# On Helmholtz equation and Dancer's type entire solutions for nonlinear elliptic equations 

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Abstract
Starting from a bound state (positive or sign-changing) solution to

$$
-\Delta \omega_{m}=\left|\omega_{m}\right|^{p-1} \omega_{m}-\omega_{m} \text { in } \mathbb{R}^{m}
$$

and solutions to the Helmholtz equation

$$
\Delta u_{0}+\lambda u_{0}=0 \text { in } \mathbb{R}^{n}, \lambda>0
$$

we build new Dancer's type entire solutions to the nonlinear scalar equation

$$
-\Delta u=|u|^{p-1} u-u \text { in } \mathbb{R}^{m+n}
$$

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## 1 Introduction

The purpose of this note is to construct new entire (positive or sign-changing) solutions for the elliptic equation

$$
\begin{equation*}
-\Delta u=|u|^{p-1} u-u \text { in } \mathbb{R}^{m+n} \tag{1}
\end{equation*}
$$

where the exponent $p>1$ and satisfies some conditions. Here $m$ and $n$ are nonnegative integers and $m+n \geq 1$. A solution to (1) corresponds to a standing wave to the nonlinear Schrödinger equation

$$
\begin{equation*}
-i u_{t}=\Delta u+|u|^{p-1} u \text { in } \mathbb{R}^{m+n} \tag{2}
\end{equation*}
$$

It also serves as models in different areas of applied mathematics such as pattern formation in mathematical biology. See [21].

Equation (1) has been studied extensively and there is a vast literature on this subject. Let us first of all mention the classical example of Dancer's solutions. To describe these solutions, we recall that when $n=0$, equation (1) reduces to

$$
\begin{equation*}
-\Delta u=|u|^{p-1} u-u \text { in } \mathbb{R}^{m} \tag{3}
\end{equation*}
$$

which admits a unique positive radially symmetric ground state solution $w_{m}$ decaying exponentially fast to zero at infinity, provided that $p$ is subcritical, i.e. $1<p<\frac{m+2}{m-2}$. The linearized equation of (3) around $w_{m}$ is

$$
L_{w_{m}} \eta:=-\Delta \eta+\left(1-p\left|w_{m}\right|^{p-1}\right) \eta
$$

acting on $H^{2}\left(\mathbb{R}^{m}\right)$. The essential spectrum of $L_{w_{m}}$ is $[1,+\infty)$. It is known that this operator has a unique negative eigenvalue $-\lambda_{1}$. We choose a corresponding positive eigenfunction $Z_{1}(x)$. Dancer [8] first constructed new positive solutions with only partial decaying using the Crandall-Rabinowitz bifurcation theory. He proved that for $n=1$, there exists a family of solutions to (1) with the following behavior:

$$
\begin{equation*}
u(x, y)=w_{m}(x)+\epsilon Z_{1}(x) \cos \left(\sqrt{\lambda_{1}} y\right)+o\left(\epsilon e^{-\frac{1}{2}|x|}\right),|\epsilon| \ll 1,(x, y) \in \mathbb{R}^{m+1} \tag{4}
\end{equation*}
$$

Moreover such solutions are periodic in $y$. We call this type of solutions as Dancer's type.
The existence of Dancer's solution generates lots of interests in constructing other type of solutions. Variational and gluing methods have been successfully applied in the construction of new entire solutions. There is also a deep connection between the solutions of (1) and the constant mean curvature surfaces (CMC). We refer to $[2,8,18,19,20]$ and the references therein for more discussions.

In this paper we extend Dancer's type solutions to general dimensions $n \geq 3$. Let $\omega_{m}$ be a bound state solution (not necessary positive) of equation (3) with $\omega_{m}(x) \rightarrow 0$ as $|x| \rightarrow+\infty$. There is an abundance of existence results of this type solutions for subcritical exponent $p$. See [2, 3, 4, 5, 7]. For example, for each integer $k \geq 0$ there are radial solutions with $k$ zeroes. There are also infinitely many sign-changing solutions without any symmetry. See $[2,5,7]$. Slightly abusing the notation, we use $(x, y)$ to denote the vectors in $\mathbb{R}^{m+n}$, where $x$ represents the first $m$ coordinates. Denote the negative eigenvalues of $L_{\omega_{m}}$ as $-\lambda_{1}, \ldots,-\lambda_{k}$ (counting multiplicity), with the corresponding eigenfunctions $Z_{1}, \ldots, Z_{k}$. Let $Z_{k+1}, \ldots, Z_{l}$ be the eigenfunctions of the zero eigenvalue. We could also assume that $Z_{1}, \ldots, Z_{l}$ consists an orthonormal basis for the non-positive eigenspace of $L_{\omega_{m}}$ in $L^{2}\left(\mathbb{R}^{m}\right)$ (Note that we don't assume the non-degeneracy of $\omega_{m}$.)

