

Solutions to Assignment 6, MATH301-201

1 (a). We can compute V in two ways.

$$\operatorname{Re}(\Omega(z)) = V_0 \left(x + \frac{a^2}{x^2+y^2} x \right) - \frac{\gamma}{2\pi} \operatorname{Arctan} \frac{y}{x} = \Phi$$

$$V = \nabla \Phi \Rightarrow$$

$$V_1 = \frac{\partial \Phi}{\partial x} = V_0 \left(1 + \frac{a^2}{x^2+y^2} - \frac{2a^2 x^2}{(x^2+y^2)^2} \right) + \frac{\gamma}{2\pi} \frac{y}{x^2+y^2}$$

$$V_2 = \frac{\partial \Phi}{\partial y} = V_0 \left(-\frac{2a^2 xy}{(x^2+y^2)^2} \right) - \frac{\gamma}{2\pi} \frac{x}{x^2+y^2}$$

Another way:

$$V = \Omega'(z) = V_0 \left(1 - \frac{a^2}{z^2} \right) + i \frac{\gamma}{2\pi z} \Rightarrow$$

$$V_1 = \dots, \quad V_2 = \dots$$

(b). $\Omega'(z) = 0$ gives stagnation points.

$$z^2 - a^2 + i \frac{\gamma}{2\pi V_0} z = 0$$

$$z = -\frac{i\gamma}{4\pi V_0} \pm \sqrt{a^2 - \frac{\gamma^2}{16\pi^2 V_0^2}}$$

Critical γ_c is: $a^2 - \frac{\gamma_c^2}{16\pi^2 V_0^2} = 0 \Rightarrow \underline{\gamma_c = 4\pi a V_0}$

where $\gamma < \gamma_c \Rightarrow$

$$z = -\frac{i\gamma}{4\pi V_0} \pm \sqrt{a^2 - \frac{\gamma^2}{16\pi^2 V_0^2}}$$

where $\gamma > \gamma_c \Rightarrow$

$$z = -\frac{i\gamma}{4\pi V_0} \pm \sqrt{\frac{\gamma^2}{16\pi^2 V_0^2} - a^2} i$$

where $\gamma < \gamma_c$

$|z|^2 = a^2 \Rightarrow$ stagnation points on other body

$$\{|z|=a\}$$

Note that $\psi = \text{Constant}$ on $z = a e^{i\varphi} \sin \varrho$

$$\begin{aligned} \text{Im}(\Omega) &= \text{Im} \left(a v_0 (e^{i\varphi} + e^{-i\varphi}) + \frac{i\gamma}{2\pi} (\log a + i\varphi) \right) \\ &= \frac{\gamma}{2\pi} \log a. \end{aligned}$$

So $\{|z|=a\}$ is the body of the flow.

where $\gamma > \gamma_c$, then

$$z_1 = -\frac{\gamma}{4\pi v_0} + \sqrt{\frac{\gamma^2}{16\pi^2 v_0^2} - a^2}, \quad |z_1| < a$$

$$z_2 = -\frac{\gamma}{4\pi v_0} - \sqrt{\frac{\gamma^2}{16\pi^2 v_0^2} - a^2}, \quad |z_2| > a.$$

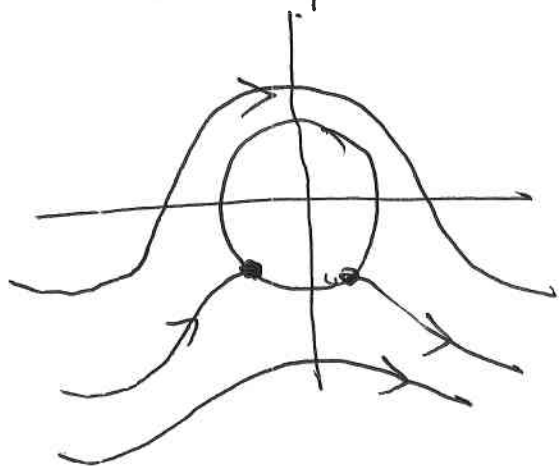
The stagnation point is z_2 .

