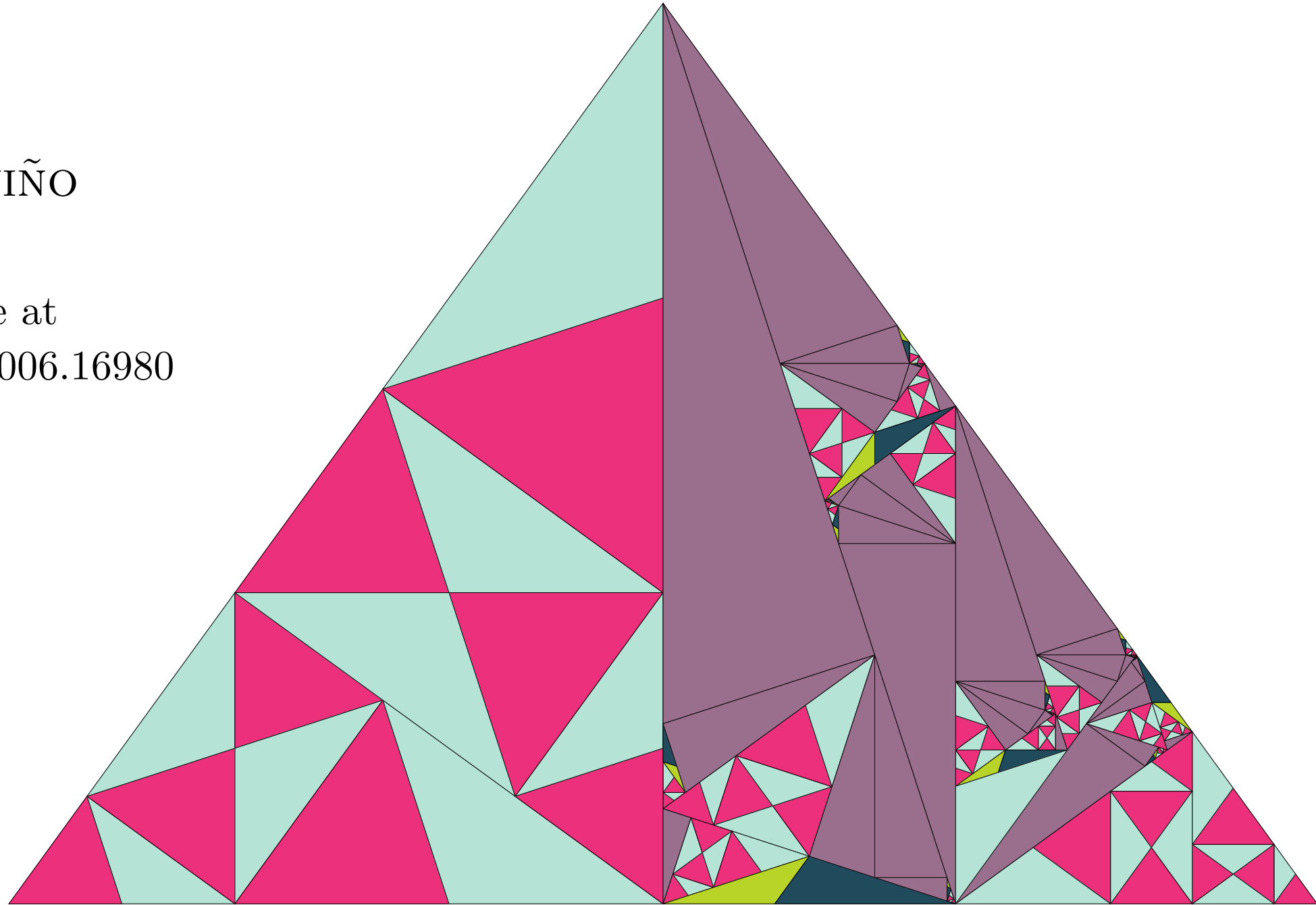


# QUANTITATIVE WEAK MIXING FOR RANDOM SUBSTITUTION TILINGS

RODRIGO TREVIÑO

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<https://arxiv.org/abs/2006.16980>



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Quantitative weak mixing is about bounding the dimension of spectral measures from below (away from 0).