Our main result can be stated roughly as follows: Starting from solutions to the Helmholtz equation

$$
\begin{equation*}
\Delta u_{j}+\lambda_{j} u_{j}=0 \text { in } \mathbb{R}^{n}, j=1, \ldots, k \tag{5}
\end{equation*}
$$

we build a family of solutions to (1) with the following asymptotic behavior:

$$
\begin{equation*}
u(x, y)=\omega_{m}(x)+\epsilon \sum_{j=1}^{k} Z_{j}(x) u_{j}(y)+o\left(\epsilon e^{-\frac{1}{2}|x|}\right), \quad(x, y) \in \mathbb{R}^{m+n},|\epsilon| \ll 1 . \tag{6}
\end{equation*}
$$

As a consequence, for $n \geq 3$, there are abundance of solutions near $\omega_{m}(x)$. Unlike the classical Dancer's solution, these solutions are not periodic in the $y$ variable. As a matter of fact, they converge to $\omega_{m}(x)$ as $|y| \rightarrow \infty$. The existence of these type of solutions makes it more difficult to classify entire solutions near the ground state profile. Nevertheless we expect that all solutions near $\omega_{m}$ should be described by (6). In $[6,14,15]$, there have been some partial results on this issue. For example, it is proved in $[14,15]$ that positive bounded solutions periodic or even in certain variables and uniformly decaying in other variables must be radially symmetric in these decaying directions.

Our idea of the proof is in the spirit similar to that of [16], where existence of small amplitude solutions to the Ginzburg-Landau equation in dimension 3 and 4 has been proved. However there the background state is the trivial solution 0 . We should also mention another recent work [10] in which solutions to Allen-Cahn equation perturbed from the constant zero state are constructed using the Helmholtz equation. In [13], using dual variational method, the existence of a sequence of solutions $u_{k}$ of

$$
\Delta u+u+|u|^{p-1} u=0 \quad \text { in } \mathbb{R}^{n}
$$

with $\left\|u_{k}\right\|_{L^{p}} \rightarrow+\infty$, has been proved under certain condition on $p$ and $n$. A similar functional-analytical frame was used. See also [11, 12] for related recent results in this respect.

To describe our main results, we need to introduce some notations. Let $\lambda>0$ be a fixed positive number. Consider the so-called Helmholtz equation

$$
\begin{equation*}
\Delta u+\lambda u=0 \text { in } \mathbb{R}^{n} \tag{7}
\end{equation*}
$$

We are interested in solutions to (7) with the following decaying property

$$
\begin{equation*}
|u(y)| \leq C(1+|y|)^{-\frac{n-1}{2}} \tag{8}
\end{equation*}
$$

There are plenty many solutions to (7) satisfying (8). We start with radial solutions. Let $s$ be a parameter and $n \geq 2$. Consider the equation

$$
\begin{equation*}
\varphi^{\prime \prime}+\frac{n-1}{r} \varphi^{\prime}+\left(1-\frac{s^{2}}{r^{2}}\right) \varphi=0 . \tag{9}
\end{equation*}
$$

For $n=2$, it has a regular solution $J_{2, s}$, which is the Bessel functions of the first kind. For general $n \geq 2$, (9) has a regular solution

$$
J_{n, s}(r)=r^{1-\frac{n}{2}} J_{2, \sqrt{\left(\frac{n}{2}-1\right)^{2}+s^{2}}}(r) .
$$

It is known that

$$
J_{n, s}(r) \leq C(1+r)^{-\frac{n-1}{2}}
$$

Hence $J_{n, 0}(\sqrt{\lambda}|y|)$ is a solution to (7)-(8).
Given finitely many points $y_{j} \in \mathbb{R}^{n}, j=1, \ldots, q$, functions of the form

$$
\sum_{j=1}^{q} J_{n, 0}\left(\sqrt{\lambda}\left|y-y_{j}\right|\right)
$$

are also solutions of (7) satisfying (8). In [10], solutions of (7) satisfying (8) with zero level sets arbitrarily close to any compact smooth hyper-surfaces are constructed.

Our main result states that from these solutions of the Helmholtz equation we could construct solutions of (1).
Theorem 1. Let $n \geq 6$ and $\frac{n+2}{n-2} \leq p<\frac{m+2}{m-2}$. For any $\varepsilon$ with $|\varepsilon|$ small enough, there is a solution $u_{\varepsilon}$ to the equation

$$
\Delta u+|u|^{p-1} u-u=0, \text { in } \mathbb{R}^{m+n},
$$

such that

$$
u_{\varepsilon}=\omega_{m}(x)+\varepsilon \sum_{j=1}^{k} Z_{j}(x) u_{j}(y)+o(\varepsilon)
$$

where $u_{j}$ are solutions of (7)-(8), with $-\lambda_{j}$ being the negative eigenvalues of $L_{\omega_{m}}$.
As a corollary of the proof of this theorem, in the case that $\omega_{m}$ is the positive radially symmetric solution $w_{m}$, we have the following result.
Corollary 2. Let $n \geq 5$ and $\frac{n+3}{n-1} \leq p<\frac{m+2}{m-2}$. Let $w_{m}$ be the unique positive solution of (1) described before. For any $\varepsilon$ with $|\varepsilon|$ small enough, there is a positive solution $u_{\varepsilon}$ to (1) such that

$$
u_{\varepsilon}=w_{m}(x)+\varepsilon Z_{1}(x) u_{1}(y)+o(\varepsilon)
$$

Observe that in this corollary, we allow $n=5$. This is partly due to the fact that $w_{m}$ is nondegenerate in certain sense.