(c). Let $z = r e^{i\varphi}$. Then

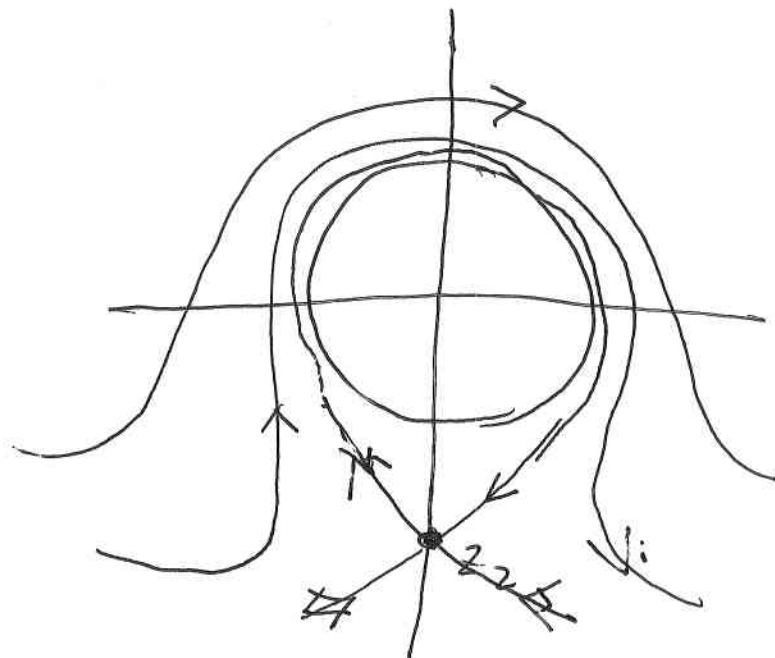
$$\text{Im}(\Omega) = v_0 \left(r - \frac{a^2}{r} \right) \sin \varphi + \frac{\gamma}{2\pi} \log r.$$

The streamline $v_0 \left(r - \frac{a^2}{r} \right) \sin \varphi + \frac{\gamma}{2\pi} \log r = C$

The flow picture is



$$\gamma < \gamma_c$$



2. (a). $f(t) = \frac{2}{t^2+4}$

$$f(t) = \frac{\frac{1}{2}}{1 + (\frac{t}{2})^2} = \frac{1}{2} \frac{1}{1 + (\frac{t}{2})^2}$$

Using the fact that the F.T. of $\frac{1}{1+t^2}$ is $\pi e^{-|k|}$

We have

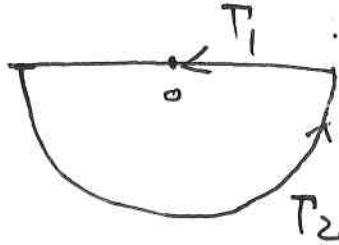
$$\hat{f}(k) = \frac{1}{2} \cdot 2 \pi \cdot e^{-2|k|} = \underline{\pi e^{-2|k|}}$$

(b). Since $\widehat{e^{-|x|}} = \frac{2}{1+k^2}$

$$\widehat{e^{-2|x|}} = \frac{1}{2} \cdot \frac{2}{1 + (\frac{k}{2})^2} = \underline{\frac{4}{k^2+4}}$$

$$(c) \hat{f}(k) = \int e^{-2k\eta} \frac{1}{\eta^4+1} d\eta$$

For $k > 0$, we use



$$\text{on } P_1, \int_R^{-R} e^{-2kp} \frac{1}{p^4+1} dp$$

$$\text{on } P_2, \int_{P_2} \rightarrow 0.$$

$$\eta^4+1=0 \Rightarrow \eta = e^{\frac{(2k+1)\pi}{4}i}, \quad k=0, 1, 2, 3.$$

$$z_3 = e^{\frac{5\pi}{4}i}, \quad z_2 = e^{\frac{7\pi}{4}i}$$

$$\text{Res}\left(e^{-2kz} \frac{1}{z^4+1}; e^{\frac{5\pi}{4}i}\right) = \frac{e^{-2kz_1}}{4z_1^3}$$

