

**Mathematical Cell Biology Graduate Summer Course**  
**University of British Columbia, May 1-31, 2012**  
Leah Edelstein-Keshet

# Cell polarity models

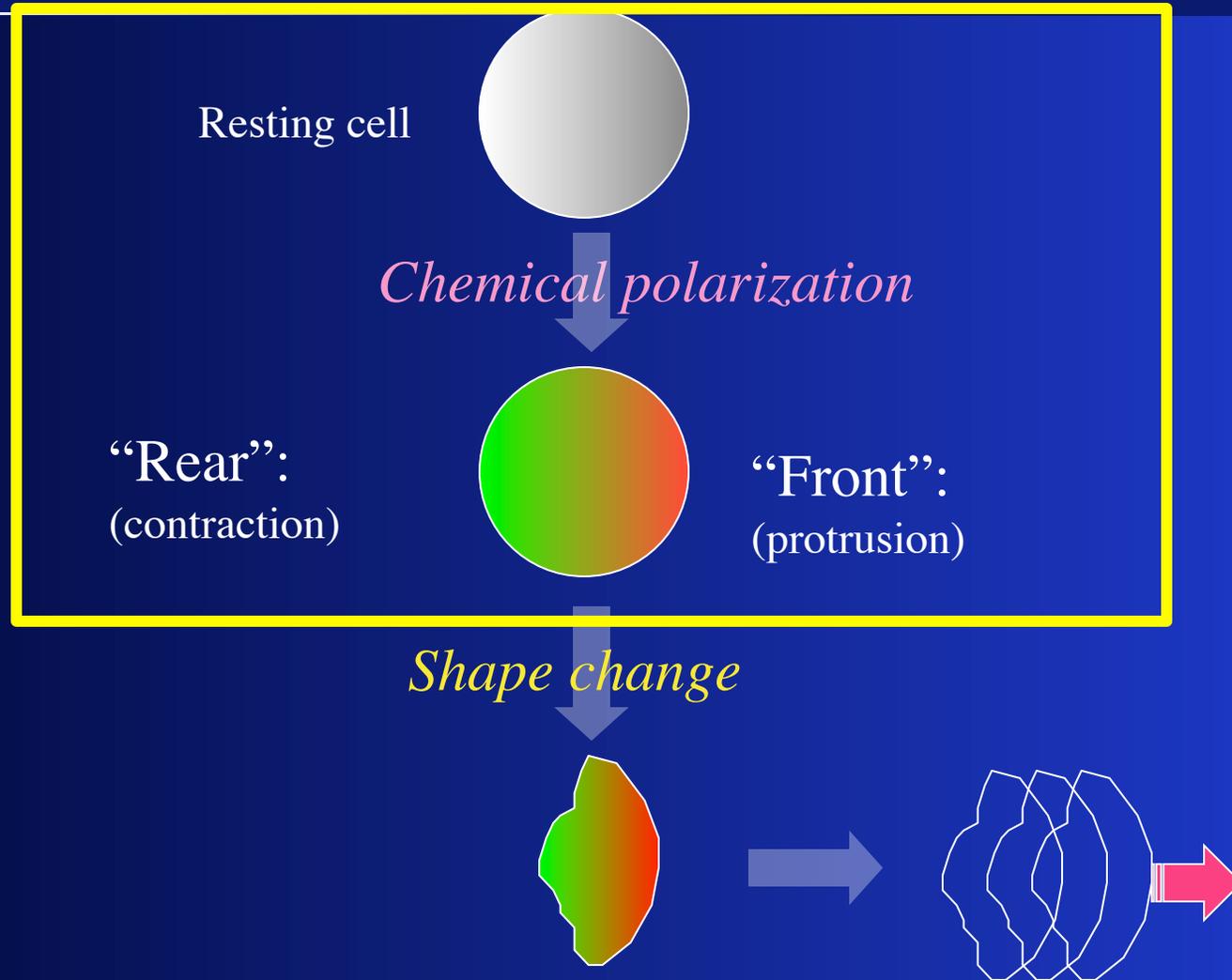


[www.math.ubc.ca/~keshet/MCB2012/](http://www.math.ubc.ca/~keshet/MCB2012/)

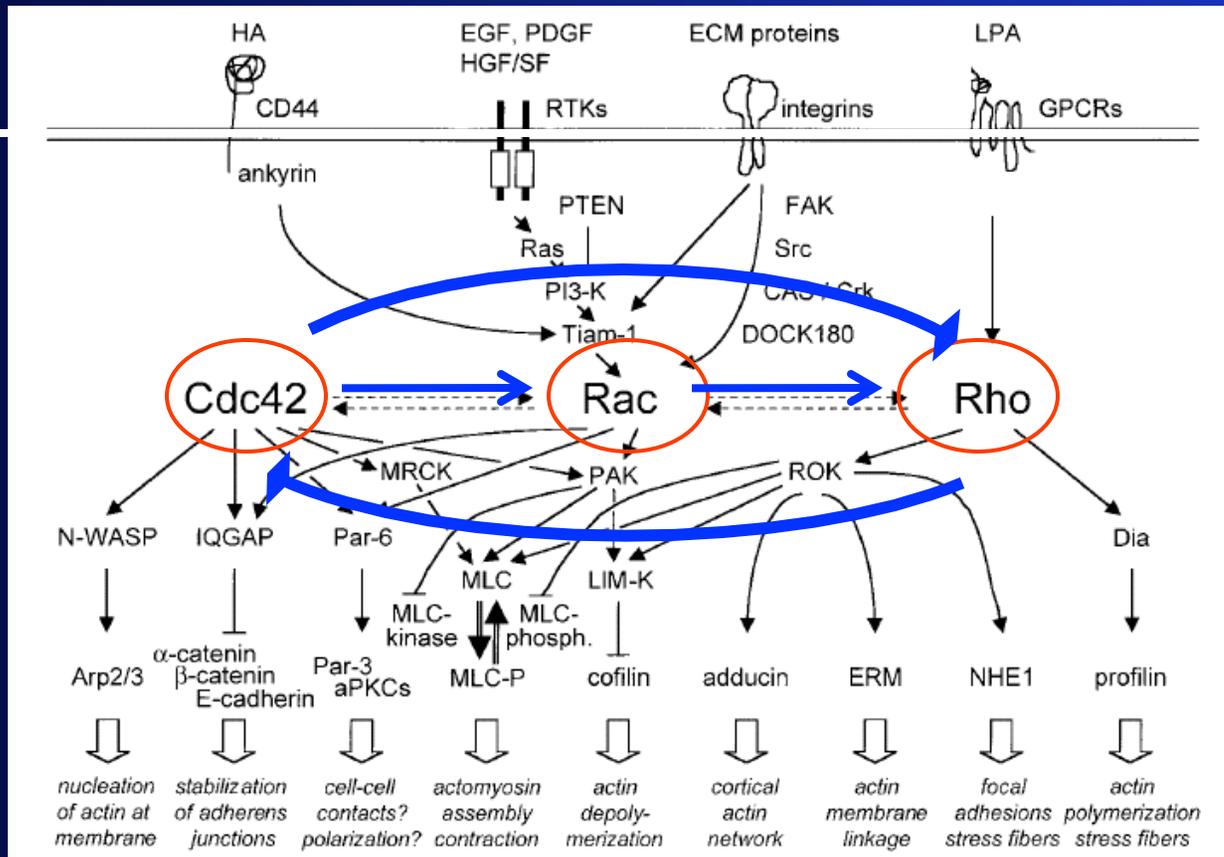
# Universal features of polarizing cells

1. Ability to sense both steep and shallow external gradients (as small as 1%–2%) in vast range of concentrations. Polarization leads to an *amplification* of this asymmetry to some macroscopic level.
2. Remain *sensitive to new stimuli*, and can reorient when the stimulus gradient is changed.
3. Polarity maintained after stimulus is removed (*maintenance*).

