Vortex rings for the Gross-Pitaevskii equation in \mathbb{R}^3

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Abstract

By rigorous mathematical method, we construct traveling wave solutions with a stationary or traveling vortex ring to the Gross-Pitaevskii equation

$$i\hat{u}_t = \varepsilon^2 \bigtriangleup \hat{u} + \left(\tilde{V} - |\hat{u}|^2\right)\hat{u}, \quad \hat{u} \in H^1(\mathbb{R}^3),$$

where the unknown function \hat{u} is defined as $\hat{u} : \mathbb{R}^3 \times \mathbb{R} \to \mathbb{C}$, ε is a small positive parameter and \tilde{V} is a smooth potential.

Keywords: Vortex Ring, Bose-Einstein Condensates, Traveling Wave

1. Introduction

In this paper, we consider the existence of traveling wave solutions with vortex rings to the nonlinear schrödinger type problem

$$i\hat{u}_t = \varepsilon^2 \bigtriangleup \hat{u} + \left(\tilde{V} - |\hat{u}|^2\right)\hat{u}, \quad \hat{u} \in H^1(\mathbb{R}^3), \tag{1.1}$$

where the unknown function \hat{u} is defined as $\hat{u} : \mathbb{R}^3 \times \mathbb{R} \to \mathbb{C}$, \triangle is the Laplace operator in \mathbb{R}^3 , ε is a small positive parameter and \tilde{V} is a smooth potential. The equation (1.1) called Gross-Pitaevskii equation[49] is a well-known mathematical model to describe Bose-Einstein condensates.

Vortex flow is one of the fundamental types of fluid and gas motion. The most spectacular form, called concentrated vortices, is characterized by local circulation of fluid around a core[3]. Among all vortical structures, vortex rings with closed-loop cores are perhaps the most familiar to our daily experience such as the well-known smoke rings of cigarettes and the vortex rings observed in the wakes of aircraft. The simplicity of their generation and observation sparked interest of many researchers in mechanics and physics for more than a century[53], [2]. Quantized vortices have gained major interest in the past few years due to the experimental realization of Bose-Einstein

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condensates (cf. [5]). Vortices in Bose-Einstein condensates are quantized, and their size, origin, and significance are quite different from those in normal fluids since they exemplify superfluid properties (cf. [20], [6], [7]).

In addition to the simpler two-dimensional point vortices, two types of individual topological defects in three-dimensional Bose-Einstein condensates have focused attention of the scientific community in recent years: vortex lines [59, 56, 26] and vortex rings. Quantized vortex rings with cores have proved to exist when charged particles are accelerated through superfluid helium [50]. The achievements of quantized vortices in a trapped Bose-Einstein condensate [60], [44], [43] have suggested the possibility of producing vortex rings in ultracold atoms. The existence and dynamics of vortex rings in a trapped Bose-Einstein condensates have been studied by several authors [4], [30], [31], [21], [51], [25], [52], [29]. Vortex ring and their two-dimensional analogy(vortex-antivortex pair) have played an important role in the study of complex quantized structures such as superfluid turbulence and so attracted much attention [7], [6], [36], [28]. The reader can refer to the review papers [22], [24], [7] for more details of quantized vortices in physical works.

In this paper, we concern the construction of vortex rings by rigorous mathematical method. We are looking for a traveling wave solution to problem (1.1) in form

$$\hat{u}(\tilde{y},t) = e^{i\nu_{\varepsilon}t} \,\tilde{u}\Big(\tilde{y}_1,\,\tilde{y}_2,\,\tilde{y}_3-\kappa\,\varepsilon^2|\log\varepsilon|t\Big),\,$$

which also has a vortex ring. Here κ and ν_{ε} are two constants to be determined latter (c.f. (1.10), (1.15) and (1.19)). Then \tilde{u} is a solution of the nonlinear elliptic problem

$$-i\varepsilon^{2}|\log\varepsilon|\kappa\frac{\partial\tilde{u}}{\partial\tilde{y}_{3}} = \varepsilon^{2}\bigtriangleup\tilde{u} + \left(\nu_{\varepsilon} + \tilde{V}(\tilde{y}) - |\tilde{u}|^{2}\right)\tilde{u}, \quad \tilde{u}\in H^{1}(\mathbb{R}^{3}).$$
(1.2)

Here we have assumed that the trapping potential \tilde{V} is of the form $\tilde{V}(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3 - \kappa \varepsilon^2 | \log \varepsilon | t)$. To prove the existence and describe the profile of a traveling wave solution with vortex ring, we will use the powerful reduction method in partial differential equation theory, other than the formal expansion method in physical works. We believe that our study here also provides a relatively simple and unified approach to more complex vortex structures such as vortex helices and skyrmions.

For the stationary case, i.e. $\kappa = 0$, it becomes the eigenvalue problem

$$\varepsilon^2 \bigtriangleup \tilde{u} + \left(\nu_{\varepsilon} + \tilde{V}(\tilde{y}) - |\tilde{u}|^2\right) \tilde{u} = 0, \quad \tilde{u} \in H^1(\mathbb{R}^3),$$
(1.3)

where the unknown function \tilde{u} is defined as $\tilde{u} : \mathbb{R}^3 \to \mathbb{C}$, ε is a small positive parameter and \tilde{V} is a smooth potential. The study of the problem (1.3) in homogeneous case, i.e. $\nu_{\varepsilon} + \tilde{V} \equiv 1$, on bounded domain with suitable boundary condition started from [8] by F. Bethuel, H. Brezis, F. Helein in 1994, see also the book by K. Hoffmann and Q. Tang[27]. Since then, there is a large pool of literatures on the existence, asymptotic behavior, and dynamical behavior of solutions. We refer to the books [1] and [54] for references and backgrounds. Regarding to the construction of solutions, we mention two papers which are relevant to this paper. F. Pacard and T. Riviere derived a non-variational method to construct solutions with coexisting degrees of +1 and -1 in [48]. The proof is based on a analysis of the linearized operator around an approximation. M. del Pino, M. Kowalczyk and M. Musso [19] derived a reduction method for general existence for vortex solutions under Neumann (or Dirichlet)boundary conditions. The reader can refer to [37]-[39], [40], [57], [61], [16]-[17], [32]-[35], [58] and the references therein.

On the other hand, when $\nu_{\varepsilon} + \tilde{V} \equiv 1$, there are references on the construction of the traveling wave(i.e. $\kappa \neq 0$) on the whole unbounded domain. In two dimensional plane, F. Bethuel and J. Saut constructed a traveling wave with two vortices of degree ± 1 in [12]. In higher dimension, by

minimizing the energy, F. Bethuel, G. Orlandi and D. Smets constructed solutions with a vortex ring[11]. See [15] for another proof by Mountain Pass Lemma and the extension of results in [10]. The reader can refer to the review paper [9] by F. Bethuel, P. Gravejat and J. Saut and the references therein. For a similar existence result of vortex rings for Shrödinger map, F. Lin and J. Wei [41] gave a new proof by using a reduction method.

In this paper, we will prove the existence of solutions possessing vortex rings for the Gross-Pitaevskii equation with inhomogeneous trap potential \tilde{V} . Due to the existence of trap potential, we can show the existence of a stationary vortex ring for problem (1.3) by the reduction method in [41]. Then we construct a traveling vortex ring for (1.2).

We first consider the stationary case $\kappa = 0$, i.e. the problem (1.3). We assume that the real function \tilde{V} in (1.3) has the following properties (A1)-(A3). (A1): \tilde{V} is a symmetric function with the form

$$\tilde{V}(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) = \tilde{V}(\tilde{r}, \tilde{y}_3) = \tilde{V}(\tilde{r}, -\tilde{y}_3) \quad \text{with } \tilde{r} = \sqrt{\tilde{y}_1^2 + \tilde{y}_2^2} \,.$$

(A2): There is a point \tilde{r}_0 such that the following solvability condition holds

$$\frac{\partial \tilde{V}}{\partial \tilde{r}}\Big|_{(\tilde{r}_0,0)} + \frac{d}{\tilde{r}_0} = 0.$$
(1.4)

Here d is a positive constant defined by (c.f. (6.3))

$$d \equiv \frac{1}{\pi} \int_{\mathbb{R}^2} w(|s|) w'(|s|) \frac{1}{|s|} \, \mathrm{d}s > 0, \tag{1.5}$$

where w is defined by (2.1). We also assume that \tilde{r}_0 is non-degenerate in the sense that

$$\frac{\partial^2 \tilde{V}}{\partial \tilde{r}^2}\Big|_{(\tilde{r}_0,0)} - \frac{d}{\tilde{r}_0^2} \neq 0.$$
(1.6)

Remark 1.1. There are some works on the dynamics of vortex line with the action of trapped potential, base on formal expansion. In fact, A. Svidzinsky and A. Fetter [59] showed that the vortex velocity has the form

$$\mathcal{V} \sim -(T \times \bigtriangledown \tilde{V} + kB)A(\varepsilon) + \dots$$

where T and B are tangent vector and binormal of the vortex line. k is the curvature of the vortex line. For more details, the reader can refer to [59] and the references therein. Here we want the stationary vortex ring is trapped by the potential \tilde{V} , so we impose the condition (1.4) because of the symmetry.

We will construct a solution to (1.3) with a vortex ring, characterized by the curve

$$\sqrt{\tilde{y}_1^2 + \tilde{y}_2^2} = \tilde{r}_0 + \tilde{f} \equiv \tilde{r}_{1\varepsilon}, \quad \tilde{y}_3 = 0,$$
(1.7)

where \tilde{f} is a parameter of order $O(\varepsilon)$ to be determined in the reduction procedure. (A3): There exists a number $\tilde{r}_{2\varepsilon}$ with $\tilde{r}_{2\varepsilon} - \tilde{r}_{1\varepsilon} = \tau_0 + O(\varepsilon)$ such that the following conditions

$$1 + \left(\tilde{V}(\tilde{r}, \tilde{y}_3) - \tilde{V}(\tilde{r}_{1\varepsilon}, 0)\right) = 0, \quad \tilde{V}'(\tilde{r}, \tilde{y}_3) < 0, \quad \tilde{V}''(\tilde{r}, \tilde{y}_3) \le 0, \tag{1.8}$$

hold along the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \tilde{r}_{2\varepsilon}$. In (1.8), τ_0 is a universal positive constant independent of ε and the derivatives were taken with respect to the out normal of the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \tilde{r}_{2\varepsilon}$. We also assume that

$$1 + \left[\tilde{V}(\tilde{r}, \tilde{y}_{3}) - \tilde{V}(\tilde{r}_{1\varepsilon}, 0)\right] \ge c_{1}, \quad if \sqrt{\tilde{r}^{2} + \tilde{y}_{3}^{2}} \in \left(0, \, \tilde{r}_{2\varepsilon} - \tau_{1}\right), \\ 1 + \left[\tilde{V}(\tilde{r}, \tilde{y}_{3}) - \tilde{V}(\tilde{r}_{1\varepsilon}, 0)\right] \le -c_{2}, \quad if \sqrt{\tilde{r}^{2} + \tilde{y}_{3}^{2}} \in (\tilde{r}_{2\varepsilon} + \tau_{2}, +\infty),$$
(1.9)

for some positive constants c_1, c_2, τ_1 and τ_2 .

Remark 1.2. A typical form of \tilde{V} in physical model is the harmonic type, see [59]

$$\tilde{V}(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) = -\tilde{y}_1^2 - \tilde{y}_2^2 - \tilde{y}_3^2.$$

It is obvious that this special \tilde{V} possess the properties in (A1)-(A3).

By setting

$$\nu_{\varepsilon} = 1 - \tilde{V}(\tilde{r}_{1\varepsilon}, 0), \tag{1.10}$$

to problem (1.3) and then defining $V(\tilde{r}, \tilde{y}_3) = \tilde{V}(\tilde{r}, \tilde{y}_3) - \tilde{V}(\tilde{r}_{1\varepsilon}, 0)$, we shall consider the following problem

$$\varepsilon^2 \bigtriangleup \tilde{u} + \left(1 + V(\tilde{r}, \tilde{y}_3) - |\tilde{u}|^2\right) \tilde{u} = 0, \quad \tilde{u} \in H^1(\mathbb{R}^3).$$

$$(1.11)$$

Here the new potential V possesses the properties:

$$\frac{\partial V}{\partial \tilde{y}_3}\Big|_{(\tilde{r},0)} = 0, \qquad \frac{\partial V}{\partial \tilde{r}}\Big|_{(0,\tilde{y}_3)} = 0, \qquad V(\tilde{r}_{1\varepsilon},0) = 0, \qquad \frac{\partial V}{\partial \tilde{r}}\Big|_{(\tilde{r}_0,0)} + \frac{d}{\tilde{r}_0} = 0, \tag{1.12}$$

and also

$$1 + V(\tilde{r}, \tilde{y}_3) = 0,$$

along the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \tilde{r}_{2\varepsilon}$.

The main object of this paper is to construct a solution to problem (1.11) with a stationary vortex ring approaching the circle $(\tilde{r}_0, 0)$ in the (\tilde{r}, \tilde{y}_3) coordinates. The result reads:

Theorem 1.3. For ε sufficiently small, there exists an axially symmetric solution to problem (1.11) in the form $u = u(|\tilde{y}'|, \tilde{y}_3) \in C^{\infty}(\mathbb{R}^3, \mathbb{C})$ with a stationary vortex ring of degree +1 locating at the circle $(|\tilde{y}'|, \tilde{y}_3) = (a_{\varepsilon}, 0)$, where $a_{\varepsilon} \sim \tilde{r}_0$. More precisely, the solution u posses the following asymptotic profile

$$u(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) \sim \begin{cases} w\left(\frac{\tilde{\rho}}{\varepsilon}\right) e^{i\varphi_0^+}, & \tilde{y} \in \mathcal{D}_2 = \{\tilde{\rho} < \tau_0\}, \\ \sqrt{1 + V(\tilde{r}, \tilde{y}_3)} e^{i\varphi_0^+}, & \tilde{y} \in \mathcal{D}_1 = \{\tilde{\ell} < \tilde{r}_{2\varepsilon} - \tau_1\} \setminus \mathcal{D}_2 \\ \delta_{\varepsilon}^{1/3} q\left(\delta_{\varepsilon}^{1/3} \frac{\tilde{\ell} - \tilde{r}_{2\varepsilon}}{\varepsilon}\right) e^{i\varphi_0^+}, & \tilde{y} \in \mathcal{D}_3 = \{\tilde{\ell} > \tilde{r}_{2\varepsilon} - \tau_1\}, \end{cases}$$

where we have denoted

$$\tilde{\rho} = \sqrt{\tilde{y}_1^2 + \tilde{y}_2^2 + \tilde{y}_3^2 - \tilde{r}_{1\varepsilon}^2}, \qquad \tilde{\ell} = \sqrt{\tilde{y}_1^2 + \tilde{y}_2^2 + \tilde{y}_3^2}, \qquad \delta_{\varepsilon} = -\varepsilon \frac{\partial V}{\partial \tilde{\ell}}\Big|_{(\tilde{r}_{2\varepsilon}, 0)} > 0,$$

and $\varphi_0^+(\tilde{y}_1, \tilde{y}_2, \tilde{y}_3) = \varphi_0^+(\tilde{r}, \tilde{y}_3)$ is the angle argument of the vector $(\tilde{r} - \tilde{r}_{1\varepsilon}, \tilde{y}_3)$ in the (\tilde{r}, \tilde{y}_3) plane. Here q is the function defined by Lemma 2.4. **Remark 1.4.** Due to the assumption (A3), in the region \mathcal{D}_1 we use the classical Thomas-Fermi approximation to describe the wave function. The reader can refer to then monograph [49] for more discussions. For the asymptotic behavior of u in \mathcal{D}_3 , there are also some formal expansions in physical works such as [42] and [23]. Here we use q in Lemma 2.4 to describe the profile beyond the Thomas-Fermi approximation.

We now consider the problem (1.2) for the case $\kappa \neq 0$. We assume that the real function \tilde{V} in (1.2) has the following two properties (**P2**) and (**P3**), as well as (A1). (**P2**): There is a point \hat{r}_0 such that

$$\frac{\partial \tilde{V}}{\partial \tilde{r}}\Big|_{(\hat{r}_0,0)} + \frac{d}{\hat{r}_0} \neq 0 \quad and \quad \frac{\partial \tilde{V}}{\partial \tilde{r}}\Big|_{(\hat{r}_0,0)} < 0, \tag{1.13}$$

where d is a positive constant defined in (1.5). We also assume that \hat{r}_0 is non-degenerate in the sense that

$$\frac{\partial^2 \tilde{V}}{\partial \tilde{r}^2}\Big|_{(\hat{r}_0,0)} - \frac{d}{\hat{r}_0^2} \neq 0.$$
(1.14)

Then we set the parameter κ by the relation (c.f. (7.35))

$$\frac{\partial \tilde{V}}{\partial \tilde{r}}\Big|_{(\hat{r}_0,0)} + \frac{d}{\hat{r}_0} = \kappa d.$$
(1.15)

We assume that the vortex ring is characterized by the curve

$$\sqrt{\tilde{y}_1^2 + \tilde{y}_2^2} = \hat{r}_0 + \hat{f} \equiv \hat{r}_{1\varepsilon}, \quad \tilde{y}_3 = 0,$$
(1.16)

where \hat{f} is a parameter of order $O(\varepsilon)$ to be determined in the reduction procedure. (P3): There also exists a number $\hat{r}_{2\varepsilon}$ with $\hat{r}_{2\varepsilon} - \hat{r}_{1\varepsilon} = \hat{\tau}_0 + O(\varepsilon)$ such that the following conditions

$$1 + \left(\tilde{V}(\tilde{r}, \tilde{y}_3) - \tilde{V}(\hat{r}_{1\varepsilon}, 0)\right) = 0, \quad \tilde{V}'(\tilde{r}, \tilde{y}_3) < 0, \quad \tilde{V}''(\tilde{r}, \tilde{y}_3) \le 0, \tag{1.17}$$

hold along the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \hat{r}_{2\varepsilon}$. In the above, $\hat{\tau}_0$ is a universal positive constant independent of ε and the derivatives were taken with respect to the outer normal of the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \hat{r}_{2\varepsilon}$. We also assume that

$$1 + \left[\tilde{V}(\tilde{r}, \tilde{y}_{3}) - \tilde{V}(\hat{r}_{1\varepsilon}, 0)\right] \ge \hat{c}_{1}, \quad if \sqrt{\tilde{r}^{2} + \tilde{y}_{3}^{2}} \in \left(0, \, \hat{r}_{2\varepsilon} - \hat{\tau}_{1}\right), \\ 1 + \left[\tilde{V}(\tilde{r}, \tilde{y}_{3}) - \tilde{V}(\hat{r}_{1\varepsilon}, 0)\right] \le -\hat{c}_{2}, \quad if \sqrt{\tilde{r}^{2} + \tilde{y}_{3}^{2}} \in (\hat{r}_{2\varepsilon} + \hat{\tau}_{2}, +\infty),$$

$$(1.18)$$

for some positive constants $\hat{c}_1, \hat{c}_2, \hat{\tau}_1$ and $\hat{\tau}_2$.

By setting

$$\nu_{\varepsilon} = 1 - \tilde{V}(\hat{r}_{1\varepsilon}, 0), \qquad (1.19)$$

to problem (1.2) and then defining $\check{V}(\tilde{r}, \tilde{y}_3) = \tilde{V}(\tilde{r}, \tilde{y}_3) - \tilde{V}(\hat{r}_{1\varepsilon}, 0)$, we shall consider the following problem

$$\varepsilon^2 \bigtriangleup \tilde{u} + \left(1 + \check{V}(\tilde{r}, \tilde{y}_3) - |\tilde{u}|^2\right) \tilde{u} + i\varepsilon^2 |\log \varepsilon| \kappa \frac{\partial \tilde{u}}{\partial \tilde{y}_3} = 0, \quad \tilde{u} \in H^1(\mathbb{R}^3).$$
(1.20)

Here the new potential \check{V} possesses the properties:

$$\frac{\partial \check{V}}{\partial \tilde{y}_3}\Big|_{(\tilde{r},0)} = 0, \quad \frac{\partial \check{V}}{\partial \tilde{r}}\Big|_{(0,\tilde{y}_3)} = 0, \quad \check{V}(\hat{r}_{1\varepsilon},0) = 0, \quad \frac{\partial \check{V}}{\partial \tilde{r}}\Big|_{(\hat{r}_0,0)} + \frac{d}{\hat{r}_0} = \kappa \, d, \tag{1.21}$$

and also

$$1 + \dot{V}(\tilde{r}, \tilde{y}_3) = 0,$$

along the circle $\sqrt{\tilde{r}^2 + \tilde{y}_3^2} = \hat{r}_{2\varepsilon}$.

The main object of the last section is to construct a solution to problem (1.20) with a traveling vortex ring approaching the circle $(\hat{r}_0, 0)$ in the (\tilde{r}, \tilde{y}_3) coordinates.

Theorem 1.5. For ε sufficiently small, there exists an axially symmetric solution of problem (1.20) with the form $u = u(|\tilde{y}'|, \tilde{y}_3) \in C^{\infty}(\mathbb{R}^3, \mathbb{C})$ possessing a traveling vortex ring of degree +1 locating at $(|\tilde{y}'|, \tilde{y}_3) = (\hat{a}_{\varepsilon}, 0)$, where $\hat{a}_{\varepsilon} \sim \hat{r}_0$. The profile of u is the same as the solution in Theorem 1.3.

Remark 1.6. In both theorems, the solutions we have constructed satisfy

$$\int_{\mathbb{R}^3} (|\nabla \tilde{u}|^2 + |\tilde{u}|^2) < +\infty.$$
(1.22)

Thus the asymptotic behavior of the solutions is quite different from those constructed with constant trapping potential ([11]). The reason for this is clear: because of the trapping potential, there exists a vortexless solution satisfying (1.22). Outside the vortex our solutions behaves like this vortexless solution. A major difficulty (or problem) is the matching of vortex solution with vortexless solution. \Box

The remaining part of this paper is devoted to the complete proof of Theorem 1.3 and Theorem 1.5. The organization is as follows: in section 2, we give some preliminary results. Sections 3-6 are devoted to the proof of Theorem 1.3, with arguments on details, while we sketch the similar proof for Theorem 1.5 in Section 7.