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PROPOSITION (Hof): If  $|\mathcal{S}_R^x(f, \lambda)| \leq CR^{d-\alpha}$  for any  $x$  and  $R > R_0$ , then

$$\mu_f(B_r(\lambda)) \leq C' r^{2\alpha}$$

for all  $r$  small enough, which implies that

$$d_{\mu_f}^-(\lambda) \geq 2\alpha.$$

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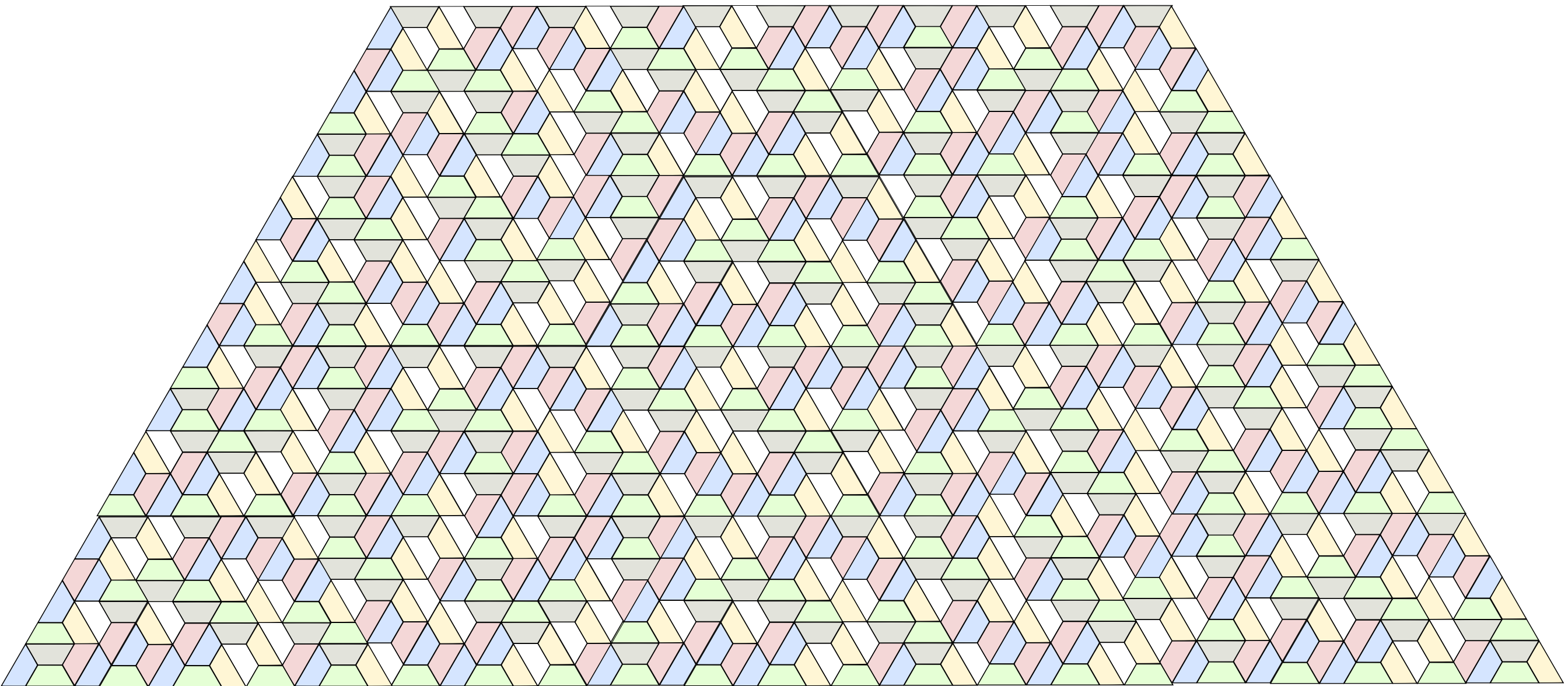
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Avila-Forni (2007): Weak mixing for typical translation flows and IETs



