R} \backslash B_R} |\Delta u|,$$

where C = C(n, p, a) > 0 does not depend on R.

Step 2. Multiply the both sides of $-\Delta u = v$ with $u\phi^2$ where ϕ is the same test function as Step 1. Again doing integration by parts we get

$$\int_{\mathbb{R}^n} |\nabla u|^2 \phi^2 = \int_{\mathbb{R}^n} uv\phi^2 - 2 \int_{\mathbb{R}^n} u\nabla u \cdot \nabla \phi \phi
\leq \int_{\mathbb{R}^n} uv\phi^2 + \delta \int_{\mathbb{R}^n} |\nabla u|^2 \phi^2 + C(\delta) \int_{\mathbb{R}^n} |\nabla \phi|^2 u^2,$$

where we have also used the Cauchy's inequality for $0 < \delta < 1$. So,

(2.13)
$$\int_{B_R} |\nabla u|^2 \le C \int_{B_{2R}} |\Delta u| + CR^{-2} \int_{B_{2R} \setminus B_R} u,$$

where we have used the boundedness of u. From (2.12) and (2.13) we get

(2.14)
$$\int_{B_R} |\Delta u|^2 \le \int_{B_{2R}} |x|^a u^{p+1} + CR^{-2} \int_{B_{2R}} |\Delta u| + CR^{-4} \int_{B_{2R} \setminus B_R} u.$$

This completes the proof.

We now apply Lemma 2.1, Lemma 2.5 and Corollary 2.1 to get the following.

Corollary 2.3. Suppose that the assumptions of Lemma 2.1 hold. Moreover, let u be bounded then

(2.15)
$$\int_{B_{P}} |\Delta u|^{2} \le CR^{n - \frac{4p + a}{p - 1}},$$

where C = C(n, p, a) > 0 is independent from R.

Lemma 2.6. (Sobolev inequalities on the sphere S^{n-1}) Let $n \geq 2$, integer $i \geq 1$ and $1 < t < \tau \leq \infty$. For $z \in W^{i,t}(S^{n-1})$, the following estimate holds

$$||z||_{L^{\tau}(S^{n-1})} \le C||D_{\theta}^{i}z||_{L^{t}(S^{n-1})} + C||z||_{L^{1}(S^{n-1})},$$

where

$$\left\{ \begin{array}{l} \frac{1}{\tau} = \frac{1}{t} - \frac{i}{n-1}, & if \ it+1 < n, \\ \tau = \infty, & if \ it+1 > n, \end{array} \right.$$

and $C = C(i, t, n, \tau) > 0$

3. Developing the Iteration argument

In this section, we develop a counterpart of the Moser iteration argument [22] for solutions of (1.1). We define a sequence of functions $(w_k)_{k=-1}$ of the form

$$w_k := \Delta u + \alpha_k |\nabla u|^2 (u + \epsilon)^{-1} + \beta_k |x|^{\frac{a}{2}} u^{\frac{p+1}{2}}$$

where α_k and β_k are certain nondecreasing sequences of nonnegative numbers where $\alpha_{-1} = \beta_{-1} = 0$.

Assuming that $w_k \leq 0$, that is essentially a lower bound on the negative Laplacian operator, holds we construct a differential inequality for w_{k+1} where $\alpha_{k+1} \geq \alpha_k$ and $\beta_{k+1} \geq \beta_k$. Then, applying certain maximum principle type arguments, we show that $w_{k+1} \leq 0$. Note that $w_{k+1} \leq 0$ is stronger than $w_k \leq 0$, because it forces a stronger lower bound on the negative of Laplacian operator.

We start with proving that w_{-1} , which is the Laplacian operator of u, is non-positive, see Proposition 2.1. Then, using this fact and applying (1.9) and (1.10) when q = 1 and b = 0, we get the following inequality for nonnegative solutions of the fourth order Hénon equation (1.1)

(3.1)
$$-\Delta u \ge \sqrt{\frac{2}{p+1}} |x|^{\frac{a}{2}} u^{\frac{p+1}{2}} \text{ in } \mathbb{R}^n,$$

where $0 \le a \le (n-2)(p-1)$. Inequality (3.1) is the first step of the iteration argument meaning that $w_0 \le 0$ for $\alpha_0 = 0$ and $\beta_0 = \sqrt{\frac{2}{p+1}}$.

We now perform the iteration argument.

Proposition 3.1. Let u be a positive classical solution of (1.1). Suppose that $(\alpha_k)_{k=0}$ and $(\beta_k)_{k=0}$ are sequences of numbers. Define the following sequence of functions

(3.2)
$$w_k := \Delta u + \alpha_k |\nabla u|^2 (u + \epsilon)^{-1} + \beta_k |x|^{\frac{a}{2}} u^{\frac{p+1}{2}},$$

where $\epsilon = \epsilon(k)$ is a positive constant. Suppose that $w_k \leq 0$, then w_{k+1} satisfies the following differential inequality

$$(3.3) \qquad \Delta w_{k+1} - 2\alpha_{k+1}(u+\epsilon)^{-1}\nabla u \cdot \nabla w_{k+1}$$

$$+\alpha_{k+1}w_{k+1}(u+\epsilon)^{-2}|\nabla u|^2 - \frac{\beta_{k+1}(p+1)}{2}u^{\frac{p-1}{2}}|x|^{\frac{a}{2}}w_{k+1}$$

$$\geq I_{\epsilon,\beta_k}^{(1)}|x|^a u^p + \alpha_{k+1}I_{\alpha_k}^{(2)}|\nabla u|^4(u+\epsilon)^{-3} + I_{a,\alpha_k,\beta_k}^{(4)}|x|^{a-2}u^{\frac{p+1}{2}}$$

$$+I_{\epsilon,\alpha_k,\beta_k}^{(3)}|x|^a u^{\frac{p+1}{2}} \left| \frac{\nabla u}{u} + \frac{a\beta_{k+1}\left(\frac{p+1}{2} - \alpha_{k+1}\frac{u}{u+\epsilon}\right)}{2I_{\epsilon,\alpha_k,\beta_k}^{(3)}} \frac{x}{|x|^2} \right|^2,$$

where

$$I_{\epsilon,\alpha_{k},\beta_{k}}^{(1)} := 1 - \frac{p+1}{2}\beta_{k+1}^{2} + \frac{2}{n}\alpha_{k+1}\beta_{k}^{2}\frac{u}{u+\epsilon},$$

$$I_{\alpha_{k}}^{(2)} := \frac{2}{n}(\alpha_{k+1} + \alpha_{k} + 1)^{2} - 2\alpha_{k+1}(\alpha_{k+1} + 1) + \alpha_{k+1},$$

$$I_{\epsilon,\alpha_{k},\beta_{k}}^{(3)} := \frac{4}{n}\alpha_{k+1}\beta_{k}(\alpha_{k+1} + \alpha_{k} + 1)\frac{u^{2}}{(u+\epsilon)^{2}} + \beta_{k+1}\alpha_{k+1}\frac{u^{2}}{(u+\epsilon)^{2}}$$

$$-(p+1)\beta_{k+1}\alpha_{k+1}\frac{u}{(u+\epsilon)} + \frac{p+1}{2}\left(\frac{p-1}{2} - \alpha_{k+1}\frac{u}{(u+\epsilon)}\right)\beta_{k+1},$$

$$I_{a,\epsilon,\alpha_{k},\beta_{k}}^{(4)} := \frac{a}{2}\beta_{k+1}(n+\frac{a}{2}-2) - \frac{a^{2}\beta_{k+1}^{2}\left(\frac{p+1}{2} - \alpha_{k+1}\frac{u}{u+\epsilon}\right)^{2}}{4I_{\epsilon,\alpha_{k},\beta_{k}}^{(3)}}.$$