# Polarization



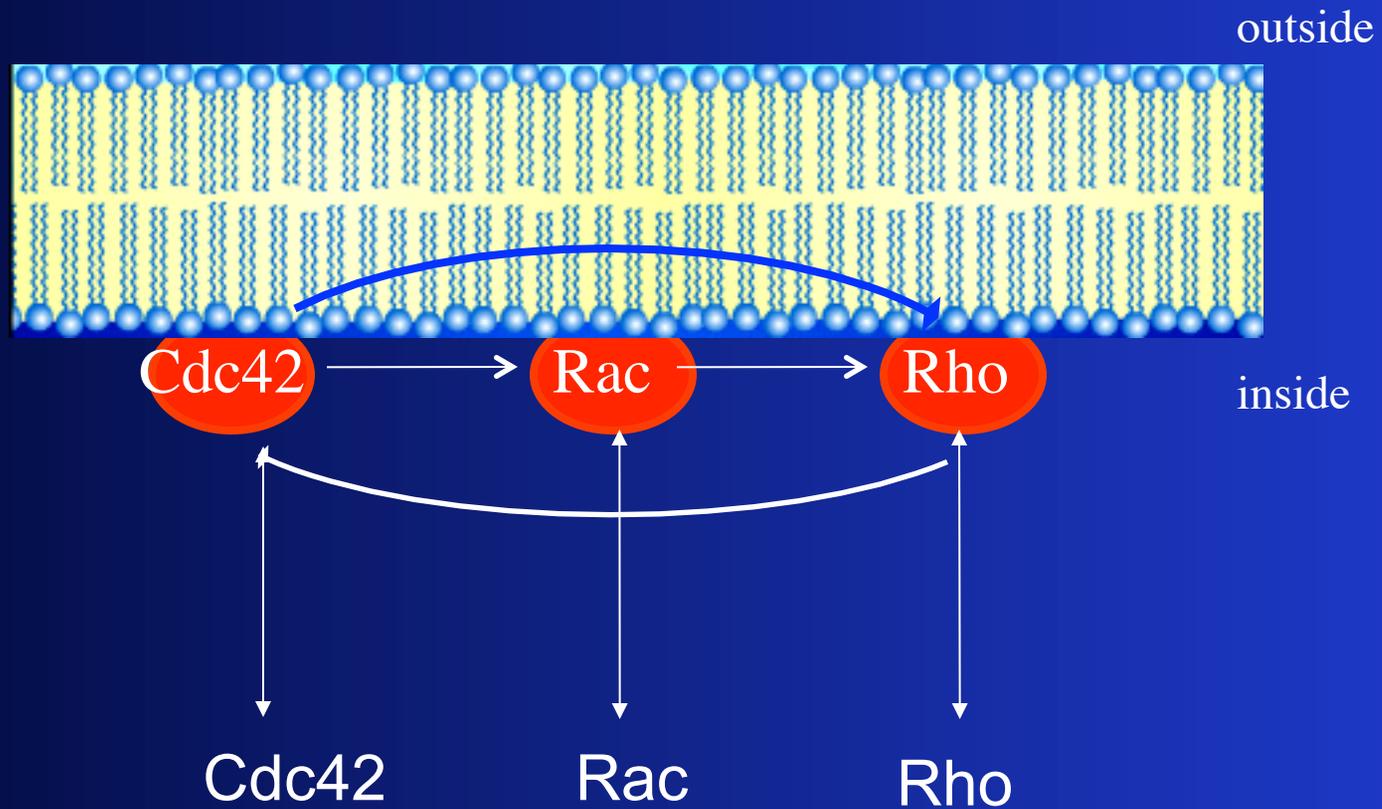
# GTPases



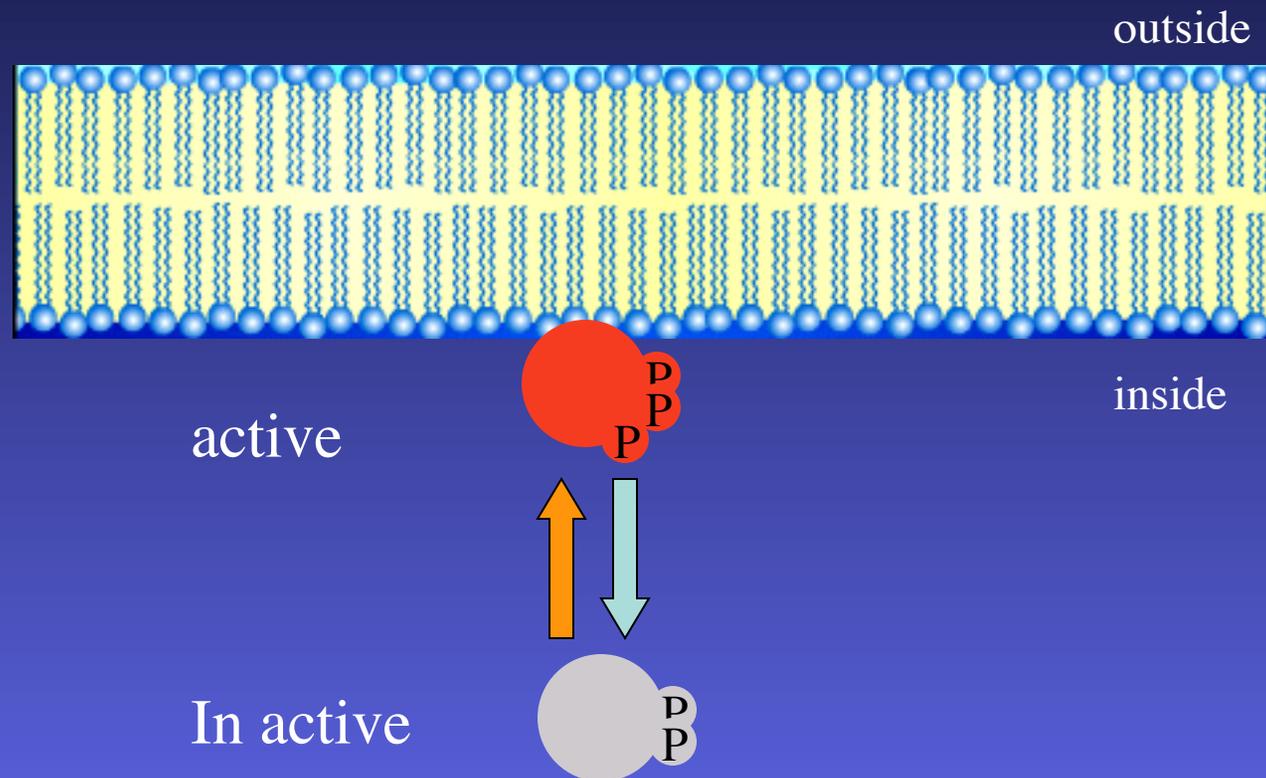
out  
in

Schmitz et al (2000) Expt Cell Res 261:1-12

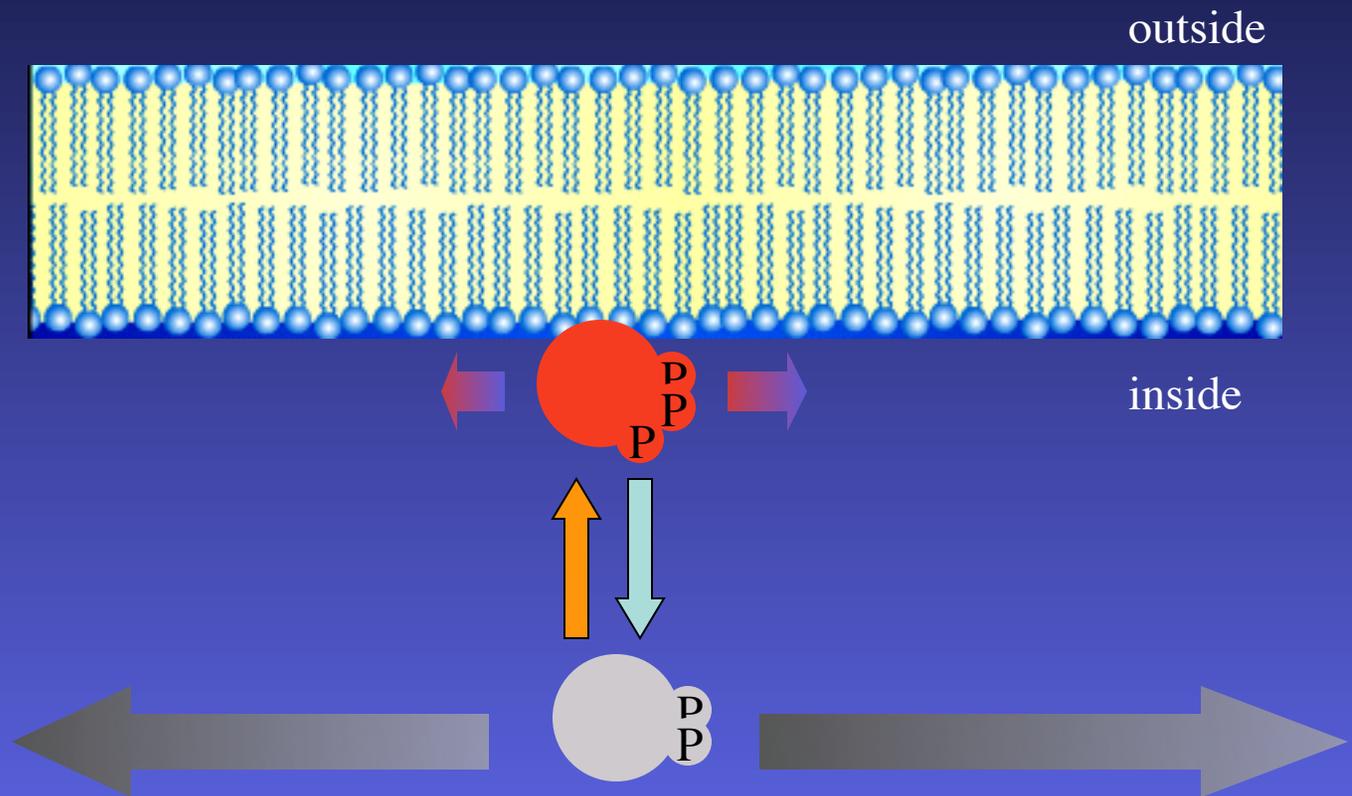
# Active and inactive forms



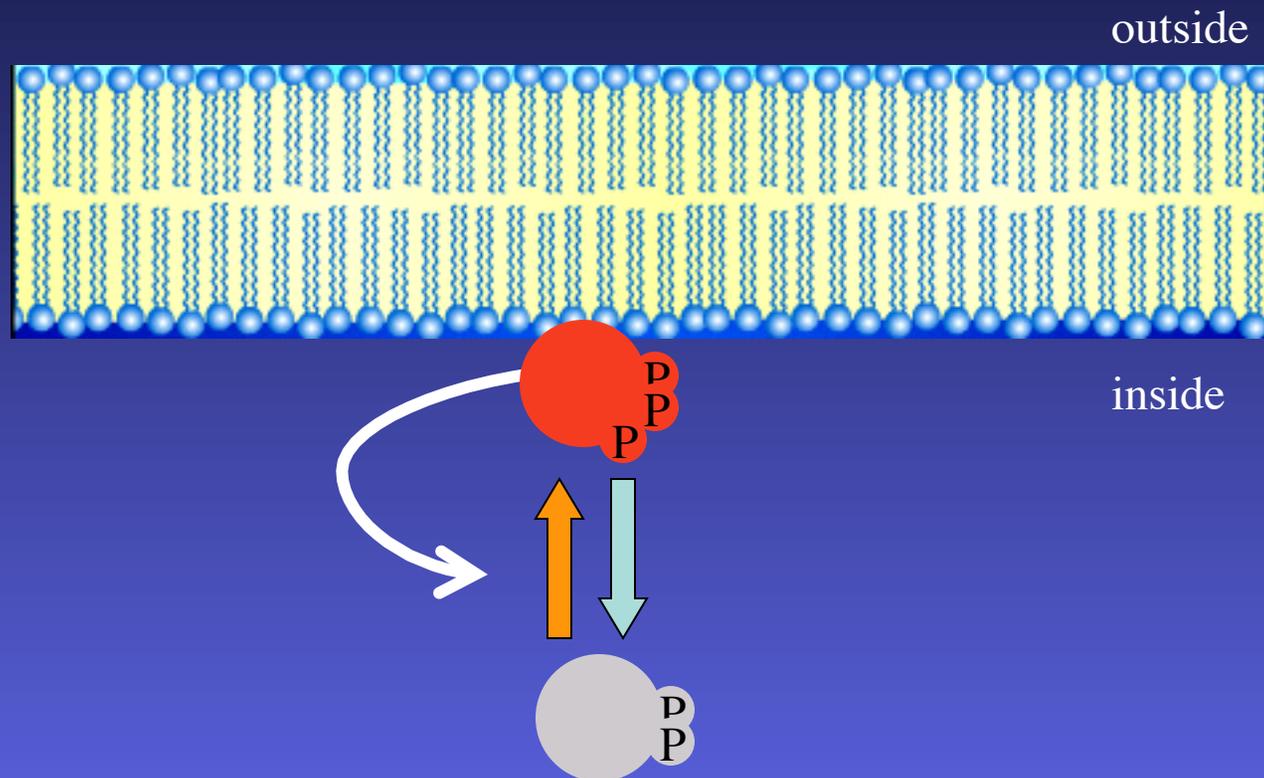