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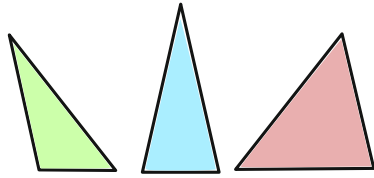
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The Čech cohomology is

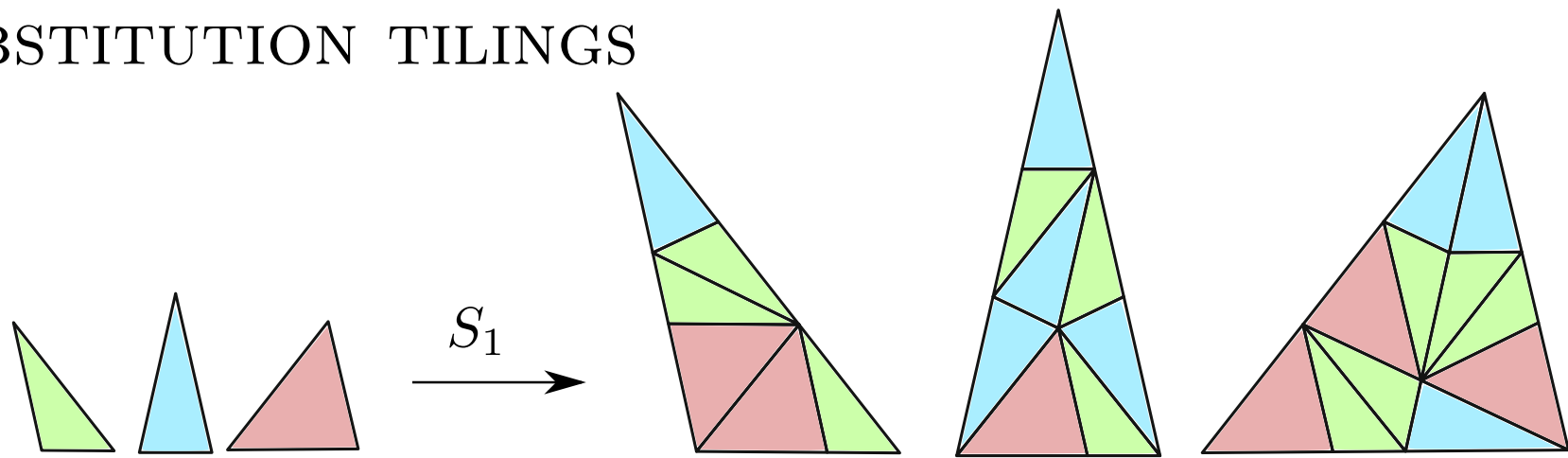
$$\check{H}^*(\Omega; \mathbb{Z}) = \varinjlim (H^*(\Gamma_k; \mathbb{Z}), \gamma_k^*)$$