Proof: For the sake of simplicity in calculations, set $b := \frac{a}{2}$ and $q := \frac{p+1}{2}$. From (3.2) the function w_{k+1} is defined as

$$w_{k+1} := \Delta u + \alpha_{k+1} |\nabla u|^2 (u + \epsilon)^{-1} + \beta_{k+1} |x|^b u^q.$$

Taking Laplacian of w_{k+1} and using equation (1.1) we get

(3.4)
$$\Delta w_{k+1} = \Delta^2 u + \alpha_{k+1} \Delta (|\nabla u|^2 (u+\epsilon)^{-1}) + \beta_{k+1} \Delta (|x|^b u^q)$$
$$= |x|^a u^p + I + J,$$

where $I := \alpha_{k+1} \Delta(|\nabla u|^2 (u+\epsilon)^{-1})$ and $J := \beta_{k+1} \Delta(|x|^b u^q)$. In what follows, we simplify I and J as well as finding lower bounds for these terms. We start with Jthat is

$$\begin{split} \frac{J}{\beta_{k+1}} &= & \Delta(|x|^b u^q) = \Delta|x|^b u^q + \Delta u^q |x|^b + 2\nabla |x|^b \cdot \nabla u^q \\ &= & b(n+b-2)|x|^{b-2} u^q + q(q-1)|x|^b u^{q-2} |\nabla u|^2 \\ &+ q|x|^b u^{q-1} \Delta u + 2bq|x|^{b-2} u^{q-1} \nabla u \cdot x. \end{split}$$

From the definition of w_{k+1} , we have

(3.5)
$$\Delta u = w_{k+1} - \alpha_{k+1} |\nabla u|^2 (u+\epsilon)^{-1} - \beta_{k+1} |x|^b u^q.$$

Substitute this into the last equation to simplify J as

(3.6)
$$\frac{J}{\beta_{k+1}} = qu^{q-1}|x|^b w_{k+1} - q\beta_{k+1}u^{2q-1}|x|^{2b} + \left(q(q-1) - q\alpha_{k+1}\frac{u}{u+\epsilon}\right)|x|^b u^{q-2}|\nabla u|^2 + b(n+b-2)|x|^{b-2}u^q + 2bq|x|^{b-2}u^{q-1}\nabla u \cdot x.$$

We now simplify I as what follows,

$$\frac{I}{\alpha_{k+1}} = \Delta(|\nabla u|^2 (u+\epsilon)^{-1}) = \sum_{i,j} \partial_{jj} (u_i^2 (u+\epsilon)^{-1})$$

$$= 2(u+\epsilon)^{-1} \sum_{i,j} (\partial_{ij} u)^2 + 2(u+\epsilon)^{-1} \nabla u \cdot \nabla \Delta u - 4(u+\epsilon)^{-2} \sum_{i,j} \partial_i u \partial_j u \partial_{ij} u$$

$$-|\nabla u|^2 (u+\epsilon)^{-2} \Delta u + 2|\nabla u|^4 (u+\epsilon)^{-3}.$$

Again substituting (3.5) into the term $2(u+\epsilon)^{-1}\nabla u\cdot\nabla\Delta u$ appeared above, we get

$$\frac{I}{\alpha_{k+1}} = 2(u+\epsilon)^{-1} \sum_{i,j} (\partial_{ij}u)^2 - 4(u+\epsilon)^{-2} \sum_{i,j} \partial_i u \partial_j u \partial_{ij} u
+ 2|\nabla u|^4 (u+\epsilon)^{-3} - |\nabla u|^2 (u+\epsilon)^{-3} \Delta u
+ 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1} - 2\alpha_{k+1} (u+\epsilon)^{-1} \nabla u \cdot (|\nabla u|^2 (u+\epsilon)^{-1})
- 2\beta_{k+1} (u+\epsilon)^{-1} \nabla u \cdot \nabla (|x|^b u^q).$$

Then, collecting the similar terms we obtain

$$\frac{I}{\alpha_{k+1}} - 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1} = 2(u+\epsilon)^{-1} \sum_{i,j} (\partial_{ij} u)^{2}
-4(\alpha_{k+1} + 1)(u+\epsilon)^{-2} \sum_{i,j} \partial_{i} u \partial_{j} u \partial_{ij} u
+2(\alpha_{k+1} + 1) |\nabla u|^{4} (u+\epsilon)^{-3} - |\nabla u|^{2} (u+\epsilon)^{-2} \Delta u
-2\beta_{k+1} b |x|^{b-2} (u+\epsilon)^{-1} u^{q} \nabla u \cdot x
-2\beta_{k+1} q |x|^{b} u^{q-1} (u+\epsilon)^{-1} |\nabla u|^{2}.$$

Completing the square we get

(3.7)
$$\frac{I}{\alpha_{k+1}} - 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1}$$

$$= 2(u+\epsilon)^{-1} \sum_{i,j} \left(\partial_{ij} u - (\alpha_{k+1} + 1)(u+\epsilon)^{-1} \partial_i u \partial_j u \right)^2$$

$$-2\alpha_{k+1} (\alpha_{k+1} + 1) |\nabla u|^4 (u+\epsilon)^{-3} - |\nabla u|^2 (u+\epsilon)^{-2} \Delta u$$

$$-2\beta_{k+1} b|x|^{b-2} (u+\epsilon)^{-1} u^q \nabla u \cdot x - 2\beta_{k+1} q|x|^b u^{q-1} (u+\epsilon)^{-1} |\nabla u|^2.$$

Note that for any $n \times n$ matrix $A = (a_{i,j})$ the Hilbert-Schmidt norm is defined by $||A||_2 = \sqrt{\sum_{i,j} |a_{i,j}|^2} = \sqrt{\operatorname{trace}(AA^*)}$, where A^* denotes the conjugate transpose of A. From the Cauchy-Schwarz' inequality, the following inequality holds,

(3.8)
$$|\operatorname{trace} A|^2 = |(A, I)|^2 \le ||A||_2^2 ||I||_2^2 = n \sum_{i,j} |a_{i,j}|^2.$$

Set $a_{i,j} := \partial_{i,j} u - (\alpha_{k+1} + 1)(u + \epsilon)^{-1} \partial_i u \partial_j u$ in (3.8) to get

$$\sum_{i,j}^{n} \left(\partial_{ij} u - (\alpha_{k+1} + 1)(u + \epsilon)^{-1} \partial_i u \partial_j u \right)^2 \ge \frac{1}{n} \left(\Delta u - (\alpha_{k+1} + 1)(u + \epsilon)^{-1} |\nabla u|^2 \right)^2.$$

From this lower bound for the Hessian and (3.7), we get

(3.9)
$$\frac{I}{\alpha_{k+1}} - 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1}$$

$$\geq \frac{2}{n} (u+\epsilon)^{-1} \left(\Delta u - (\alpha_{k+1}+1)(u+\epsilon)^{-1} |\nabla u|^2 \right)^2$$

$$-2\alpha_{k+1} (\alpha_{k+1}+1) |\nabla u|^4 (u+\epsilon)^{-3} - |\nabla u|^2 (u+\epsilon)^{-2} \Delta u + T_k,$$

where

$$T_k := -2\beta_{k+1}b|x|^{b-2}(u+\epsilon)^{-1}u^q\nabla u \cdot x - 2\beta_{k+1}q|x|^bu^{q-1}(u+\epsilon)^{-1}|\nabla u|^2.$$