# Simplified view:



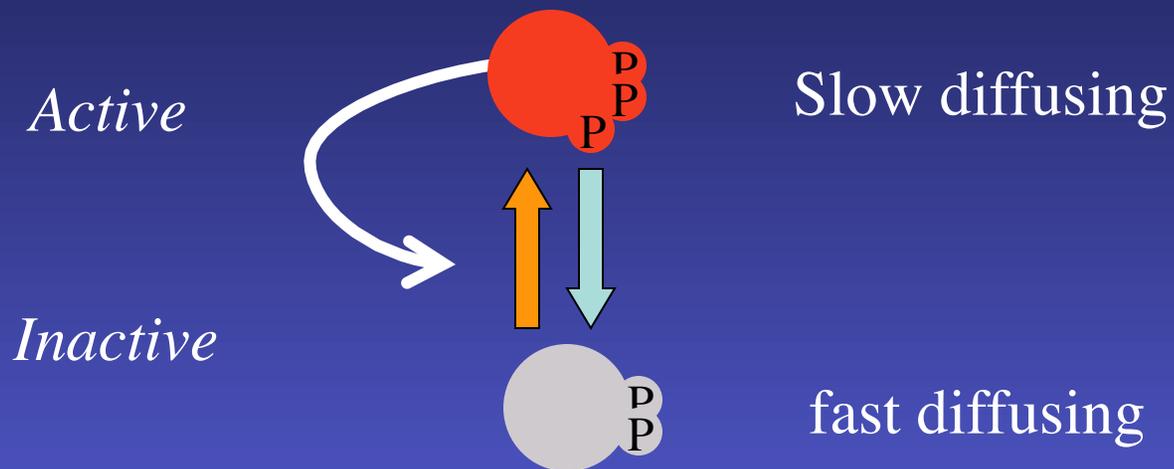
# 100-1000 fold difference in rates of diffusion



# Caricature model

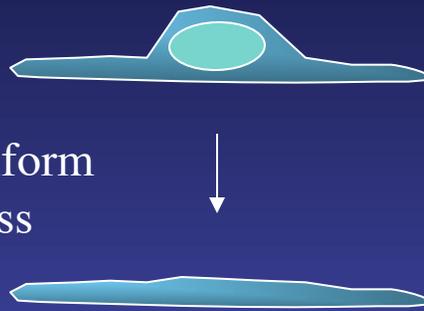


# Only two variables



# Geometry

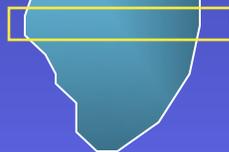
Assume uniform  
cell thickness



“Thin strip”