Remark 3. We don't know the decay rates of these solutions to $\omega_{m}$ as y goes to infinity.
When we are considering the existence of solutions radially symmetric in the $y$ variable, the requirement that $p \geq \frac{n+3}{n-1}$ can be slightly relaxed. This is the content of our next theorem.
Theorem 4. Let $n \geq 4$ and $\frac{n+1}{n-1}<p<\frac{m+2}{m-2}$. For any $\varepsilon$ with $|\varepsilon|$ small enough, there is a positive solution $u_{\varepsilon}$ to (1) which is radially symmetric in the $y$ variable and

$$
u_{\varepsilon}=w_{m}(x)+\varepsilon J_{n, 0}\left(\sqrt{\lambda_{1}}|y|\right)+o(\varepsilon)
$$

When $p$ is an integer, using the same method, we have similar result for $n=3$.
Theorem 5. Let $n=3$ and $1<p<\frac{m+2}{m-2}$. Suppose $p$ is an integer. For any $\varepsilon$ with $|\varepsilon|$ small enough, there is a positive solution $u_{\varepsilon}$ to $(1)$, radially symmetric in the $y$ variable, such that

$$
u_{\varepsilon}=w_{m}(x)+\varepsilon J_{n, 0}\left(\sqrt{\lambda_{1}}|y|\right)+o(\varepsilon) .
$$

Remark 6. An open question is the case of $n=2$. We don't know whether or not there are similar solutions. We expect that our method of proof for these theorems could potentially be used in other settings.

We will use contraction mapping principle to prove these results. The conditions on $p$ and $n$ are used to ensure the contraction mapping properties. In Section 2, we prove Theorem 1 and sketch the proof of Corollary 2. In section 3, we prove Theorem 4 and Theorem 5.

Throughout the paper, we use $C$ to denote a general constant which may vary from step to step.
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## 2 Proof of Theorem 1 and Corollary 2

We first prove Theorem 1. For each $\varepsilon$ with $|\varepsilon|$ small enough, we will construct a solution $u_{\varepsilon}$ to (1) in the form:

$$
u_{\varepsilon}(x, y)=\omega_{m}(x)+\sum_{i=1}^{l} Z_{i}(x) f_{i}(y)+\Phi(x, y)
$$

where we require that $\Phi$ is orthogonal to $Z_{i}$ in the following sense:

$$
\int_{\mathbb{R}^{m}} \Phi(x, y) Z_{i}(x) d x=0, \text { for any } y, i
$$

We obtain that the equations satisfied by $f_{i}$ and $\Phi$ are

$$
-\Delta \Phi+\left(1-p\left|\omega_{m}\right|^{p-1}\right) \Phi+\left[-\Delta f_{i}-\lambda_{i} f_{i}\right] Z_{i}(x)=N(f, \Phi)
$$

Here

$$
N(f, \Phi)=\left|u_{\varepsilon}\right|^{p-1} u_{\varepsilon}-\left|\omega_{m}\right|^{p-1} \omega_{m}-p\left|\omega_{m}\right|^{p-1}\left(\sum_{i=1}^{l} Z_{i}(x) f_{i}(y)+\Phi\right)
$$

Introduce the constant $\bar{p}:=\min \{p, 2\}$. We have the following estimate for $N$ :

$$
\begin{equation*}
|N(f, \Phi)| \leq C\left(\sum_{i=1}^{l}\left|f_{i}\right|^{\bar{p}}+|\Phi|^{\bar{p}},\right) \tag{10}
\end{equation*}
$$

provided that $\left|f_{i}\right|$ and $|\Phi|$ are small.
Let $f_{i}(y)=\varepsilon u_{i}(|y|)+h_{i}(y)$, where for $i=1, \ldots, k, \lambda_{i}>0$ and $u_{i}$ satisfies

$$
\begin{equation*}
\Delta u_{i}+\lambda_{i} u_{i}=0 \text { in } \mathbb{R}^{n},\left|u_{i}\right| \leq C(1+|y|)^{-\frac{n-1}{2}} \tag{11}
\end{equation*}
$$

For $i=k+1, \ldots, l, \lambda_{i}=0$, we simply put $u_{i} \equiv 0$.
Then we need to solve

$$
\begin{equation*}
-\Delta \Phi+\left(1-p\left|\omega_{m}\right|^{p-1}\right) \Phi+\left[-\Delta h_{i}-\lambda_{i} h_{i}\right] Z_{i}(x)=N(f, \Phi) . \tag{12}
\end{equation*}
$$

For the sake of convenience, we introduce the notation

$$
L \Phi:=-\Delta \Phi+\left(1-p\left|\omega_{m}\right|^{p-1}\right) \Phi
$$

To get a solution for (12), it will be sufficient to deal with the system

$$
\left\{\begin{array}{l}
-\Delta h_{i}-\lambda_{i} h_{i}=\int_{\mathbb{R}^{m}}\left[Z_{i}(x) N(f, \Phi)\right] d x, i=1, \ldots, l,  \tag{13}\\
L \Phi=N(f, \Phi)-\sum_{i=1}^{l} Z_{i}(x) \int_{\mathbb{R}^{m}}\left[Z_{i}(x) N(f, \Phi)\right] d x .
\end{array}\right.
$$

Throughout the paper, we use $q^{\prime}$ to denote the conjugate exponent of $q$. That is,

$$
q^{\prime}=\frac{q}{q-1}
$$

We need the following important generalized Sobolev type inequality (Theorem 2.3 in [17]).