Note also that from the assumption $w_k \leq 0$ we have this upper bound on the Laplacian operator, $\Delta u \leq -\alpha_k |\nabla u|^2 (u+\epsilon)^{-1} - \beta_k |x|^b u^q$. Elementary calculations show that if $t \leq t_* \leq 0$ and $s \geq 0$ then $(t-s)^2 \geq t_*^2 - 2t_*s + s^2$. Set the parameters as $t = \Delta u$, $t_* = -\alpha_k |\nabla u|^2 (u + \epsilon)^{-1} - \beta_k |x|^b u^q$ and $s = (\alpha_{k+1} + 1)(u + \epsilon)^{-1} |\nabla u|^2$ to get the following lower bound on the square term that appears in (3.9),

$$(3.10) \quad \left(\Delta u - (\alpha_{k+1} + 1)(u + \epsilon)^{-1} |\nabla u|^2\right)^2 \ge \left(\alpha_k |\nabla u|^2 (u + \epsilon)^{-1} + \beta_k |x|^b u^q\right)^2 + 2\left(\alpha_k |\nabla u|^2 (u + \epsilon)^{-1} + \beta_k |x|^b u^q\right) (\alpha_{k+1} + 1)(u + \epsilon)^{-1} |\nabla u|^2 + (\alpha_{k+1} + 1)^2 (u + \epsilon)^{-2} |\nabla u|^4.$$

Substitute (3.5) into the term $-|\nabla u|^2(u+\epsilon)^{-2}\Delta u$ that appears in (3.9) to eliminate the Laplacian operator. Then, apply inequality (3.10) to simplify (3.9) as

$$\begin{split} &\frac{I}{\alpha_{k+1}} - 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1} \geq \frac{2}{n} (u+\epsilon)^{-1} \{ (\alpha_{k+1} + \alpha_k + 1)^2 |\nabla u|^4 (u+\epsilon)^{-2} \\ &+ \beta_k^2 |x|^{2b} u^{2q} + 2\beta_k (\alpha_{k+1} + \alpha_k + 1) |x|^b u^q (u+\epsilon)^{-1} |\nabla u|^2 \} - w_{k+1} (u+\epsilon)^{-2} |\nabla u|^2 \\ &- \alpha_{k+1} (2\alpha_{k+1} + 1) |\nabla u|^4 (u+\epsilon)^{-3} + \beta_{k+1} |x|^b u^q (u+\epsilon)^{-2} |\nabla u|^2 + T_k. \end{split}$$

Collecting similar terms and using the value of T_k , we end up with

$$\frac{I}{\alpha_{k+1}} - 2(u+\epsilon)^{-1} \nabla u \cdot \nabla w_{k+1} + w_{k+1}(u+\epsilon)^{-2} |\nabla u|^{2}
\geq \frac{2}{n} \beta_{k}^{2} |x|^{2b} u^{2q} (u+\epsilon)^{-1} + I_{\alpha_{k}}^{(2)} |\nabla u|^{4} (u+\epsilon)^{-3} + S_{\epsilon,\alpha_{k},\beta_{k}} |\nabla u|^{2} u^{q-2} |x|^{b}
-2\beta_{k+1} b |x|^{b-2} (u+\epsilon)^{-1} u^{q} \nabla u \cdot x,$$

where

$$I_{\alpha_k}^{(2)} := \frac{2}{n} (\alpha_{k+1} + \alpha_k + 1)^2 - 2\alpha_{k+1}(\alpha_{k+1} + 1) + \alpha_{k+1},$$

$$S_{\epsilon,\alpha_k,\beta_k} := \frac{4}{n} \beta_k (\alpha_{k+1} + \alpha_k + 1) \frac{u^2}{(u+\epsilon)^2} + \beta_{k+1} \frac{u^2}{(u+\epsilon)^2} - 2\beta_{k+1} q \frac{u}{u+\epsilon}.$$

Therefore, the following lower bound for I holds,

$$(3.11) I \geq 2\alpha_{k+1}(u+\epsilon)^{-1}\nabla u \cdot \nabla w_{k+1} -\alpha_{k+1}w_{k+1}(u+\epsilon)^{-2}|\nabla u|^{2} + \frac{2}{n}\alpha_{k+1}\beta_{k}^{2}|x|^{2b}u^{2q}(u+\epsilon)^{-1} + I_{\alpha_{k}}|\nabla u|^{4}(u+\epsilon)^{-3} + S_{\epsilon,\alpha_{k},\beta_{k}}|\nabla u|^{2}u^{q-2}|x|^{b} - 2\beta_{k+1}b|x|^{b-2}(u+\epsilon)^{-1}u^{q}\nabla u \cdot x.$$

Finally, applying this lower bound for I and the lower bound given for J in (3.6), from (3.3) we get

$$\Delta w_{k+1} - 2\alpha_{k+1}(u+\epsilon)^{-1}\nabla u \cdot \nabla w_{k+1} + \alpha_{k+1}(u+\epsilon)^{-2}|\nabla u|^{2}w_{k+1} - \beta_{k+1}qu^{q-1}|x|^{b}w_{k+1}$$

$$\geq |x|^{a}u^{p}\left(1 - q\beta_{k+1}^{2} + \frac{2}{n}\alpha_{k+1}\beta_{k}^{2}\frac{u}{u+\epsilon}\right) + \alpha_{k+1}I_{\alpha_{k}}^{(2)}|\nabla u|^{4}(u+\epsilon)^{-3}$$

$$+ \left(\alpha_{k+1}S_{\epsilon,\alpha_{k},\beta_{k}} + \left(q(q-1) - \alpha_{k+1}q\frac{u}{u+\epsilon}\right)\beta_{k+1}\right)|\nabla u|^{2}u^{q-2}|x|^{b}$$

$$+2b\beta_{k+1}\left(q - \alpha_{k+1}\frac{u}{u+\epsilon}\right)|x|^{b-2}u^{q-1}\nabla u \cdot x + b\beta_{k+1}(n+b-2)|x|^{b-2}u^{q}.$$

Completing the square finishes the proof.

4. Proof of Theorem 1.3 via Iteration Arguments

To apply the iteration argument, we need to develop a maximum principle argument for the following equation (4.1)

$$\Delta w - 2\alpha(u+\epsilon)^{-1}\nabla u \cdot \nabla w + \alpha w(u+\epsilon)^{-2}|\nabla u|^2 - \frac{\beta(p+1)}{2}|x|^{\frac{\alpha}{2}}u^{\frac{p-1}{2}}w = f(x) \ge 0 \quad \mathbb{R}^n$$

that appears in Proposition 3.1, where α, β are positive constants, u is a solution of (1.1) and $w, f \in C^{\infty}(\mathbb{R}^n)$.