1D

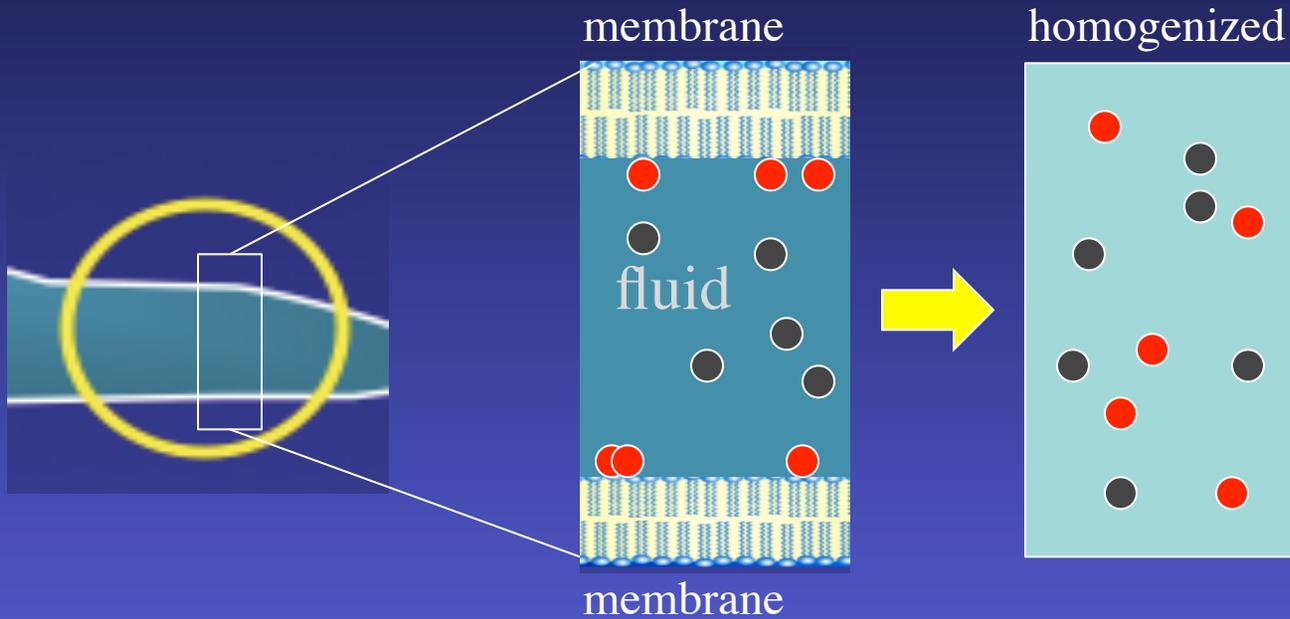
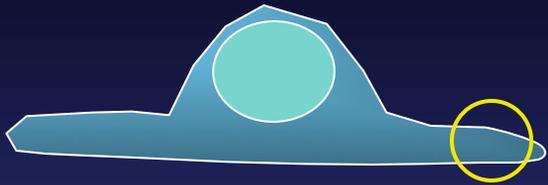


“Thin sheet”

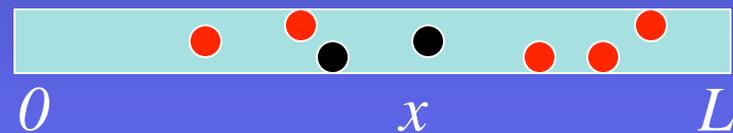


2D

# Simplified geometry



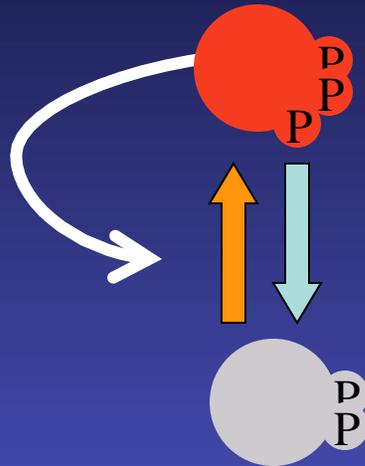
1D thin strip:



# RD model

*Active*

*Inactive*



$$\begin{aligned}\frac{\partial u}{\partial t} &= D_u \frac{\partial^2 u}{\partial x^2} + f(u, v), \\ \frac{\partial v}{\partial t} &= D_v \frac{\partial^2 v}{\partial x^2} - f(u, v),\end{aligned}$$

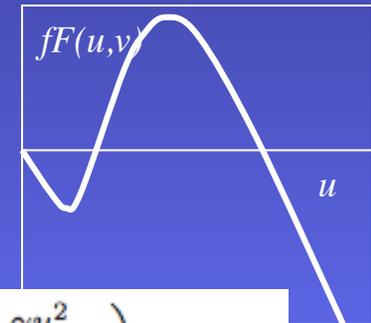
$$D_u \ll D_v$$



A Jilkiné

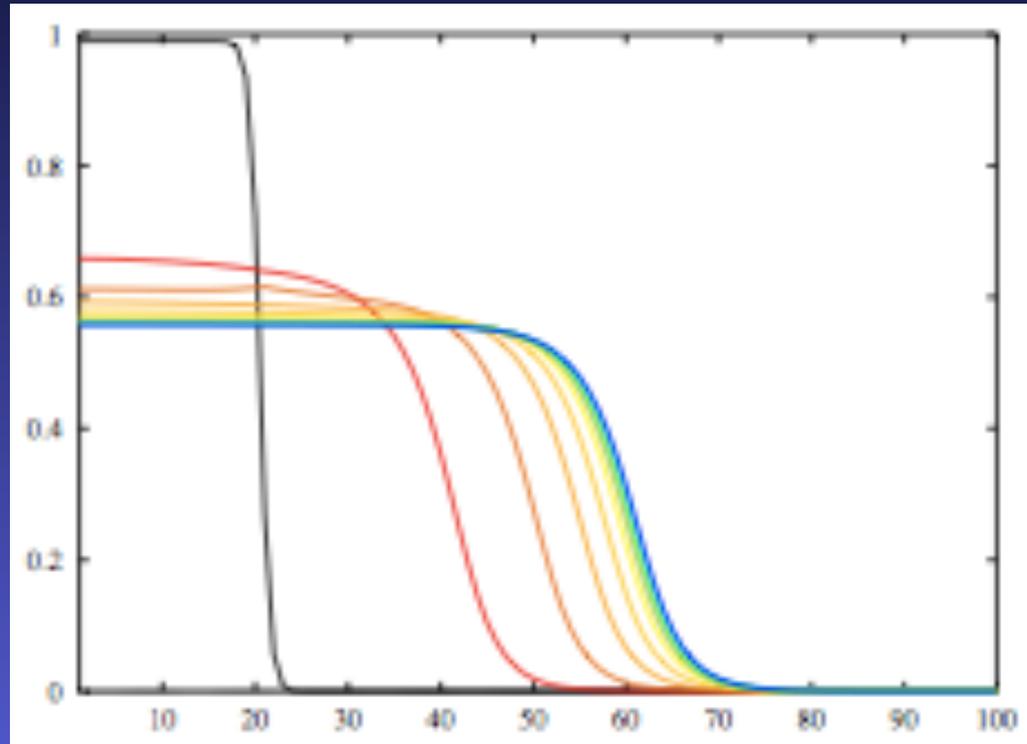


Y Mori



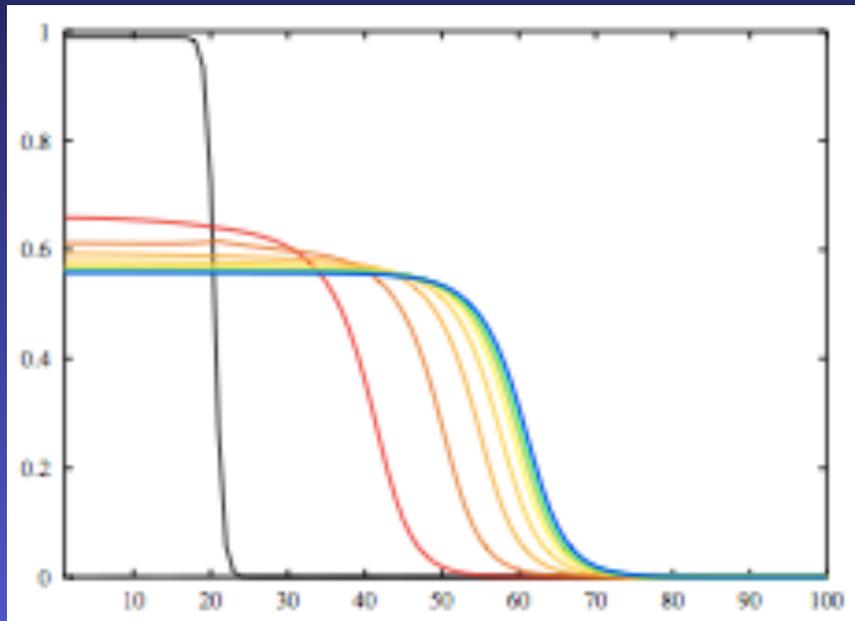
$$f(u, v) = \eta \left( \delta + \frac{\gamma u^2}{m^2 + u^2} \right) v - \eta u$$