Lemma 7. Suppose the exponent $q$ satisfies

$$
\begin{equation*}
\frac{2}{n+1} \leq \frac{1}{q^{\prime}}-\frac{1}{q} \leq \frac{2}{n} \tag{14}
\end{equation*}
$$

Then

$$
\begin{equation*}
\|u\|_{L^{q}\left(\mathbb{R}^{n}\right)} \leq C\|\Delta u+u\|_{L^{q^{\prime}}\left(\mathbb{R}^{n}\right)} . \tag{15}
\end{equation*}
$$

Note that if $u \in L^{q}$, then $u^{q-1} \in L^{q^{\prime}}$. Inequality (14) is equivalent to

$$
\frac{n-2}{n} \leq \frac{2}{q} \leq \frac{n-1}{n+1}
$$

That is,

$$
\frac{2(n+1)}{n-1} \leq q \leq \frac{2 n}{n-2}
$$

Recall that $\bar{p}=\min \{p, 2\}$. Hence under the assumption that $n \geq 6$ and $p \geq \frac{n+2}{n-2}$, we have

$$
\bar{p} \geq \frac{2 n}{n-2}-1=\frac{n+2}{n-2}
$$

To solve (13), we first consider the solvability of the equation

$$
\begin{equation*}
L \Phi=\xi \tag{16}
\end{equation*}
$$

for given function $\xi$. For this purpose, we introduce the functional space to work with.
Definition 8. The space $E_{\alpha}$ consists of functions $\xi$ defined on $\mathbb{R}^{m+n}$ satisfying

$$
\|\xi\|_{*, \alpha}:=\|\xi\|_{L^{\alpha}\left(\mathbb{R}^{m+n}\right)}+\|\xi\|_{L^{\infty}\left(\mathbb{R}^{m+n}\right)}<+\infty .
$$

The space $\bar{E}_{\alpha}$ consists of l-tuple of functions $\eta=\left(\eta_{1}, \ldots, \eta_{l}\right)$ with $\eta_{i}$ defined on $\mathbb{R}^{n}$, satisfying

$$
\|\eta\|_{* *, \alpha}:=\Sigma_{i=1}^{l}\left\|\eta_{i}\right\|_{L^{\alpha}\left(\mathbb{R}^{n}\right)}+\Sigma_{i=1}^{l}\left\|\eta_{i}\right\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}<+\infty .
$$

We will choose $q$ to be $\frac{2 n}{n-2}$. Then

$$
q^{\prime}=\frac{q}{q-1}=\frac{2 n}{n+2}
$$

Lemma 9. Suppose $\|\xi\|_{*, q^{\prime}}<+\infty$ and

$$
\int_{\mathbb{R}^{m}} \xi(x, y) Z_{i}(x) d x=0, \text { for any } y, i .
$$

Then the equation (16) has a solution $\Phi$ satisfying

$$
\|\Phi\|_{*, q} \leq C\|\xi\|_{*, q^{\prime}}
$$

and

$$
\int_{\mathbb{R}^{m}} \Phi(x, y) Z_{i}(x) d x=0, \text { for any } y, i
$$

Proof. Note that $q=\frac{2 n}{n-2}>2$ and hence $q^{\prime}<2$. We then have

$$
\|\xi\|_{L^{2}} \leq C\|\xi\|_{*, q^{\prime}}
$$

Consider the operator $L$ acting on the space of functions in $H^{2}\left(\mathbb{R}^{m+n}\right)$ which additionally orthogonal to $Z_{i}(x)$ for each $y, i$. Then 0 is not in the spectrum of $L$ and hence we have a solution $\Phi$ for the equation $L \Phi=\xi$, with $\|\Phi\|_{L^{2}} \leq C\|\xi\|_{L^{2}} \leq C\|\xi\|_{*, q^{\prime}}$ and

$$
\int_{\mathbb{R}^{m}} \Phi(x, y) Z_{i}(x) d x=0, \text { for any } y, i
$$

On the other hand, since we impose the orthogonality condition on $\Phi$, we also have the $L^{\infty}$ bounds for $\Phi$, that is,

$$
\|\Phi\|_{L^{\infty}} \leq C\|\xi\|_{L^{\infty}} \leq C\|\xi\|_{*, q^{\prime}}
$$

Therefore, using the fact that $q>2$, we find that $\|\Phi\|_{L^{q}} \leq C\|\Phi\|_{*, 2} \leq C\|\xi\|_{*, q^{\prime}}$. This finishes the proof.

With all these estimates at hand, we now can use the contraction mapping principle to prove Theorem 1.
Proof of Theorem 1. For each $h=\left(h_{1}, \ldots, h_{l}\right)$ with $\|h\|_{* *, q} \leq M_{1} \varepsilon^{\bar{p}}$, where $M_{1}$ is a large constant, we consider the equation

$$
L \Phi=N(f, \Phi)-\sum_{i=1}^{l} Z_{i}(x) \int_{\mathbb{R}^{m}}\left[Z_{i}(x) N(f, \Phi)\right] d x
$$

Note that the right hand side of this equation is automatically orthogonal to $Z_{i}(x)$ for each $y$. By Lemma 9, we can write it as

$$
\Phi=L^{-1}\left[N(f, \Phi)-\sum_{i=1}^{l} Z_{i}(x) \int_{\mathbb{R}^{m}} Z_{i}(x) N(f, \Phi) d x\right]:=\bar{N}(h, \Phi) .
$$

Observe that the function $\left|u_{i}\right|^{\bar{p}}$ is in $L^{q^{\prime}}$ :

$$
\int_{\mathbb{R}^{n}}\left|u_{i}\right|^{\bar{p} q^{\prime}} d y \leq C \int_{0}^{+\infty}(1+r)^{-\frac{n-1}{2} \frac{n+2}{n-2} \frac{2 n}{n+2}} r^{n-1} d r \leq C
$$