2. Preliminaries

By (ℓ, φ) designating the usual polar coordinates $s_1 = \ell \cos \varphi$, $s_2 = \ell \sin \varphi$, we introduce the standard vortex block solution

$$U_0(s_1, s_2) = w(\ell)e^{i\varphi}, \qquad (2.1)$$

with degree +1 in the whole plane, where $w(\ell)$ is the unique solution of the problem

$$w'' + \frac{1}{\ell}w' - \frac{1}{\ell^2}w + (1 - |w|^2)w = 0 \quad \text{for } \ell \in (0, +\infty), \quad w(0) = 0, \quad w(+\infty) = 1.$$
 (2.2)

The properties of the function w are stated in the following lemma.

Lemma 2.1. There hold the following properties: (1) w(0) = 0, w'(0) > 0, $0 < w(\ell) < 1$, $w'(\ell) > 0$ for all $\ell > 0$, (2) $w(\ell) = 1 - \frac{1}{2\ell^2} + O(\frac{1}{\ell^4})$ for large ℓ , (3) $w(\ell) = k\ell - \frac{k}{8}\ell^3 + O(\ell^5)$ for ℓ close to 0, (4) Define $T = \frac{dw}{d\ell} - \frac{w}{\ell}$, then T < 0 in $(0, +\infty)$. **Proof.** Partial proof of this lemma can be found in [14] and the references therein.

We introduce the bilinear form

$$\mathcal{B}(\phi,\phi) = \int_{\mathbb{R}^2} |\nabla \phi|^2 - \int_{\mathbb{R}^2} (1-w^2) |\phi|^2 + 2 \int_{\mathbb{R}^2} |\operatorname{Re}(\bar{U}_0\phi)|^2,$$
(2.3)

defined in the natural space \mathcal{H} of all locally- H^1 functions with

$$||\phi||_{\mathcal{H}} = \int_{\mathbb{R}^2} |\nabla \phi|^2 - \int_{\mathbb{R}^2} (1 - w^2) |\phi|^2 + 2 \int_{\mathbb{R}^2} |\operatorname{Re}(\bar{U}_0 \phi)|^2 < +\infty.$$
(2.4)

Let us consider, for a given ϕ , its associated ψ defined by the relation

$$\phi = iU_0\psi. \tag{2.5}$$

Then we decompose ψ by the form

$$\psi = \psi_0(\ell) + \sum_{m \ge 1} \left[\psi_m^1 + \psi_m^2 \right],$$
(2.6)

where we have denoted

$$\begin{split} \psi_0 &= \psi_{01}(\ell) + i\psi_{02}(\ell), \\ \psi_m^1 &= \psi_{m1}^1(\ell)\cos(m\vartheta) + i\psi_{m2}^1(\ell)\sin(m\vartheta), \\ \psi_m^2 &= \psi_{m1}^2(\ell)\sin(m\vartheta) + i\psi_{m2}^2(\ell)\cos(m\vartheta). \end{split}$$

This bilinear form is non-negative, as it follows from various results in [8, 13, 45, 46, 55], see also [18, 47]. The nondegeneracy of U_0 is contained in the following lemma, whose proof can be found in the appendix of [19].

Lemma 2.2. There exists a constant C > 0 such that if $\phi \in \mathcal{H}$ decomposes like in (2.5)-(2.6) with $\psi_0 \equiv 0$, and satisfies the orthogonality conditions

$$\operatorname{Re} \int_{B(0,1/2)} \bar{\phi} \, \frac{\partial U_0}{\partial s_l} = 0, \quad l = 1, 2.$$

then there holds

$$\mathcal{B}(\phi,\phi) \ge C \int_{\mathbb{R}^2} \frac{|\phi|^2}{1+\ell^2}.$$

The linear operator L_0 corresponding to the bilinear form \mathcal{B} can be defined by

$$L_0(\phi) = \left(\frac{\partial^2}{\partial s_1^2} + \frac{\partial^2}{\partial s_2^2}\right)\phi + (1 - |w|^2)\phi - 2\operatorname{Re}\left(\bar{U}_0\phi\right)U_0.$$

The nondegeneracy of U_0 can be also stated as following lemma, whose proof can be found in [18].

Lemma 2.3. Suppose that $L_0[\phi] = 0$ with $\phi \in \mathcal{H}$, then

$$\phi = c_1 \frac{\partial U_0}{\partial s_1} + c_2 \frac{\partial U_0}{\partial s_2},\tag{2.7}$$

for some real constants c_1, c_2 .

To construct approximate solution in Section 3, we also prepare the following lemma.

Lemma 2.4. There exists a unique solution q to the following problem

$$q'' - q(\ell + q^2) = 0 \quad on \mathbb{R},$$

$$(2.8)$$

such that the properties hold

$$\begin{aligned} q(\ell) &> 0 \quad \text{for all } \ell \in \mathbb{R}, \qquad q'(\ell) < 0 \quad \text{for any } \ell > 0, \\ q(\ell) &\sim \exp\left(-\ell^{3/2}\right) \quad as \; \ell \to +\infty, \qquad q(\ell) \sim \sqrt{-\ell} \quad as \; \ell \to -\infty. \end{aligned}$$

Proof. We first prove the existence by sub-super solution method. To this end, we set

$$q_1(\ell) = \delta \exp(-4\ell - \ell^2/2).$$

By choosing δ such that $11 - 4\delta^2 e^{16} = 0$, we obtain

$$q_1'' - q_1(\ell + q_1^2) = \delta \exp(-4\ell - \ell^2/2) \Big[\ell^2 + 7\ell + 15 - \delta^2 \exp(-8\ell - \ell^2) \Big]$$

$$\geq \delta \exp(-4\ell - \ell^2/2) \Big[\frac{11}{4} - \delta^2 e^{16} \Big] = 0.$$

We also let $q_2(\ell) = \exp(-\ell/2)$. Then it is easy to derive that

$$q_2'' - q_2(\ell + q_2^2) = \exp(-\ell/2) \left[\frac{1}{4} - \ell - \exp(-\ell)\right] \le 0.$$

Note that q_1 is a subsolution, while q_2 is a supersolution with the property $q_1 \leq q_2$. By standard elliptic theory, there exists a positive solution to (2.8) with the property

$$q(\ell) \to 0 \text{ as } \ell \to +\infty, \quad q(\ell) \to \infty \text{ as } \ell \to -\infty.$$

It is easy to check that $q'(\ell) < 0$ as $\ell \to +\infty$. Moreover, there exists a sequence of $\{\ell_n\}_n$ approaching $-\infty$ such that $q'(\ell_n) < 0$. Now, we claim that $q'(\ell) < 0$ for all $\ell \in \mathbb{R}$. Suppose it is not the case, i.e. $q'(\ell_0) > 0$ for some point ℓ_0 . Then there exists an interval (a, b) such that

$$q'(a) = q'(b) = 0, \ q'(\ell) > 0 \text{ for } \ell \in (a, b).$$

We further define the function $\mathfrak{g} = q'/q$ on (a, b). There still holds

$$\mathfrak{g}(a) = \mathfrak{g}(b) = 0, \ \mathfrak{g}(\ell) > 0 \text{ for } \ell \in (a, b).$$

Hence, \mathfrak{g} attains a local positive maximum at $\ell_* \in (a, b)$ with $\mathfrak{g}'(\ell_*) = 0$. By using the inequality

$$q''' - q'(\ell + q^2) = 2q^2q' + q > 0$$
 on (a, b) ,

we have $\mathfrak{g}''(\ell_*) > 0$. It is a contradiction with the fact that ℓ_* is a local maximum point of \mathfrak{g} .

Let \bar{q}_1 and \bar{q}_2 be two solutions of (2.8). We claim that $\bar{q}_1 = \bar{q}_2$. In fact, the previous argument shows that either $\bar{q}_1 > \bar{q}_2$ or $\bar{q}_1 < \bar{q}_2$. Without loss of generality, we assume that $\bar{q}_1 > \bar{q}_2$. Let $v = \bar{q}_1 - \bar{q}_2$. Then there holds

$$v'' - v\left(\ell + \bar{q}_1^2 + \bar{q}_1\bar{q}_2 + \bar{q}_2^2\right) = 0.$$

Now we also consider $\bar{v} = \frac{v}{\bar{q}_1}$. There also hold

$$\bar{v}'' + \frac{2\bar{q}'_1}{\bar{q}_1}\bar{v}' - \bar{v}\big(\bar{q}_1\bar{q}_2 + \bar{q}_2^2\big) = 0.$$
(2.9)

It is easy to see that $\bar{v}(\ell) \to 0$ as $\ell \to -\infty$. So $\bar{v}' > 0$ and $\bar{v} \to C_0$ as $\ell \to +\infty$. From (2.9), we have $\bar{v}'' > 0$. It contradicts with the fact $\bar{v}'(\ell) \to 0$ as $\ell \to \pm\infty$. The uniqueness is also proved.

3. Outline of the proof and approximate solutions

By using the symmetry, we will first transfer the problem (1.11) to a two dimensional case in form (3.3)-(3.4) and then give an outline of the proof for Theorem 1.3. The main object of this section will focus on the construction a good approximate solution in a suitable form and then estimate its error.

3.1. The reduction of the problem

Making rescaling $\tilde{y} = \varepsilon \hat{y}$, problem (1.11) takes the form

$$\Delta u + \left(1 + V(\varepsilon \hat{y}) - |u|^2\right)u = 0.$$
(3.1)

Introduce a new coordinates $(r, \theta, \hat{y}_3) \in (0, +\infty) \times (0, 2\pi] \times \mathbb{R}$ as the form

$$\hat{y}_1 = r\cos\theta, \quad \hat{y}_2 = r\sin\theta, \quad \hat{y}_3 = \hat{y}_3.$$

Then problem (3.1) takes the form

$$S[u] = \left(\frac{\partial^2}{\partial r^2} + \frac{\partial^2}{\partial \hat{y}_3^2} + \frac{1}{r^2}\frac{\partial^2}{\partial \theta^2} + \frac{1}{r}\frac{\partial}{\partial r}\right)u + \left(1 + V(\varepsilon r, \varepsilon \hat{y}_3) - |u|^2\right)u = 0.$$
(3.2)

In this paper, we want to construct a solution with a vortex ring, which does not depend on the variable θ . Hence, we consider a two-dimensional problem, for $(x_1, x_2) \in \mathbb{R}^2$

$$S[u] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)u + \left(1 + V(\varepsilon|x_1|, \varepsilon x_2) - |u|^2\right)u = 0, \tag{3.3}$$

with Neumann boundary condition

$$\frac{\partial u}{\partial x_1}(0, x_2) = 0, \quad |u| \to 0 \text{ as } |x| \to +\infty.$$
(3.4)

Notations: For further convenience, we have used x_1, x_2 to denote r, \hat{y}_3 in the above equations, and also $x = (x_1, x_2), \ \ell = |x|$ in the sequel. In this rescaled coordinates, we write

$$r_{1\varepsilon} = \tilde{r}_{1\varepsilon}/\varepsilon = \tilde{r}_0/\varepsilon + f \quad with \ f = \tilde{f}/\varepsilon, \qquad r_{2\varepsilon} = \tilde{r}_{2\varepsilon}/\varepsilon, \tag{3.5}$$

where the constants \tilde{f} , $\tilde{r}_{1\varepsilon}$ and $\tilde{r}_{2\varepsilon}$ are defined in (1.7) and (1.8). By setting, $\xi_{+} = (r_{1\varepsilon}, 0)$ and $\xi_{-} = (-r_{1\varepsilon}, 0)$, we also introduce the translated variable

$$s = x - \xi_+$$
 or $s = x - \xi_-$, (3.6)

in a small neighborhood of the vortices. We will use these notations without any further statement in the sequel. $\hfill \Box$

To handle the influence of the potential, we here look for vortex ring solutions vanishing as |x| approaching $+\infty$. As we stated in (1.7), we assume that the vortex ring is characterized by the curve, in the original coordinates $\hat{y} = (\hat{y}_1, \hat{y}_2, \hat{y}_3)$

$$\sqrt{\hat{y}_1^2 + \hat{y}_2^2} = r_0/\varepsilon + f = r_{1\varepsilon}, \quad \hat{y}_3 = 0.$$
(3.7)

In other words, in the two dimensional situation with (x_1, x_2) coordinates, we will construct a vortex with degree +1 at $(r_{1\varepsilon}, 0)$ and its anti-pair with degree -1 at $(-r_{1\varepsilon}, 0)$.

Finally, we decompose the operator as

$$S[u] \equiv S_0[u] + S_1[u], \tag{3.8}$$

with the explicit form

$$S_0[u] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)u, \quad S_1[u] \equiv \left(1 + V(\varepsilon|x_1|, \varepsilon x_2) - |u|^2\right)u.$$
(3.9)



Figure 1: Decomposition of Domain: $D_2 = \bigcup_{j=1}^4 D_{2,j}$, $D_3 = D_{3,1} \cup D_{3,2}$. The components of D_2 center at ξ_+ or ξ_- .

3.2. Outline of the Proof

To construct a solution to (3.3)-(3.4) and prove the result in Theorem 1.3, the first step is to construct an approximate solution, denoted by u_2 in (3.34), possessing a pair of vortices with degree ± 1 locating at $\xi_+ = (r_{1\varepsilon}, 0)$ and $\xi_- = (-r_{1\varepsilon}, 0)$. The heuristic method is to find suitable approximations in different regions and then patch them together. So we decompose the plane into different regions D_1, D_2, D_3 as in (3.13), see Figure 1. Note that the components of D_2 center at ξ_+ or ξ_- . The first approximation u_1 to a solution has a profile of a pair of standard vortices in D_2 , which possess the degrees ± 1 and centers ξ_+ and ξ_- , see (3.14). Then in D_1 we set u_1 by Thomas-Fermi approximation in form (3.15) and make a trivial extension to the region D_3 .

Now there are two types of singularities caused by the phase term of standard vortices and the Thomas-Fermi approximation, which will be described in subsection 3.3. In fact, to cancel the singularity caused by $\frac{1}{x_1} \frac{\varphi_0}{\partial x_1}$ with the standard phase φ_0 in (3.14) we here add one more correction term φ_1 in (3.21) to the pase component as the work [41]. Moreover, by some type of rescaling, in D_3 we use q in Lemma 2.4 as a bridge when |x| crossing $r_{2\varepsilon}$ and then reduce the norm of the approximate solution to zero as |x| tends to ∞ . Finally we get the approximate solution u_2 in (3.34), which has the symmetry

$$u_2(x_1, x_2) = \overline{u_2(x_1, -x_2)}, \qquad u_2(x_1, x_2) = u_2(-x_1, x_2).$$
 (3.10)

These are done in subsections 3.3 and 3.4. The subsection 3.5 is devoted to estimation of the errors in suitable weighted norms. The reader can refer to the papers [19] and [41].

To get explicit information of the linearized problem, we then also divide further D_2 and D_3 into small parts in (4.8), see Figure 1. In section 4, we then express the error and formulate the problem in suitable local forms in different regions by the method in [19]. More precisely, for the perturbation $\psi = \psi_1 + i\psi_2$ with symmetry (4.5), we take the solution u in form (4.4). The

key points that we shall mention are the roles of local forms of the linearized problem for further deriving of the linear resolution theory in section 5. In D_1 , the linear operators have approximate forms, (c.f. (4.12))

$$\begin{split} \tilde{L}_1(\psi_1) &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_1 + \frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \bigtriangledown \psi_1, \\ \bar{L}_1(\psi_2) &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_2 - 2|u_2|^2\psi_2 + \frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \bigtriangledown \psi_2. \end{split}$$

The type of the linear operator \tilde{L}_1 was handled in [41], while \bar{L}_1 is a good operator since $|u_2|$ stays uniformly away from 0 in D_1 by the assumption (A3), see (4.10). In the vortex core regions $D_{2,1}$ and $D_{2,2}$, we use a type of symmetry (3.10) to deal with the kernel of the linear operator related to the standard vortex. In $D_{3,1}$, the lowest approximations of the linear operators are, (c.f. (4.34))

$$L_{31*}(\psi_1) = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 - (z + q^2(z))\psi_1,$$

$$L_{31**}(\psi_2) = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - (z + 3q^2(z))\psi_2.$$

By Lemma 2.4, the facts that $L_{31*}(q) = 0$ and $L_{31**}(-q') = 0$ with -q' > 0 and q > 0 on \mathbb{R} will give the application of maximum principle. The linear operators in the region $D_{3,2}$ can be approximated by a good linear operator of the form, (c.f.(4.39))

$$L_{32*}[\tilde{\psi}] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\tilde{\psi} + (1+V)\tilde{\psi},$$

with $(1 + V) < -c_2 < 0$ by the assumption (A3). For more details, the reader can refer to proof of Lemma 5.1.

After deriving the linear resolution theory by Lemmas 5.1 and 5.2, and then solving the nonlinear projected problem (4.41) in section 5, as the standard reduction method we adjust the parameter \tilde{f} to get a solution with a vortex ring in Theorem 1.3. It is showed in section 6 that this is equivalent to solve the following algebraic equation, (c.f. (6.5))

$$c(\tilde{f}) = -2\varepsilon\pi \left[\left. \frac{\partial V}{\partial \tilde{r}} \right|_{(\tilde{r}_0 + \tilde{f}, 0)} \log \frac{1}{\varepsilon} + \frac{d}{\tilde{r}_0 + \tilde{f}} \log \frac{\tilde{r}_0 + \tilde{f}}{\varepsilon} \right] + O(\varepsilon), \tag{3.11}$$

where $O(\varepsilon)$ is a continuous function of the parameter \tilde{f} . By the solvability condition (1.4) and the non-degeneracy condition (1.6), we can find a zero of $c(\tilde{f})$ at some small \tilde{f} with the help of the simple mean-value theorem.

However, to prove Theorem 1.5 in section 7, we need to solve the equation, (c.f.(7.35))

$$c(\hat{f}) = -2\pi\varepsilon \left[\frac{\partial\check{V}}{\partial\tilde{r}} \Big|_{(\hat{r}_0 + \hat{f}, 0)} \log \frac{1}{\varepsilon} + \frac{d}{\hat{r}_0 + \hat{f}} \log \frac{\hat{r}_0 + \hat{f}}{\varepsilon} - d\kappa \log \frac{1}{\varepsilon} \right] + O(\varepsilon),$$

where $O(\varepsilon)$ is a continuous function of the parameter \hat{f} . By simple mean-value theorem and the solvability condition (1.13) and the non-degeneracy condition (1.14), we can find a zero of $c(\hat{f})$ at some small \hat{f} .

3.3. First approximate solution

For any given $(x_1, x_2) \in \mathbb{R}^2$, let $\varphi_0^+(x_1, x_2)$ and $\varphi_0^-(x_1, x_2)$ be respectively the angle arguments of the vectors $(x_1 - r_{1\varepsilon}, x_2)$ and $(x_1 + r_{1\varepsilon}, x_2)$ in the (x_1, x_2) plane. We also let

$$\ell_2(x_1, x_2) = \sqrt{(x_1 - r_{1\varepsilon})^2 + x_2^2}, \quad \ell_1(x_1, x_2) = \sqrt{(x_1 + r_{1\varepsilon})^2 + x_2^2}$$
(3.12)

be the distance functions between the point (x_1, x_2) and the pair of vortices of degree ± 1 at the points ξ_+ and ξ_- . In this subsection, we only consider the case for $x_1 > 0$ because of the symmetry of the problem. We decompose the plane into different regions D_1, D_2 and D_3 in the following form, see Figure 1

$$D_{2} \equiv \left\{ (x_{1}, x_{2}) : \ell_{1} < \frac{\tau_{0}}{\varepsilon} \text{ or } \ell_{2} < \frac{\tau_{0}}{\varepsilon} \right\},$$

$$D_{1} \equiv \left\{ (x_{1}, x_{2}) : |x| < r_{2\varepsilon} - \frac{\tau_{1}}{\varepsilon} \right\} \setminus D_{2},$$

$$D_{3} \equiv \left\{ (x_{1}, x_{2}) : |x| > r_{2\varepsilon} - \frac{\tau_{1}}{\varepsilon} \right\}.$$
(3.13)

Here τ_0 and τ_1 are given in the assumption (A3). Recalling the definition of the standard vortex of degree +1 in (2.1), then it can be roughly done as follows:

(1) If $(x_1, x_2) \in D_2$, we choose u_1 by

$$u_1(x_1, x_2) = U_2(x_1, x_2) \equiv w(\ell_2)w(\ell_1)e^{i\varphi_0}, \qquad (3.14)$$

where the phase term φ_0 is defined by $\varphi_0 = \varphi_0^+ - \varphi_0^-$. (2) If $(x_1, x_2) \in D_1$, we write

$$u_1(x_1, x_2) = U_1(x_1, x_2) \equiv \sqrt{1 + V(\varepsilon |x_1|, \varepsilon x_2)} e^{i\varphi_0}.$$
(3.15)

The choice of u_1 here is well defined due to the assumption (A3). Here we use the standard Thomas-Fermi approximation, see [49].

(3) As we have stated that we look for solutions vanishing at infinity, so we heuristically define $u_1 = \tilde{U}_3 \equiv 0$ for $(x_1, x_2) \in D_3$,.

For further improvement of the approximation, it is crucial to evaluate the error of this approximation, which will be carried out as follows. Obviously, there hold the trivial formulas

$$\nabla_{x_1,x_2} w(\ell_2) = \frac{w'(\ell_2)}{\ell_2} (x_1 - r_{1\varepsilon}, x_2), \qquad \nabla_{x_1,x_2} w(\ell_1) = \frac{w'(\ell_1)}{\ell_1} (x_1 + r_{1\varepsilon}, x_2),$$

$$\nabla_{x_1,x_2} \varphi_0(x_1, x_2) = \left(\frac{-x_2}{(\ell_2)^2} + \frac{x_2}{(\ell_1)^2}, \ \frac{x_1 - r_{1\varepsilon}}{(\ell_2)^2} - \frac{x_1 + r_{1\varepsilon}}{(\ell_1)^2} \right).$$
(3.16)

As we have stated, we work directly in the half space $\mathbb{R}^2_+ = \{(x_1, x_2) : x_1 > 0\}$ in the sequel because of the symmetry of the problem.