# Behaviour: Wave-pinning



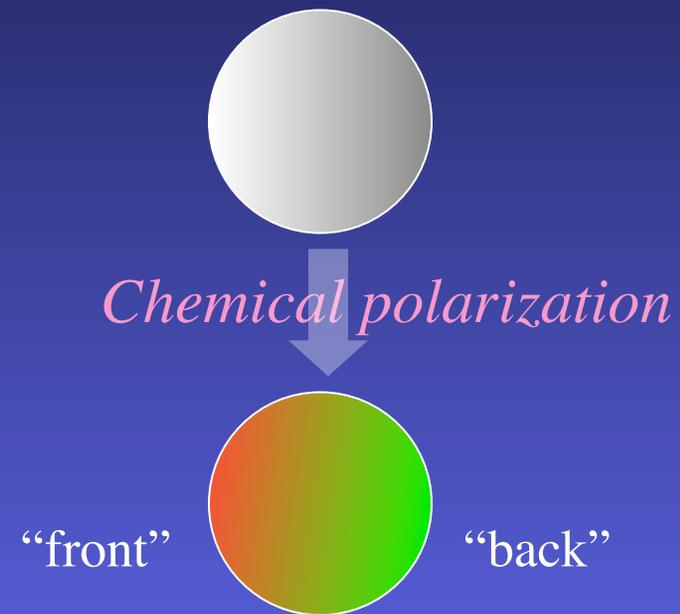
Mori Y, Jilkine A, LEK (2008) Biophys J, 94: 3684-3697.  
Mori Y, Jilkine A, LEK (2011) in press SIAM J Appl Math

# WP = polarization



“front”

“back”



# Rescaled (there is a small parameter)

$$\epsilon \frac{\partial u}{\partial t} = \epsilon^2 \frac{\partial^2 u}{\partial x^2} + f(u, v),$$

$$\epsilon \frac{\partial v}{\partial t} = D \frac{\partial^2 v}{\partial x^2} - f(u, v),$$

$$f(u, v) = \left( \delta + \frac{\gamma u^2}{1 + u^2} \right) v - u.$$

$$D_u \ll D_v$$

$$\epsilon^2 = \frac{D_u}{\eta L^2}, \quad D = \frac{D_v}{\eta L^2}$$

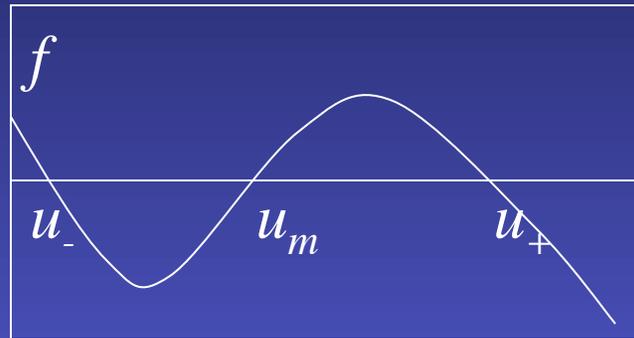
Analyse location and speed of wave front using matched asymptotic expansions..

# Conditions for Wave-pinning:

1. For  $v$  fixed in some range,  $v_{min} < v < v_{max}$ ,

$f(u,v)=0$  has 3 roots

Shape of  $f$ :



2. There is a  $v_c$  in the above range such that

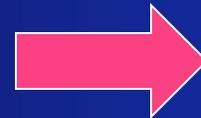
3. Conservation of  $u+v$

4.  $D_u \ll D_v$

$$\int_{u_-}^{u_+} f(u, v_c) du = 0$$

# Methods of analysis

$$\begin{aligned}\frac{\partial u}{\partial t}(x, t) &= f(u, v) + D_u \Delta u, \\ \frac{\partial v}{\partial t}(x, t) &= g(u, v) + D_v \Delta v,\end{aligned}$$



Linearization,  
Linear stability analysis of full  
PDE, look for +ve eigenvalues



$D_u \ll D_v$   
Local pulse analysis

# Methods of analysis, RD systems

$$\begin{aligned}\frac{\partial u}{\partial t}(x, t) &= f(u, v) + D_u \Delta u, \\ \frac{\partial v}{\partial t}(x, t) &= g(u, v) + D_v \Delta v,\end{aligned}$$

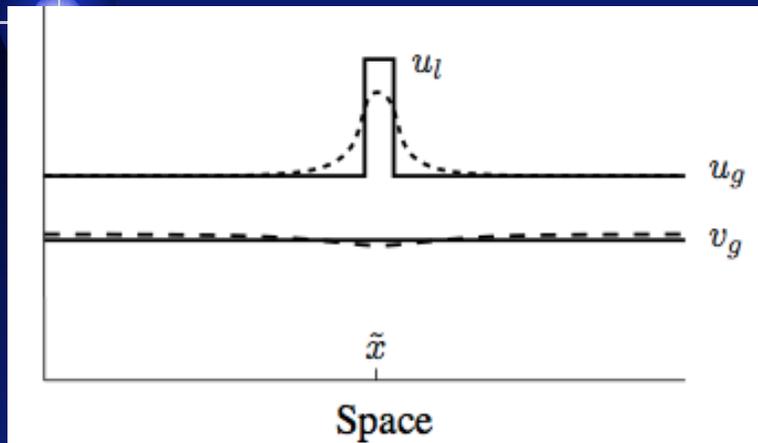


$$D_u \ll D_v$$

Local pulse analysis

Due to: Stan Maree, Veronica Grieneisen, with Bill Holmes

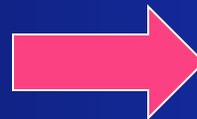
# Local Pulse Analysis



Approximate PDEs  
by ODEs for local  
and global variables:

$$\begin{aligned}\frac{\partial u}{\partial t}(x, t) &= f(u, v) + D_u \Delta u, \\ \frac{\partial v}{\partial t}(x, t) &= g(u, v) + D_v \Delta v\end{aligned}$$

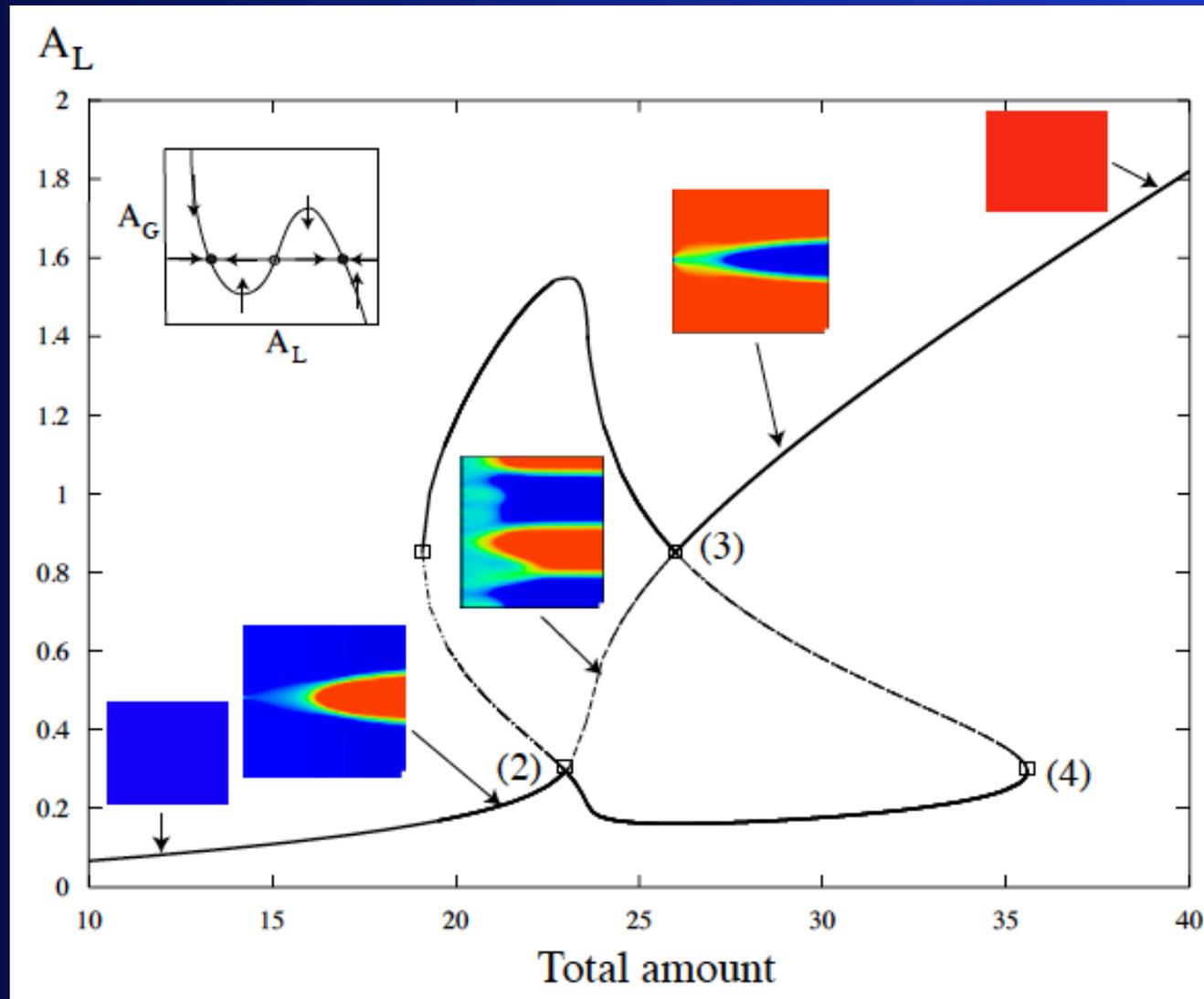
$$D_u \ll D_v$$



$$\begin{aligned}\frac{du^g}{dt}(x, t) &= f(u^g, v^g), \\ \frac{dv^g}{dt}(x, t) &= g(u^g, v^g), \\ \frac{du^l}{dt}(x, t) &= f(u^l, v^g)\end{aligned}$$