Now suppose $\|\Phi\|_{*, q} \leq M_{2} \varepsilon^{\bar{p}}$, where $M_{2}$ is a large constant. Then using the fact that $\bar{p} \geq q-1$, we deduce

$$
\begin{aligned}
\left\||\Phi|^{\bar{p}}\right\|_{L^{q^{\prime}}\left(\mathbb{R}^{m+n}\right)} & =\left(\int|\Phi|^{\bar{p} q^{\prime}}\right)^{\frac{1}{q^{\prime}}} \leq\left(\|\Phi\|_{L^{\infty}\left(\mathbb{R}^{m+n}\right)}^{\left(\bar{p}-(q-1) q^{\prime}\right.} \int|\Phi|^{(q-1) q^{\prime}}\right)^{\frac{1}{q^{\prime}}} \\
& \leq\left|M_{2}\right|^{\bar{p}} \varepsilon^{\bar{p}^{2}}
\end{aligned}
$$

Also we observe that

$$
\begin{aligned}
\int_{\mathbb{R}^{n}}\left(\int_{\mathbb{R}^{m}} Z_{i}(x)|\eta(x, y)| d x\right)^{q^{\prime}} d y & \leq \int_{\mathbb{R}^{n}}\left[\left(\int_{\mathbb{R}^{m}}[Z(x)]^{q} d x\right)^{\frac{1}{q}}\left(\int_{\mathbb{R}^{m}}|\eta(x, y)|^{q^{\prime}} d x\right)^{\frac{1}{q^{\prime}}}\right]^{q^{\prime}} d y \\
& \leq C\|\eta\|_{L^{q^{\prime}}}^{q^{\prime}}
\end{aligned}
$$

This together with (10) implies that

$$
\|N(f, \Phi)\|_{L^{q^{\prime}}} \leq C \varepsilon^{\bar{p}}+\left(\left|M_{1}\right|^{\bar{p}}+\left|M_{2}\right|^{\bar{p}}\right) \varepsilon^{\bar{p}^{2}}
$$

On the other hand, it follows from direct computation that

$$
\|N(f, \Phi)\|_{L^{\infty}} \leq C \varepsilon^{\bar{p}}+\left(\left|M_{1}\right|^{\bar{p}}+\left|M_{2}\right|^{\bar{p}}\right) \varepsilon^{\bar{p}^{2}}
$$

We can then check that $\bar{N}$ maps the balls of radius $M_{2} \varepsilon^{\bar{p}}$ of $E_{q}$ into itself for $M_{2}$ large enough and $\varepsilon$ sufficiently small.

Next we show that $\bar{N}$ is a contraction mapping. To see this, for two functions $\Phi_{1}, \Phi_{2}$ in this ball, we compute, for $\varepsilon$ small,

$$
\begin{aligned}
& \left\|\bar{N}\left(h, \Phi_{1}\right)-\bar{N}\left(h, \Phi_{2}\right)\right\|_{L^{q^{\prime}}} \leq C \varepsilon^{\bar{p}-1}\left\|\Phi_{1}-\Phi_{2}\right\|_{L^{q^{\prime}}} \\
& \left\|\bar{N}\left(h, \Phi_{1}\right)-\bar{N}\left(h, \Phi_{2}\right)\right\|_{L^{\infty}} \leq C \varepsilon^{\bar{p}-1}\left\|\Phi_{1}-\Phi_{2}\right\|_{L^{\infty}} .
\end{aligned}
$$

This in turn will imply that $\bar{N}$ is a contraction map. We then conclude that it has a unique fixed point in the ball of radius $M_{2} \varepsilon^{\bar{p}}$, denote it by $\Phi_{h}$.

To solve the system (13), it remains to solve the system of equations

$$
-\Delta h_{j}-\lambda_{j} h_{j}=\int_{\mathbb{R}^{m}}\left[Z_{j}(x) N\left(f, \Phi_{h}\right)\right] d x, j=1, \ldots, l
$$

We write it as

$$
h_{j}=\mathfrak{D}_{j}\left(\int_{\mathbb{R}^{m}} Z_{j}(x) N\left(f, \Phi_{h}\right) d x\right):=D_{j}(h), j=1, \ldots, l
$$

Here the operator $\mathfrak{D}_{j}=\lim _{\varepsilon \rightarrow 0}\left(-\Delta-\lambda_{j}+i \varepsilon\right)^{-1}$. Then we are finally lead to solve the fixed point problem

$$
\begin{equation*}
h=D(h):=\left(D_{1}(h), \ldots, D_{l}(h)\right) . \tag{17}
\end{equation*}
$$

Making use of the estimate of Lemma 7, we can show that $D(h)$ maps the ball of radius $M_{1} \varepsilon^{\bar{p}}$ of $\bar{E}_{q}$ into itself for $M_{1}$ large and $\varepsilon$ small and is a contraction mapping. We therefore get a fixed point $h$ for this mapping, which yields a solution for our original problem.

In the rest of this section, we sketch the proof of Corollary 2. In this case, we seek for a solution in the form

$$
u_{\varepsilon}(x, y)=w_{m}(x)+Z_{1}(x) f(y)+\Phi(x, y)
$$

Note that $Z_{1}$ is radially symmetric in $x$. Here $\Phi$ is required to be radially symmetric in $x$ and orthogonal to $Z_{1}$ for each $y$. Remember that $w_{m}$ is nondegenerate in the sense that the operator $L_{w_{m}}$ is positive on the space of functions defined on $\mathbb{R}^{m}$ radially symmetric and orthogonal to $Z_{1}$. Hence we still could solve the equation (16). We write the function $f$ in the form $f(y)=\varepsilon u_{1}(y)+h(y)$. Then similar as before, we prove the existence of solution by contraction mapping principle in suitable Banach spaces. Here we will work with functions $\Phi$ in the space $F_{\alpha}$, and $h$ in the space $\bar{F}_{\alpha}$, defined similarly as before.