Firstly, we estimate the error near the vortex ring. Note that for $x_1 > 0$, the error between 1 and $w(\ell_1)$ is $(\ell_1)^2$, which is of order ε^2 , we may ignore $w(\ell_1)$ in the computations below. Note that

$$S_{0}[U_{2}] = S_{0}[w(\ell_{1})]w(\ell_{2})e^{i\varphi_{0}} + S_{0}[w(\ell_{2})]w(\ell_{1})e^{i\varphi_{0}} + 2e^{i\varphi_{0}}\nabla w(\ell_{2})\cdot\nabla w(\ell_{1}) - U_{2}|\nabla\varphi_{0}|^{2} + iS_{0}[\varphi_{0}]U_{2} + 2ie^{i\varphi_{0}}\nabla \Big(w(\ell_{2})w(\ell_{1})\Big)\cdot\nabla\varphi_{0}.$$

Then, there holds

$$\begin{split} S_0 \big[w(\ell_1) \big] \, w(\ell_2) e^{i\varphi_0} \, + \, S_0 \big[w(\ell_2) \big] \, w(\ell_1) e^{i\varphi_0} \, - \, U_2 \big| \nabla \varphi_0 \big|^2 \\ &= \Big[\, w''(\ell_1) \, + \, \frac{1}{\ell_1} w'(\ell_1) \, - \, \frac{1}{(\ell_1)^2} w(\ell_1) \Big] \, \frac{U_2}{w(\ell_1)} \, + \, \frac{x_1 - d_1}{x_1 \ell_1} w'(\ell_1) \frac{U_2}{w(\ell_1)} \\ &+ \, \Big[\, w''(\ell_2) \, + \, \frac{1}{\ell_2} w'(\ell_2) \, - \, \frac{1}{(\ell_2)^2} w(\ell_2) \Big] \, \frac{U_2}{w(\ell_2)} \, + \, \frac{x_1 - d_2}{x_1 \ell_2} w'(\ell_2) \frac{U_2}{w(\ell_2)} \\ &- \, 2U_2 \frac{x_2^2 + (x_1 - r_{1\varepsilon})(x_1 + r_{1\varepsilon})}{(\ell_1)^2 (\ell_2)^2} \,, \end{split}$$

and also

$$2e^{i\varphi_0}\nabla w(\ell_2)\cdot\nabla w(\ell_1) = 2U_2\frac{x_2^2 + (x_1 - r_{1\varepsilon})(x_1 + r_{1\varepsilon})}{\ell_1\ell_2}\frac{w'(\ell_1)}{w(\ell_1)}\frac{w'(\ell_2)}{w(\ell_2)} = O(\varepsilon^2).$$

Note that $\nabla w(\ell_2) \cdot \nabla \varphi_0^+ = 0$ and $\nabla w(\ell_1) \cdot \nabla \varphi_0^- = 0$. By the formulas in (3.16), we get

$$2ie^{i\varphi_0}\nabla\left(w(\ell_2)w(\ell_1)\right)\cdot\nabla\varphi_0$$

= $2ie^{i\varphi_0}\nabla w(\ell_2)\cdot\nabla\varphi_0^- + 2ie^{i\varphi_0}\nabla w(\ell_1)\cdot\nabla\varphi_0^+ + O(\varepsilon^2)$
= $-4iU_2\frac{x_2r_{1\varepsilon}}{\ell_1(\ell_2)^2}\frac{w'(\ell_1)}{w(\ell_1)} - 4iU_2\frac{x_2r_{1\varepsilon}}{\ell_2(\ell_1)^2}\frac{w'(\ell_2)}{w(\ell_2)} + O(\varepsilon^2)$
= $O(\varepsilon^2).$

Recall that

$$\frac{\partial V}{\partial \tilde{y}_3}\Big|_{(\tilde{r},0)} = 0$$

In a small neighborhood of the point $(\tilde{r}_{1\varepsilon}, 0) = (\varepsilon r_{1\varepsilon}, 0)$, by Taylor expansion we also write $V(\varepsilon |x_1|, \varepsilon x_2)$ as the form

$$V(\varepsilon|x_1|,\varepsilon x_2) = \varepsilon \frac{\partial V}{\partial \tilde{r}}\Big|_{(\varepsilon r_{1\varepsilon},0)}(x_1 - r_{1\varepsilon}) + \varepsilon^2 O(\ell_2^2),$$

where we have used the assumption (1.12). It is easy to derive that

$$S_1[U_2] = \left(1 + V - |U_2|^2\right)U_2 = \left(1 - |w(\ell_2)|^2\right)U_2 + \varepsilon U_2 \frac{\partial V}{\partial \tilde{r}}\Big|_{(\varepsilon r_{1\varepsilon}, 0)}(x_1 - r_{1\varepsilon}) + \varepsilon^2 O(\ell_2^2)U_2.$$

By using the equation (2.2), the error, near the vortex ring, takes the form

$$S[U_2] = U_2 \frac{x_1 - r_{1\varepsilon}}{x_1 \ell_2} \frac{w'(\ell_2)}{w(\ell_2)} + iS_0[\varphi_0] U_2 + U_2 \Big[\varepsilon \frac{\partial V}{\partial \tilde{r}} \Big|_{(\varepsilon r_{1\varepsilon}, 0)} (x_1 - r_{1\varepsilon}) + \varepsilon^2 O(\ell_2^2) \Big]$$

$$\equiv F_{21} + F_{22}.$$

$$(3.17)$$

In the above, we have denoted the term ${\cal E}_{21}$ by

$$F_{21} \equiv iS_0[\varphi_0] U_2 = iU_2 \frac{1}{x_1} \frac{\partial \varphi_0}{\partial x_1} = -iU_2 \frac{4x_2 r_{1\varepsilon}}{(\ell_2)^2 (\ell_1)^2}, \qquad (3.18)$$

which is a singular term. Whence we need a further correction to improve the approximation.

Secondly, we compute the error for U_1 . There holds

$$\frac{\partial}{\partial x_1}\sqrt{1+V(\varepsilon|x_1|,\varepsilon x_2)} = \frac{\varepsilon}{2}(1+V)^{-1/2}\frac{\partial V}{\partial \tilde{r}},$$

$$\frac{\partial^2}{\partial x_1^2}\sqrt{1+V(\varepsilon|x_1|,\varepsilon x_2)} = -\frac{\varepsilon^2}{4}(1+V)^{-3/2}\left|\frac{\partial V}{\partial \tilde{r}}\right|^2 + \frac{\varepsilon^2}{2}(1+V)^{-1/2}\frac{\partial^2 V}{\partial \tilde{r}^2}.$$
(3.19)

It is easy to check that the error of U_1 is

$$S[U_1] = S_0[U_1].$$

Note that

$$S_0[U_1] = S_0 \left[\sqrt{1+V} \right] e^{i\varphi_0} + 2i e^{i\varphi_0} \nabla \sqrt{1+V} \cdot \nabla \varphi_0 - \sqrt{1+V} e^{i\varphi_0} \left| \nabla \varphi_0 \right|^2$$

+ $i S_0[\varphi_0] \sqrt{1+V} e^{i\varphi_0}.$

Hence the error is

$$S[U_1] = -\frac{1}{4} \varepsilon^2 \left| \tilde{\nabla} V \right|^2 \frac{U_1}{\left(1+V\right)^2} + \frac{1}{2} \varepsilon^2 \tilde{\Delta} V \frac{U_1}{1+V} - i\varepsilon \frac{U_1}{1+V} \tilde{\nabla} V \cdot \nabla \varphi_0 + U_1 \left| \nabla \varphi_0 \right|^2 + \frac{1}{2} \varepsilon U_1 \frac{1}{x_1} \frac{\partial V}{\partial \tilde{r}} \frac{1}{1+V} + iU_1 S_0[\varphi_0] \equiv F_{11},$$

where we have denoted

$$\tilde{\nabla}V = \left(rac{\partial V}{\partial \tilde{r}}, rac{\partial V}{\partial \tilde{y}_3}
ight), \quad \tilde{\bigtriangleup}V = rac{\partial^2 V}{\partial \tilde{r}^2} + rac{\partial^2 V}{\partial \tilde{y}_3^2}$$

Note that the following term in the above formula

$$iS_0[\varphi_0]U_1 = iU_1 \frac{1}{x_1} \frac{\partial \varphi_0}{\partial x_1} = -iU_1 \frac{4x_2 r_{1\varepsilon}}{(\ell_2)^2 (\ell_1)^2}.$$

is not a singular term. The condition $\left.\frac{\partial V}{\partial \tilde{r}}\right|_{(0,\tilde{y}_3)}=0$ implies that

$$\frac{1}{x_1}\frac{\partial V}{\partial \tilde{r}} = O(\varepsilon).$$

Moreover, in the region D_1 , by the assumption (A3) we have $V \ge c_1 > 0$. Note that the formula in (3.16) implies that $|\nabla \varphi_0|$ is of order $O(\varepsilon)$ in D_1 . Whence, the error is small in the sense that

$$S[U_1] = O(\varepsilon^2). \tag{3.20}$$

On the other hand, if |x| is close to $r_{2\varepsilon}$, then $(1+V)^{-1}$ brings singularity. So we need another correction term to improve the approximation in a neighborhood of the curve $|x| = r_{2\varepsilon}$.

3.4. Further improvement of approximation

To handle the singular term $F_{21} = iS_0[\varphi_0]U_2$, as the argument in [41], we here introduce a further correction $\varphi_1(x_1, x_2)$ to the phase term in form

$$\varphi_1 = \varphi_s + \varphi_r. \tag{3.21}$$

By setting the smooth cut-off function

$$\eta(s) = \begin{cases} 1, & |s| \le 1/10, \\ 0, & |s| \ge 1/5, \end{cases}$$
(3.22)

the singular part φ_s is defined as

$$\varphi_s = \frac{x_2}{4r_{1\varepsilon}} \eta(\varepsilon \ell_2) \log \frac{(\ell_2)^2}{(\ell_1)^2}.$$
(3.23)

Note that the function φ_s is continuous but $\nabla \varphi_s$ is not. The singularity of φ_s comes from its derivatives, which will play an important role in the final reduction procedure.

Remark 3.1. The reader can also refer to formula (16) in [59] for the formal derivation of general type improvement of the phase term. \Box

On the other hand, we choose the regular part φ_r by solving the equation

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\varphi_r = -\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\left(\varphi_0 + \varphi_s\right).$$
(3.24)

It can be done as follows. For further references, we first compute:

$$\frac{\partial \varphi_s}{\partial x_1} = \frac{x_2}{4r_{1\varepsilon}} \varepsilon \eta' (\varepsilon \ell_2) \frac{x - r_{1\varepsilon}}{\ell_2} \log \frac{(\ell_2)^2}{(\ell_1)^2} + \eta (\varepsilon \ell_2) \frac{x_2 [x_1^2 - x_2^2 - (r_{1\varepsilon})^2]}{(\ell_2)^2 (\ell_1)^2},$$
(3.25)
$$\frac{\partial \varphi_s}{\partial x_2} = \frac{x_2}{4r_{1\varepsilon}} \varepsilon \eta' (\varepsilon \ell_2) \frac{x_2}{\ell_2} \log \frac{(\ell_2)^2}{(\ell_1)^2} + \frac{1}{4r_{1\varepsilon}} \eta (\varepsilon \ell_2) \log \frac{(\ell_2)^2}{(\ell_1)^2} + \eta (\varepsilon \ell_2) \log \frac{(\ell_2)^2}{(\ell_1)^2} + \eta (\varepsilon \ell_2) \log \frac{(\ell_2)^2}{(\ell_1)^2}.$$
(3.26)

Trivial computation gives that, for $(x_1, x_2) \in B_{1/10}(r_{1\varepsilon}\vec{e_1})$

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1} \frac{\partial}{\partial x_1} \right) [\varphi_0 + \varphi_s] = \frac{4x_2(x_1 - r_{1\varepsilon})}{(\ell_2)^2 (\ell_1)^2} + \frac{x_2[x_1^2 - x_2^2 - (r_{1\varepsilon})^2]}{x_1 (\ell_2)^2 (\ell_1)^2}$$
$$= O(x_1^{-2}) = O(\varepsilon^2).$$

For $(x_1, x_2) \in (B_{1/5}(r_{1\varepsilon}\vec{e_1}))^c$, the error is also $O(\varepsilon^2)$. In fact, for $(x_1, x_2) \in (B_{1/5}(r_{1\varepsilon}\vec{e_1}))^c$, we have $\varphi_s = 0$ and then

$$\Big(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\Big)[\varphi_0 + \varphi_s] = \frac{-4x_2 r_{1\varepsilon}}{(\ell_2)^2(\ell_1)^2}.$$

Going back to the original variables (\tilde{r}, \tilde{y}_3) and setting $\hat{\varphi}(\tilde{r}, \tilde{y}_3) = \varphi_r(\tilde{r}/\varepsilon, \tilde{y}_3/\varepsilon)$, we see that

$$\left(\frac{\partial^2}{\partial \tilde{r}^2} + \frac{\partial^2}{\partial \tilde{y}_3^2} + \frac{1}{\tilde{r}}\frac{\partial}{\partial \tilde{r}}\right)\hat{\varphi} \le C\left(1 + \tilde{r}^2 + \tilde{y}_3^2\right)^{-3/2}$$

Whence, by solving problem (3.24), we can choose φ_r such that there holds

$$\hat{\varphi} = O\left(\frac{1}{\sqrt{1 + \tilde{r}^2 + \tilde{y}_3^2}}\right).$$

Moreover the term φ_r is C^1 -smooth. As a consequence, we have chosen φ_1 in way such that the singular term $\frac{4x_2 r_{1\varepsilon}}{(\ell_2)^2(\ell_1)^2}$ has been canceled and moreover there holds

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\varphi_1 = -\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\varphi_0.$$
(3.27)

Now we shall deal with the singularity as x approaching the circle $|x| = r_{2\varepsilon}$. By the assumption (A3), there exists a small positive ε_0 such that for $0 < \varepsilon < \varepsilon_0$

$$\delta_{\varepsilon} = -\varepsilon \frac{\partial V}{\partial \tilde{\ell}} \Big|_{(\tilde{r}_{2\varepsilon}, 0)} > 0, \qquad (3.28)$$

where $\tilde{\ell} = \sqrt{\tilde{r}^2 + \tilde{y}_3^2}$. Then for (\tilde{r}, \tilde{y}_3) with foot point $(\tilde{p}_1, \tilde{p}_2)$ on the circle of radius $\tilde{r}_{2\varepsilon}$, there holds

$$1 + V(\tilde{r}, \tilde{y}_3) = 1 + V(\tilde{p}_1, \tilde{p}_2) + \frac{\partial V}{\partial \tilde{\ell}} \Big|_{(\tilde{p}_1, \tilde{p}_2)} \varepsilon(\tilde{\ell} - \tilde{r}_{2\varepsilon}) + O\left(\varepsilon^2(\tilde{\ell} - \tilde{r}_{2\varepsilon})^2\right)$$

$$= -\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + O\left(\varepsilon^2(\ell - r_{2\varepsilon})^2\right).$$
(3.29)

Let q be the unique solution given by Lemma 2.4. Now we define $\tilde{q}(z) = \delta_{\varepsilon}^{1/3} q(\delta_{\varepsilon}^{1/3} z)$. Then it is easy to check that

$$\tilde{q}_{zz} - \tilde{q} \left(\delta_{\varepsilon} z + \tilde{q}^2 \right) = 0.$$
(3.30)

In other words, if we choose $\hat{q}(x_1, x_2) = \delta_{\varepsilon}^{1/3} q \left(\delta_{\varepsilon}^{1/3} (\ell - r_{2\varepsilon}) \right)$ with $\ell = \sqrt{x_1^2 + x_2^2}$, then \hat{q} satisfies

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\hat{q} + \left(1 + V(\varepsilon|x_1|, \varepsilon x_2)\right)\hat{q} - \hat{q}^3 = O(\varepsilon^2).$$
(3.31)

This implies that we can use

$$U_3(x_1, x_2) = \hat{q}(x_1, x_2)e^{i\varphi_0}, \qquad (3.32)$$

as an approximation near $r_{2\varepsilon}$.

By defining smooth cut-off functions as follows

$$\tilde{\eta}_2(s) = \begin{cases} 1, & |s| \le \tau_3, \\ 0, & |s| \ge 2\tau_3, \end{cases} \qquad \tilde{\eta}_3(s) = \begin{cases} 1, & s \ge -\tau_4, \\ 0, & s \le -2\tau_4, \end{cases}$$
(3.33)

where the exponents τ_3, τ_4 are small enough in such a way that $\tau_3, \tau_4 < \min\{\tilde{r}_0, \tau_0, \tau_1, \tau_2\}/10$, we choose the cut-off functions by

$$\eta_2(\varepsilon x_1, \varepsilon x_2) = \tilde{\eta}_2(\varepsilon \ell_1) + \tilde{\eta}_2(\varepsilon \ell_2), \eta_3(\varepsilon x_1, \varepsilon x_2) = \tilde{\eta}_3(\varepsilon (\ell - r_{2\varepsilon})), \eta_1(\varepsilon x_1, \varepsilon x_2) = 1 - \eta_2 - \eta_3.$$

We then choose the final approximate solution to (3.3) by, for $(x_1, x_2) \in \mathbb{R}^2$,

$$u_2(x_1, x_2) = \sqrt{1 + V(\varepsilon |x_1|, \varepsilon x_2)} \eta_1 e^{i\varphi} + w(\ell_2) w(\ell_1) \eta_2 e^{i\varphi} + \hat{q}(x_1, x_2) \eta_3 e^{i\varphi},$$
(3.34)

where the new phase term $\varphi = \varphi_0 + \varphi_1$. By recalling the definition of U_1, U_2, U_3 in (3.15), (3.14) and (3.32), we also write the approximation as

$$u_2 = U_1 \eta_1 e^{i\varphi_1} + U_2 \eta_2 e^{i\varphi_1} + U_3 \eta_3 e^{i\varphi_1}.$$
(3.35)

It is easy to check that u_2 has the symmetry

$$u_2(x_1, x_2) = \overline{u_2(x_1, -x_2)}, \qquad u_2(x_1, x_2) = u_2(-x_1, x_2).$$
 (3.36)

Moreover, there holds

$$\frac{\partial u_2}{\partial x_1}(0, x_2) = 0. \tag{3.37}$$

3.5. Estimates of the error

As we have stated, we work directly in the half space $\mathbb{R}^2_+ = \{(x_1, x_2) : x_1 > 0\}$ in the sequel because of the symmetry of the problem. Recalling the definitions of the operators in (3.9), let us start to compute the error:

$$\mathbb{E} = S[u_2] = S[U_1]\eta_1 e^{i\varphi_1} + U_1 S_0[\eta_1 e^{i\varphi_1}] + 2\nabla U_1 \cdot \nabla \left(\eta_1 e^{i\varphi_1}\right)
+ S[U_2]\eta_2 e^{i\varphi_1} + U_2 S_0[\eta_2 e^{i\varphi_1}] + 2\nabla U_2 \cdot \nabla \left(\eta_2 e^{i\varphi_1}\right)
+ S[U_3]\eta_3 e^{i\varphi_1} + U_3 S_0[\eta_3 e^{i\varphi_1}] + 2\nabla U_3 \cdot \nabla \left(\eta_3 e^{i\varphi_1}\right) + \mathbb{N},$$
(3.38)

where the nonlinear term $\mathbb N$ is defined by

$$\mathbb{N} = \eta_1 |U_1|^2 U_1 e^{i\varphi_1} + \eta_2 |U_2|^2 U_2 e^{i\varphi_1} + \eta_3 |U_3|^2 U_3 e^{i\varphi_1} - |u_2|^2 u_2.$$
(3.39)

The main components in the above formula can be estimated as follows.

Using the equation (3.27), the singular term $F_{21} = iS_0[\varphi_0]U_2$ in $S[U_2]$ in is canceled and we then get

$$S[U_2] \eta_2 e^{i\varphi_1} + U_2 S_0[\eta_2 e^{i\varphi_1}] = F_{22} \eta_2 e^{i\varphi_1} + U_2 S_0[\eta_2] e^{i\varphi_1} + 2iU_2 \nabla \eta_2 \cdot \nabla \varphi_1 - U_2 \eta_2 e^{i\varphi_1} |\nabla \varphi_1|^2.$$

Whence, there holds

$$S[U_2] \eta_2 e^{i\varphi_1} + U_2 S_0[\eta_2 e^{i\varphi_1}] = F_{22} \eta_2 e^{i\varphi_1} + \varepsilon^2 O(|\ell_2|^2).$$

The formulas in (3.25)-(3.26) imply that

$$2\nabla U_{2} \cdot \nabla \left(\eta_{2} e^{i\varphi_{1}}\right) = 2\eta_{2} U_{2} e^{i\varphi_{1}} \frac{4x_{1}x_{2} r_{1\varepsilon}}{(\ell_{1}\ell_{2})^{2}} \frac{x_{2} \left[x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2}\right]}{(\ell_{2})^{2}(\ell_{1})^{2}} \\ + 2i\eta_{2} U_{2} e^{i\varphi_{1}} \frac{x_{1} - r_{1\varepsilon}}{\ell_{2}} \frac{w'(\ell_{2})}{w(\ell_{2})} \frac{x_{2} \left[x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2}\right]}{(\ell_{2})^{2}(\ell_{1})^{2}} \\ + 2i\eta_{2} U_{2} e^{i\varphi_{1}} \frac{x_{2}}{\ell_{2}} \frac{w'(\ell_{2})}{w(\ell_{2})} \frac{2x_{1}x_{2}^{2}}{(\ell_{2})^{2}(\ell_{1})^{2}} \\ - 4\eta_{2} U_{2} e^{i\varphi_{1}} \frac{r_{1\varepsilon} \left[x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2}\right]}{(\ell_{1}\ell_{2})^{2}} \frac{1}{4r_{1\varepsilon}} \log \frac{(\ell_{2})^{2}}{(\ell_{1})^{2}} \\ + 2i\eta_{2} U_{2} e^{i\varphi_{1}} \frac{x_{2}}{\ell_{2}} \frac{w'(\ell_{2})}{w(\ell_{2})} \frac{1}{4r_{1\varepsilon}} \log \frac{(\ell_{2})^{2}}{(\ell_{1})^{2}} + O(\varepsilon) \\ = 2\eta_{2} U_{2} e^{i\varphi_{1}} \frac{(x_{1} + r_{1\varepsilon})(x_{1} - r_{1\varepsilon})}{(\ell_{1}\ell_{2})^{2}} \log r_{1\varepsilon} \\ - i\eta_{2} U_{2} e^{i\varphi_{1}} \frac{x_{2}}{\ell_{2}} \frac{w'(\ell_{2})}{w(\ell_{2})} \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} + O(\varepsilon \log \ell_{2}). \end{cases}$$

It is worth to mention that, in the vortex-core region

$$D_2 = \left\{ (x_1, x_2) : \ell_1 < \frac{\tau_0}{\varepsilon} \text{ or } \ell_2 < \frac{\tau_0}{\varepsilon} \right\},\$$

we estimate the error by

$$\mathbb{E} = U_2 \eta_2 e^{i\varphi_1} \left[\frac{x_1 - r_{1\varepsilon}}{x_1 \ell_2} \frac{w'(\ell_2)}{w(\ell_2)} + \varepsilon (x_1 - r_{1\varepsilon}) \frac{\partial V}{\partial \tilde{r}} \Big|_{(\varepsilon r_{1\varepsilon}, 0)} \right] + \eta_2 U_2 e^{i\varphi_1} \frac{2(x_1 + r_{1\varepsilon})(x_1 - r_{1\varepsilon})}{(\ell_1 \ell_2)^2} \log r_{1\varepsilon} - i\eta_2 U_2 e^{i\varphi_1} \frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} + O(\varepsilon \log \ell_2).$$
(3.41)

The singularity of the last formula will play an important role in the final reduction step.