Lemma 4.1. Suppose that w is a solution of the differential inequality (4.1) where u is a solution of (1.1) and

(4.2)
$$w = \Delta u + \alpha (u + \epsilon)^{-1} |\nabla u|^2 + \beta |x|^{\frac{\alpha}{2}} u^{\frac{p+1}{2}}$$

for positive constants ϵ , α and β . Then, assuming that $p+1>2\alpha$ the following holds

(4.3)
$$\Delta \tilde{w} \ge 0 \quad on \ \{w \ge 0\} \subset \mathbb{R}^n$$

where $\tilde{w} = (u + \epsilon)^t w$ for $t = -\alpha$.

Proof: Straightforward calculations show that

$$\Delta \tilde{w} = (u+\epsilon)^t \Delta w + 2t(u+\epsilon)^{t-1} \nabla u \cdot \nabla w + t(u+\epsilon)^{t-1} w \Delta u + t(t-1)w(u+\epsilon)^{t-2} |\nabla u|^2$$

$$\Delta \tilde{w} = (u+\epsilon)^t \left(\Delta w + 2t(u+\epsilon)^{-1} \nabla u \cdot \nabla w - tw(u+\epsilon)^{-2} |\nabla u|^2 - \frac{\beta(p+1)}{2} |x|^{\frac{a}{2}} u^{\frac{p-1}{2}} w \right) + \frac{\beta(p+1)}{2} |x|^{\frac{a}{2}} u^{\frac{p-1}{2}} (u+\epsilon)^t w + tw(u+\epsilon)^{t-2} |\nabla u|^2 + t(u+\epsilon)^{t-1} w \Delta u + t(t-1)w(u+\epsilon)^{t-2} |\nabla u|^2.$$

From the fact that $t = -\alpha$ and w satisfies (4.1) we get

$$\Delta \tilde{w} \ge \frac{\beta(p+1)}{2} |x|^{\frac{a}{2}} u^{\frac{p-1}{2}} (u+\epsilon)^t w + t(u+\epsilon)^{t-1} w \Delta u + t^2 w (u+\epsilon)^{t-1} \frac{|\nabla u|^2}{u+\epsilon}$$

Note that we can eliminate the gradient term using (4.2) that is $\alpha(u+\epsilon)^{-1}|\nabla u|^2 = w - \Delta u - \beta|x|^{\frac{\alpha}{2}}u^{\frac{p+1}{2}}$. Therefore, after collecting the similar terms we get

$$\Delta \tilde{w} \geq \frac{t^2}{\alpha} w^2 (u+\epsilon)^{t-1} + (u+\epsilon)^{t-1} wt \left(1 - \frac{t}{\alpha}\right) \Delta u$$
$$+\beta (u+\epsilon)^{t-1} |x|^{\frac{\alpha}{2}} u^{\frac{p-1}{2}} w \left(\frac{(p+1)\epsilon}{2} + u \left(\frac{p+1}{2} - \frac{t^2}{\alpha}\right)\right)$$
$$=: R_1 + R_2 + R_3.$$

We claim that the above three terms R_1, R_2, R_3 are nonnegative when $w \geq 0$. From the fact that $\alpha > 0$ one can see that R_1 is nonnegative. From the definition of $t = -\alpha < 0$ we have $t(1 - \frac{t}{\alpha}) = -2\alpha < 0$. This together with Proposition 2.1, that is $\Delta u \leq 0$, confirms that R_2 is nonnegative. Positivity of R_3 is an immediate consequence of the assumptions. In other words, note that β is positive and $\frac{p+1}{2} - \frac{t^2}{\alpha} = \frac{p+1}{2} - \alpha$ is also positive based on the assumptions. This finishes the proof.

We now apply Lemma 4.1 to show that w that is a solution of (4.1) is negative.

Lemma 4.2. Suppose that \tilde{w} and w are the same as Lemma 4.1. Let u be a bounded solution of (1.1) then $w \leq 0$.

Proof: The methods and ideas that we apply in the proof are motivated by the ones provided by Souplet in [28]. Multiply (4.3) with \tilde{w}_{+}^{s} where s > 0 is a parameter that will be determined later. Then, integration by parts over B_{R} gives us

$$(4.4) 0 \le \int_{B_R} \Delta \tilde{w} \tilde{w}_+^s = -s \int_{B_R} |\nabla \tilde{w}_+|^2 \tilde{w}_+^{s-1} + R^{n-1} \int_{S^{n-1}} \tilde{w}_r \tilde{w}_+^s.$$

Therefore,

(4.5)
$$\int_{B_R} |\nabla \tilde{w}_+|^2 \tilde{w}_+^{s-1} \le \frac{1}{s(s+1)} R^{n-1} \int_{S^{n-1}} (\tilde{w}_+^{s+1})_r = C(s) R^{n-1} I'(R),$$

where

$$I(R) := \int_{S^{n-1}} \tilde{w}_{+}^{s+1} = \int_{S^{n-1}} (u+\epsilon)^{-(s+1)\alpha} w_{+}^{s+1}$$

and C(s) is a constant independent from R. Note that w given as $w = \Delta u + \alpha |\nabla u|^2 (u+\epsilon)^{-1} + \beta |x|^{\frac{\alpha}{2}} u^{\frac{p+1}{2}}$ satisfies $w \geq 0$ if and only if $-\Delta u \leq \alpha |\nabla u|^2 (u+\epsilon)^{-1} + \beta |x|^{\frac{\alpha}{2}} u^{\frac{p+1}{2}}$. Therefore,

$$(4.6) w_+^{s+1} \le C|\nabla u|^{2(s+1)}(u+\epsilon)^{-(s+1)} + C|x|^{(s+1)a/2}u^{(s+1)(p+1)/2}$$

where $C = C(\alpha, \beta, s)$. Applying this upper bound for w_+ , we can get an upper bound for I(R) as following.

$$(4.7) I(R) \leq C \int_{S^{n-1}} (u+\epsilon)^{-(s+1)(\alpha+1)} |\nabla u|^{2(s+1)}$$

$$+ CR^{\frac{s+1}{2}a} \int_{S^{n-1}} (u+\epsilon)^{-\alpha(s+1)} u^{(s+1)(p+1)/2}$$

$$\leq C(\epsilon) \int_{S^{n-1}} |\nabla u|^{2(s+1)} + C(\epsilon) R^{\frac{s+1}{2}a} \int_{S^{n-1}} u^{\frac{s+1}{2}(p+1)}$$

$$=: C(\epsilon) (I_1(R) + I_2(R)).$$

In what follows we show that there is a sequence R such that the two terms $I_1(R)$ and $I_2(R)$ decay to zero, for a fixed ϵ . We start with $I_2(R)$ that includes an integral of a positive power of u over the sphere. Due to the boundedness assumption on u, it is straightforward to relate this term to L^p estimates of u over the sphere. As a matter of fact, if (s+1)(p+1) > 2p then from the boundedness of u we have

(4.8)
$$\int_{S^{n-1}} u^{\frac{s+1}{2}(p+1)} \le C(n) ||u||_{L^p(S^{n-1})}^p$$

and for the case $(s+1)(p+1) \leq 2p$ we can perform the Hölder's inequality to get

(4.9)
$$\int_{S^{n-1}} u^{\frac{s+1}{2}(p+1)} \le C(n,p) ||u||_{L^p(S^{n-1})}^{\frac{(p+1)(s+1)}{2}}.$$

So, to prove a decay estimate for $I_2(R)$ we need to construct a decay estimate for $||u||_{L^p(S^{n-1})}$. On the other hand, we apply Lemma 2.6 to get an upper bound for the first term in (4.7) that is $I_1(R)$. In fact, from Lemma 2.6 where i=1, $\tau=2(s+1)$ and t=2 we have

$$(4.10) ||D_x u||_{L^{2(s+1)}(S^{n-1})} \leq C||D_\theta D_x u||_{L^2(S^{n-1})} + C||D_x u||_{L^1(S^{n-1})}$$

$$\leq CR||D_x^2 u||_{L^2(S^{n-1})} + C||D_x u||_{L^1(S^{n-1})}$$

for $s = \frac{2}{n-3}$. In order to get a decay estimate for $I_1(R)$, we need decay estimates for the two terms in the right-hand side of (4.10) which are $||D_x^2 u||_{L^2(S^{n-1})}$ and $||D_x u||_{L^1(S^{n-1})}$.