Definition 10. The space $F_{\alpha}$ consists of functions $\xi$ defined on $\mathbb{R}^{m+n}$ which is radially symmetric in $x$, satisfying

$$
\|\xi\|_{L^{\alpha}\left(\mathbb{R}^{m+n}\right)}+\|\xi\|_{L^{\infty}\left(\mathbb{R}^{m+n}\right)}<+\infty .
$$

The space $\bar{F}_{\alpha}$ consists of functions $\eta$ defined on $\mathbb{R}^{n}$, satisfying

$$
\|\eta\|_{L^{\alpha}\left(\mathbb{R}^{n}\right)}+\|\eta\|_{L^{\infty}\left(\mathbb{R}^{n}\right)}<+\infty
$$

We now choose the exponent $\alpha$ to be

$$
\alpha=\frac{2(n+1)}{n-1}
$$

With this choice, under the assumption of Corollary 2 , for $n \geq 5$, we have $\bar{p}=\min \{p, 2\} \geq \alpha-1$. One then could use the estimate in Lemma 7. The rest of the proof follows from the arguments in that of Theorem 1.

## 3 Proof of Theorem 4 and Theorem 5

We first prove Theorem 4. The idea is still using contraction mapping principle but we take the advantage of radial symmetry in $y$. For the sake of convenience, we drop the subscript of $w_{m}$ and simply write it as $w$. We also write $Z_{1}$ as $Z, \lambda_{1}$ as $\lambda$. Denoting $r=|y|$. We are looking for a solution $u_{\varepsilon}$ in the form

$$
u_{\varepsilon}(x, y)=w(x)+Z(x) f(r)+\Phi(x, y)
$$

Here $\Phi$ is radially symmetric in $x$ and in $y$. Plug this into the equation

$$
-\Delta u_{\varepsilon}+u_{\varepsilon}-\left|u_{\varepsilon}\right|^{p}=0
$$

we get

$$
L \Phi+\left[-f^{\prime \prime}-\frac{n-1}{r} f^{\prime}-\lambda f\right] Z(x)=N(f, \Phi) .
$$

Let $f(r)=\varepsilon J_{n}(r)+h(r)$, where $J_{n}(r)=J_{n, 0}(\sqrt{\lambda} r)$. Then we need to solve

$$
\begin{equation*}
L \Phi+\left[-h^{\prime \prime}-\frac{n-1}{r} h^{\prime}-\lambda h\right] Z(x)=N\left(\varepsilon J_{n}+h, \Phi\right) \tag{18}
\end{equation*}
$$

Here we require that

$$
\int_{\mathbb{R}^{m}} \Phi(x, y) Z(x) d x=0, \text { for any } y
$$

We are lead to solve

$$
\left\{\begin{array}{l}
-h^{\prime \prime}-\frac{n-1}{r} h^{\prime}-\lambda h=\int_{\mathbb{R}^{m}} Z(x) N\left(\varepsilon J_{n}+h, \Phi\right) d x \\
L \Phi=N\left(\varepsilon J_{n}+h, \Phi\right)-Z(x) \int_{\mathbb{R}^{m}} Z(x) N\left(\varepsilon J_{n}+h, \Phi\right) d x .
\end{array}\right.
$$

We need to solve the equation

$$
\begin{equation*}
L \Phi=\xi \tag{19}
\end{equation*}
$$

for given function $\xi$ defined in $\mathbb{R}^{m+n}$.
Definition 11. Let $\alpha \in(0,1)$. The space $S_{\beta}$ consists of those functions $\xi$ radially symmetric in the $x$ and $y$ variable, with

$$
\|\xi\|:=\sup _{(x, y)}\left\|\xi(x, y)(1+|y|)^{\beta} e^{-\frac{1}{2}|x|}\right\|_{C^{0, \alpha}\left(B_{(x, y)}(1)\right)}<+\infty
$$

The space $\bar{S}_{\beta}$ consists of those radially symmetric functions $\eta$ defined in $\mathbb{R}^{n}$, with

$$
\|\eta\|_{\uparrow, \beta}:=\sup _{y}\left\|(1+|y|)^{\beta} \eta(y)\right\|_{C^{0, \alpha}\left(B_{y}(1)\right)}<+\infty .
$$

Lemma 12. Suppose $\xi$ is function radially symmetric in $x, y$ with $\|\xi\|<+\infty$ and

$$
\int_{\mathbb{R}^{m}} \xi(x, y) Z(x) d x=0, \text { for any } y .
$$

Then the equation (19) has a solution $\Phi$, radially symmetric in $x, y$, satisfying

$$
\|\Phi\| \leq C\|\xi\|
$$

Proof. The proof of this type result is by now standard, we omit the details and refer to [9] for a proof.
Next we proceed to the analysis of the first equation of the system. Let $\eta$ be a function which decays at certain rate at infinity. The homogeneous equation

$$
h^{\prime \prime}+\frac{n-1}{r} h^{\prime}+\lambda h=0
$$

has two linearly independent solutions $J_{n}(\cdot)$ and $N_{n}(\cdot)$. They both decay like $r^{-\frac{n-1}{2}}$ at infinity. $J_{n}$ is regular near 0 and $N_{n}$ is singular near 0 . Moreover, $N_{n}(r)=O\left(r^{2-n}\right)$ for $r$ close to 0 . Variation of parameter formula tells us up to a multiplicative constant that the function

$$
N_{n}(r) \int_{0}^{r} J_{n}(s) \eta(s) s^{n-1} d s-J_{n}(r) \int_{0}^{r} N_{n}(s) \eta(s) s^{n-1} d s
$$

is a solution of the nonhomogeneous equation

$$
\begin{equation*}
h^{\prime \prime}+\frac{n-1}{r} h^{\prime}+\lambda h=\eta . \tag{20}
\end{equation*}
$$