$$D_u \rightarrow 0 \quad D_v \rightarrow \infty$$

# LPA bifurcation and patterns



# Cell Polarization, a review of Models and Experiments

Jilkine A, Edelstein-Keshet L (2011) A Comparison of  
Mathematical Models for Polarization of Single Eukaryotic  
Cells in Response to Guided Cues.

PLoS Comput Biol 7(4): e1001121.

(Images on next slides taken from this source)

# Additional features of some cells

1. *Spontaneous polarization*, in absence of spatial cues.
2. *Adaptation*: a persistent response to a gradient stimulus, but transient response to a spatially uniform stimulus.
3. Response to multiple stimuli: either *multiple “fronts”* or a *unique axis of polarity*.
4. Pseudopods continually extended and retracted. Reorient by splitting a pseudopod, one part becoming dominant.

# Cell type comparisons

Cell type	Polarization Behaviors	Scale
Budding yeast	Spontaneous polarization, unique axis of polarity	Size: 5 $\mu\text{m}$ , TP: 3 min
<i>D. discoideum</i>	Gradient sensing (1% and up), adaptation (Lat), spontaneous polarization, high amplification, reorientation, maintenance, multiple fronts (Lat), unique axis (WT)	Size: 10–20 $\mu\text{m}$ , TP: 30–60 s, speed: 3–15 $\mu\text{m}/\text{min}$
Fibroblasts	Gradient sensing, reorientation	Size: 50–150 $\mu\text{m}$ , TP: 30–50 min, speed: 1 $\mu\text{m}/\text{min}$
Keratocytes	Spontaneous polarization, maintenance	Size: 10 $\mu\text{m}$ (fragments), 30–40 $\mu\text{m}$ (cells), speed: 10–40 $\mu\text{m}/\text{min}$ ,
Neutrophils	Gradient sensing, spontaneous polarization, high amplification, reorientation, unique axis (WT)	Size: 10 $\mu\text{m}$ , TP: 30 s, speed: 10–20 $\mu\text{m}/\text{min}$
Neurons	Attractive/repulsive turning, gradient detection, adaptation	

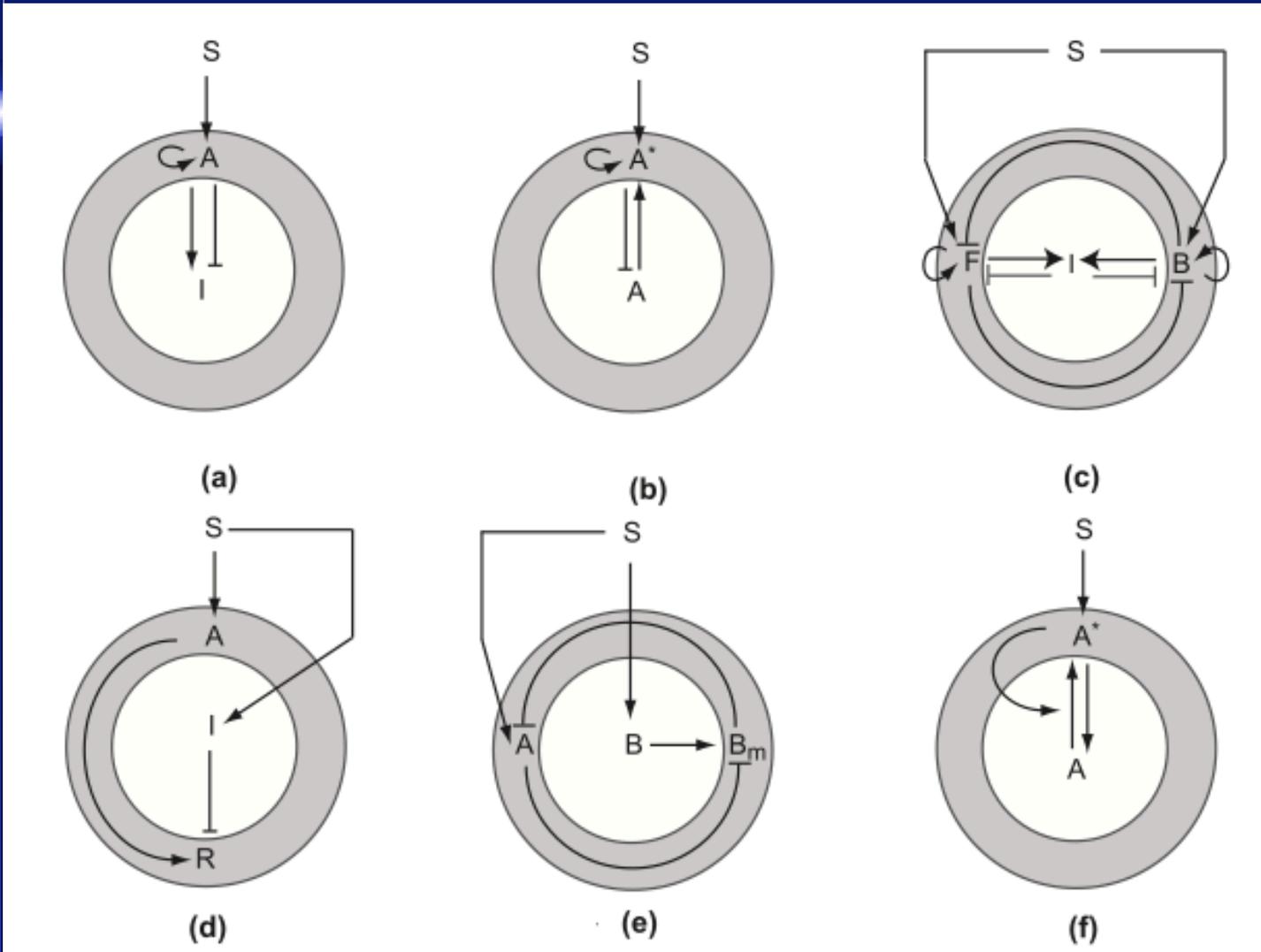
# Stimuli and signaling proteins

Cell type	Feedback Loops	Stimulus	Cytoskeleton
Budding yeast	Cdc42→Cdc24→Cdc42, Cdc42→actin→Cdc42	Bud1	Actin (MO)
<i>D. discoideum</i>	Amplification upstream of PI3K	cAMP	Actin (MO)
Fibroblasts	Cdc42→Rac→RhoA	PDGF, fibronectin, interleukins	Actin, MT, FA
Keratocytes		Mechanical	Actin
Neutrophils	Front/back mutual inhibition PIP3→actin→PIP3	fMLP, interleukins, others	Actin
Neurons	Rac/Rho mutual inhibition	Netrins, semaphorins, ephrins	Actin, MT

Lateral Inhibition, Turing  
 Meinhardt (1999). J Cell Sci  
 112: 2867–2874.

Substrate depletion  
 Otsuji et al. (2007) PLoS  
 Comput Biol 3: e108.