We then consider the error in the region

$$D_1 = \left\{ (x_1, x_2) : |x| < r_{2\varepsilon} - \frac{\tau_1}{\varepsilon} \right\} \setminus D_2.$$

From the relation (3.27), there holds

$$\eta_1 e^{i\varphi_1} S[U_1] + U_1 S_0[\eta_1 e^{i\varphi_1}] = \eta_1 e^{i\varphi_1} E_{11} + U_1 S_0[\eta_1] e^{i\varphi_1} + 2iU_1 e^{i\varphi_1} \nabla \eta_1 \cdot \nabla \varphi_1 - U_1 \eta_1 e^{i\varphi_1} |\nabla \varphi_1|^2.$$

In this region, $|\bigtriangledown \varphi_0| = O(\varepsilon)$ and $|\bigtriangledown \varphi_1| = O(\varepsilon)$. Whence, by using (3.20), we obtain $\eta_1 e^{i\varphi_1} S[U_1] + U_1 S_0[\eta_1 e^{i\varphi_1}] = \eta_1 e^{i\varphi_1} U_1 O(\varepsilon^2).$

Using the formulas (3.25)-(3.26), we obtain

$$\begin{split} 2\nabla U_{1} \cdot \nabla \Big(\eta_{1} e^{i\varphi_{1}} \Big) &= 2\eta_{1} i U_{1} e^{i\varphi_{1}} \Bigg[\frac{1}{2} \big(1+V \big)^{-1} \varepsilon \frac{\partial V}{\partial \tilde{r}} - i \frac{4x_{1}x_{2} r_{1\varepsilon}}{(\ell_{2})^{2}(\ell_{1})^{2}} \Bigg] \\ & \times \left(\frac{x_{2}}{4r_{1\varepsilon}} \varepsilon \eta' (\varepsilon \ell_{2}) \frac{x_{1} - r_{1\varepsilon}}{\ell_{2}} \log \frac{(\ell_{2})^{2}}{(\ell_{1})^{2}} \right. \\ & + \eta (\varepsilon \ell_{2}) \frac{x_{2} \big(x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2} \big)}{(\ell_{2})^{2}(\ell_{1})^{2}} + O(\varepsilon) \Bigg) \\ & + 2\eta_{1} U_{1} e^{i\varphi_{1}} \Bigg[\frac{1}{2} \big(1+V \big)^{-1} \varepsilon \frac{\partial V}{\partial \tilde{y}_{3}} - \frac{2r_{1\varepsilon} \big[x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2} \big]}{(\ell_{2})^{2}(\ell_{1})^{2}} \Bigg] \\ & \times \Bigg[\frac{x_{2}}{4r_{1\varepsilon}} \varepsilon \eta' (\varepsilon \ell_{2}) \frac{x_{2}}{\ell_{2}} \log \frac{(\ell_{2})^{2}}{(\ell_{1})^{2}} + \frac{1}{4r_{1\varepsilon}} \eta (\varepsilon \ell_{2}) \log \frac{(\ell_{2})^{2}}{(\ell_{1})^{2}} \\ & + \eta (\varepsilon \ell_{2}) \frac{2x_{1}x_{2}^{2}}{(\ell_{2})^{2}(\ell_{1})^{2}} + O(\varepsilon) \Bigg] \\ & + 2U_{1} e^{i\varphi_{1}} \Bigg[\frac{1}{2} \big(1+V \big)^{-1} \varepsilon \frac{\partial V}{\partial \tilde{r}} - i \frac{4x_{1}x_{2}r_{1\varepsilon}}{(\ell_{2})^{2}(\ell_{1})^{2}} \Bigg] \times \frac{\partial \eta_{1}}{\partial x_{1}} \\ & + 2U_{1} e^{i\varphi_{1}} \Bigg[\frac{1}{2} \big(1+V \big)^{-1} \varepsilon \frac{\partial V}{\partial \tilde{y}_{3}} - \frac{2r_{1\varepsilon} \big[x_{1}^{2} - x_{2}^{2} - (r_{1\varepsilon})^{2} \big]}{(\ell_{2})^{2}(\ell_{1})^{2}} \Bigg] \times \frac{\partial \eta_{1}}{\partial x_{2}} \\ & = \eta_{1} U_{1} e^{i\varphi_{1}} O(\varepsilon^{2}). \end{split}$$

Whence we conclude that, in D_1 , the error is estimated by

$$\mathbb{E} = \eta_1 e^{i\varphi_1} U_1 O(\varepsilon^2).$$

In the region

$$D_3 = \left\{ (x_1, x_2) : |x| > r_{2\varepsilon} - \frac{\tau_1}{\varepsilon} \right\}.$$

we finally compute the error of U_3

$$S[U_3] = S_0[U_3] + S_1[U_3],$$

where

$$S_0[U_3] = \delta_{\varepsilon} q'' \Big(\delta_{\varepsilon}^{1/3} (\ell - r_{2\varepsilon}) \Big) e^{i\varphi_0} + 2i e^{i\varphi_0} \nabla \hat{q} \cdot \nabla \varphi_0 - \hat{q} e^{i\varphi_0} \big| \nabla \varphi_0 \big|^2 + i S_0[\varphi_0] \hat{q} e^{i\varphi_0}.$$

We also write $S_1[U_3]$ of the form

$$S_1[U_3] = \delta_{\varepsilon} \left[\delta_{\varepsilon}^{1/3}(\ell - r_{2\varepsilon}) - q^2 \left(\delta_{\varepsilon}^{1/3}(\ell - r_{2\varepsilon}) \right) \right] q \left(\delta_{\varepsilon}^{1/3}(\ell - r_{2\varepsilon}) \right) e^{i\varphi_0} \\ + \left[(1+V) - \delta_{\varepsilon}(\ell - r_{2\varepsilon}) \right] \hat{q} e^{i\varphi_0}.$$

The equation of q in Lemma 2.4 implies that there holds

$$S[U_3] = 2ie^{i\varphi_0} \nabla \hat{q} \cdot \nabla \varphi_0 - \hat{q} e^{i\varphi_0} |\nabla \varphi_0|^2 + iS_0[\varphi_0] \hat{q} e^{i\varphi_0} + \left[(1+V) - \delta_{\varepsilon} (\ell - r_{2\varepsilon}) \right] \hat{q} e^{i\varphi_0},$$

$$\equiv F_{31} + F_{32},$$

where the term F_{31} of the form

$$F_{31} \equiv i S_0[\varphi_0] \,\hat{q} \, e^{i\varphi_0}.$$

is also not a singular term. Using the equation (3.31) and the similar computations as before, we now obtain

$$\eta_3 e^{i\varphi_1} S[U_3] + U_3 S_0[\eta_3 e^{i\varphi_1}] = \eta_3 e^{i\varphi_1} F_{32} + \eta_3 e^{i\varphi} O(\varepsilon^2) = \eta_3 e^{i\varphi} O(\varepsilon^2).$$

In the above, we have use the relation (3.27). Hence, there holds

$$\mathbb{E} = \eta_3 e^{i\varphi} O(\varepsilon^2).$$

For a function $h = h_1 + ih_2$ with real functions h_1, h_2 , define a norm of the form

$$||h||_{**} \equiv \sum_{j=1}^{2} ||iu_{2}h||_{L^{p}(\ell_{j}<3)} + \sum_{j=1}^{2} \left[||\ell_{j}^{2+\sigma}h_{1}||_{L^{\infty}(\tilde{D})} + ||\ell_{j}^{1+\sigma}h_{2}||_{L^{\infty}(\tilde{D})} \right] + \sum_{j=1}^{2} ||h_{j}||_{L^{p}(D_{3})}, \qquad (3.42)$$

where we have denoted

$$\tilde{D} = D_2 \cup D_1 \setminus \{\ell_1 < 3 \text{ or } \ell_2 < 3\},$$
(3.43)

for ℓ_1 and ℓ_2 defined in (3.12). As a conclusion, we have the following lemma.

Lemma 3.2. There holds for $\ell_1 > 2$ and $\ell_2 > 2$

$$\begin{aligned} \left| \operatorname{Re}(\mathbb{E}) \right| &\leq \frac{C\varepsilon^{1-\sigma}}{(1+\ell_1)^3} + \frac{C\varepsilon^{1-\sigma}}{(1+\ell_2)^3}, \\ \left| \operatorname{Im}(\mathbb{E}) \right| &\leq \frac{C\varepsilon^{1-\sigma}}{(1+\ell_1)^{1+\sigma}} + \frac{C\varepsilon^{1-\sigma}}{(1+\ell_2)^3}, \\ \left\| \mathbb{E} \right\|_{L^p(\{\ell_1 < 3\} \cup \{\ell_2 < 3\})} &\leq C\varepsilon |\log \varepsilon|, \end{aligned}$$

where $\sigma \in (0,1)$ is a constant. As a consequence, there also holds

$$||\mathbb{E}||_{**} \le C\varepsilon^{1-\sigma}.$$

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4. Local setting-up of the Problem

We look for a solution $u = u(x_1, x_2)$ to problem (3.3)-(3.4) in the form of small perturbation of u_2 , with additional symmetry:

$$u(x_1, x_2) = \bar{u}(x_1, -x_2). \tag{4.1}$$

Let $\tilde{\chi} : \mathbb{R} \to \mathbb{R}$ be a smooth cut-off function defined by

$$\tilde{\chi}(s) = \begin{cases} 1, & s \le 1, \\ 0, & s \ge 2. \end{cases}$$
(4.2)

Recalling (3.33)-(3.35) and setting the components of the approximation u_2 as

$$v_1(x_1, x_2) = \eta_1 U_1 e^{i\varphi_1}, \quad v_2(x_1, x_2) = \eta_2 U_2 e^{i\varphi_1}, \quad v_3(x_1, x_2) = \eta_3 U_3 e^{i\varphi_1}, \tag{4.3}$$

we want to choose the ansatz of the form

$$u = \left[\chi (v_2 + iv_2\psi) + (1 - \chi)(v_1 + v_2)e^{i\psi}\right] + \left[v_3 + i\eta_3 e^{i\varphi}\psi\right],\tag{4.4}$$

where $\chi(x_1, x_2) = \tilde{\chi}(\ell_2) + \tilde{\chi}(\ell_1)$. The above nonlinear decomposition of the perturbation was first introduced in [19], see also [41].

To find the perturbation terms, the main object of this section is to write the equation for the perturbation as a linear one with a right hand side given by a lower order nonlinear term. The symmetry imposed on u can be transmitted to the symmetry on the perturbation terms

$$\psi(x_1, -x_2) = -\overline{\psi(x_1, x_2)}, \quad \psi(x_1, x_2) = \psi(-x_1, x_2).$$
(4.5)

This type of symmetry will play an important role in our further arguments. Let us observe that

$$u = \left[(v_1 + v_2) + i(v_1 + v_2)\psi + (1 - \chi)(v_1 + v_2)(e^{i\psi} - 1 - i\psi) \right] + \left(v_3 + \eta_3 e^{i\varphi}\psi \right)$$

= $u_2 + i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma$

where we have denoted

$$\Gamma = (1 - \chi)(v_1 + v_2)(e^{i\psi} - 1 - i\psi).$$
(4.6)

A direct computation shows that u is a solution to problem (3.3)-(3.4) if and only if

$$i(v_{1}+v_{2})S_{0}[\psi] + 2i \bigtriangledown (v_{1}+v_{2}) \cdot \bigtriangledown \psi + i \Big[1+V - |u_{2}|^{2} \Big] (v_{1}+v_{2})\psi + iS_{0}[v_{1}+v_{2}]\psi - 2\operatorname{Re}(\bar{u}_{2}i(v_{1}+v_{2})\psi)u_{2} + \eta_{3}e^{i\varphi}S_{0}[\psi] + \eta_{3}e^{i\varphi} \Big[1+V - |u_{2}|^{2} \Big]\psi - 2\eta_{3}\operatorname{Re}(\bar{u}_{2}e^{i\varphi}\psi)u_{2} + 2 \bigtriangledown \Big[\eta_{3}e^{i\varphi} \Big] \cdot \bigtriangledown \psi + S_{0} \Big[\eta_{3}e^{i\varphi} \Big]\psi = -E + N,$$

$$(4.7)$$

where the error term E is defined as \mathbb{E} in (3.38) and N is the nonlinear operator defined by

$$N = -S_0[\Gamma] - (1 + V - |u_2|^2)\Gamma + \left[2\operatorname{Re}(\bar{u}_2 i(v_1 + v_2)\psi) + 2\eta_3\operatorname{Re}(\bar{u}_2 e^{i\varphi}\psi)\right] \times \left(i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma\right) + \left[2\operatorname{Re}(\bar{u}_2\Gamma) + |i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma|^2\right] \times \left(u_2 + i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma\right).$$

We shall explicitly write the equation in suitable local forms and then analyze the property of the corresponding linear operators, which will be done in the following.

Before going further, we first give some notations, see Figure 1. By recalling the notation ℓ_1 and ℓ_2 in (3.12), and also D_1, D_2, D_3 in (3.13), we set

$$D_{2,1} \equiv \{(x_1, x_2) : \ell_1 < 1\}, \qquad D_{2,2} \equiv \{(x_1, x_2) : \ell_2 < 1\}, \\ D_{2,3} \equiv \{(x_1, x_2) : \ell_1 < \frac{\tau_0}{\varepsilon}\} \setminus D_{2,1}, \qquad D_{2,4} \equiv \{(x_1, x_2) : \ell_2 < \frac{\tau_0}{\varepsilon}\} \setminus D_{2,2}, \quad (4.8) \\ D_{3,1} \equiv \{(x_1, x_2) : r_{2\varepsilon} - \frac{\tau_1}{\varepsilon} < |x| < r_{2\varepsilon} + \frac{\tau_2}{\varepsilon}\}, \qquad D_{3,2} \equiv \{(x_1, x_2) : |x| > r_{2\varepsilon} + \frac{\tau_2}{\varepsilon}\}.$$

Here $\tau_0, \tau_1, \tau_2, r_{1\varepsilon}$ and $r_{2\varepsilon}$ are given in the assumption (A3).

In the region D_1 far from the vortex core region, directly from the form of the ansatz $u = u_2 e^{i\psi}$ with the approximation as

$$u_2(x_1, x_2) = \sqrt{1+V} \eta_1 e^{i(\varphi_0 + \varphi_1)} + w(\ell_2) w(\ell_1) \eta_2 e^{i(\varphi_0 + \varphi_1)},$$

we see that the equation takes the simple form

$$L_1(\psi) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi + 2\frac{\nabla u_2}{u_2} \cdot \nabla \psi - 2i|u_2|^2\psi_2$$
$$= E_1 - i(\nabla \psi)^2 + i|u_2|^2\left(1 - e^{-2\psi_2} + 2\psi_2\right),$$

where $E_1 = i \mathbb{E}/u_2$. We intend next to describe in more accurate form the equation above. Let us also write

$$u_2 = e^{i\varphi}\beta_1$$
 with $\beta_1 = \sqrt{1+V}\eta_1 + w(\ell_2)w(\ell_1)\eta_2$.

For $|x| < r_{2\varepsilon} - 2\tau_1/\varepsilon$, there holds,

$$u_2 = \beta_1 e^{i\varphi} = \sqrt{1+V} e^{i\varphi}, \tag{4.9}$$

and hence, by using the assumption (A3), we have

$$|u_2|^2 = 1 + V > 1. (4.10)$$

Direct computation also gives that

$$2\frac{\nabla u_2}{u_2} \cdot \nabla \psi = \frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \nabla \psi_1 - 2 \bigtriangledown \varphi \cdot \nabla \psi_2 + i\frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \nabla \psi_2 + 2i \bigtriangledown \varphi \cdot \nabla \psi_1$$
$$= (A_1, 0) \cdot \nabla \psi_1 - (A_2, B_2) \cdot \nabla \psi_2 + i(A_1, 0) \cdot \nabla \psi_2 + i(A_2, B_2) \cdot \nabla \psi_1,$$

where $A_1 = O(\varepsilon |\log \varepsilon|)$, $A_2 = O(\varepsilon)$, $B_2 = O(\varepsilon)$. For $r_{2\varepsilon} - 2\tau_1/\varepsilon < |x| < r_{2\varepsilon} - \tau_1/\varepsilon$, similar estimates hold. The equations become

$$\tilde{L}_1(\psi_1) = \tilde{E}_1 + \tilde{N}_1, \qquad \bar{L}_1(\psi_2) = \bar{E}_1 + \bar{N}_1.$$
(4.11)

In the above, we have denoted the linear operators by

$$\tilde{L}_{1}(\psi_{1}) \equiv \left(\frac{\partial^{2}}{\partial x_{1}^{2}} + \frac{\partial^{2}}{\partial x_{2}^{2}} + \frac{1}{x_{1}}\frac{\partial}{\partial x_{1}}\right)\psi_{1} + \frac{2}{\beta_{1}}\bigtriangledown\beta_{1}\lor\bigtriangledown\psi_{1},$$

$$\bar{L}_{1}(\psi_{2}) \equiv \left(\frac{\partial^{2}}{\partial x_{1}^{2}} + \frac{\partial^{2}}{\partial x_{2}^{2}} + \frac{1}{x_{1}}\frac{\partial}{\partial x_{1}}\right)\psi_{2} - 2|u_{2}|^{2}\psi_{2} + \frac{2}{\beta_{1}}\bigtriangledown\beta_{1}\lor\bigtriangledown\psi_{2}.$$
(4.12)

The nonlinear operators are

$$N_1 = -2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_2 + 2 \bigtriangledown \psi_1 \cdot \bigtriangledown \psi_2,$$

$$\bar{N}_1 = 2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_1 + |u_2|^2 (1 - e^{-2\psi_2} + 2\psi_2) + |\bigtriangledown \psi_1|^2 - |\bigtriangledown \psi_2|^2.$$

Consider the linearization of the problem on the vortex-core region $D_{2,1} \cup D_{2,2}$. Here we only argue in the region $D_{2,2} = \{(x_1, x_2) : \ell_2 < 1\}$. It is more convenient to do this in the translated variable $(s_1, s_2) = (x_1 - r_{1\varepsilon}, x_2)$ and then denote $\ell = \ell_2$ for brevity of notation. Now the term ψ is small, however possibly unbounded near the vortex. Whence, in the sequel, by setting

$$\hat{\phi} = iv_2\psi \quad \text{with } \psi = \psi_1 + i\psi_2,$$
(4.13)

we shall require that $\tilde{\phi}$ is bounded (and smooth) near the vortices. We shall write the equation in term of a type of the function $\tilde{\phi}$ for $\ell < \delta/\varepsilon$. In the region $D_{2,2}$, let us write u_2 , i.e. v_2 , as the form

$$v_2 = \beta U_0 \quad \text{with } \beta = w(\ell_1) e^{-i\varphi_0^- + i\varphi_1},$$
(4.14)

where U_0 , φ_0^- and φ_1 are defined in (2.1), (3.12) and (3.21). We define the function

$$\phi(s) = iU_0\psi \quad \text{for } |s| < \delta/\varepsilon, \tag{4.15}$$

namely

$$\tilde{\phi} = \beta \phi. \tag{4.16}$$

Hence, in the translated variable, the ansatz becomes in this region

$$u_2 = \beta(s)U_0 + \beta(s)\phi + (1-\chi)\beta(s)U_0 \Big(e^{\phi/U_0} - 1 - \frac{\phi}{U_0}\Big).$$
(4.17)

We also call $\Gamma_{2,2} = (1 - \chi)U_0 \left(e^{\phi/U_0} - 1 - \frac{\phi}{U_0}\right)$. The support of this function is contained in set |s| > 1. In this vortex-core region, the problem, written in (s_1, s_2) coordinates, can be stated as

$$L_{2,2}(\phi) = E_{2,2} + N_{2,2}. \tag{4.18}$$

Let us consider the linear operator defined in the following way: for ϕ and ψ linked through formula (4.15) we set

$$L_{2,2}(\phi) = L_0(\phi) + \frac{1}{s_1 + r_{1\varepsilon}} \frac{\partial}{\partial s_1} \phi + 2(1 - |\beta|^2) \operatorname{Re}(\bar{U}_0 \phi) U_0 + \left[\varepsilon \frac{\partial V}{\partial \tilde{r}} \Big|_{(r_{1\varepsilon} + \vartheta s_1, 0)} + 1 - |\beta|^2 \right] \phi + 2 \frac{\nabla \beta}{\beta} \cdot \nabla \phi + \chi \frac{E_{2,2}}{U_0} \phi, \qquad (4.19)$$

where ϑ is a small constant. Here we also have defined L_0 as

$$L_0(\phi) = \left(\frac{\partial^2}{\partial s_1^2} + \frac{\partial^2}{\partial s_2^2}\right)\phi + (1 - |w|^2)\phi - 2\operatorname{Re}(\bar{U}_0\phi)U_0.$$

Here, by writing the error \mathbb{E} in the translated variable s, the error $E_{2,2}$ is given by

$$E_{2,2} = \mathbb{E}/\beta. \tag{4.20}$$

Observe that, in the region $D_{2,2}$, the error $E_{2,2}$ takes the expression

$$E_{2,2} = w(\ell_2) e^{i\varphi_0^+} \left[\frac{x_1 - r_{1\varepsilon}}{x_1 \ell_2} \frac{w'(\ell_2)}{w(\ell_2)} + \varepsilon \frac{\partial V}{\partial \tilde{r}} \Big|_{(\varepsilon r_{1\varepsilon}, 0)} (x_1 - r_{1\varepsilon}) \right] + w(\ell_2) e^{i\varphi_0^+} \frac{2(x_1 + r_{1\varepsilon})(x_1 - r_{1\varepsilon})}{(\ell_1 \ell_2)^2} \log r_{1\varepsilon} - iw(\ell_2) e^{i\varphi_0^+} \frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} + O(\varepsilon \log \ell_2),$$
(4.21)

while the nonlinear term is given by

$$N_{2,2}(\phi) = -\frac{\Delta(\beta \Gamma_{2,2})}{\beta} + \left(1 + V - |U_0|^2\right)\Gamma_{2,2} - 2|\beta|^2 \operatorname{Re}(\bar{U}_0\phi)(\phi + \Gamma_{2,2}) - \left(2|\beta|^2 \operatorname{Re}(\bar{U}_0\Gamma_{2,2}) + |\beta|^2 |\phi + \Gamma_{2,2}|^2\right) (U_0 + \phi + \Gamma_{2,2}) + (\chi - 1)\frac{E_{2,2}}{U_0}\phi.$$
(4.22)

Taking into account to the explicit form of the function β we get

$$\nabla \beta = O(\varepsilon), \quad \Delta \beta = O(\varepsilon^2), \quad |\beta| \sim 1 + O(\varepsilon^2),$$
(4.23)

provided that $|s| < \delta/\varepsilon$. With this in mind, we see that the linear operator is a small perturbation of L_0 .