Lemma 13. Let $\eta \in \bar{S}_{\beta}$ with $\beta>\frac{n+1}{2}$. Then the equation (20) has a solution $h \in \bar{S}_{\frac{n-1}{2}}$ satisfies

$$
\|h\|_{\uparrow, \frac{n-1}{2}} \leq C\|\eta\|_{\uparrow, \beta} .
$$

Proof. Consider the following solution for (20) :

$$
h(r):=N_{n}(r) \int_{0}^{r} J_{n}(s) \eta(s) s^{n-1} d s-J_{n}(r) \int_{0}^{r} N_{n}(s) \eta(s) s^{n-1} d s
$$

We have, for $r>1$,

$$
\begin{aligned}
|h(r)| & \leq C\|\eta\|_{\gamma, \beta} r^{-\frac{n-1}{2}}\left(1+\int_{1}^{r} s^{\frac{n-1}{2}-\beta} d s\right) \\
& \leq C\|\eta\|_{\gamma, \beta}(1+r)^{-\frac{n-1}{2}}
\end{aligned}
$$

This gives us the desired estimate.

With these a priori estimates, one can prove Theorem 4 by using fixed point theorem in the space $S_{(n-1) / 2}$. Indeed, under the assumption that $p>\frac{n+1}{n-1}$ and $n>3$, by Lemma 13, the corresponding nonlinear term will be in the space $S_{\beta}$ for some fixed $\beta>(n+1) / 2$, and the loop of contraction mapping will be closed. We thus get a solution. We note that the condition $n>3$ is needed, because when $n=3, \frac{n+1}{n-1}$ will be equal to 2 , then in this case, we lose the estimate of Lemma 13 when it is applied to the nonlinear quadratic term. The details of the proof will be omitted.

Now we proceed to prove Theorem 5. We consider the case $p=2$. The other cases are similar, but notations will be heavier. The main point to prove this theorem is to prove a priori estimate for the solutions of the equation (20). Since $n=3$, we may assume that the fundamental solutions $J_{3}$ and $N_{3}$ of the ODE

$$
\varphi^{\prime \prime}+\frac{2}{r} \varphi^{\prime}+\lambda \varphi=0
$$

have the asymptotic behavior

$$
\begin{aligned}
J(r) & :=J_{3}(r)=r^{-1} \cos (\sqrt{\lambda} r-\zeta)+O\left(r^{-2}\right), \text { as } r \rightarrow+\infty, \\
N(r) & :=N_{3}(r)=r^{-1} \sin (\sqrt{\lambda} r-\zeta)+O\left(r^{-2}\right), \text { as } r \rightarrow+\infty
\end{aligned}
$$

where $\zeta \in \mathbb{R}$ is a constant depending on $\lambda$. Let $\rho$ be a cutoff function such that

$$
\rho(r)=\left\{\begin{array}{l}
1, r>2 \\
0, r<1
\end{array}\right.
$$

The key observation is the following
Lemma 14. Let

$$
\eta(r)=\rho(r) r^{-2}\left[k_{1} \sin ^{2}(\sqrt{\lambda} r-\zeta)+k_{2} \cos ^{2}(\sqrt{\lambda} r-\zeta)+k_{3} \sin (\sqrt{\lambda} r-\zeta) \cos (\sqrt{\lambda} r-\zeta)\right]+\bar{\eta}
$$

with

$$
K:=\left\|\bar{\eta}(r)(1+r)^{3}\right\|_{C^{0, \alpha}}+\sum\left|k_{i}\right|<+\infty
$$

Then the equation

$$
h^{\prime \prime}+\frac{2}{r} h^{\prime}+\lambda h=\eta
$$

has a solution $h \in C^{0, \alpha}[0,+\infty)$, with

$$
h(r)=c_{1} r^{-1} \sin (\sqrt{\lambda} r-\zeta)+\bar{h}(r), r>1,
$$

where $c_{1}$ is independent of $r$ and

$$
\left|(1+r)^{2} \bar{h}\right|+\left|c_{1}\right| \leq C K
$$

The solution $h$ will be denoted by $H(\eta)$.
Proof. Consider the case $\eta(r)=\rho(r) r^{-2} \sin ^{2}(\sqrt{\lambda} r-\zeta)$. We compute

$$
\begin{aligned}
h(r) & =N(r) \int_{0}^{r} J(s) \eta(s) s^{2} d s-J(r) \int_{0}^{r} N(s) \eta(s) s^{2} d s \\
& =N(r) \int_{0}^{r} J(s) \rho(s) \sin ^{2}(\sqrt{\lambda} s-\zeta) d s+J(r) \int_{r}^{+\infty} N(s) \rho(s) \sin ^{2}(\sqrt{\lambda} s-\zeta) d s+a J(r)
\end{aligned}
$$