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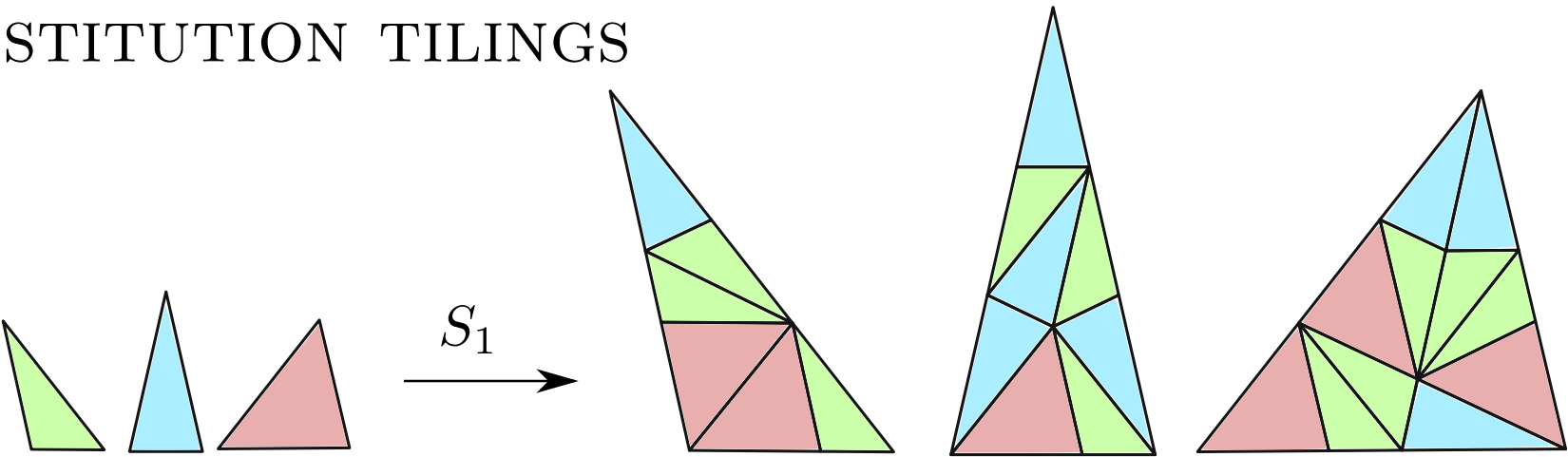


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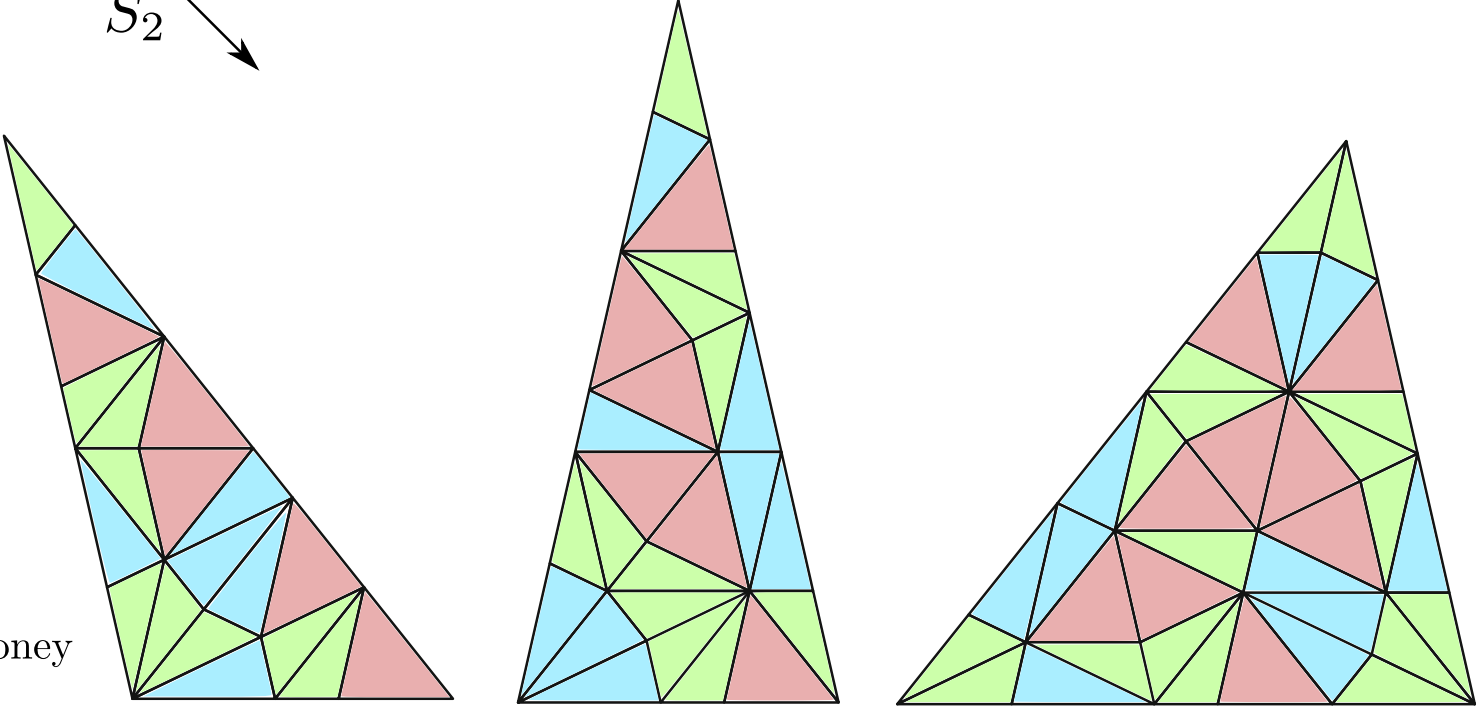
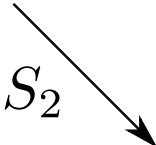