In the region $D_{2,4}$ far from the vortex core, directly from the form of the ansatz $u = (1-\chi)u_2 e^{i\psi}$, we see that, for $\ell_2 > 2$, the equation takes the simple form

$$L_{2,4}(\psi) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi + 2\frac{\nabla u_2}{u_2} \cdot \nabla \psi - 2i|u_2|^2\psi_2 = E_{2,4} - i(\nabla \psi)^2 + i|u_2|^2(1 - e^{-2\psi_2} + 2\psi_2),$$
(4.24)

where $E_{2,4} = i\mathbb{E}/u_2$. We intend next to describe in more accurate form the equation above. As before, let us also write

$$u_2 = \beta U_0 \quad \text{with } \beta = w(\ell_1) e^{-i\varphi_0^- + i\varphi_1}. \tag{4.25}$$

where U_0 , φ_0^+ and φ_1 are defined in (2.1), (3.12) and (3.21). For $\ell_2 < \frac{\delta}{\varepsilon}$, there are two real functions A and B such that

$$\beta = e^{iA+B},\tag{4.26}$$

furthermore, a direct computation shows that, in this region, there holds

$$\nabla A = O(\varepsilon), \qquad \triangle A = O(\varepsilon^2), \qquad \nabla B = O(\varepsilon^3), \qquad \triangle B = O(\varepsilon^4).$$
 (4.27)

The equations become

$$\tilde{L}_{2,4}(\psi_1) = \tilde{E}_{2,4} + \tilde{N}_{2,4}, \qquad \bar{L}_{2,4}(\psi_2) = \bar{E}_{2,4} + \bar{N}_{2,4}.$$
(4.28)

In the above, we have denoted the linear operators by

$$\tilde{L}_{2,4}(\psi_1) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_1 + \left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right)\cdot\bigtriangledown\psi_1,$$

$$\bar{L}_{2,4}(\psi_2) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_2 - 2|u_2|^2\psi_2 + 2\left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right)\cdot\bigtriangledown\psi_2,$$

where have used $s = (x_1 - r_{1\varepsilon}, x_2)$. The nonlinear operators are

$$\begin{split} \tilde{N}_{2,4} &= -2(\bigtriangledown A + \bigtriangledown \varphi_0^+) \cdot \bigtriangledown \psi_2 + 2 \bigtriangledown \psi_1 \bigtriangledown \psi_2, \\ \bar{N}_{2,4} &= -2(\bigtriangledown A + \bigtriangledown \varphi_0^+) \cdot \bigtriangledown \psi_1 + |u_2|^2 (1 - e^{-2\psi_2} + 2\psi_2) + |\bigtriangledown \psi_1|^2 - |\bigtriangledown \psi_2|^2. \end{split}$$

In the region

$$D_{3,1} = \Big\{ (x_1, x_2) : r_{2\varepsilon} - \tau_1 / \varepsilon < |x| < r_{2\varepsilon} + \tau_2 / \varepsilon \Big\},$$

the approximation takes the form

$$u_2 = w(\ell_2)w(\ell_1) \eta_2 e^{i\varphi} + \hat{q} \eta_3 e^{i\varphi}.$$

We write the ansatz as

$$u = u_2 + i e^{i\varphi} \psi + \Gamma_{3,1}, \tag{4.29}$$

where $\Gamma_{3,1}$ is defined as

$$\Gamma_{3,1} = i\eta_2 \Big(w(\ell_1)w(\ell_2) - 1 \Big) e^{i\varphi}\psi + \eta_2 w(\ell_1)w(\ell_2)e^{i\varphi} \Big(e^{i\psi} - 1 - i\psi \Big).$$
(4.30)

The equation becomes

$$L_{3,1}[\psi] \equiv S_0[\psi] + 2i \bigtriangledown \varphi \cdot \bigtriangledown \psi - |\bigtriangledown \varphi|^2 \psi + iS_0[\varphi]\psi + \left(1 + V - |u_2|^2\right)\psi + 2ie^{-i\varphi} \operatorname{Re}(\bar{u}_2 i e^{i\varphi}\psi)u_2 = E_{3,1} + N_{3,1},$$

where $E_{3,1} = ie^{-i\varphi}\mathbb{E}$. The nonlinear operator is defined by

$$N_{3,1}(\psi) = ie^{-i\varphi} \Big[\bigtriangleup \Gamma_4 + \frac{1}{x_1} \frac{\partial}{\partial x_1} \Gamma_4 + (1 + V - |u_2|^2) \Gamma_4 \Big] \\ - ie^{-i\varphi} \Big[2\operatorname{Re}(\bar{u}_2\Gamma_4) - |ie^{i\varphi}\psi + \Gamma_4|^2 \Big] (u_2 + ie^{i\varphi}\psi + \Gamma_4) \\ - 2ie^{-i\varphi} \operatorname{Re}(\bar{u}_2 ie^{i\varphi}\psi) (ie^{i\varphi}\psi + \Gamma_4).$$

More precisely, in the region $D_{3,1}$, the linear operator $L_{3,1}$ is defined as

$$L_{3,1}[\psi] = S_0[\psi] - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + \hat{q}^2\right)\psi + 2ie^{-i\varphi}\operatorname{Re}\left(\bar{u}_2 i e^{i\varphi}\psi\right)u_2 + \left[1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon})\right]\psi + 2i\bigtriangledown\varphi\cdot\bigtriangledown\psi + S_0[\varphi]\psi - |\bigtriangledown\varphi|^2\psi.$$

where we have used the definition of \hat{q} in (3.31). We shall analyze other terms in the linear operator $L_{3,1}$. For $r_{2\varepsilon} - \tau_1/\varepsilon < |x| < r_{2\varepsilon} + \tau_2/\varepsilon$, there holds $u_2 = \hat{q} e^{i\varphi}$. It is obvious that

$$2ie^{-i\varphi}\operatorname{Re}(\bar{u}_2ie^{i\varphi}\psi)u_2 = -2i\,\hat{q}^2\,\psi_2. \tag{4.31}$$

For $r_{2\varepsilon} + \tau_2/\varepsilon < |x| < r_{2\varepsilon} + 2\tau_2/\varepsilon$, there holds

$$u_2 = w(\ell_2)w(\ell_1) \eta_2 e^{i\varphi} + \hat{q} \eta_3 e^{i\varphi}$$

Whence we decompose the equation in form

$$\tilde{L}_{3,1}[\psi_1] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + \hat{q}^2\right)\psi_1 + \left[1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon})\right]\psi_1 \\
+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_1 - 2\bigtriangledown\varphi\cdot\bigtriangledown\psi_2 + S_0[\varphi]\psi_1 - |\bigtriangledown\varphi|^2\psi_1 \\
= \tilde{E}_{3,1} + \tilde{N}_{3,1},$$
(4.32)

$$\bar{L}_{3,1}[\psi_2] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + 3\hat{q}^2\right)\psi_2 + \left[1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon})\right]\psi_2 \\
+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 + 2\bigtriangledown\varphi\cdot\bigtriangledown\psi_1 + S_0[\varphi]\psi_2 - |\bigtriangledown\varphi|^2\psi_2 \\
= \bar{E}_{3,1} + \bar{N}_{3,1}.$$
(4.33)

If $r_{2\varepsilon} - \tau_1/\varepsilon < |x| < r_{2\varepsilon} + \tau_2/\varepsilon$, by using (3.28), we then have

$$\Xi_{3,1} \equiv 1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon}) = \frac{\varepsilon^2}{2} \frac{\partial^2 V}{\partial \tilde{\ell}^2} (\ell - r_{2\varepsilon})^2 + O(\varepsilon^3 (\ell - r_{2\varepsilon})^3).$$

The other terms with φ_0 are also lower order terms. Whence the linear operators $\tilde{L}_{3,1}$ and $\bar{L}_{3,1}$ are small perturbations of the following linear operators

$$L_{31*}[\psi_1] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + \hat{q}^2\right)\psi_1,$$

$$L_{31**}[\psi_2] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + 3\hat{q}^2\right)\psi_2.$$
(4.34)

In the region $D_{3,2}$ the approximation takes the form

$$u_2 = \hat{q}(x_1, x_2)e^{i\varphi}$$

and the ansatz is

$$u = u_2 + i e^{i\varphi} \psi.$$

The equation becomes

$$L_{3,2}[\psi] \equiv S_0[\psi] + (1+V)\psi - |u_2|^2\psi + 2ie^{-i\varphi}\operatorname{Re}(\bar{u}_2 i e^{i\varphi}\psi)u_2 - |\bigtriangledown \varphi|^2\psi + iS_0[\varphi]\psi + 2i\bigtriangledown \varphi \cdot \bigtriangledown \psi = E_{3,2} + N_{3,2},$$

$$(4.35)$$

where $E_{3,2} = i e^{-i\varphi} \mathbb{E}$. The nonlinear operator is defined by

$$N_{3,2}(\psi) = -ie^{-i\varphi}(u_2 + ie^{i\varphi}\psi)|\psi|^2 + 2i\operatorname{Re}(\bar{u}_2 ie^{i\varphi}\psi)\psi.$$

More precisely, for other term, we have

$$-|u_2|^2\psi + 2ie^{-i\varphi} \operatorname{Re}(\bar{u}_2 i e^{i\varphi}\psi)u_2 = -\hat{q}^2\psi_1 - 3i\hat{q}^2\psi_2.$$

The equation can be decomposed in the form

$$\tilde{L}_{3,2}[\psi_1] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 + \left(1+V\right)\psi_1 - \hat{q}\,\psi_1 \\
+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 - |\bigtriangledown\varphi|^2\psi_1 + iS_0[\varphi]\psi_1 - 2\bigtriangledown\varphi\cdot\bigtriangledown\psi_2 \\
= \tilde{E}_{3,2} + \tilde{N}_{3,2},$$
(4.36)

$$\bar{L}_{3,2}[\psi_2] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 + \left(1+V\right)\psi_2 - \hat{q}\,\psi_2
+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 - |\bigtriangledown\varphi|^2\psi_2 + iS_0[\varphi]\psi_2 + 2\bigtriangledown\varphi\cdot\bigtriangledown\psi_1
= \bar{E}_{3,2} + \bar{N}_{3,2}.$$
(4.37)

The assumption (A3) implies that, for any sufficiently small ε there holds

$$\Xi_{3,2} = 1 + V < -c_2 \quad \text{for } |x| > r_{2\varepsilon} + \tau_2/\varepsilon. \tag{4.38}$$

The other terms with φ_0 are lower order terms. From the asymptotic properties of q in Lemma 2.4, $\hat{q} \psi_2$ and $\hat{q} \psi_1$ are also lower order term. Whence the linear operators $\tilde{L}_{3,2}$ and $\bar{L}_{3,2}$ are small perturbations of the following linear operator

$$L_{32*}[\tilde{\psi}] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\tilde{\psi} + (1+V)\tilde{\psi}.$$
(4.39)

Let χ be the cut-off function defined in (4.2). By recalling the definition of β in (4.14), we define

$$\Lambda \equiv \frac{\partial u_2}{\partial f} \cdot \frac{\chi (|x - \xi_+|/\varepsilon) + \chi (|x - \xi_-|/\varepsilon)}{\beta} \,. \tag{4.40}$$

In summary, for any given f in (3.7), we want to solve the projected equation for ψ satisfying the symmetry (4.5)

$$\mathcal{L}(\psi) = \mathcal{N}(\psi) + \mathcal{E} + c\Lambda, \qquad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0,$$
(4.41)

where have denoted

$$\mathcal{L}(\psi) = L_1(\phi) \text{ in } D_1, \qquad \mathcal{L}(\psi) = L_{2,j}(\psi) \text{ in } D_{2,j} \text{ for } j = 1, 2, 3, 4,$$
$$\mathcal{L}(\psi) = L_{3,1}(\psi) \text{ in } D_{3,1}, \qquad \mathcal{L}(\psi) = L_{3,2}(\psi) \text{ in } D_{3,2},$$

with the relation

$$\phi = iu_2\psi \quad \text{in } D_2. \tag{4.42}$$

As we have stated, the nonlinear operator \mathcal{N} and the error term \mathcal{E} also have suitable local forms in different regions.

5. The Resolution of the Projected Nonlinear Problem

5.1. The linear resolution theory

The main object is to consider the resolution of the linear part in previous section, which was stated in Lemma 5.2.

For that purpose, we shall firs get a priori estimates expressed in suitable norms. By recalling the norm $\|\cdot\|_{**}$ defined in (3.42), for fixed small positive numbers $0 < \sigma < 1$, $0 < \gamma < 1$, we define

$$\begin{split} ||\psi||_{*} &\equiv \sum_{i=1}^{2} \left[\, ||\phi||_{W^{2,p}(\ell_{i}<3)} \, + \, ||\ell_{i}^{\sigma}\psi_{1}||_{L^{\infty}(\tilde{D})} + ||\ell_{i}^{1+\sigma}\bigtriangledown\psi_{1}||_{L^{\infty}(\tilde{D})} \\ &+ \, ||\ell_{i}^{1+\sigma}\psi_{2}||_{L^{\infty}(\tilde{D})} + ||\ell_{i}^{2+\sigma}\bigtriangledown\psi_{2}||_{L^{\infty}(\tilde{D})} \, \right] + \, ||\psi||_{W^{2,p}(D_{3})}, \end{split}$$

where we have use the relation $\phi = iu_2\psi$ and the region \tilde{D} is defined in (3.43). We then consider the following problem: finding ψ with the symmetry in (4.5)

$$\mathcal{L}(\psi) = h \quad \text{in } \mathbb{R}^2, \quad \text{Re} \int_{\mathbb{R}^2} \bar{\phi} \Lambda = 0 \quad \text{with } \phi = i u_2 \psi.$$
 (5.1)

Lemma 5.1. There exists a constant C, depending on γ, σ only, such that for all ε sufficiently small, and any solution of (5.1), we have the estimate

$$||\psi||_* \le ||h||_{**}$$

Proof. We prove the result by contradiction. Suppose that there is a sequence of $\varepsilon = \varepsilon_n$, functions ψ^n , h_n which satisfy (5.1) with

$$||\psi^n||_* = 1, \quad ||h_n||_{**} = o(1).$$

Before any further argument, by the symmetry assumption (4.5) for $\psi = \psi_1 + i\psi_2$, we have

$$\psi_1(x_1, -x_2) = -\psi_1(x_1, x_2), \quad \psi_1(-x_1, x_2) = \psi_1(x_1, x_2), \psi_2(x_1, -x_2) = \psi_2(x_1, x_2), \quad \psi_2(-x_1, x_2) = \psi_2(x_1, x_2).$$
(5.2)

We may just need to consider the problem in $\mathbb{R}^2_+ = \{(x_1, x_2) : x_1 > 0\}$. Then we have

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}_n \Lambda = 2\operatorname{Re} \int_{\mathbb{R}^2_+} \bar{\phi}_n \Lambda = 0, \qquad (5.3)$$

for any $\phi_n = iu_2\psi^n$. To get good estimate and then derive a contradiction, we will use suitable forms of the linear operator \mathcal{L} in different regions, which was stated in previous section. Hence we divide the proof into five parts.

Part 1. In the outer part D_1 , we use the following barrier function

$$\mathcal{B}(x) = \mathcal{B}_1(x) + \mathcal{B}_2(x),$$

where

$$\mathcal{B}_1(x) = |x - \xi_+|^{\varrho} |x_2|^{\gamma} + |x - \xi_-|^{\varrho} |x_2|^{\gamma}, \qquad \mathcal{B}_2(x) = C_1(1 + |x|^2)^{-\sigma/2},$$

where $\rho + \gamma = -\sigma$, $0 < \sigma < \gamma < 1$, and C_1 is a large number depending on σ, ρ, γ only. Trivial computations derive that

$$\Delta \mathcal{B}_1 \leq -C(|x-\xi_+|^2+|x-\xi_-|^2)^{-1-\sigma/2}, \\ \Delta \mathcal{B}_2 + \frac{1}{x_1} \frac{\partial \mathcal{B}_2}{\partial x_1} \leq -CC_1(1+|x|^2)^{-1-\sigma/2}.$$

On the other hand,

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le \frac{|x_2|^{\gamma}}{x_1} \left[|x - \xi_+|^{\varrho - 2}(x_1 - r_{1\varepsilon}) + |x - \xi_-|^{\varrho - 2}(x_1 - r_{1\varepsilon}) \right].$$

Thus for $|x - \xi_+| < c_\sigma r_{1\varepsilon}$, where c_σ is small, we have

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le Cc_{\sigma} \Big[|x - \xi_+|^2 + |x - \xi_-|^2 \Big]^{-1 - \sigma/2}.$$

For $|x - \xi_+| > c_\sigma r_{1\varepsilon}$, where c_σ is small, we have

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le C(1+|x|^2)^{-1-\sigma/2}.$$

By choosing C_1 large, we have

$$\Delta \mathcal{B} + \frac{1}{x_1} \frac{\partial \mathcal{B}}{\partial x_1} \leq -C \left(|x - \xi_+|^2 + |x - \xi_-|^2 \right)^{-1 - \sigma/2}.$$

For the details of the above computations, the reader can refer to the proof of Lemma 7.2 in [41]. In D_1 , we have

$$\Big(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\Big)\psi_1 + \frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \bigtriangledown \psi_1 = h_1.$$

By comparison principle on the set D_1 , we obtain

$$|\psi_1| \le C\mathcal{B}\big(||h||_{**} + o(1)\big), \quad \forall x \in D_1.$$

On the other hand, the equation for ψ_2 is

$$\Big(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\Big)\psi_2 - 2|u_2|^2\psi_2 + \frac{2}{\beta_1} \bigtriangledown \beta_1 \cdot \psi_2 = h_2.$$

For $x \in D_1$, there holds $|u_2| \sim 1$. By standard elliptic estimates we have

$$\begin{aligned} |\psi_2||_{L^{\infty}(\ell_i > 4)} &\leq C ||\psi_2||_{L^{\infty}(\ell_i = 4)} (1 + ||\psi||_*) ||h||_{**} (1 + \ell_1 + \ell_2)^{-1 - \sigma}, \\ |\nabla \psi_2| &\leq C ||\psi_2||_{L^{\infty}(\ell_i = R)} (1 + ||\psi||_*) ||h||_{**} (1 + \ell_1 + \ell_2)^{-2 - \sigma}. \end{aligned}$$

Part 2. We here only derive the estimates in the vortex-core region $D_{2,2}$ near ξ_+ . Since $||h||_{**} = o(1), \psi^n \to \psi^0$, which satisfies

$$L_{2,2}(\psi_0) = 0, \quad ||\psi^0||_* \le 1.$$

Whence, we get $L_0(\phi_0) = 0$. By the nondegeneracy in Lemma 2.3, we have

$$\phi_0 = c_1 \frac{\partial U_0}{\partial s_1} + c_2 \frac{\partial U_0}{\partial s_2}.$$

Observe that ϕ_0 inherits the symmetries of ϕ and hence $\phi_0 = \overline{\phi_0(x_1, -x_2)}$, while the other symmetry is not preserved under the translation $s = x - \xi_+$. Obviously, the term $\frac{\partial U_0}{\partial s_2}$ does not enjoy the above symmetry. This implies that $\phi_0 = c_1 \frac{\partial U_0}{\partial s_1}$. On the other hand, taking a limit of the orthogonality condition $\operatorname{Re} \int_{\mathbb{R}^2} \overline{\phi}_n \Lambda = 0$, we obtain

$$\operatorname{Re}\int_{\mathbb{R}^2} \bar{\phi}_0 \frac{U_0}{\partial s_1} = 0,$$

and moreover $c_1 = 0$ and $\phi_0 = 0$. Hence, for any fixed R > 0, there holds

$$||\phi_1||_{L^{\infty}(\ell < R)} + ||\phi_2||_{L^{\infty}(\ell < R)} + ||\nabla \phi_1||_{L^{\infty}(\ell < R)} + ||\nabla \phi_2||_{L^{\infty}(\ell < R)} = O(1).$$

Part 3. In the outer part $D_{2,3} \cup D_{2,4}$, we use the following barrier function

$$\mathcal{B}(x) = \mathcal{B}_1(x) + \mathcal{B}_2(x),$$

where

$$\mathcal{B}_1(x) = |x - \xi_+|^{\varrho} |x_2|^{\gamma} + |x - \xi_-|^{\varrho} |x_2|^{\gamma}, \qquad \mathcal{B}_2(x) = C_1(1 + |x|^2)^{-\sigma/2},$$

where $\rho + \gamma = -\sigma$, $0 < \sigma < \gamma < 1$, and C_1 is a large number depending on σ, ρ, γ only. Trivial computations derive that

$$\Delta \mathcal{B}_1 \leq -C (|x - \xi_+|^2 + |x - \xi_-|^2)^{-1 - \sigma/2},$$

$$\Delta \mathcal{B}_2 + \frac{1}{x_1} \frac{\partial \mathcal{B}_2}{\partial x_1} \leq -CC_1 (1+|x|^2)^{-1-\sigma/2}.$$

On the other hand,

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le \frac{|x_2|^{\gamma}}{x_1} \left[|x - \xi_+|^{\varrho - 2}(x_1 - r_{1\varepsilon}) + |x - \xi_-|^{\varrho - 2}(x_1 - r_{1\varepsilon}) \right].$$

Thus for $|x - \xi_+| < c_\sigma r_{1\varepsilon}$, where c_σ is small, we have

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le Cc_{\sigma} \Big[|x - \xi_+|^2 + |x - \xi_-|^2 \Big]^{-1 - \sigma/2}.$$