We now apply the elliptic estimates given in Section 2 to provide decay estimates for $||u||_{L^p(S^{n-1})}$, $||D_x u||_{L^1(S^{n-1})}$ and $||D_x^2 u||_{L^2(S^{n-1})}$. To do so we first find appropriate upper bounds for these terms on the ball of radius R. Then we use certain comparing measure arguments to construct decay estimates over the sphere. So, from Lemma 2.4 when $\tau = 2$, we get

$$(4.11) \quad \int_{R/2}^{R} ||D_x^2 u||_{L^2(S^{n-1})}^2 r^{n-1} dr \le C \int_{B_{2R} \backslash B_{R/4}} |\Delta u|^2 + CR^{-4} \int_{B_{2R} \backslash B_{R/4}} u^2.$$

We now apply Corollary 2.3 and Corollary 2.1 to get a decay estimate for the right-hand side of (4.11) that is

$$R^{-4} \int_{B_{2R} \backslash B_{R/4}} u^2 \leq CR^{-4} \int_{B_{2R} \backslash B_{R/4}} u \leq CR^{-4} R^{n - \frac{a+4}{p-1}} = CR^{n - \frac{a+4p}{p-1}},$$

$$\int_{B_{2R} \backslash B_{R/4}} |\Delta u|^2 \leq CR^{n - \frac{a+4p}{p-1}},$$

where C is independent from R. From this and (4.11) we obtain the following desired decay estimate on the Hessian operator of u

(4.12)
$$\int_{R/2}^{R} ||D_x^2 u||_{L^2(S^{n-1})}^2 r^{n-1} dr \le C R^{n - \frac{4p+a}{p-1}}.$$

Similarly, from Corollary 2.2 and Lemma 2.1 we have

(4.13)
$$\int_{R/2}^{R} ||D_x u||_{L^1(S^{n-1})} r^{n-1} dr \leq CR^{n - \frac{p+3+a}{p-1}},$$

(4.14)
$$\int_{R/2}^{R} ||u||_{L^{p}(S^{n-1})}^{p} r^{n-1} dr \leq CR^{n-\frac{a+4}{p-1}p}.$$

Now let's define the following sets. These sets are meant to facilitate our arguments towards construction of decay estimates for $||u||_{L^p(S^{n-1})}$, $||D_x u||_{L^1(S^{n-1})}$ and $||D_x^2 u||_{L^2(S^{n-1})}$. For a large number M, that will be determined later, define

$$\Gamma_{1}(R) := \left\{ r \in (R/2, R); \ ||u||_{L^{p}(S^{n-1})}^{p} > MR^{-\frac{a+4}{p-1}p} \right\},
\Gamma_{2}(R) := \left\{ r \in (R/2, R); \ ||D_{x}u||_{L^{1}(S^{n-1})} > MR^{-\frac{p+3+a}{p-1}} \right\},
\Gamma_{3}(R) := \left\{ r \in (R/2, R); \ ||D_{x}^{2}u||_{L^{2}(S^{n-1})}^{2} > MR^{-\frac{a+4p}{p-1}} \right\}.$$

We claim that $|\Gamma_i(R)| \le R/4$ for $1 \le i \le 3$. Using (4.12), we get

$$C \geq R^{-n+\frac{a+4p}{p-1}} \int_{R/2}^{R} ||D_x^2 u||_{L^2(S^{n-1})}^2 r^{n-1} dr$$

$$\geq NR^{-n+\frac{a+4p}{p-1}} R^{n-1} \int_{R/2}^{R} ||D_x^2 u||_{L^2(S^{n-1})}^2 dr$$

$$\geq NMR^{-n+\frac{a+4p}{p-1}} R^{n-1} \int_{|\Gamma_3(R)|} R^{-\frac{a+4p}{p-1}} dr$$

$$\geq NMR^{-n+\frac{a+4p}{p-1}} R^{n-1} |\Gamma_3(R)| R^{-\frac{a+4p}{p-1}}$$

$$= NM|\Gamma_3(R)| R^{-1},$$

where $N=(1/2)^{n-1}$. Therefore, $|\Gamma_3(R)|\leq \frac{C}{NM}R$. Now choosing M to be large enough that is $M > \frac{4C}{N}$, we get $|\Gamma_3(R)| \leq R/4$. Similarly, applying (4.13) and (4.14), one can show that $|\Gamma_i(R)| \leq R/4$ for $1 \leq i \leq 2$. Hence, $|\Gamma_i(R)| \leq R/4$ for $1 \le i \le 3$ while $\Gamma_i(R) \subset (R/2, R)$. So, we can find a sequence \tilde{R} such that

(4.15)
$$\tilde{R} \in (R/2, R) \setminus \bigcup_{i=1}^{i=3} \Gamma_i(R) \neq \phi.$$

Therefore, for the sequence \hat{R} , we obtain

$$(4.16) ||u||_{L^{p}(S^{n-1})}^{p} \leq MR^{-\frac{a+4}{p-1}p},$$

$$(4.17) ||D_x u||_{L^1(S^{n-1})} \le MR^{-\frac{p+3+a}{p-1}}$$

$$(4.18) ||D_x^2 u||_{L^2(S^{n-1})}^2 \le M R^{-\frac{a+4p}{p-1}}.$$

Substituting (4.16) into (4.8) and (4.9) we get the following decay estimate on $I_2(R)$ that is

$$(4.19) I_{2}(R) \leq C\chi\{(s+1)(p+1) > 2p\}R^{\frac{s+1}{2}a - \frac{a+4}{p-1}p}$$

$$+C\chi\{(s+1)(p+1) \leq 2p\}R^{\frac{s+1}{2}a - \frac{a+4}{p-1}(p+1)\frac{s+1}{2}}$$

$$= C\chi\{(s+1)(p+1) > 2p\}R^{-\eta_{1}}$$

$$+C\chi\{(s+1)(p+1) > 2p\}R^{-\eta_{2}},$$

where χ is the characteristic function, $\eta_1 := a\left(\frac{p}{p-1} - \frac{s+1}{2}\right) + \frac{4p}{p-1} > 0$ and $\eta_2 := \frac{s+1}{p+1}(ap+2(p+1)) > 0$. Note that we have used the fact that $\frac{p}{p-1} - \frac{s+1}{2} > 0$ because $0 < s = \frac{2}{n-3} \le 1$ when $n \ge 5$. On the other hand, substituting (4.17) and (4.18) into the Sobolev embedding (4.10) we get

$$(4.20) ||D_x u||_{L^{2(s+1)}(S^{n-1})} \le CR^{1-\frac{a+4p}{p-1}} + CR^{-\frac{p+3+a}{p-1}} = 2CR^{-\frac{p+3+a}{p-1}}.$$