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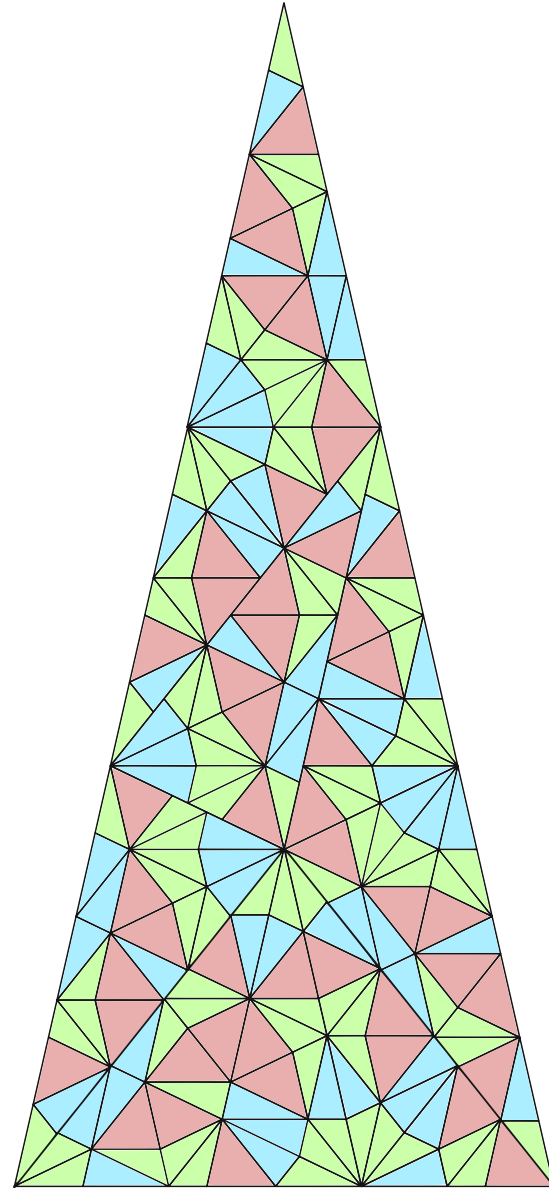
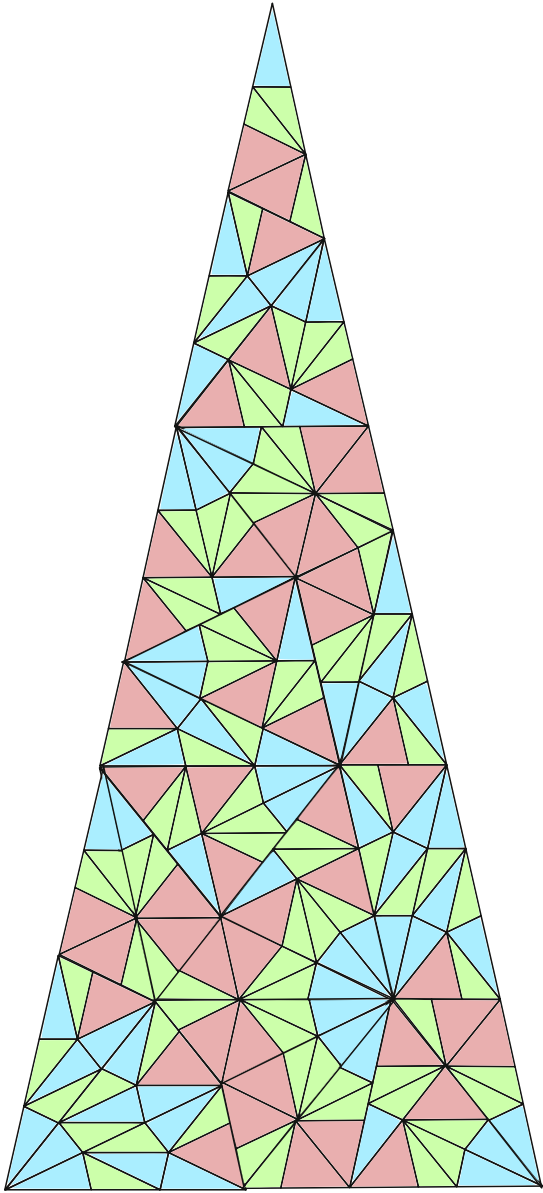