For $|x - \xi_+| > c_\sigma r_{1\varepsilon}$, where c_σ is small, we have

$$\frac{1}{x_1}\frac{\partial \mathcal{B}_1}{\partial x_1} \le C(1+|x|^2)^{-1-\sigma/2}$$

By choosing C_1 large, we have

$$\Delta \mathcal{B} + \frac{1}{x_1} \frac{\partial \mathcal{B}}{\partial x_1} \leq -C \left(|x - \xi_+|^2 + |x - \xi_-|^2 \right)^{-1 - \sigma/2}.$$

For the details of the above computations, the reader can refer to the proof of Lemma 7.2 in [41]. In the region $D_{2,3} \cup D_{2,4}$, we have

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_1 + \left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right) \cdot \bigtriangledown \psi_1 = h_1,$$

where have used $s = (x_1 - r_{1\varepsilon}, x_2)$. By comparison principle on the set $D_{2,3} \cup D_{2,4}$, we obtain

$$|\psi_1| \le C\mathcal{B}(||h||_{**} + o(1)), \quad \forall x \in D_{2,3} \cup D_{2,4}.$$

On the other hand, the equation for ψ_2 is

$$\left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_2 - 2|u_2|^2\psi_2 + 2\left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right)\cdot\bigtriangledown\psi_2 = h_2.$$

For $x \in D_{2,3} \cup D_{2,4}$, there holds $|u_2| \sim 1$. By standard elliptic estimates we have

$$||\psi_2||_{L^{\infty}(\ell_i > 4)} \leq C||\psi_2||_{L^{\infty}(\ell_i = 4)}(1 + ||\psi||_*)||h||_{**}(1 + \ell_1 + \ell_2)^{-1-\sigma},$$
$$|\nabla \psi_2| \leq C||\psi_2||_{L^{\infty}(\ell_i = R)}(1 + ||\psi||_*)||h||_{**}(1 + \ell_1 + \ell_2)^{-2-\sigma}.$$

Part 4. In the region $D_{3,1}$, we have

$$\begin{split} L_{3,1}[\psi_1] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + \hat{q}^2\right)\psi_1 + \left[1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon})\right]\psi_1 \\ &+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_1 - 2\bigtriangledown\varphi_0\cdot\bigtriangledown\psi_2 + S_0[\varphi_0]\psi_1 - |\bigtriangledown\varphi_0|^2\psi_1 \\ &= h_1, \end{split}$$

$$\begin{split} L_{3,1}[\psi_2] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - \left(\delta_{\varepsilon}(\ell - r_{2\varepsilon}) + 3\hat{q}^2\right)\psi_2 + \left[1 + V + \delta_{\varepsilon}(\ell - r_{2\varepsilon})\right]\psi_2 \\ &+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 + 2\bigtriangledown\varphi_0\cdot\bigtriangledown\psi_1 + S_0[\varphi_0]\psi_2 - |\bigtriangledown\varphi_0|^2\psi_2 \\ &= h_2. \end{split}$$

By defining a new translated variable $z = \delta_{\varepsilon}^{1/3} (\ell - r_{\varepsilon})$, the linear operators L_{31*} and L_{31**} in (4.34) become

$$L_{31*}(\psi_{1*}) = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_{1*} - (z+q^2(z))\psi_{1*},$$

$$L_{31**}(\psi_{2**}) = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_{2**} - (z+3q^2(z))\psi_{2**}.$$

From Lemma 2.4, -q'(z) > 0 for all $z \in \mathbb{R}$, and $L_{31**}(-q') = 0$. We apply the maximum principle to $-\psi_2/q'$ and then obtain

$$|\psi_2| \le C|q'|(||h||_{**} + o(1)), \quad \forall x \in D_{3,1}.$$

On the other hand, q(z) > 0 for all $z \in \mathbb{R}$, and $L_{31*}(q) = 0$. We apply the maximum principle to ψ_1/q and then obtain

$$|\psi_1| \le Cq(||h||_{**} + o(1)), \quad \forall x \in D_{3,1}.$$

Part 5. In $D_{3,2}$, we consider the problem

$$\begin{split} L_{3,2}[\psi_1] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 + (1+V)\psi_1 - \hat{q}\,\psi_1 \\ &+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 - |\bigtriangledown\varphi_0|^2\psi_1 + iS_0[\varphi_0]\psi_1 - 2\bigtriangledown\varphi_0\cdot\bigtriangledown\psi_2 \\ &= h_1, \end{split}$$

$$\begin{split} L_{3,2}[\psi_2] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 + (1+V)\psi_2 - \hat{q}(|x_1|)\psi_2 \\ &+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 - |\bigtriangledown \varphi_0|^2\psi_2 + iS_0[\varphi_0]\psi_2 + 2\bigtriangledown \varphi_0 \cdot \bigtriangledown \psi_1 \\ &= h_2. \end{split}$$

By using the properties of $\Xi_{3,2}$ in (4.38), i.e.

$$\Sigma_{3,2} = (1+V) < -c_2$$
 in D_5 .

we have

$$||\psi_2||_{L^{\infty}(\ell_i > 4)} \leq C||\psi_2||_{L^{\infty}(\ell_i = 4)} (1 + ||\psi||_*)||h||_{**} (1 + \ell_1 + \ell_2)^{-1-\sigma},$$

$$|\nabla \psi_2| \leq C ||\psi_2||_{L^{\infty}(\ell_i = R)} (1 + ||\psi||_*) ||h||_{**} (1 + \ell_1 + \ell_2)^{-2-\sigma}.$$

Combining all the estimates in the above, we obtain that $||\psi||_* = o(1)$, which is a contradiction.

We now consider the following linear projected problem: finding ψ with the symmetry in (4.5)

$$\mathcal{L}[\psi] = h + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0 \quad \text{with } \phi = iu_2\psi.$$
 (5.4)

Lemma 5.2. There exists a constant C, depending on γ, σ only, such that for all ε sufficiently small, the following holds: if $||h||_{**} < +\infty$, there exists a unique solution $(\psi_{\varepsilon,f}, c_{\varepsilon,f}) = \mathcal{T}_{\varepsilon,f}(h)$ to (5.4). Furthermore, there holds

$$||\psi||_* \le C||h||_{**}$$

Proof. The proof is similar to that of Proposition 4.1 in [19]. Instead of solving (5.4) in \mathbb{R}^2 , we solve it in a bounded domain first:

$$\mathcal{L}[\psi] = h + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0 \quad \text{with } \phi = iu_2\psi,$$

$$\phi = 0 \quad \text{on } \partial B_M(0), \quad \psi \text{ satisfies the symmetry (4.5).}$$

where $M > 10r_{1\varepsilon}$. By the standard proof of a priori estimates, we also obtain the following estimates for any solution ψ_M of above problem

$$||\psi||_* \le C||h||_{**}$$

By working with the Sobole space $H_0^1(B_M(0))$, the existence will follow by Fredholm alternatives. Now letting $M \to +\infty$, we obtain a solution with the required properties.

5.2. Solving the Projected Nonlinear Problem

We then consider the following problem: finding ψ with the symmetry in (4.5)

$$\mathcal{L}[\psi] + \mathcal{N}[\psi] = \mathcal{E} + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0 \quad \text{with } \phi = iu_2\psi.$$
 (5.5)

Proposition 5.3. There exists a constant C, depending on γ, σ only, such that for all ε sufficiently small, there exists a unique solution $\psi_{\varepsilon,f}, c_{\varepsilon,f}$ to (5.5), and

$$||\psi||_* \le C||h||_{**}$$

Furthermore, ψ is continuous in the parameter f.

Proof. Using of the operator defined by Lemma 5.2, we can write problem (5.5) as

$$\psi = \mathcal{T}_{\varepsilon,f} \left(-\mathcal{N}[\psi] + \mathcal{E} \right) \equiv \mathcal{G}_{\varepsilon}(\psi).$$

Using Lemma 3.2, we see that

$$||\mathcal{E}||_{**} \le C\varepsilon^{1-\sigma}.$$

Let

$$\psi \in \mathbb{B} = \left\{ ||\psi||_* < C\varepsilon^{1-\sigma} \right\},\$$

then we have, using the explicit form of $\mathcal{N}(\psi)$ in section 4

$$||\mathcal{N}(\psi)||_{**} \le C\varepsilon.$$

Whence, there holds

$$||\mathcal{G}_{\varepsilon}(\psi)||_{**} \leq C\Big(||\mathcal{N}(\psi)||_{**} + ||\mathcal{E}||_{**}\Big) \leq C\varepsilon^{1-\sigma}.$$

Similarly, we can also show that, for any $\check{\psi}, \hat{\psi} \in \mathbb{B}$

$$||\mathcal{G}_{\varepsilon}(\check{\psi}) - \mathcal{G}_{\varepsilon}(\hat{\psi})||_{**} \le o(1)||\check{\psi} - \hat{\psi}||_{**}.$$

By contraction mapping theorem, we confirm the result of the Lemma.

6. Reduction procedure

To find a real solution to problem (3.3)-(3.4), in this section, we solve the reduced problem by finding a suitable f such that the constant c in (4.41) is identical zero for any sufficiently small ε .

In previous section, for any given f in (3.7), we have deduced the existence of ψ with the symmetry (4.5) to the projected problem

$$\mathcal{L}(\psi) = \mathcal{N}(\psi) + \mathcal{E} + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0,$$
 (6.1)

with the relation

$$\phi = i u_2 \psi$$
 in D_2 .

Multiplying (6.1) by $\overline{\Lambda}$ and integrating, we obtain

$$c\operatorname{Re}\int_{\mathbb{R}^2}\bar{\Lambda}\Lambda = \operatorname{Re}\int_{\mathbb{R}^2}\bar{\Lambda}\mathcal{L}(\psi) - \operatorname{Re}\int_{\mathbb{R}^2}\bar{\Lambda}\mathcal{N}(\psi) - \operatorname{Re}\int_{\mathbb{R}^2}\bar{\Lambda}\mathcal{E}.$$
(6.2)

Hence we can derive the estimate for c by computing the integrals of the right hand side.

We begin with the computation of $\operatorname{Re} \int_{\mathbb{R}^2} \overline{\Lambda} \mathcal{E}$. The term Λ has its support contained in the region $\{(x_1, x_2) : \ell_1 < \tau_0/\varepsilon \text{ or } \ell_2 < \tau_0/\varepsilon\}$. It is convenient to compute $\operatorname{Re} \int_{\mathbb{R}^2} \overline{\Lambda} \mathcal{E}$ on the variables (s_1, s_2) . Note that, in the vortex-core region, there holds

$$\frac{\partial u_2}{\partial f} = \left[-\frac{w'(\ell_2)}{w(\ell_2)} \frac{x_1 - r_{1\varepsilon}}{\ell_2} + i \frac{x_2}{(\ell_2)^2} \right] u_2 + O(\varepsilon^2) u_2,$$

which implies that

$$\Lambda = \chi \left(|x - \xi_+| / \varepsilon \right) \left[-\frac{w'(\ell_2)}{w(\ell_2)} \frac{x_1 - r_{1\varepsilon}}{\ell_2} + i \frac{x_2}{(\ell_2)^2} \right] w(\ell_2) e^{i\varphi_0^+} + O(\varepsilon^2).$$

By using of local form of \mathcal{E} in the formula (4.21), we obtain

$$\operatorname{Re} \int_{\mathbb{R}^{2}} \bar{\Lambda} \mathcal{E} dx = 2\operatorname{Re} \int_{\mathbb{R}^{2}_{+}} \bar{\Lambda} \mathcal{E} dx$$

$$= -2 \int_{\mathbb{R}^{2}_{+}} \chi \left(\ell_{2} / \varepsilon \right) \left[w'(\ell_{2}) \right]^{2} \frac{(x_{1} - r_{1\varepsilon})^{2}}{x_{1}(\ell_{2})^{2}} dx$$

$$- 2\varepsilon \frac{\partial V}{\partial \tilde{r}} \Big|_{(\tilde{r}_{1\varepsilon}, 0)} \int_{\mathbb{R}^{2}_{+}} \chi \left(\ell_{2} / \varepsilon \right) w(\ell_{2}) w'(\ell_{2}) \frac{(x_{1} - r_{1\varepsilon})(x_{1} - r_{1\varepsilon})}{\ell_{2}} dx$$

$$- 2 \log r_{1\varepsilon} \int_{\mathbb{R}^{2}_{+}} \chi \left(\ell_{2} / \varepsilon \right) w(\ell_{2}) w'(\ell_{2}) \frac{2(x_{1} + r_{1\varepsilon})(x_{1} - r_{1\varepsilon})^{2}}{(\ell_{1})^{2}(\ell_{2})^{3}} dx$$

$$- 2 \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} \int_{\mathbb{R}^{2}_{+}} \chi \left(\ell_{2} / \varepsilon \right) w(\ell_{2}) w'(\ell_{2}) \frac{x_{2}^{2}}{(\ell_{2})^{3}} dx + O(\varepsilon)$$

By the translation in (3.6), we further derive that

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{E} \mathrm{d}x = -2 \int_{\mathbb{R}^2} \chi \left(|s|/\varepsilon \right) \left[w'(|s|) \right]^2 \frac{s_1^2}{(s_1 + r_{1\varepsilon})|s|^2} \, \mathrm{d}s \\ - 2\varepsilon \frac{\partial V}{\partial \tilde{r}} \Big|_{(\tilde{r}_{1\varepsilon}, 0)} \int_{\mathbb{R}^2} \chi \left(|s|/\varepsilon \right) w(|s|) w'(|s|) \frac{s_1^2}{|s|} \, \mathrm{d}s \\ - 2 \log r_{1\varepsilon} \int_{\mathbb{R}^2} \chi \left(|s|/\varepsilon \right) w(|s|) w'(|s|) \frac{2(s_1 + 2r_{1\varepsilon} + 2f)s_1^2}{\left[(s_1 + 2r_{1\varepsilon} + 2f)^2 + s_2^2 \right] |s|^3} \, \mathrm{d}s \\ - 2 \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} \int_{\mathbb{R}^2} \chi \left(|s|/\varepsilon \right) w(|s|) w'(|s|) \frac{s_2^2}{|s|^3} \, \mathrm{d}s + O(\varepsilon) \, .$$

We compute the first two terms in above formula

$$-2\int_{\mathbb{R}^2} \chi\big(|s|/\varepsilon\big) \Big[w'(|s|)\Big]^2 \frac{s_1^2}{(s_1+r_{1\varepsilon})|s|^2} \,\mathrm{d}s = O(\varepsilon),$$

and

$$\begin{aligned} &-2\varepsilon \frac{\partial V}{\partial \tilde{r}}\Big|_{(\tilde{r}_{1\varepsilon},0)} \int_{\mathbb{R}^2} \chi\big(|s|/\varepsilon\big) w(|s|) w'(|s|) \frac{s_1^2}{|s|} \,\mathrm{d}s \\ &= -2\varepsilon \frac{\partial V}{\partial \tilde{r}}\Big|_{(\tilde{r}_{1\varepsilon},0)} \int_{\mathbb{R}^2} w(|s|) w'(|s|) \frac{s_1^2}{|s|} \,\mathrm{d}s + O(\varepsilon) \\ &= -2\pi\varepsilon |\log\varepsilon| \frac{\partial V}{\partial \tilde{r}}\Big|_{(\tilde{r}_{1\varepsilon},0)} + O(\varepsilon). \end{aligned}$$

On the other hand, the last two terms can be estimated by

$$\begin{aligned} &-2\log r_{1\varepsilon} \int_{\mathbb{R}^2} \chi\big(|s|/\varepsilon\big) w(|s|) w'(|s|) \frac{2(s_1+2r_{1\varepsilon}+2f)s_1^2}{\left[(s_1+2r_{1\varepsilon}+2f)^2+s_2^2\right]|s|^3} \,\mathrm{d}s \\ &-2\frac{1}{r_{1\varepsilon}}\log r_{1\varepsilon} \int_{\mathbb{R}^2} \chi\big(|s|/\varepsilon\big) w(|s|) w'(|s|) \frac{s_2^2}{|s|^3} \,\mathrm{d}s \\ &=-\frac{2}{r_{1\varepsilon}}\log r_{1\varepsilon} \int_{\mathbb{R}^2} w(|s|) w'(|s|) \frac{1}{|s|} \,\mathrm{d}s + O(\varepsilon) \\ &= -2\frac{d\pi}{r_{1\varepsilon}}\log r_{1\varepsilon} + O(\varepsilon), \end{aligned}$$

where

$$d = \frac{1}{\pi} \int_{\mathbb{R}^2} w(|s|) w'(|s|) \frac{1}{|s|} \,\mathrm{d}s > 0.$$
(6.3)

Hence, there holds

$$I_1 \equiv \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{E} dx = -2\pi\varepsilon \left. \frac{\partial V}{\partial \tilde{r}} \right|_{(\tilde{r}_{1\varepsilon},0)} \log \frac{1}{\varepsilon} - 2 \, d \, \pi \frac{1}{r_{1\varepsilon}} \log r_{1\varepsilon} + O(\varepsilon).$$
(6.4)

Using Proposition 5.3, and the expression in (4.22), we deduce that

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{N}(\psi) = \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} N_2(\psi) = O(\varepsilon).$$

On the other hand, integration by parts, we have

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{L}(\psi) = \operatorname{Re} \int_{\mathbb{R}^2} \bar{\psi} \mathcal{L}(\bar{\Lambda}) = O(\varepsilon).$$

Combining all estimates together and recalling $\tilde{r}_{1\varepsilon} = \tilde{r}_0 + \tilde{f}$, we obtain the following equation

$$c(\tilde{f}) = -2\varepsilon\pi \left[\left. \frac{\partial V}{\partial \tilde{r}} \right|_{(\tilde{r}_0 + \tilde{f}, 0)} \log \frac{1}{\varepsilon} + \frac{d}{\tilde{r}_0 + \tilde{f}} \log \frac{\tilde{r}_0 + \tilde{f}}{\varepsilon} \right] + O(\varepsilon), \tag{6.5}$$

where $O(\varepsilon)$ is a continuous function of the parameter \tilde{f} . By the solvability condition (1.4) and the non-degeneracy condition (1.6), we can find a zero of $c(\tilde{f})$ at some small \tilde{f} with the help of the simple mean-value theorem.

7. Traveling wave

The main object of this section to prove Theorem 1.5 by using the same method in previous sections.

7.1. The formulation of problem

Making rescaling $\tilde{y} = \varepsilon \tilde{y}$, problem (1.20) takes the form

$$\Delta u + \left(1 + \check{V}(\varepsilon \check{y}) - |u|^2\right) u + i\varepsilon |\log \varepsilon| \kappa \frac{\partial u}{\partial \check{y}_3} = 0.$$
(7.1)

Introduce a new coordinates $(r, \theta, \check{y}_3) \in (0, +\infty) \times (0, 2\pi] \times \mathbb{R}$ as the form

$$\check{y}_1 = r\cos\theta, \quad \check{y}_2 = r\sin\theta, \quad \check{y}_3 = \check{y}_3.$$

Then problem (7.1) takes the form

$$S[u] \equiv \left(\frac{\partial^2}{\partial r^2} + \frac{\partial^2}{\partial \check{y}_3^2} + \frac{1}{r^2}\frac{\partial^2}{\partial \theta^2} + \frac{1}{r}\frac{\partial}{\partial r}\right)u + \left(1 + \check{V}(\varepsilon r, \varepsilon \check{y}_3) - |u|^2\right)u + i\varepsilon|\log\varepsilon|\kappa\frac{\partial u}{\partial \check{y}_3} = 0.$$

In this paper, we want to construct a solution with a vortex ring, which does not depend on the variable θ . Hence, we consider a two-dimensional problem, for $(x_1, x_2) \in \mathbb{R}^2$

$$S[u] = \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)u + \left(1 + \check{V}(\varepsilon|x_1|, \varepsilon x_2) - |u|^2\right)u + i\varepsilon|\log\varepsilon|\kappa\frac{\partial u}{\partial x_2} = 0, \quad (7.2)$$

with Neumann boundary condition

$$\frac{\partial u}{\partial x_1}(0, x_2) = 0, \quad |u| \to 0 \text{ as } |x| \to +\infty.$$
(7.3)

Notations: As before, we have used $x = (x_1, x_2) = (r, \check{y}_3)$ and also write $\ell = |x|$. In this rescaled coordinates, we write

$$\check{r}_{1\varepsilon} \equiv \hat{r}_0/\varepsilon + \check{f} \equiv \hat{r}_{1\varepsilon}/\varepsilon \quad \text{with } \check{f} = \hat{f}/\varepsilon, \qquad \check{r}_{2\varepsilon} \equiv \hat{r}_{2\varepsilon}/\varepsilon,$$
(7.4)

where the constants \hat{f} , $\hat{r}_{1\varepsilon}$ and $\hat{r}_{2\varepsilon}$ are defined in (1.16) and (1.17). By setting, $\xi_{+} = (\check{r}_{1\varepsilon}, 0)$ and $\xi_{-} = (-\check{r}_{1\varepsilon}, 0)$, we introduce the translated variable

$$s = x - \xi_+$$
 or $s = x - \xi_-$, (7.5)

in a small neighborhood of the vortices. We will use these notations without any further statement in the sequel. $\hfill \Box$

To handle the influence of the potential, we here look for vortex ring solutions vanishing as |x| approaching $+\infty$. As we stated in (1.16), we assume that the vortex ring is characterized by the curve, in the original coordinates $\check{y} = (\check{y}_1, \check{y}_2, \check{y}_3)$

$$\sqrt{\check{y}_1^2 + \check{y}_2^2} = \check{r}_{1\varepsilon}, \quad \check{y}_3 = 0$$

In other words, in the two dimensional situation with (x_1, x_2) coordinates, we will construct a vortex with degree +1 at $(\check{r}_{1\varepsilon}, 0)$ and its anti-pair with degree -1 at $(-\check{r}_{1\varepsilon}, 0)$.