From this and the definition of $I_1(R)$ we end up with the following decay estimate on $I_1(R)$ that is

$$(4.21) I_1(R) = \int_{S^{n-1}} |\nabla u|^{2(s+1)} \le CR^{-\frac{2(p+3+a)(s+1)}{p-1}} = CR^{-\eta_3},$$

where $\eta_3 := \frac{2(p+3+a)(s+1)}{p-1} > 0$. Finally from (4.21) and (4.19) we observe that

$$I(R) \le CR^{-\eta}$$
 for all $R > 1$,

where $\eta := \min\{\eta_1, \eta_2, \eta_3\} > 0$. So, $I(R) \to 0$ as $R \to \infty$. Note that as $R \to \infty$ then $\tilde{R} \to \infty$. Since I(R) is a positive function and converges to zero, there is a sequence such that the functional I'(R) is nonpositive. Therefore, (4.5) yields

(4.22)
$$\int_{B_R} |\nabla \tilde{w}_+|^2 \tilde{w}_+^{s-1} \le 0.$$

Hence, \tilde{w}_+ has to be a constant. From continuity of \tilde{w} , we have $\tilde{w} \equiv C$. Note that the constant C cannot be strictly positive. So, $\tilde{w}_+ = 0$ and therefore $w_+ = 0$. This finishes the proof.

Note that Lemma 4.1 and lemma 4.2 imply an iteration argument for the following sequence of functions when $k \ge -1$

(4.23)
$$w_k = \Delta u + \alpha_k (u + \epsilon)^{-1} |\nabla u|^2 + \beta_k |x|^{\frac{a}{2}} u^{\frac{p+1}{2}}$$

as long as the right-hand side of (3.3) stays nonnegative. For the rest of this section, we construct sequences $\{\alpha_k\}_{k=-1}$ and $\{\beta_k\}_{k=-1}$ such that the right-hand side of (3.3) is nonnegative.

4.1. Constructing sequences α_k and β_k . In this part, we define sequences α_k and β_k needed for the iteration argument.

Lemma 4.3. Suppose $\alpha_0 = 0$ and define

(4.24)
$$\alpha_{k+1} := \frac{4(\alpha_k + 1) - n + \sqrt{n(16\alpha_k^2 + 24\alpha_k + n + 8)}}{4(n-1)}.$$

Then $(\alpha_k)_k$ is a positive, bounded and increasing sequence that converges to $\alpha := \frac{2}{n-4}$ provided n > 4 and p > 1. Moreover, for this choice of $(\alpha_k)_k$, one of the sequences of coefficients defined in Proposition 3.1 is zero, i.e. $I_{\alpha_k}^{(2)} = 0$.

Proof: It is straightforward to show that for any $k \geq 0$ sequences $\alpha_k > 0$. Also, direct calculations show that $\alpha_k \to \alpha := \frac{2}{n-4}$ provided α_k is convergent. Note that $\alpha_1 = \frac{4-n+\sqrt{n^2+8n}}{4n-4} < \frac{2}{n-4}$ and by induction one can see that $\alpha_k \leq \alpha$ for all $k \geq 0$. In what follows we show that α_k is an increasing sequence. For any k the difference of α_k and α_{k+1} is the following

$$\alpha_{k+1} - \alpha_k = \frac{\sqrt{n(16\alpha_k^2 + 24\alpha_k + n + 8)} - ((n-4) + 4a_k(n-2))}{4(n-1)}$$

$$= \frac{8(n-1)(n-4)(2\alpha_k + 1)}{S_{n,k}} \left(\frac{2}{n-4} - \alpha_k\right)$$

where $S_{n,k} = \sqrt{n(16\alpha_k^2 + 24\alpha_k + n + 8)} + (n-4) + 4a_k(n-2) > 0$. Therefore, from the fact that $\alpha_k \le \alpha = \frac{2}{n-4}$, we get the desired result.

Similarly, in what follows we provide an explicit formula for the sequence β_k .

Lemma 4.4. Suppose $\beta_0 = \sqrt{\frac{2}{p+1}}$ and define

(4.25)
$$\beta_{k+1} := \sqrt{\frac{2}{p+1} + \frac{4}{(p+1)n} \alpha_k \beta_k^2},$$

where $(\alpha_k)_k$ is as in Lemma 4.3. Then $(\beta_k)_k$ is a positive, bounded and increasing sequence that converges to $\beta := \sqrt{\frac{2}{(p+1)-c_n}}$ where $c_n = \frac{8}{n(n-4)}$ provided n > 4and p > 1. Moreover, for this choice of $(\alpha_k)_k$ and $(\beta_k)_k$, one of the sequences of coefficients defined in Proposition 3.1 is strictly positive, i.e. $I_{0,\alpha_k,\beta_k}^{(1)} > 0$.

Proof: The sequence $(\beta_k)_k$ for all $k \geq 0$ is positive. Note that boundedness of the sequence $(\alpha_k)_k$ forces the boundedness of the $(\beta_k)_k$ meaning that $\beta_{k+1} \leq$ $\sqrt{\frac{2}{p+1} + \frac{4\alpha}{(p+1)n}\beta_k^2}$ for any k. By straightforward calculations we get

$$\beta_{k+1}^2 \le \frac{2}{p+1} \sum_{i=0}^{k+1} \left(\frac{4\alpha}{n(p+1)} \right)^i.$$

Note that $\frac{4\alpha}{n(p+1)} = \frac{8}{n(n-4)(p+1)} < 1$ provided n > 4 and p > 1. Therefore,

 $\sum_{i=0}^{\infty} \left(\frac{4\alpha}{n(p+1)}\right)^i < \infty.$ This proves the boundedness of $(\beta_k)_k$. Since $(\alpha_k)_{k=0}$ is an increasing sequence, the sequence $(\beta_k)_{k=0}$ will be nondecreasing by induction. Note that $\beta_1 = \beta_0$ and $\beta_2 = \sqrt{\frac{2}{p+1} + \frac{8}{(p+1)^2n} \frac{4-n+\sqrt{n^2+8n}}{4n-4}} > 0$ $\beta_1 = \sqrt{\frac{2}{p+1}}$. Suppose that $\beta_{k-1} \leq \beta_k$ for a certain index $k \geq 2$ then we apply the fact that $\alpha_k \geq \alpha_{k-1}$ to show $\beta_k \leq \beta_{k+1}$. This can be found as a consequence of the

$$\beta_{k+1} - \beta_k = \frac{\beta_{k+1}^2 - \beta_k^2}{\beta_{k+1} + \beta_k} = \frac{4}{(p+1)n(\beta_{k+1} + \beta_k)} (\beta_k^2 \alpha_k - \beta_{k-1}^2 \alpha_{k-1})$$

$$\geq \frac{4\alpha_{k-1}(\beta_k + \beta_{k-1})}{(p+1)n(\beta_{k+1} + \beta_k)} (\beta_k - \beta_{k-1}).$$

So, $(\beta_k)_k$ is convergent and converges to $\beta := \sqrt{\frac{2n(n-4)}{(p+1)(n-4)n-8}}$. Note that $(p+1)_{(p+1)(n-4)n-8}$ 1)n(n-4) > 8 for p > 1 and n > 4. Therefore, β is well-defined

Note that based on the definition of the sequences $\{\alpha_k\}_{k=-1}$ and $\{\beta_k\}_{k=-1}$ we concluded that $I_{0,\alpha_k,\beta_k}^{(1)}>0$ and $I_{\alpha_k}^{(2)}=0$. In the next two lemmata we investigate the positivity of sequences $I_{\epsilon,\alpha_k,\beta_k}^{(3)}$ and $I_{a,\epsilon,\alpha_k,\beta_k}^{(4)}$ appeared in (3.3) in Proposition 3.1.