$$\text{Res}\left(e^{-2kz} \frac{1}{z^4+1}; e^{\frac{7\pi}{4}i}\right) = \frac{e^{-2kz_2}}{4z_2^3}$$

$$\text{Hence } \int_{-\infty}^{\infty} e^{-2k\eta} \frac{1}{\eta^4+1} d\eta = -2\pi i \left(\frac{e^{-2kz_1}}{4z_1^3} + \frac{e^{-2kz_2}}{4z_2^3} \right)$$

$$= \sqrt{2}\pi e^{-\frac{\sqrt{2}}{2}k} \left(\sin \frac{\sqrt{2}}{2}k + \cos \frac{\sqrt{2}}{2}k \right)$$

For $k < 0$, we get

$$\hat{f}(k) = \sqrt{2}\pi e^{\frac{\sqrt{2}}{2}k} \left(\sin \frac{\sqrt{2}}{2}k + \cos \frac{\sqrt{2}}{2}k \right).$$

$$(d). \hat{f}(k) = \int \frac{1}{(x+i)^2} e^{-2ikx} dx$$

$$= \begin{cases} 2\pi i \operatorname{Res} \left[\frac{e^{-2ikz}}{(z+i)^2} ; i \right], & k < 0 \\ -2\pi i \operatorname{Res} \left[\frac{e^{-2ikz}}{(z+i)^2} ; -i \right], & k > 0. \end{cases}$$

$$\text{For } k < 0, \operatorname{Res} \left[\frac{e^{-2ikz}}{(z+i)^2} ; i \right] = \left. \frac{d}{dz} \left(\frac{e^{-2ikz}}{(z+i)^2} \right) \right|_{z=i}$$

$$\text{So } \hat{f}(k) = 2\pi \left(\frac{-1-k}{4} \right) e^k$$

$$\text{For } k > 0, \hat{f}(k) = 2\pi \left(\frac{1+k}{4} \right) e^{-k}$$

$$\text{So } \hat{f}(k) = \frac{\pi}{2} (1+|k|) e^{-|k|}$$

(e). The F.T. of

$$e^{-\frac{x^2}{2\sigma^2}} \text{ is } \sqrt{2\pi} \sigma e^{-\frac{\sigma^2 k^2}{2}}$$

$$\text{Now } 2\sigma^2 = 1 \Rightarrow \sigma = \sqrt{\frac{1}{2}},$$

$$\text{So } \hat{e^{-t^2}} = \sqrt{\pi} e^{-\frac{k^2}{4}}$$

$$(f). \widehat{f(t)} = \widehat{(-\frac{1}{2})(e^{-t^2})'} = -\frac{1}{2} (\widehat{ik}) e^{-t^2} \quad \text{---}$$

$$= -\frac{1}{2} (\widehat{ik}) \sqrt{\pi} e^{-k^2/4}$$

$$= -\frac{\sqrt{\pi} k}{2} i e^{-k^2/4}$$

$$3. \widehat{u}(k, t) = \int_{-\infty}^{+\infty} u(x, t) e^{-ikx} dx$$

$$i\widehat{u}_t + (ik)^2 \widehat{u} = 0$$

$$\widehat{u}_t + ik^2 \widehat{u} = 0, \quad \widehat{u}(k, 0) = \widehat{f}(k)$$

$$\widehat{u} = \widehat{f}(k) e^{-ik^2 t}$$

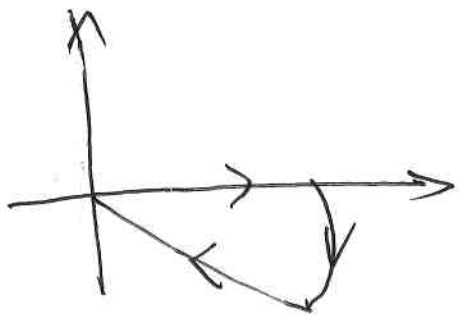
We need to find the I.F.T. of $e^{-ik^2 t}$, which is