Finally, we decompose the operator as

$$S[u] = S_0[u] + S_1[u] + S_2[u],$$

with the explicit form

$$S_{0}[u] = \left(\frac{\partial^{2}}{\partial x_{1}^{2}} + \frac{\partial^{2}}{\partial x_{2}^{2}} + \frac{1}{x_{1}}\frac{\partial}{\partial x_{1}}\right)u, \qquad S_{1}[u] = \left(1 + \check{V}(\varepsilon|x_{1}|, \varepsilon x_{2}) - |u|^{2}\right)u,$$

$$S_{2}[u] = i\varepsilon \kappa |\log \varepsilon| \frac{\partial u}{\partial x_{2}}.$$
(7.6)

7.2. The approximation and its error

As we have done in (3.13) and (4.8), we decompose the plane into different regions D_1, D_2 and D_3 in form

$$D_{2} \equiv \left\{ (x_{1}, x_{2}) : \ell_{1} < \frac{\hat{\tau}_{0}}{\varepsilon} \text{ or } \ell_{2} < \frac{\hat{\tau}_{0}}{\varepsilon} \right\},$$

$$D_{1} \equiv \left\{ (x_{1}, x_{2}) : |x| < \hat{\tau}_{2\varepsilon} - \frac{\hat{\tau}_{1}}{\varepsilon} \right\} \setminus D_{2},$$

$$D_{3} = \left\{ (x_{1}, x_{2}) : |x| > \hat{\tau}_{2\varepsilon} - \frac{\hat{\tau}_{1}}{\varepsilon} \right\}.$$

$$(7.7)$$

and then we set

$$D_{2,1} \equiv \left\{ (x_1, x_2) : \ell_1 < 1 \right\}, \qquad D_{2,2} \equiv \left\{ (x_1, x_2) : \ell_2 < 1 \right\}, \\ D_{2,3} \equiv \left\{ (x_1, x_2) : \ell_1 < \frac{\hat{\tau}_0}{\varepsilon} \right\} \setminus D_{2,1}, \qquad D_{2,4} \equiv \left\{ (x_1, x_2) : \ell_2 < \frac{\hat{\tau}_0}{\varepsilon} \right\} \setminus D_{2,2}, \quad (7.8) \\ D_{3,1} \equiv \left\{ (x_1, x_2) : \hat{r}_{2\varepsilon} - \frac{\hat{\tau}_1}{\varepsilon} < |x| < \hat{r}_{2\varepsilon} + \frac{\hat{\tau}_2}{\varepsilon} \right\}, \qquad D_{3,2} \equiv \left\{ (x_1, x_2) : |x| > \hat{r}_{2\varepsilon} + \frac{\hat{\tau}_2}{\varepsilon} \right\}.$$

where $\hat{\tau}_0$, $\hat{\tau}_1$, $\hat{\tau}_2$, $\hat{r}_{1\varepsilon}$ and $\hat{r}_{2\varepsilon}$ are given in the assumption (**P3**). Here we still use the same notations to denote the regions. The reader can refer to Figure 1.

By defining smooth cut-off functions as follows

$$\tilde{\eta}_2(s) = \begin{cases} 1, & |s| \le \check{\tau}_3, \\ 0, & |s| \ge 2\check{\tau}_3; \end{cases} \qquad \tilde{\eta}_3(s) = \begin{cases} 1, & s \ge -\check{\tau}_4, \\ 0, & s \le -2\check{\tau}_4; \end{cases}$$
(7.9)

where $\check{\tau}_3, \check{\tau}_4 < \min\{\hat{r}_0, \hat{\tau}_0, \hat{\tau}_1, \hat{\tau}_2\}/10$, we then choose the approximate solution to (7.2)-(7.3) by, for $(x_1, x_2) \in \mathbb{R}^2$,

$$u_2(x_1, x_2) = \sqrt{1 + \check{V}(\varepsilon | x_1 |, \varepsilon x_2)} \eta_1 e^{i\varphi} + w(\ell_2) w(\ell_1) \eta_2 e^{i\varphi} + \hat{q}(x_1, x_2) \eta_3 e^{i\varphi},$$
(7.10)

where the new phase term $\varphi = \varphi_0 + \varphi_1$ with the functions φ_0 and φ_1 defined in (3.14) and (3.27). The cut-off functions are defined by

$$\eta_1(\varepsilon x_1, \varepsilon x_2) = 1 - \eta_2 - \eta_3, \eta_2(\varepsilon x_1, \varepsilon x_2) = \tilde{\eta}_2(\varepsilon \ell_1) + \tilde{\eta}_2(\varepsilon \ell_2), \eta_3(\varepsilon x_1, \varepsilon x_2) = \tilde{\eta}_3(\varepsilon(\ell - \check{r}_{2\varepsilon})).$$

By recalling the functions U_1, U_2, U_3 in (3.15), (3.14), (3.32), we also write the approximation as

$$u_2 = U_1 \eta_1 e^{i\varphi_1} + U_2 \eta_2 e^{i\varphi_1} + U_3 \eta_3 e^{i\varphi_1}.$$
(7.11)

It is easy to check that u_2 has the symmetry

$$u_2(x_1, x_2) = \overline{u_2(x_1, -x_2)}, \qquad u_2(x_1, x_2) = u_2(-x_1, x_2).$$
 (7.12)

Moreover, there holds

$$\left. \frac{\partial u_2}{\partial x_1} \right|_{(0,x_2)} = 0. \tag{7.13}$$

As we have stated, we work directly in the half space $\mathbb{R}^2_+ = \{(x_1, x_2) : x_1 > 0\}$ in the sequel because of the symmetry of the problem. Recalling the definitions of the operators in (7.6), let us

start to compute the error:

$$\mathbb{E} = S[u_2]
= S[U_1]\eta_1 e^{i\varphi_1} + U_1 S_0[\eta_1 e^{i\varphi_1}] + 2i e^{i\varphi_1} \nabla U_1 \cdot \nabla \varphi_1
+ S[U_2]\eta_2 e^{i\varphi_1} + U_2 S_0[\eta_2 e^{i\varphi_1}] + 2i e^{i\varphi_2} \nabla U_1 \cdot \nabla \varphi_1
+ S[U_3]\eta_3 e^{i\varphi_1} + U_3 S_0[\eta_3 e^{i\varphi_1}] + 2i e^{i\varphi_1} \nabla U_3 \cdot \nabla \varphi_1 + \mathbb{N},$$
(7.14)

where the nonlinear term \mathbb{N} is defined by

$$\mathbb{N} = \eta_1 |U_1|^2 U_1 e^{i\varphi_1} + \eta_2 |U_2|^2 U_2 e^{i\varphi_1} + \eta_3 |U_3|^2 U_3 e^{i\varphi_1} - |u_2|^2 u_2.$$

The main components in the above formula can be estimated as before.

It is worth to mention that, in the vortex-core region $\{(x_1, x_2) : \ell_2 < 1 \text{ or } \ell_1 < 1\}$, we estimate the error by

$$\mathbb{E} = U_2 \eta_2 e^{i\varphi_1} \left[\frac{x_1 - \check{r}_{1\varepsilon}}{x_1 \ell_2} \frac{w'(\ell_2)}{w(\ell_2)} + \varepsilon \frac{\partial \check{V}}{\partial \check{r}} \Big|_{(\varepsilon\check{r}_{1\varepsilon},0)} (x_1 - \check{r}_{1\varepsilon}) \right]
+ \eta_2 U_2 e^{i\varphi_1} \frac{2(x_1 + \check{r}_{1\varepsilon})(x_1 - \check{r}_{1\varepsilon})}{(\ell_1 \ell_2)^2} \log \check{r}_{1\varepsilon} - i\eta_2 U_2 e^{i\varphi_1} \frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} \frac{1}{\check{r}_{1\varepsilon}} \log \check{r}_{1\varepsilon}$$
(7.15)

$$+ \kappa \varepsilon |\log \varepsilon| \eta_2 U_2 e^{i\varphi_1} \left[i \frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} - \frac{2(x_1^2 - x_2^2 - (\check{r}_{1\varepsilon})^2)\check{r}_{1\varepsilon}}{(\ell_1 \ell_2)^2} \right] + O(\varepsilon \log \ell_2).$$

The singularity of the last two terms in the above formula will play an important role in the final reduction step.

For a function $h = h_1 + ih_2$ with real functions h_1, h_2 , define a norm of the form

$$\begin{split} ||h||_{**} &\equiv \sum_{j=1}^{2} ||iu_{2}h||_{L^{p}(\ell_{j}<3)} + \sum_{j=1}^{2} \left[||\ell_{j}^{2+\sigma}h_{1}||_{L^{\infty}(\tilde{D})} + ||\ell_{j}^{1+\sigma}h_{2}||_{L^{\infty}(\tilde{D})} \right] \\ &+ \sum_{j=1}^{2} ||h_{j}||_{L^{p}(D_{3})} \,. \end{split}$$

where we have denoted \tilde{D} by

$$\tilde{D} = D_1 \cup D_2 \setminus \{\ell_1 < 3 \text{ or } \ell_2 < 3\}.$$
(7.16)

As a conclusion, we have the following lemma.

Lemma 7.1. There holds for $\ell_1 > 2$ and $\ell_2 > 2$

$$\begin{aligned} \left| \operatorname{Re}(\mathbb{E}) \right| &\leq \frac{C\varepsilon^{1-\sigma}}{(1+\ell_1)^3} + \frac{C\varepsilon^{1-\sigma}}{(1+\ell_2)^3}, \\ \left| \operatorname{Im}(\mathbb{E}) \right| &\leq \frac{C\varepsilon^{1-\sigma}}{(1+\ell_1)^{1+\sigma}} + \frac{C\varepsilon^{1-\sigma}}{(1+\ell_2)^3}, \\ \left\| \mathbb{E} \right\|_{L^p(\{\ell_1 < 3\} \cup \{\ell_2 < 3\})} &\leq C\varepsilon |\log \varepsilon|, \end{aligned}$$

where $\sigma \in (0,1)$ is a constant. As a consequence, there also holds

$$||\mathbb{E}||_{**} \le C\varepsilon^{1-\sigma}.$$

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7.3. Local setting-up of the problem

We look for a solution $u = u(x_1, x_2)$ to problem (7.2)-(7.3) in the form of small perturbation of u_2 , with additional symmetry:

$$u(x_1, x_2) = \bar{u}(x_1, -x_2). \tag{7.17}$$

Let $\tilde{\chi}:\mathbb{R}\to\mathbb{R}$ be a smooth cut-off function defined by

$$\tilde{\chi}(s) = \begin{cases} 1, & s \le 1, \\ 0, & s \ge 2. \end{cases}$$
(7.18)

Recalling (7.9)-(7.11) and setting the components of the approximation u_2 as

$$v_1(x_1, x_2) = \eta_1 U_1 e^{i\varphi_1}, \quad v_2(x_1, x_2) = \eta_2 U_2 e^{i\varphi_1}, \quad v_3(x_1, x_2) = \eta_3 U_3 e^{i\varphi_1}, \tag{7.19}$$

we want to choose the ansatz of the form

$$u = \left[\chi(v_2 + iv_2\psi) + (1 - \chi)(v_1 + v_2)e^{i\psi}\right] + \left[v_3 + i\eta_3 e^{i\varphi}\psi\right],\tag{7.20}$$

where $\chi(x_1, x_2) = \tilde{\chi}(\ell_2) + \tilde{\chi}(\ell_1)$.

To find the perturbation terms, the main object of this subsection is to write the equation for the perturbation as a linear one with a right hand side given by a lower order nonlinear term. The symmetry imposed on u can be transmitted to the symmetry on the perturbation terms

$$\psi(x_1, -x_2) = -\overline{\psi(x_1, x_2)}, \quad \psi(x_1, x_2) = \psi(-x_1, x_2).$$
 (7.21)

Let us observe that

$$u = \left[(v_1 + v_2) + i(v_1 + v_2)\psi + (1 - \chi)(v_1 + v_2)(e^{i\psi} - 1 - i\psi) \right] + (v_3 + \eta_3 e^{i\varphi}\psi)$$

= $u_2 + i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma,$

where we have denoted

$$\Gamma = (1 - \chi)(v_1 + v_2)(e^{i\psi} - 1 - i\psi).$$
(7.22)

A direct computation shows that u is a solution to problem (7.2)-(7.3) if and only if

$$i(v_{1}+v_{2})S_{0}[\psi] + 2i \bigtriangledown (v_{1}+v_{2}) \cdot \bigtriangledown \psi + i(v_{1}+v_{2})S_{2}[\psi] + \eta_{3} e^{i\varphi}S_{0}[\psi] + \eta_{3} e^{i\varphi}S_{2}[\psi] + i\Big[1 + \check{V} - |u_{2}|^{2}\Big](v_{1}+v_{2})\psi - 2\operatorname{Re}(\bar{u}_{2}i(v_{1}+v_{2})\psi)u_{2} + iS_{0}[v_{1}+v_{2}]\psi + iS_{2}[v_{1}+v_{2}]\psi + 2\bigtriangledown (\eta_{3} e^{i\varphi}) \cdot \bigtriangledown \psi + S_{0}[\eta_{3} e^{i\varphi}]\psi$$
(7.23)
$$+ S_{2}\Big[\eta_{3} e^{i\varphi}\Big]\psi + \eta_{3} e^{i\varphi}(1 + \check{V} - |u_{2}|^{2})\psi - 2\eta_{3}\operatorname{Re}(\bar{u}_{2}e^{i\varphi}\psi)u_{2} = -E + N,$$

where the error term E is defined as \mathbb{E} in (7.14) and N is the nonlinear operator defined by

$$N = -S_0[\Gamma] - S_2[\Gamma] - (1 + \check{V} - |u_2|^2)\Gamma + \left[2\operatorname{Re}(\bar{u}_2 i(v_1 + v_2)\psi) + 2\eta_3 \operatorname{Re}(\bar{u}_2 e^{i\varphi}\psi)\right] \times \left(i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma\right) + \left[2\operatorname{Re}(\bar{u}_2\Gamma) + \left|i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma\right|^2\right] \times \left(u_2 + i(v_1 + v_2)\psi + \eta_3 e^{i\varphi}\psi + \Gamma\right).$$

We shall explicitly write the equation in suitable local forms and then analyze the property of the corresponding linear operators, which will be done in the following.

In the region

$$D_1 = \left\{ (x_1, x_2) : |x| < \check{r}_{2\varepsilon} - \hat{\tau}_1 / \varepsilon \right\} \setminus D_2,$$

far from the vortex core region, directly from the form of the ansatz $u = u_2 e^{i\psi}$ with the approximation as

$$u_2(x_1, x_2) = \sqrt{1 + \check{V}} \eta_1 e^{i(\varphi_0 + \varphi_1)} + w(\ell_2) w(\ell_1) \eta_2 e^{i(\varphi_0 + \varphi_1)},$$

we see that the equation (7.23) takes the simple form

$$L_1(\psi) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi + 2\frac{\nabla u_2}{u_2} \cdot \nabla \psi - 2i|u_2|^2\psi_2 + i\varepsilon|\log\varepsilon|\kappa\frac{\partial\psi}{\partial x_2}$$
$$= E_1 - i(\nabla\psi)^2 + i|u_2|^2\left(1 - e^{-2\psi_2} + 2\psi_2\right),$$

where $E_1 = i\mathbb{E}/u_2$. We intend next to describe in more accurate form the equation above. Let us also write

$$u_2 = e^{i\varphi}\beta_1$$
 with $\beta_1 = \sqrt{1 + \check{V}}\eta_1 + w(\ell_2)w(\ell_1)\eta_2$.

For $|x| < \check{r}_{2\varepsilon} - 2\hat{\tau}_0/\varepsilon$, there holds,

$$u_2 = \beta_1 e^{i\varphi} = \sqrt{1 + \check{V}} e^{i\varphi},$$

and hence, by using the assumption $(\mathbf{P}3)$, we have

$$|u_2|^2 = 1 + \check{V} > \hat{c}_1.$$

Direct computation also gives that

$$2\frac{\nabla u_2}{u_2} \cdot \nabla \psi = \frac{2}{\beta_1} \nabla \beta_1 \cdot \nabla \psi_1 - 2 \nabla \varphi \cdot \nabla \psi_2 + i\frac{2}{\beta_1} \nabla \beta_1 \cdot \nabla \psi_2 + 2i \nabla \varphi \cdot \nabla \psi_1$$
$$= (A_1, 0) \cdot \nabla \psi_1 - (A_2, B_2) \cdot \nabla \psi_2 + i(A_1, 0) \cdot \nabla \psi_2 + i(A_2, B_2) \cdot \nabla \psi_1,$$

where $A_1 = O(\varepsilon)$, $A_2 = O(\varepsilon)$, $B_2 = O(\varepsilon)$. For $\check{r}_{1\varepsilon} - 2\hat{\tau}_0/\varepsilon < |x| < \check{r}_{1\varepsilon} - \hat{\tau}_0/\varepsilon$, similar estimates hold. The equations become

$$\tilde{L}_1(\psi_1) = \tilde{E}_1 + \tilde{N}_1, \qquad \bar{L}_1(\psi_2) = \bar{E}_1 + \bar{N}_1.$$

In the above, we have denoted the linear operators by

$$\tilde{L}_{1}(\psi_{1}) \equiv \left(\frac{\partial^{2}}{\partial x_{1}^{2}} + \frac{\partial^{2}}{\partial x_{2}^{2}} + \frac{1}{x_{1}}\frac{\partial}{\partial x_{1}}\right)\psi_{1} - \varepsilon|\log\varepsilon|\kappa\frac{\partial\psi_{2}}{\partial x_{2}} + \frac{2}{\beta_{1}}\bigtriangledown\beta_{1}\cdot\bigtriangledown\psi_{1},$$

$$\bar{L}_{1}(\psi_{2}) \equiv \left(\frac{\partial^{2}}{\partial x_{1}^{2}} + \frac{\partial^{2}}{\partial x_{2}^{2}} + \frac{1}{x_{1}}\frac{\partial}{\partial x_{1}}\right)\psi_{2} - 2|u_{2}|^{2}\psi_{2} + \varepsilon|\log\varepsilon|\kappa\frac{\partial\psi_{1}}{\partial x_{2}} + \frac{2}{\beta_{1}}\bigtriangledown\beta_{1}\cdot\bigtriangledown\psi_{2}.$$

The nonlinear operators are

$$\begin{split} \tilde{N}_1 &= -2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_2 + 2 \bigtriangledown \psi_1 \cdot \bigtriangledown \psi_2, \\ \bar{N}_1 &= 2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_1 + |u_2|^2 \big(1 - e^{-2\psi_2} + 2\psi_2 \big) + |\bigtriangledown \psi_1|^2 - |\bigtriangledown \psi_2|^2. \end{split}$$

Consider the vortex-core region D_{21} and D_{22} . Here we only argue in the region D_{22} . It is more convenient to do this in the translated variable $(s_1, s_2) = (x_1 - \check{r}_{1\varepsilon}, x_2)$ and then denote $\ell = \ell_2$ for brevity of notation. Now the term ψ is small, however possibly unbounded near the vortex. Whence, in the sequel, by setting

$$\tilde{\phi} = iv_2\psi \quad \text{with } \psi = \psi_1 + i\psi_2, \tag{7.24}$$

we shall require that $\tilde{\phi}$ is bounded (and smooth) near the vortices. We shall write the equation in term of a type of the function $\tilde{\phi}$ for $\ell < \delta/\varepsilon$. In the region D_{22} , let us write u_2 , i.e. v_2 , as the form

$$v_2 = \beta U_0 \quad \text{with } \beta = w(\ell_1) e^{-i\varphi_0^- + i\varphi_1},$$
 (7.25)

where U_0 is defined in (2.1). We define the function

$$\phi(s) = iU_0\psi \quad \text{for } |s| < \delta/\varepsilon, \tag{7.26}$$

namely

$$\tilde{\phi} = \beta \phi$$

Hence, in the translated variable, the ansatz becomes in this region

$$u_2 = \beta(s)U_0 + \beta(s)\phi + (1-\chi)\beta(s)U_0 \left(e^{\phi/U_0} - 1 - \frac{\phi}{U_0}\right)$$

We also call $\Gamma_{2,2} = (1-\chi)U_0 \left(e^{\phi/U_0} - 1 - \frac{\phi}{U_0}\right)$. The support of this function is contained in set |s| > 1. In this vortex-core region, the problem, written in (s_1, s_2) coordinates, can be stated as

$$L_{2,2}(\phi) = E_{2,2} + N_{2,2}.$$

Let us consider the linear operator defined in the following way: for ϕ and ψ linked through formula (7.26) we set

$$\begin{split} L_{2,2}(\phi) &= L_0(\phi) + \frac{1}{s_1 + \check{r}_{1\varepsilon}} \frac{\partial}{\partial s_1} \phi + 2\left(1 - |\beta|^2\right) \operatorname{Re}(\bar{U}_0 \phi) U_0 + i\varepsilon |\log \varepsilon| \kappa \frac{\partial \phi}{\partial x_2} \\ &+ \left[\varepsilon \frac{\partial \check{V}}{\partial \tilde{r}}\Big|_{\left(\check{r}_{1\varepsilon} + \vartheta s_1, 0\right)} + 1 - |\beta|^2\right] \phi + 2 \frac{\nabla \beta}{\beta} \cdot \nabla \phi + \chi \frac{E_{2,2}}{U_0} \phi, \end{split}$$

where ϑ is a small constant. Here we also have defined L_0 as

$$L_0(\phi) = \left(\frac{\partial^2}{\partial s_1^2} + \frac{\partial^2}{\partial s_2^2}\right)\phi + (1 - |w|^2)\phi - 2\operatorname{Re}(\bar{U}_0\phi)U_0.$$

Here, by writing the error \mathbb{E} in the translated variable s, the error $E_{2,2}$ is given by

$$E_{2,2} = \mathbb{E}/\beta.$$

Observe that, in the region D_{22} , the error $E_{2,2}$ takes the expression

$$E_{2,2} = w(\ell_2)e^{i\varphi_0^+} \left[\frac{x_1 - \check{r}_{1\varepsilon}}{x_1\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} + \varepsilon \frac{\partial\check{V}}{\partial\check{r}} \Big|_{(\varepsilon\check{r}_{1\varepsilon},0)} (x_1 - \check{r}_{1\varepsilon}) \right] + w(\ell_2)e^{i\varphi_0^+} \frac{2(x_1 + \check{r}_{1\varepsilon})(x_1 - \check{r}_{1\varepsilon})}{(\ell_1\ell_2)^2} \log\check{r}_{1\varepsilon} - iw(\ell_2)e^{i\varphi_0^+} \frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} \frac{1}{\check{r}_{1\varepsilon}} \log\check{r}_{1\varepsilon}$$
(7.27)
$$+ \varepsilon |\log\varepsilon| \kappa w(\ell_2)e^{i\varphi_0^+} \left[i\frac{x_2}{\ell_2} \frac{w'(\ell_2)}{w(\ell_2)} - \frac{2(x_1^2 - x_2^2 - (\check{r}_{1\varepsilon})^2)\check{r}_{1\varepsilon}}{(\ell_1\ell_2)^2} \right] + O(\varepsilon \log \ell_2).$$

while the nonlinear term is given by

$$N_{2,2}(\phi) = -\frac{\Delta(\beta\Gamma_{2,2})}{\beta} + \left(1 + \check{V} - |U_0|^2\right)\Gamma_{2,2} - 2|\beta|^2 \operatorname{Re}(\bar{U}_0\phi)(\phi + \Gamma_{2,2}) - S_2[\Gamma] - \left(2|\beta|^2 \operatorname{Re}(\bar{U}_0\Gamma_{2,2}) + |\beta|^2 |\phi + \Gamma_{2,2}|^2\right) (U_0 + \phi + \Gamma_{2,2}) + (\chi - 1)\frac{E_{2,2}}{U_0}\phi.$$
(7.28)

Taking into account to the explicit form of the function β we get

$$\nabla \beta = O(\varepsilon), \quad \Delta \beta = O(\varepsilon^2), \quad |\beta| \sim 1 + O(\varepsilon^2),$$

provided that $|s| < \delta/\varepsilon$. With this in mind, we see that the linear operator is a small perturbation of L_0 .