Turing, mutual inhibition  
 Narang A (2006) J Theor  
 Biol 240: 538–553

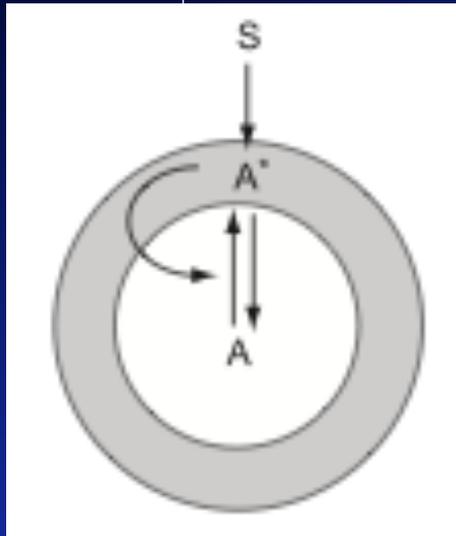


LEGI  
 Levchenko A, Iglesias P (2002).  
 Biophys J 82: 50–63

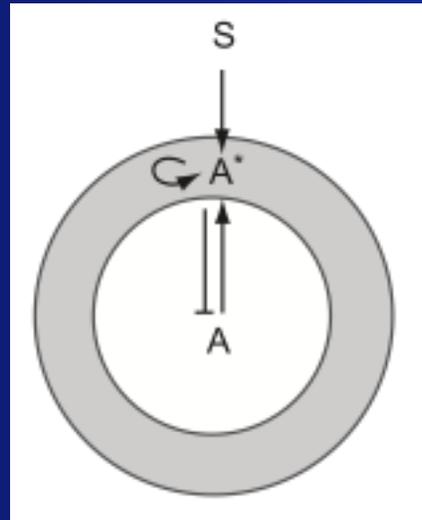
Balanced inactivation  
 Levine H, Kessler DA, Rappel  
 WJ (2006) PNAS 103: 9761–  
 9766

Wave-pinning  
 Mori Y, Jilkine A, LEK (2008)  
 Biophys J 94: 3684–3697

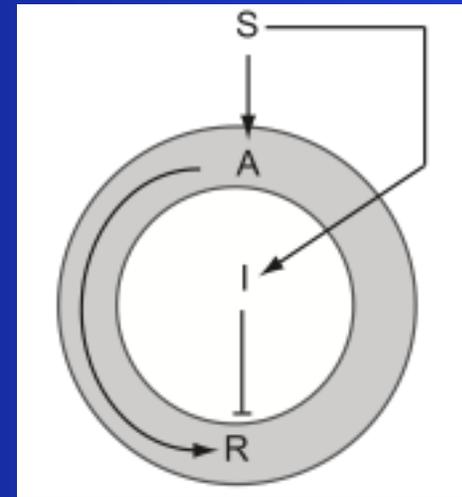
# Testing four models



Wave-Pinning



Goryachev



Otsuji

LEGI

# Types of models

- Reaction-diffusion with slow and fast variables

$$\frac{\partial u}{\partial t} = D_u \frac{\partial^2 u}{\partial x^2} + f(u, v),$$

$$\frac{\partial v}{\partial t} = D_v \frac{\partial^2 v}{\partial x^2} + g(u, v),$$

- Wave-pining

$$f(u,v) = -g(u,v) = v \left( k_0 + \frac{\gamma u^2}{K^2 + u^2} \right) - \delta u.$$

- Otsuji

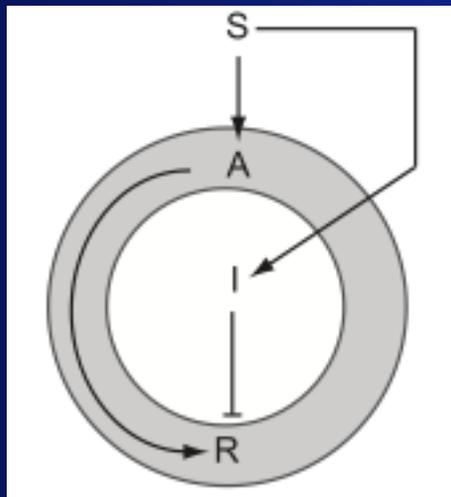
$$f(u,v) = -g(u,v) = a_1 \left[ v - \frac{u+v}{(a_2 s(u+v) + 1)^2} \right],$$

- Goryachev

$$f(u,v) = -g(u,v) = \alpha E_c u^2 v + \beta E_c u v - \gamma u, \quad E_c = \frac{E_c^0}{1 + \int_S f(u) ds}.$$

- LEGI: see over

# Local excitation global inhibition (LEGI)



$$\frac{\partial A}{\partial t} = k_A S(t, x) - k_{-A} A,$$

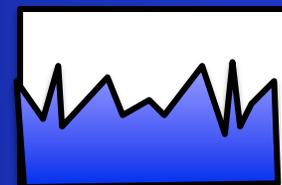
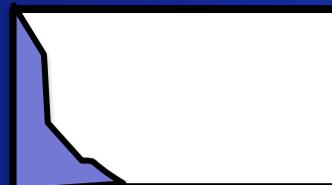
$$\frac{\partial I}{\partial t} = D \frac{\partial^2 I}{\partial x^2} + k_I S(t, x) - k_{-I} I,$$

$$\frac{\partial R}{\partial t} = k_R A (R_T - R) - k_{-R} I R,$$

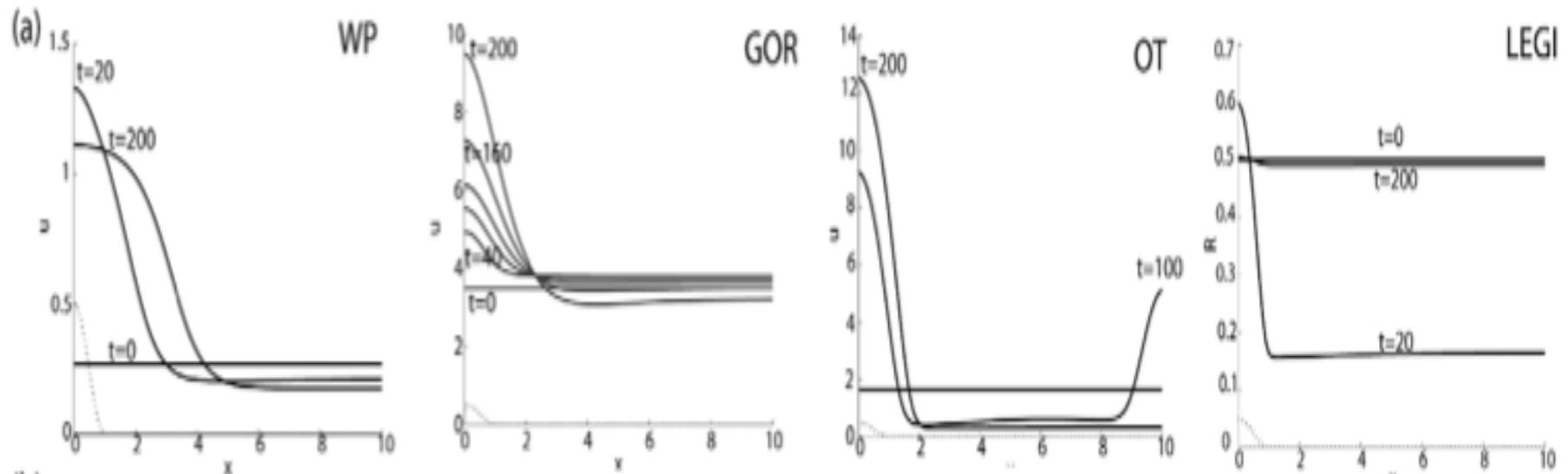
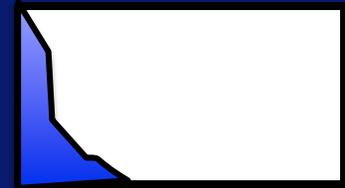
# Stimuli

$$\frac{\partial u}{\partial t} = D_u \frac{\partial^2 u}{\partial x^2} + f(u, v) + k_S v,$$

$$\frac{\partial v}{\partial t} = D_v \frac{\partial^2 v}{\partial x^2} - f(u, v) - k_S v,$$