Lemma 4.5. Set $\epsilon = 0$ in $I_{\epsilon,\alpha_k,\beta_k}^{(3)}$ that is defined in Proposition 3.1. Then,

$$(4.26) I_{0,\alpha_k,\beta_k}^{(3)} \to I_{0,\alpha,\beta}^{(3)} := \frac{4}{n} \alpha \beta (2\alpha + 1) + \alpha \beta + \beta q (q - 3\alpha - 1)$$

as $k \to \infty$. The constant $I_{0,\alpha,\beta}^{(3)}$ is positive provided $p > \frac{n+4}{n-4}$ and n > 4.

Proof: Note that when $p > \frac{n+4}{n-4}$ and n > 4, then we have $\frac{p+1}{2} > \frac{n}{n-4}$. As $k \to \infty$, from Lemma 4.3 and Lemma 4.4 the sequences $\alpha_k \to \alpha := \frac{2}{n-4}$ and $\beta_k \to \beta := \sqrt{\frac{2}{(p+1)-c_n}}$. Therefore,

$$\begin{split} \frac{I_{0,\alpha,\beta}^{(3)}}{\beta} &= \frac{4}{n} \left(\frac{2}{n-4} \right) \left(\frac{4}{n-4} + 1 \right) + \frac{2}{n-4} + \frac{p+1}{2} \left(\frac{p-1}{2} - \frac{6}{n-4} \right) \\ &= \left(\frac{p+1}{2} \right)^2 - \left(\frac{p+1}{2} \right) \left(\frac{n+2}{n-4} \right) + \frac{2n}{(n-4)^2} \\ &= \left(\frac{p+1}{2} - \frac{n}{n-4} \right) \left(\frac{p+1}{2} - \frac{2}{n-4} \right) > 0. \end{split}$$

Note that $I_{a,\epsilon,\alpha_k,\beta_k}^{(4)}$ appears in (3.3) mainly because of the weight function $|x|^a$. In other words, we have $I_{0,\epsilon,\alpha_k,\beta_k}^{(4)}=0$, in case of a=0.

Lemma 4.6. For any $k \geq 0$,

(4.27)
$$I_{0,\alpha_k,\beta_k}^{(3)} < \beta_{k+1} (\frac{p+1}{2} - \alpha_{k+1})^2,$$

provided $p > \frac{n+4}{n-4}$ and n > 4. Therefore, for any $a \ge 0$ that satisfies the following upper bound

(4.28)
$$a \le A_k := \frac{2(n-2)I_{0,\alpha_k,\beta_k}^{(3)}}{\beta_{k+1}(\frac{p+1}{2} - \alpha_{k+1})^2 - I_{0,\alpha_k,\beta_k}^{(3)}}$$

the sequence $I_{a,0,\alpha_k,\beta_k}^{(4)}$ is positive for any k.

Proof: Basic calculations show that

$$\beta_{k+1}(\frac{p+1}{2} - \alpha_{k+1})^2 - I_{0,\alpha_k,\beta_k}^{(3)}$$

$$= \beta_{k+1}(\frac{p+1}{2} - \alpha_{k+1})^2 - \frac{4}{n}\alpha_{k+1}\beta_k(\alpha_{k+1} + \alpha_k + 1) - \alpha_{k+1}\beta_{k+1} - \beta_{k+1}\frac{p+1}{2}(\frac{p+1}{2} - 3\alpha_{k+1} - 1)$$

$$\geq \beta_{k+1}((\frac{p+1}{2} - \alpha_{k+1})^2 - \frac{4}{n}\alpha_{k+1}(\alpha_{k+1} + \alpha_k + 1) - \alpha_{k+1} - \frac{p+1}{2}(\frac{p+1}{2} - 3\alpha_{k+1} - 1))$$

$$= \beta_{k+1}\left(\frac{n-4}{n}\alpha_{k+1}^2 - \frac{4}{n}\alpha_{k+1}^2 - \frac{4}{n}\alpha_{k+1} + \frac{(p-1)\alpha_{k+1}}{2} + \frac{p+1}{2}\right)$$

where we have used the fact that β_k and α_k are increasing sequences in the first and the second inequality respectively. Therefore,

$$\beta_{k+1} \left(\frac{p+1}{2} - \alpha_{k+1}\right)^2 - I_{0,\alpha_k,\beta_k}^{(3)}$$

$$\geq \beta_{k+1} \left(\frac{n-4}{n}\alpha_{k+1}^2 + \alpha_{k+1}\left(\frac{p-1}{2} - \frac{4}{n}\alpha_{k+1}\right) + \frac{p+1}{2} - \frac{4}{n}\alpha_{k+1}\right)$$

$$\geq \beta_{k+1} \left(\frac{n-4}{n}\alpha_{k+1}^2 + (\alpha_{k+1}+1)\left(\frac{p-1}{2} - \frac{4}{n}\alpha\right)\right)$$

$$> 0.$$

Note that in the last inequality we have used the fact that $\frac{p-1}{2} - \frac{4}{n}\alpha = \frac{p-1}{2} - \frac{4}{n}\frac{2}{n-4} > 0$ $\frac{4}{(n-4)n}(n-2) > 0$, since $p > \frac{n+4}{n-4}$ and n > 4.

Remark 4.1. It would be interesting if a counterpart of (1.12) could be proved for bounded solutions of the fourth order semilinear equation $\Delta^2 u = f(u)$ under certain assumptions on the arbitrary nonlinearity $f \in C^1(\mathbb{R})$. We expect that such an inequality could be established for some convex nonlinearity f.

5. Appendix

We would like to mention that given the estimates in Lemma 2.1 and Lemma 2.2, one can provide a somewhat simpler proof for Proposition 2.1 as what follows.

Second Proof for Proposition 2.1: From Lemma 2.1, we have $\int_{\mathbb{R}^n} |x|^{2-n+a} u^p dx < \int_{\mathbb{R}^n} |x|^{2-n+a} u^p dx$ ∞ . Hence we define the following function

$$w(x) = \frac{1}{n(n-2)\omega_n} \int_{\mathbb{R}^n} \frac{|y|^a u^p(y)}{|x-y|^{n-2}} dy.$$

It is clear that $w(x) \geq 0$ and $\Delta w = -|x|^a u^p$. This implies that for a solution uof (1.1), the function $h(x) := w(x) + \Delta u(x)$ is a well defined harmonic function on \mathbb{R}^n . Thus for any $x_0 \in \mathbb{R}^n$ and any R > 0, by the mean value theorem for harmonic

functions, we will have

(5.1)
$$h(x_0) := \int_{\partial B_R(x_0)} h d\sigma$$
$$= \int_{\partial B_R(x_0)} (w + \Delta u) d\sigma$$
$$\leq \int_{\partial B_R(x_0)} w d\sigma + \int_{\partial B_R(x_0)} |\Delta u| d\sigma.$$