In the region

$$D_{2,4} = \{(x_1, x_2) : \ell_2 < \hat{\tau}_0 / \varepsilon\} \setminus D_2,$$

far from the vortex core, directly from the form of the ansatz $u = (1 - \chi)u_2 e^{i\psi}$, we see that, for $\ell_2 > 2$, the equation takes the simple form

$$L_{2,4}(\psi) \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi + 2\frac{\nabla u_2}{u_2}\cdot\nabla\psi - 2i|u_2|^2\psi_2 + i\varepsilon|\log\varepsilon|\kappa\frac{\partial\psi}{\partial x_2}$$
$$= E_{2,4} - i(\nabla\psi)^2 + i|u_2|^2\left(1 - e^{-2\psi_2} + 2\psi_2\right),$$

where $E_{2,4} = i\mathbb{E}/u_2$. We intend next to describe in more accurate form the equation above. As before, let us also write

$$u_2 = \beta U_0$$
 with $\beta = w(\ell_1)e^{-i\varphi_0^- + i\varphi_1}$.

For $\ell_2 < \hat{\tau}_0 / \varepsilon$, there are two real functions A and B such that

$$\beta = e^{iA+B},$$

furthermore, a direct computation shows that, in this region, there holds

$$\nabla A = O(\varepsilon), \qquad \triangle A = O(\varepsilon^2), \qquad \nabla B = O(\varepsilon^3), \qquad \triangle B = O(\varepsilon^4).$$

The equations become

$$\tilde{L}_{2,4}(\psi_1) = \tilde{E}_{2,4} + \tilde{N}_{2,4}, \qquad \bar{L}_{2,4}(\psi_2) = \bar{E}_{2,4} + \bar{N}_{2,4}$$

In the above, we have denoted the linear operators by

$$\begin{split} \tilde{L}_{2,4}(\psi_1) &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_1 + \left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right)\cdot\bigtriangledown\psi_1 - \varepsilon|\log\varepsilon|\kappa\frac{\partial\psi_2}{\partial x_2},\\ \bar{L}_{2,4}(\psi_2) &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2} + \frac{1}{x_1}\frac{\partial}{\partial x_1}\right)\psi_2 - 2|u_2|^2\psi_2 \\ &+ 2\left(\bigtriangledown B + \frac{w'(\ell_2)}{w(\ell_2)}\frac{s}{\ell_2}\right)\cdot\bigtriangledown\psi_2 + \varepsilon|\log\varepsilon|\kappa\frac{\partial\psi_1}{\partial x_2}, \end{split}$$

where we have used $s = (x_1 - \check{r}_{1\varepsilon}, x_2)$. The nonlinear operators are

$$\tilde{N}_{2,4} = -2(\nabla A + \nabla \varphi_0^+) \cdot \nabla \psi_2 + 2 \nabla \psi_1 \nabla \psi_2,$$

$$\bar{N}_{2,4} = -2(\nabla A + \nabla \varphi_0^+) \cdot \nabla \psi_1 + |u_2|^2 (1 - e^{-2\psi_2} + 2\psi_2) + |\nabla \psi_1|^2 - |\nabla \psi_2|^2.$$

In the region

$$D_{3,1} = \left\{ (x_1, x_2) : \check{r}_{2\varepsilon} - \hat{\tau}_1 / \varepsilon < |x| < \check{r}_{2\varepsilon} + \hat{\tau}_2 / \varepsilon \right\}$$

the approximation takes the form

$$u_2 = w(\ell_2)w(\ell_1)\eta_2 e^{i\varphi} + \hat{q}(x_1, x_2)\eta_3 e^{i\varphi}.$$

We write the ansatz as

$$u = u_2 + i e^{i\varphi} \psi + \Gamma_{3,1},$$

where $\Gamma_{3,1}$ is defined as

$$\Gamma_{3,1} = i\eta_2 \Big(w(\ell_1)w(\ell_2) - 1 \Big) e^{i\varphi} \psi + \eta_2 w(\ell_1)w(\ell_2) e^{i\varphi} \Big(e^{i\psi} - 1 - i\psi \Big).$$

The equation becomes

$$\begin{split} L_{3,1}[\psi] &\equiv S_0[\psi] + 2i \bigtriangledown \varphi \cdot \bigtriangledown \psi - |\bigtriangledown \varphi|^2 \psi + iS_0[\varphi]\psi + i\varepsilon |\log \varepsilon| \kappa \frac{\partial \psi}{\partial x_2} \\ &+ \left(1 + \check{V} - |u_2|^2\right) \psi + 2ie^{-i\varphi} \operatorname{Re}\left(\bar{u}_2 i e^{i\varphi} \psi\right) u_2 \\ &= E_{3,1} + N_{3,1}, \end{split}$$

where $E_{3,1} = ie^{-i\varphi}\mathbb{E}$. The nonlinear operator is defined by

$$N_{3,1}(\psi) = ie^{-i\varphi} \Big[\bigtriangleup \Gamma_{3,1} + \frac{1}{x_1} \frac{\partial}{\partial x_1} \Gamma_{3,1} + (1 + \check{V} - |u_2|^2) \Gamma_{3,1} \Big] \\ - ie^{-i\varphi} \Big[2\operatorname{Re}(\bar{u}_2\Gamma_{3,1}) - \left| ie^{i\varphi}\psi + \Gamma_{3,1} \right|^2 \Big] (u_2 + ie^{i\varphi}\psi + \Gamma_{3,1}) \\ - 2ie^{-i\varphi}\operatorname{Re}(\bar{u}_2 ie^{i\varphi}\psi) (ie^{i\varphi}\psi + \Gamma_{3,1}) + i\varepsilon |\log\varepsilon| \kappa \frac{\partial\Gamma_{3,1}}{\partial x_2}.$$

More precisely, in the region $D_{3,1}$, the linear operator $L_{3,1}$ is defined as

$$\begin{split} L_{3,1}[\psi] &= S_0[\psi] - \left(\delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon}) + \hat{q}^2\right)\psi + 2ie^{-i\varphi}\mathrm{Re}\big(\bar{u}_2 i e^{i\varphi}\psi\big)u_2 \\ &+ \left[1 + \check{V} + \delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon})\right]\psi \\ &+ i\varepsilon|\log\varepsilon|\kappa\frac{\partial\psi}{\partial x_2} + 2i\bigtriangledown\varphi\cdot\bigtriangledown\psi + S_0[\varphi]\psi - |\bigtriangledown\varphi|^2\psi \end{split}$$

where we have used the definition of \hat{q} in (3.31). We shall analyze other terms in the linear operator $L_{3,1}$. For $\check{r}_{2\varepsilon} - \hat{\tau}_1/\varepsilon < |x| < \check{r}_{2\varepsilon} + \hat{\tau}_2/\varepsilon$, there holds $u_2 = \hat{q}e^{i\varphi}$. It is obvious that

$$2ie^{-i\varphi}\operatorname{Re}(\bar{u}_2ie^{i\varphi}\psi)u_2 = -2i\hat{q}^2\psi_2$$

For $\check{r}_{2\varepsilon} - 2\hat{\tau}_1/\varepsilon < |x| < \check{r}_{2\varepsilon} - \hat{\tau}_1/\varepsilon$, there holds

$$u_2 = w(\ell_2)w(\ell_1) \eta_2 e^{i\varphi} + \hat{q} \eta_3 e^{i\varphi}.$$

The equations become

$$\begin{split} \tilde{L}_{3,1}[\psi_1] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right) \psi_1 - \left(\delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon}) + \hat{q}^2\right) \psi_1 - \varepsilon |\log \varepsilon| \kappa \frac{\partial \psi_2}{\partial x_2} \\ &+ \left[1 + \check{V} + \delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon})\right] \psi_1 \\ &+ \frac{1}{x_1} \frac{\partial}{\partial x_1} \psi_1 - 2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_2 + S_0[\varphi] \psi_1 - |\bigtriangledown \varphi|^2 \psi_1 \\ &= \tilde{E}_{3,1} + \tilde{N}_{3,1}, \end{split}$$

$$\begin{split} \bar{L}_{3,1}[\psi_2] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - \left(\delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon}) + 3\hat{q}^2\right)\psi_2 + \varepsilon|\log\varepsilon|\kappa\frac{\partial\psi_1}{\partial x_2} \\ &+ \left[1 + \check{V} + \delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon})\right]\psi_2 \\ &+ \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 + 2\bigtriangledown\varphi\cdot\bigtriangledown\psi_1 + S_0[\varphi]\psi_2 - |\bigtriangledown\varphi|^2\psi_2 \\ &= \bar{E}_{3,1} + \bar{N}_{3,1}. \end{split}$$

Now, there hold

$$\Xi_{3,1} \equiv 1 + \check{V} + \delta_{\varepsilon} (\ell - \check{r}_{2\varepsilon}) = \frac{1}{2} \varepsilon^2 \check{V}''(\check{r}_{2\varepsilon}) (\ell - \check{r}_{2\varepsilon})^2 + O\Big((\ell - \check{r}_{2\varepsilon})^3 \Big).$$

The other terms with φ_0 are also lower order terms. Whence the linear operators $\tilde{L}_{3,1}$ and $\bar{L}_{3,1}$ are small perturbations of the following linear operators

$$L_{31*}[\psi_1] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_1 - \left(\delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon}) + \hat{q}^2\right)\psi_1,$$

$$L_{31**}[\psi_2] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 - \left(\delta_{\varepsilon}(\ell - \check{r}_{2\varepsilon}) + 3\hat{q}^2\right)\psi_2$$

In the region $D_{3,2} = \{(x_1, x_2) : |x| > \check{r}_{2\varepsilon} + \hat{\tau}_2/\varepsilon\}$, the approximation takes the form

$$u_2 = \hat{q}e^{i\varphi}$$

and the ansatz is

$$u = u_2 + i e^{i\varphi} \psi.$$

The equation becomes

$$\begin{split} L_{3,2}[\psi] &\equiv S_0[\psi] + (1+\check{V})\psi - |u_2|^2\psi + 2ie^{-i\varphi} \operatorname{Re}(\bar{u}_2 i e^{i\varphi}\psi)u_2 \\ &+ i\varepsilon |\log\varepsilon|\kappa \frac{\partial\psi}{\partial x_2} - |\bigtriangledown\varphi|^2\psi + iS_0[\varphi]\psi + 2i\bigtriangledown\varphi\cdot\bigtriangledown\psi \\ &= E_{3,2} + N_{3,2}, \end{split}$$

where $E_{3,2} = ie^{-i\varphi}\mathbb{E}$. The nonlinear operator is defined by

$$N_{3,2}(\psi) = -ie^{-i\varphi}(u_2 + ie^{i\varphi}\psi)|\psi|^2 + 2i\operatorname{Re}(\bar{u}_2 ie^{i\varphi}\psi)\psi.$$

More precisely, for other term, we have

$$-|u_2|^2\psi + 2ie^{-i\varphi}\operatorname{Re}(\bar{u}_2ie^{i\varphi}\psi)u_2 = -\hat{q}^2\psi_1 - 3i\hat{q}^2\psi_2.$$

The equations are

$$\begin{split} \tilde{L}_{3,2}[\psi_1] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right) \psi_1 + \left(1 + \check{V}\right) \psi_1 - \varepsilon |\log \varepsilon| \kappa \frac{\partial \psi_2}{\partial x_2} \\ &- \hat{q} \,\psi_1 + \frac{1}{x_1} \frac{\partial}{\partial x_1} \psi_2 - |\bigtriangledown \varphi|^2 \psi_1 + i S_0[\varphi] \psi_1 - 2 \bigtriangledown \varphi \cdot \bigtriangledown \psi_2 \\ &= \tilde{E}_{3,2} + \tilde{N}_{3,2}, \end{split}$$

$$\begin{split} \bar{L}_{3,2}[\psi_2] &\equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right)\psi_2 + (1 + \check{V})\psi_2 + \varepsilon |\log\varepsilon|\kappa \frac{\partial\psi_1}{\partial x_2} \\ &- \hat{q}\,\psi_2 + \frac{1}{x_1}\frac{\partial}{\partial x_1}\psi_2 - |\nabla\varphi|^2\psi_2 + iS_0[\varphi]\psi_2 + 2\,\nabla\varphi\cdot\nabla\psi_1 \\ &= \bar{E}_{3,2} + \bar{N}_{3,2}. \end{split}$$

The assumption (P3) implies that, for any sufficiently small ε there holds

$$\Xi_{3,2} = 1 + \check{V} < -\hat{c}_2 \quad \text{for } |x| > \check{r}_{2\varepsilon} + \hat{\tau}_2/\varepsilon.$$

The other terms with φ_0 are lower order terms. From the asymptotic properties of q in Lemma 2.4, $\hat{q} \psi_2$ and $\hat{q} \psi_1$ are also lower order term. Whence the linear operators L_{51} and L_{52} are small perturbations of the following linear operator

$$L_{32*}[\tilde{\psi}] \equiv \left(\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}\right) \tilde{\psi} + (1 + \check{V}) \tilde{\psi}.$$

Let χ be the cut-off function defined in (7.18). By recalling the definition of β in (7.25), we define

$$\Lambda \equiv \frac{\partial u_2}{\partial \check{f}} \cdot \frac{\chi \left(|x - \xi_+|/\varepsilon \right) + \chi \left(|x - \xi_-|/\varepsilon \right)}{\beta} \,. \tag{7.29}$$

In summary, for any given \check{f} in (7.4), we want to solve the projected equation for ψ satisfying the symmetry (7.21)

$$\mathcal{L}(\psi) = \mathcal{N}(\psi) + \mathcal{E} + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0,$$
 (7.30)

where have denoted

$$\mathcal{L}(\psi) = L_1(\phi) \text{ in } D_1, \quad \mathcal{L}(\psi) = L_{2,j}(\psi) \text{ in } D_{2,j} \text{ for } j = 1, 2, 3, 4,$$
$$\mathcal{L}(\psi) = L_{3,1}(\psi) \text{ in } D_{3,1}, \quad \mathcal{L}(\psi) = L_{3,2}(\psi) \text{ in } D_{3,2},$$

with the relation

$$\phi = i u_2 \psi \quad \text{in } D_2. \tag{7.31}$$

As we have stated, the nonlinear operator \mathcal{N} and the error term \mathcal{E} also have suitable local forms in different regions.

7.4. The resolution of the projected nonlinear problem

For fixed small positive numbers $0 < \sigma < 1$, $0 < \gamma < 1$, we define

$$\begin{split} ||\psi||_{*} &\equiv \sum_{i=1}^{2} \left[||\phi||_{W^{2,p}(\ell_{i}<3)} + ||\ell_{i}^{\sigma}\psi_{1}||_{L^{\infty}(\tilde{D})} + ||\ell_{i}^{1+\sigma}\bigtriangledown\psi_{1}||_{L^{\infty}(\tilde{D})} \right. \\ &+ ||\ell_{i}^{1+\sigma}\psi_{2}||_{L^{\infty}(\tilde{D})} + ||\ell_{i}^{2+\sigma}\bigtriangledown\psi_{2}||_{L^{\infty}(\tilde{D})} \left. \right] + ||\psi||_{W^{2,p}(D_{3})}, \end{split}$$

where we have used the relation $\phi = iu_2\psi$ and \tilde{D} is defined in (7.16).

We now consider the following linear projected problem: finding ψ with the symmetry in (7.21)

$$\mathcal{L}[\psi] = h + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0 \quad \text{with } \phi = iu_2\psi.$$
 (7.32)

Lemma 7.2. There exists a constant C, depending on γ, σ only, such that for all ε sufficiently small, the following holds: if $||h||_{**} < +\infty$, there exists a unique solution $(\psi_{\varepsilon,\tilde{f}}, c_{\varepsilon,\tilde{f}}) = \mathcal{T}_{\varepsilon,\tilde{f}}(h)$ to (7.32). Furthermore, there holds

$$||\psi||_* \le C||h||_{**}.$$

Proof. The proof is similar as that in Lemma 5.2.

We then consider the following problem: finding ψ with the symmetry in (7.21)

$$\mathcal{L}[\psi] + \mathcal{N}[\psi] = \mathcal{E} + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0 \quad \text{with } \phi = iu_2\psi.$$
 (7.33)

Proposition 7.3. There exists a constant C, depending on γ, σ only, such that for all ε sufficiently small, there exists a unique solution $(\psi_{\varepsilon,\tilde{f}}, c_{\varepsilon,\tilde{f}})$ to (7.33), and

$$||\psi||_* \le C ||h||_{**}$$

Furthermore, ψ is continuous in the parameter \check{f} .

Proof. The proof is similar as that in Proposition 5.3.

7.5. Reduction procedure

To find a real solution to problem (7.2)-(7.3), in this subsection, we solve the reduced problem by finding a suitable \check{f} such that the constant c in (7.30) is identical zero for any sufficiently small ε .

In previous subsection, for any given \check{f} in (7.4), we have deduced the existence of ψ with the symmetry (7.21) to the projected problem

$$\mathcal{L}(\psi) = \mathcal{N}(\psi) + \mathcal{E} + c\Lambda, \quad \operatorname{Re} \int_{\mathbb{R}^2} \bar{\phi}\Lambda = 0,$$
(7.34)

with the relation

$$\phi = iu_2\psi$$
 in D_2 .

Multiplying (7.34) by $\overline{\Lambda}$ and integrating, we obtain

$$c \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \Lambda = \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{L}(\psi) - \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{N}(\psi) - \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{E}$$

Hence we can derive the estimate for c by computing the integrals of the right hand side.

We begin with the computation of $\operatorname{Re} \int_{\mathbb{R}^2} \overline{\Lambda} \mathcal{E}$. The term Λ has its support contained in the region $\{(x_1, x_2) : \ell_1 < 1/\varepsilon \text{ or } \ell_2 < 1/\varepsilon\}$. It is convenient to compute $\operatorname{Re} \int_{\mathbb{R}^2} \overline{\Lambda} \mathcal{E}$ on the variables (s_1, s_2) . Note that, in the vortex-core region, there holds

$$\frac{\partial u_2}{\partial \check{f}} = \left[-\frac{w'(\ell_2)}{w(\ell_2)} \frac{x_1 - \check{r}_{1\varepsilon}}{\ell_2} + i \frac{x_2}{(\ell_2)^2} \right] u_2 + O(\varepsilon^2) u_2.$$

which implies that

$$\Lambda = \chi \left(|x - \xi_+| / \varepsilon \right) \left[-\frac{w'(\ell_2)}{w(\ell_2)} \frac{x_1 - \check{r}_{1\varepsilon}}{\ell_2} + i \frac{x_2}{(\ell_2)^2} \right] w(\ell_2) e^{i\varphi_0^+} + O(\varepsilon^2).$$

By using of the formula (7.27), we obtain

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{E} \mathrm{d} x \equiv I_1 + I_2,$$

where I_1 is defined in (6.4). In the above, we have denoted

$$I_{2} = 2 \kappa \varepsilon \log \frac{1}{\varepsilon} \int_{\mathbb{R}^{2}_{+}} \chi(\ell_{2}/\varepsilon) w(\ell_{2}) w'(\ell_{2}) \frac{2 \left[x_{1}^{2} - x_{2}^{2} - (\check{r}_{1\varepsilon})^{2} \right] \check{r}_{1\varepsilon}(x_{1} - \check{r}_{1\varepsilon})}{(\ell_{1})^{2} (\ell_{2})^{3}} \, \mathrm{d}x$$
$$+ 2 \kappa \varepsilon \log \frac{1}{\varepsilon} \int_{\mathbb{R}^{2}_{+}} \chi(\ell_{2}/\varepsilon) w(\ell_{2}) w'(\ell_{2}) \frac{x_{2}^{2}}{(\ell_{2})^{3}} \, \mathrm{d}x + O(\varepsilon).$$

As we have done in section 6, we get $I_2 = 2d \pi \kappa \varepsilon |\log \varepsilon| + O(\varepsilon)$. Hence, there holds

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{E} dx = -2\pi\varepsilon \left. \frac{\partial \check{V}}{\partial \tilde{r}} \right|_{(\varepsilon \check{r}_{1\varepsilon}, 0)} \log \frac{1}{\varepsilon} - 2d\pi \frac{1}{\check{r}_{1\varepsilon}} \log \check{r}_{1\varepsilon} + 2d\pi \kappa \varepsilon |\log \varepsilon| + O(\varepsilon).$$

Using Proposition 7.3, and the expression in (7.28), we deduce that

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{N}(\psi) = \operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} N_2(\psi) = O(\varepsilon).$$

On the other hand, integration by parts, we have

$$\operatorname{Re} \int_{\mathbb{R}^2} \bar{\Lambda} \mathcal{L}(\psi) = \operatorname{Re} \int_{\mathbb{R}^2} \bar{\psi} \mathcal{L}(\bar{\Lambda}) = O(\varepsilon).$$

Combining all estimates together and recalling $\varepsilon \check{r}_{1\varepsilon} = \hat{r}_{1\varepsilon} = \hat{r}_0 + \hat{f}$, we obtain the following equation

$$c(\hat{f}) = -2\pi\varepsilon \left[\frac{\partial \check{V}}{\partial \tilde{r}} \Big|_{(\hat{r}_0 + \hat{f}, 0)} \log \frac{1}{\varepsilon} + \frac{d}{\hat{r}_0 + \hat{f}} \log \frac{\hat{r}_0 + \hat{f}}{\varepsilon} - d\kappa \log \frac{1}{\varepsilon} \right] + O(\varepsilon),$$
(7.35)

where $O(\varepsilon)$ is a continuous function of the parameter \hat{f} . By simple mean-value theorem and the solvability condition (1.13) and the non-degeneracy condition (1.14), we can find a zero of $c(\hat{f})$ at some small \hat{f} .

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