# Single localized stimulus at left edge of the cell



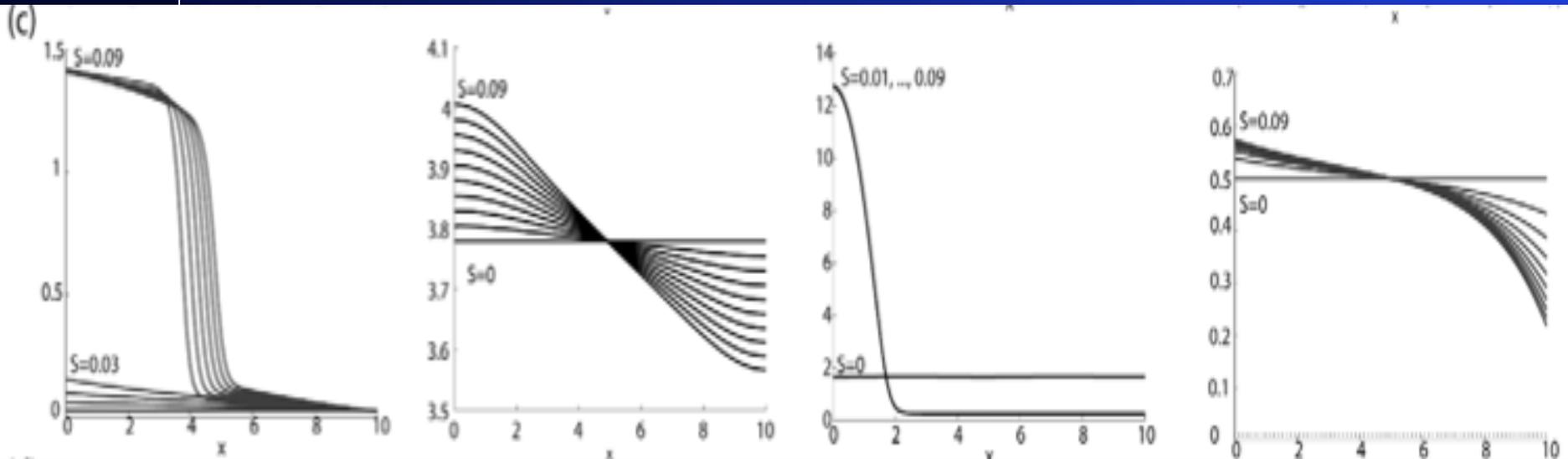
Wave-Pinning

Goryachev

Otsuji

LEGI

# Gradient stimulus



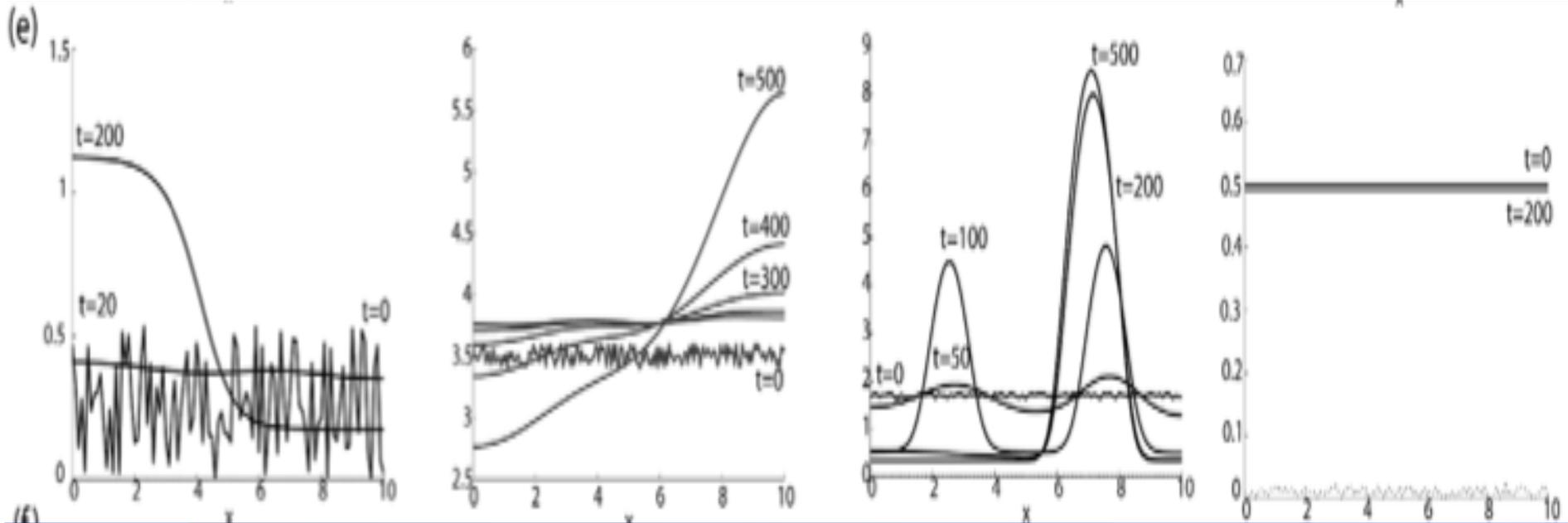
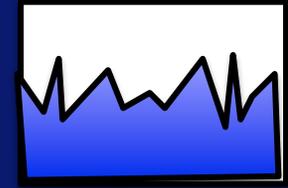
Wave-Pinning

Goryachev

Otsuji

LEGI

# Noisy initial conditions



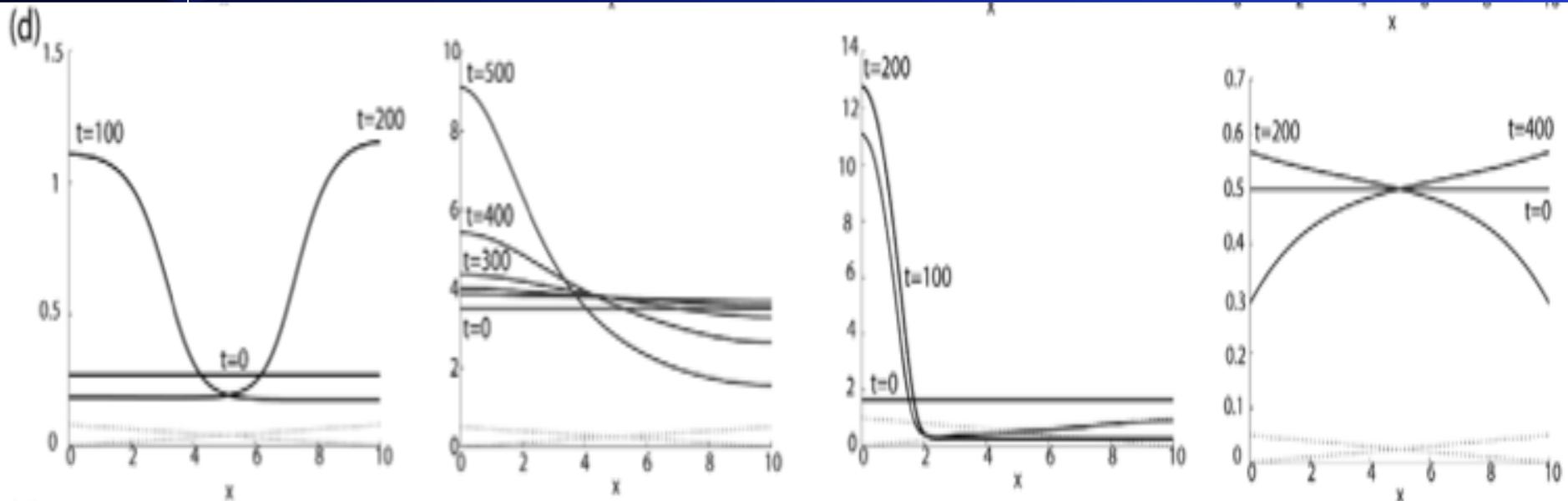
Wave-Pinning

Goryachev

Otsuji

LEGI

# Gradient + reversal



(e)

Wave-Pinning

Goryachev

Otsuji

LEGI

**In such Turing-type models, the pattern will not reverse when a new gradient of opposite polarity is applied**

# Features that models can explain

<b>Behavior</b>	<b>"Turing Type"</b>	<b>Wave-Based</b>	<b>Gradient Sensing</b>
Maintenance of polarity	Yes	Yes	No
Multi-stimuli response	Yes (transient)	Yes (long time-scale)	Yes
High amplification	Yes	Yes	No
Adaptation	No	No	Yes
Spontaneous polarization	Yes	Yes	No
Reversible asymmetry	No	Yes	Yes

A decorative graphic in the top-left corner of the slide. It features a glowing blue sphere with a bright white center, from which a thin white vertical line and a thin white horizontal line intersect. The background of the slide is a dark blue gradient, with a lighter blue vertical band on the left side.

End of Part 1