

Ex. 2 Use the method of undetermined coefficients ⁽¹⁾

to solve

$$X' = \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix} X + \begin{pmatrix} 1 \\ t \end{pmatrix}$$

Sol'n: $A = \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix}$, $\det(A - \lambda I) = \lambda^2 = 0$

$$r_1 = r_2 = 0, \quad \zeta^{(1)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$X^{(1)} = \zeta^{(1)} e^{r_1 t} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$X^{(2)} = \zeta^{(1)} t e^{r_1 t} + \eta e^{r_1 t} = t \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \eta$$

$$(A - r_1 I) \eta = \zeta \Rightarrow \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow 4\eta_1 - 2\eta_2 = 1. \text{ Choose } \eta_2 = 0, \eta_1 = \left(\frac{1}{4}\right)$$

$$X^{(2)} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} t + \begin{pmatrix} \frac{1}{4} \\ 0 \end{pmatrix} = \begin{pmatrix} t + \frac{1}{4} \\ 2t \end{pmatrix}$$

Now $\vec{g} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} t$ so \vec{g} is of polynomial degree 1.

Try $X_p = t^s$ (polynomial of degree 1) + rest lower order
 $= t^s (\vec{a} + \vec{b}t)$ + lower order

$s \neq 0$ since 1, t are in the kernel

$$\text{So } s = 2$$

Thus

$$x_p = \vec{a}_0 t^3 + \vec{a}_1 t^2 + \vec{a}_2 t + \vec{a}_3$$

$$x_p' = 3\vec{a}_0 t^2 + 2\vec{a}_1 t + \vec{a}_2$$

$$Ax_p = A\vec{a}_0 t^3 + A\vec{a}_1 t^2 + A\vec{a}_2 t + A\vec{a}_3$$

$$x_p' = Ax_p + g \Rightarrow$$

$$3\vec{a}_0 t^2 + 2\vec{a}_1 t + \vec{a}_2 = A\vec{a}_0 t^3 + A\vec{a}_1 t^2 + A\vec{a}_2 t + A\vec{a}_3 + \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} t$$

$$t^3: A\vec{a}_0 = 0 \quad \text{--- (1)}$$

$$t^2: A\vec{a}_1 = 3\vec{a}_0 \quad \text{--- (2)}$$

$$t: A\vec{a}_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 2\vec{a}_1 \quad \text{--- (3)}$$

$$1: A\vec{a}_3 + \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \vec{a}_2 \quad \text{--- (4)}$$

qn (1): $a_0 = k_0 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$, k_0 is to be determined

$$\text{qn (2): } \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 3k_0 \begin{pmatrix} 1 \\ 2 \end{pmatrix} \Rightarrow 4a_1 - 2a_2 = 3k_0$$

choose $a_2 = 0$, $a_1 = \frac{3}{4}k_0$

$$\vec{a}_1 = \begin{pmatrix} \frac{3}{4}k_0 \\ 0 \end{pmatrix} + k_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{3}{4}k_0 + k_1 \\ 2k_1 \end{pmatrix}$$

$$\text{qn (3): } \begin{pmatrix} 4 & -2 \\ 8 & -4 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = 2\vec{a}_1 - \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{3}{2}k_0 + 2k_1 \\ 2k_1 - 1 \end{pmatrix} \quad \text{--- (5)}$$

To have a solution to (5), we need (3)

$$2\left(\frac{3}{2}k_0 + 2k_1\right) = 4k_1 - 1 \quad \text{--- (6)}$$

Next, we choose a \vec{a}_2

$$\vec{a}_2 = \begin{pmatrix} \frac{1}{8}(4k_1 - 1) \\ 0 \end{pmatrix} + k_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \text{we can choose } k_2 = 0 \text{ because it leads to } X^{(2)}$$

$$\begin{aligned} \text{Eqn (3): } Aa_3 &= a_2 - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{8}(4k_1 - 1) - 1 \\ 0 \end{pmatrix} \quad \text{--- (7)} \end{aligned}$$

$$\text{(7) has a sol'n} \Rightarrow \frac{1}{8}(4k_1 - 1) - 1 = 0 \quad \text{--- (8)}$$

$$\text{Thus } k_1 = \frac{9}{4} \quad \text{--- (9)}$$

Substituting into (6), we get

$$\frac{3}{2}k_0 + \frac{9}{2} = 4 \Rightarrow k_0 = -\frac{1}{3}$$

So we can choose

$$a_3 = 0, \quad a_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$a_1 = \begin{pmatrix} \frac{3}{4}k_0 + k_1 \\ 2k_1 \end{pmatrix} = \begin{pmatrix} 2 \\ \frac{9}{2} \end{pmatrix}, \quad a_0 = -\frac{1}{3} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -\frac{1}{3} \\ -\frac{2}{3} \end{pmatrix}$$

$$x_p = \begin{pmatrix} -\frac{1}{3} \\ -\frac{2}{3} \end{pmatrix} t^3 + \begin{pmatrix} 2 \\ \frac{9}{2} \end{pmatrix} t^2 + \begin{pmatrix} 1 \\ 0 \end{pmatrix} t$$

and

$$X = X_p + C_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + C_2 \begin{pmatrix} t + \frac{1}{4} \\ 2t \end{pmatrix}$$

To check, let us use Method II:

$$\Psi(t) u' = g$$

$$\begin{pmatrix} 1 & t + \frac{1}{4} \\ 2 & 2t \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} 1 \\ t \end{pmatrix}$$

$$u_1' + (t + \frac{1}{4}) u_2' = 1$$

$$2u_1' + 2t u_2' = t$$

$$\Rightarrow \frac{1}{4} u_2' = 1 - \frac{t}{2} \Rightarrow u_2' = 4 - 2t \Rightarrow u_2 = 4t - t^2$$

$$u_1' = \frac{t}{2} - (4 - 2t)t = -\frac{7}{2}t + 2t^2$$

$$u_1 = -\frac{7}{4}t^2 + \frac{2}{3}t^3$$

$$x_p = \Psi(t) u = \begin{pmatrix} 1 & t + \frac{1}{4} \\ 2 & 2t \end{pmatrix} \begin{pmatrix} -\frac{7}{4}t^2 + \frac{2}{3}t^3 \\ 4t - t^2 \end{pmatrix}$$

$$= \begin{pmatrix} -\frac{7}{4}t^2 + \frac{2}{3}t^3 + (t + \frac{1}{4})(4t - t^2) \\ -\frac{7}{2}t^2 + \frac{4}{3}t^3 + 2t(4t - t^2) \end{pmatrix}$$

(5)

$$= \begin{pmatrix} -\frac{1}{3}t^3 + 2t^2 + t \\ -\frac{2}{3}t^3 + \frac{9}{2}t^2 \end{pmatrix}$$

$$= \begin{pmatrix} -\frac{1}{3} \\ -\frac{2}{3} \end{pmatrix} t^3 + \begin{pmatrix} 2 \\ \frac{9}{2} \end{pmatrix} t^2 + \begin{pmatrix} 1 \\ 0 \end{pmatrix} t$$