$$\frac{1}{2\pi} \int e^{2ikx - ik^2 t} = \frac{1}{2\pi} \int e^{-it(k - \frac{x}{2t})^2} dk e^{\frac{ix^2}{4t^2}}$$

$$= \frac{1}{2\pi} e^{\frac{ix^2}{4t^2}} \int e^{-itx^2} dx$$

$$= \frac{1}{2\pi} e^{\frac{ix^2}{4t^2}} \cdot 2 \int_0^{+\infty} e^{-ix^2} dx \cdot \frac{1}{\sqrt{t}}$$

The computation of $\int_0^{+\infty} e^{-ix^2} dx$ is by complex contour



$$\Rightarrow \int_0^{\infty} e^{-iz^2} dz \neq e^{-i\frac{\pi}{4}} \int_0^0 e^{-p^2} dp = 0$$

$$\Rightarrow \int_0^{\infty} e^{-iz^2} dz = \frac{\sqrt{\pi}}{2} e^{-i\frac{\pi}{4}}$$

So

$$\frac{1}{2\pi} \int e^{ikx - ik^2 t} dk = \frac{1}{\sqrt{\pi t}} e^{-i\frac{\pi}{4}} e^{i\frac{x^2}{4t}}$$

$$u(x, t) = \frac{1}{\sqrt{\pi t}} e^{-i\frac{\pi}{4}} \int f(y) e^{i\frac{(x-y)^2}{4t}} dy$$

4. Recall:

$$\hat{u}(k_1, k_2, t) = \iint e^{-ik_1 x - ik_2 y} u(x, y, t) dx dy$$

$$u(x, y, t) = \frac{1}{(2\pi)^2} \iint e^{ik_1 x + ik_2 y} \hat{u}(k_1, k_2, t) dk_1 dk_2$$

Take a F.T. \Rightarrow

$$\begin{cases} \hat{u}_t = -D(k_1^2 + k_2^2) \hat{u} \\ \hat{u}(k_1, k_2, 0) = \hat{f} \end{cases}$$

$$\text{so } \hat{u} = \hat{f}(k_1, k_2) e^{-D(k_1^2 + k_2^2)t}$$

So

$$u(x, y, t) = \iint g(x-x', y-y', t) f(x', y', t) dx' dy'$$

where

$$g = \text{I.F.T. of } e^{-D(k_1^2 + k_2^2)t}$$

$$= \frac{1}{(2\pi)^2} \iint e^{ik_1 x + ik_2 y} e^{-D(k_1^2 + k_2^2)t} dk_1 dk_2$$

$$= \frac{1}{2\pi} \int e^{ik_1 x - Dk_1^2 t} dk_1 \cdot \frac{1}{2\pi} \int e^{ik_2 y - Dk_2^2 t} dk_2$$

$$= \frac{1}{\sqrt{4\pi Dt}} e^{-x^2/(4Dt)} \cdot \frac{1}{\sqrt{4\pi Dt}} e^{-y^2/(4Dt)}$$

$$= \frac{1}{4\pi Dt} e^{-\frac{(x^2 + y^2)}{4Dt}}$$

Hence

$$u(x, y, t) = \frac{1}{4\pi Dt} \iint e^{-\frac{(x-x')^2 + (y-y')^2}{4Dt}} f(x', y') dx' dy'$$

5. Look for sol'ns of $e^{ikx + \sigma t}$

$$\Rightarrow \sigma = -D_0 k^2 - D_1 k^4$$

Hence we get $\hat{u} = \hat{f}(k) e^{(D_0 k^2 + D_1 k^4)t}$

we have

$$u(x, t) = \int g(x-y) f(y) dy$$

where

$$g = \frac{1}{2\pi} \int e^{ikx - i(k^2 - D_1 k^4)t} dk$$

which exists, but is difficult to compute.