We have

$$
\int_{0}^{r} J(s) \rho(s) \sin ^{2}(\sqrt{\lambda} s-\zeta) d s=\frac{1}{2} \int_{0}^{r} J(s) \rho(s) d s-\frac{1}{2} \int_{0}^{r} J(s) \rho(s) \cos (2 \sqrt{\lambda} s-2 \zeta) d s
$$

Using the fact that $J(s)=s^{-1} \cos (\sqrt{\lambda} s-\zeta)+O\left(s^{-2}\right)$, we estimate

$$
\begin{aligned}
\int_{0}^{r} J(s) \rho(s) d s & =\int_{0}^{+\infty} J(s) \rho(s) d s+O\left(r^{-1}\right) \\
\int_{0}^{r} J(s) \rho(s) \cos (2 \sqrt{\lambda} s-2 \zeta) d s & =\int_{0}^{+\infty} J(s) \rho(s) \cos (2 \sqrt{\lambda} s-2 \zeta) d s+O\left(r^{-1}\right)
\end{aligned}
$$

Similarly, for $r>1$,

$$
\left|\int_{r}^{+\infty} J(s) \rho(s) \bar{\eta}(s) s^{2} d s\right| \leq\left|\int_{r}^{+\infty} s^{-1} s^{-3} s^{2} d s\right| \leq C r^{-1}
$$

Hence

$$
h(r)=c_{1} r^{-1} \sin (\sqrt{\lambda} r-\zeta)+\bar{h}(r), r>1
$$

where

$$
\left|(1+r)^{2} \bar{h}\right|+\left|c_{1}\right| \leq C .
$$

The general case for $\eta$ can be proved via similar integral estimates.
Definition 15. The space $P_{\alpha}$ consists of functions $\eta(r)$ of the form

$$
\eta(r)=c_{1} \rho(r) r^{-1} \sin (\sqrt{\lambda} r-\zeta)+\bar{\eta}(r)
$$

with

$$
\|\eta\|_{\#, \alpha}=\left|c_{1}\right|+\sup _{k \geq 0}\left\|(1+r)^{2} \bar{\eta}(r)\right\|_{C^{0, \alpha}([k, k+1])}
$$

With the previous results at hand, one can use the contraction mapping principle to prove Theorem 5.
Proof of Theorem 5. The proof is similar as before. We sketch it.
We search for a solution of the form

$$
w(x)+Z(x)(\varepsilon J(|y|)+h(r))+\Phi(x, y)
$$

where $\int_{\mathbb{R}^{m}} \Phi(x, y) Z(x) d x=0$, for any $y$. We need to solve

$$
\left\{\begin{array}{l}
-h^{\prime \prime}-\frac{2}{r} h^{\prime}-\lambda h=\int_{\mathbb{R}^{m}} Z(x) N(\varepsilon J+h, \Phi) d x \\
L \Phi=N(\varepsilon J+h, \Phi)-Z(x) \int_{\mathbb{R}^{m}} Z(x) N(\varepsilon J+h, \Phi) d x
\end{array}\right.
$$

For each $h \in P_{0, \alpha}$ with $\|h\|_{\#, \alpha} \leq M \varepsilon^{2}$. We write

$$
h(r)=c_{1} \rho(r) \sin (\sqrt{\lambda} r-\zeta)+\bar{h}(r)
$$

Similar as Lemma 12, the second equation in this system could be solved and we obtain a solution $\Phi=\Phi_{h}$ with

$$
\left\|\Phi_{h}(x, y)(1+r)^{2}\right\|_{C^{2, \alpha}} \leq C \varepsilon^{2}
$$

We insert this solution into the first equation of the system and proceed to solve

$$
\begin{equation*}
-h^{\prime \prime}-\frac{2}{r} h^{\prime}-\lambda h=\int_{\mathbb{R}^{m}} Z(x) N\left(\varepsilon J+h, \Phi_{h}\right) d x \tag{21}
\end{equation*}
$$

Note that

$$
N\left(\varepsilon J+h, \Phi_{h}\right)=Z(x)(\varepsilon J+h)^{2}+\Phi_{h}^{2}+2 Z(x)(\varepsilon J+h) \Phi_{h}=Z(x)\left[2 \varepsilon J h+h^{2}+\varepsilon^{2} J^{2}\right]+O\left((1+r)^{-3}\right) .
$$

Let us write the equation (21) as

$$
h=H\left(\int_{\mathbb{R}^{m}} Z(x) N\left(\varepsilon J+h, \Phi_{h}\right) d x\right):=\bar{H}(h)
$$

Note that for the function $2 \varepsilon J h+h^{2}+\varepsilon^{2} J^{2}$, the coefficient of the $r^{-2}$ part has the form

$$
k_{1} \cos ^{2}(\sqrt{\lambda} r-\zeta)+k_{2} \sin ^{2}(\sqrt{\lambda} r-\zeta)+k_{3} \sin (\sqrt{\lambda} r-\zeta) \cos (\sqrt{\lambda} r-\zeta)
$$

We would like to get a solution for this equation by contraction mapping principle. By Lemma 14, for each $h \in P_{\alpha}$ with $\|h\|_{\#, \alpha} \leq M \varepsilon^{2}$, we have the estimate

$$
\|\bar{H}(h)\|_{\#, \alpha} \leq C \varepsilon^{2}+C M^{2} \varepsilon^{3}
$$

Hence for $\varepsilon$ small enough $\bar{H}$ maps the ball of radius $M \varepsilon^{2}$ into itself and one could also check it is a contraction map. We then get a fixed point for this map and thus complete the proof.

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