Since $w(x_0) < \infty$, through Tonelli's theorem, we can change the order of the integrations to see that the first integral on the right-hand side of (5.1) tends to zero as $R \to \infty$ for all R. To be more precise notice that, up to a constant multiple, the first integral can be written as

$$\int_{\mathbb{R}^n} \int_{\partial B_R(x_0)} \frac{d\sigma_x}{|x-y|^{n-2}} |y|^a u^p(y) dy.$$

Then we use the fact that $\int_{\partial B_R(x_0)} \frac{d\sigma_x}{|x-y|^{n-2}} = |y-x_0|^{2-n}$ if $|y-x_0| > R$ and equals to R^{2-n} if $|y-x_0| < R$. Thus the integral will split into two parts. Outside part tends to zero as $R \to \infty$ due to the fact that $w(x_0) < \infty$ while the inside part tends to zero due to the fact that, by Lemma 2.1,

$$R^{2-n} \int_{B_R(x_0)} |y|^a u^p(y) dy \leq R^{2-n} \int_{B_{R+|x_0|}(0)} |y|^a u^p dy$$

$$\leq CR^{2-n} (R+|x_0|)^{n-\frac{4p+a}{p-1}}$$

tends to zero as $R \to \infty$. The second integral will tend to zero for some sequence of R by Lemma 2.2 again. Apply the above inequality to this sequence to see that $h(x_0) \le 0$. Since x_0 is arbitrary, we have $-\Delta u \ge 0$.

References

- [1] N. Alikakos, On the structure of phase transition maps for three or more coexisting phases, Geometric Partial Differential Equations. CRM Series, vol. 15. Pisa: Scuola Normale Superiore, pp. 1-31.
- [2] T. Branson, Differential operators canonically associated to a conformal structure, Math. Scand., 57 (1985), 293-345.
- [3] L. Caffarelli, N. Garofalo, F. Segála, A gradient bound for entire solutions of quasi-linear equations and its consequences, Comm. Pure Appl. Math. 47 (1994), no. 11, 1457-1473.
- [4] D. Castellaneta, A. Farina, E. Valdinoci, A pointwise gradient estimate for solutions of singular and degenerate pde's in possibly unbounded domains with nonnegative mean curvature, Communications on Pure and Applied Analysis 11 (2012) 1983-2003.
- [5] C. Cowan, P. Esposito and N. Ghoussoub, Regularity of extremal solutions in fourth order nonlinear eigenvalue problems on general domains. Discrete Contin. Dyn. Syst. 28 (2010), no. 3, 1033-1050.
- [6] D.G. de Figueiredo, P. Felmer, On superquadratic elliptic systems, Trans. Amer. Math. Soc., 343 (1994), pp. 99-116.

- [7] D. G. De Figueiredo, C.A. Magalhaes, On nonquadratic Hamiltonian elliptic systems, Adv. Differential Equations 1 (1996), no. 5, 881-898.
- [8] A. Farina, Two results on entire solutions of Ginzburg-Landau system in higher dimensions, Journal of Functional Analysis 214 (2004) 386-395.
- [9] A. Farina, E. Valdinoci, A pointwise gradient estimate in possibly unbounded domains with nonnegative mean curvature, Adv. Math. 225 (2010), no. 5, 2808-2827.
- [10] A. Farina, E. Valdinoci, A pointwise gradient bound for elliptic equations on compact manifolds with nonnegative Ricci curvature, Discrete Contin. Dyn. Syst.-A 30 (2011), no. 4, 1139-1144.
- [11] A. Farina, E. Valdinoci, Gradient bounds for anisotropic partial differential equations, Calc. Var. DOI 10.1007/s00526-013-0605-9.
- [12] A. Farina, E. Valdinoci, Pointwise estimates and rigidity results for entire solutions of nonlinear elliptic pde's, ESAIM: COCV 19 (2013) 616-627.
- [13] A. Farina, B. Sciunzi, E. Valdinoci, Bernstein and De Giorgi type problems: new results via a geometric approach, Ann. Scuola Norm. Sup. Pisa Cl. Sci. (5) Vol. VII (2008), 1-51.
- [14] M. Fazly, Liouville theorems for the polyharmonic Hénon-Lane-Emden system, Methods and Applications of Analysis, Vol 21 no 2 (2014) 265-282.
- [15] M. Fazly, N. Ghoussoub, On the Hénon-Lane-Emden conjecture, Disc. Cont. Dyn. Syst. A 34 no 6 (2014) 2513-2533.
- [16] M. Fazly, N. Ghoussoub, De Giorgi type results for elliptic systems, Calc. Var. Partial Differential Equations 47 (2013) 809-823.
- [17] B. Gidas, J. Spruck; Global and local behavior of positive solutions of nonlinear elliptic equations, Commun. Pure Appl. Math. 34 (1981) 525-598.
- [18] B. Gidas, J. Spruck; A priori bounds for positive solutions of nonlinear elliptic equations, Comm. Partial Differential Equations 6 (1981), no. 8, 883-901.
- [19] C. Gui, Hamiltonian identities for elliptic partial differential equations, Journal of Functional Analysis 254 (2008) 904-933.
- [20] C. S. Lin, A classification of solutions of a conformally invariant fourth order equation in \mathbb{R}^N , Comment. Math. Helv. 73 (1998) 206-231.
- [21] L. Modica, A gradient bound and a Liouville theorem for nonlinear Poisson equations, Comm. Pure Appl. Math. 38 (1985), 679-684.
- [22] J. Moser, On Harnack's theorem for elliptic differential equations, Comm. Pure Appl. Math. 14 (1961) 577-591.
- [23] W. M. Ni, A nonlinear Dirichlet problem on the unit ball and its applications, Indiana Univ. Math. J. 31 (1982) 801-807.
- [24] S. Paneitz, A quartic conformally covariant differential operator for arbitrary pseudo-Riemannian manifolds, preprint (1983).
- [25] Q. H. Phan; Liouville-type theorems and bounds of solutions for Hardy-Hénon elliptic systems, Adv. Diff. Equ. 17 (2012) 605-634.
- [26] Q. H. Phan, Ph. Souplet; Liouville-type theorems and bounds of solutions of Hardy-Hénon equations, J. Diff. Equ., 252 (2012), 2544-2562.
- [27] J. Serrin, H. Zou, The existence of positive entire solutions of elliptic Hamiltonian systems. Comm. Partial Differential Equations, 23 (1998), pp. 577-599.
- [28] Ph. Souplet; The proof of the Lane-Emden conjecture in four space dimensions., Adv. Math. 221 (2009) 1409-1427.

- [29] J. Wei, X. Xu; Classification of solutions of higher order conformally invariant equations, Math. Ann. 313 (1999), no. 2, 207-228.
- [30] J. Wei, X. Xu, W. Yang; On the classification of stable solution to biharmonic problems in large dimensions, Pacific Journal of Mathematics 263 (2013) 495-512.
- [31] J. Wei, D. Ye; Liouville theorems for stable solutions of biharmonic problem, Mathematische Annalen 356 (2013) 1599-1612.

Department of Mathematical and Statistical Sciences, CAB 632, University of Alberta, Edmonton, Alberta, Canada T6G 2G1

E-mail address: fazly@ualberta.ca

Department of Mathematics, University of British Columbia, Vancouver, B.C. Canada V6T 1Z2.

 $E ext{-}mail\ address: jcwei@math.ubc.ca}$

Department of Mathematics, National University of Singapore, Singapore 119076, Singapore

 $E\text{-}mail\ address{:}\ \mathtt{matxuxw@nus.edu.sg}$