$$\lambda_2 = 2 \cos(\pi/7)(1 + 2 \cos(\pi/7)) - 1 \sim 4.0489\dots$$

Gähler, Kwan, Maloney

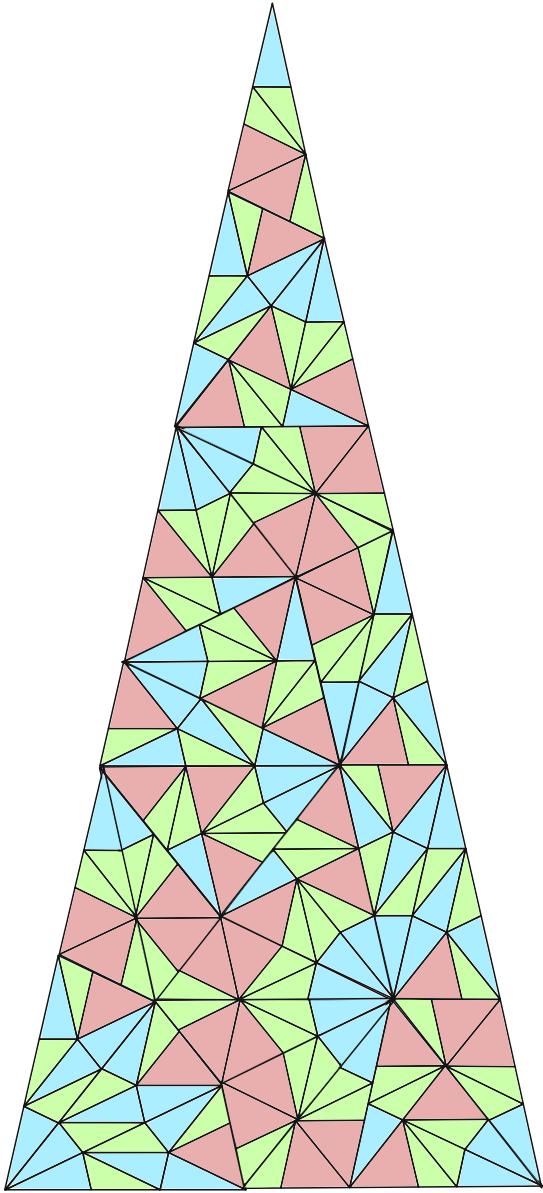


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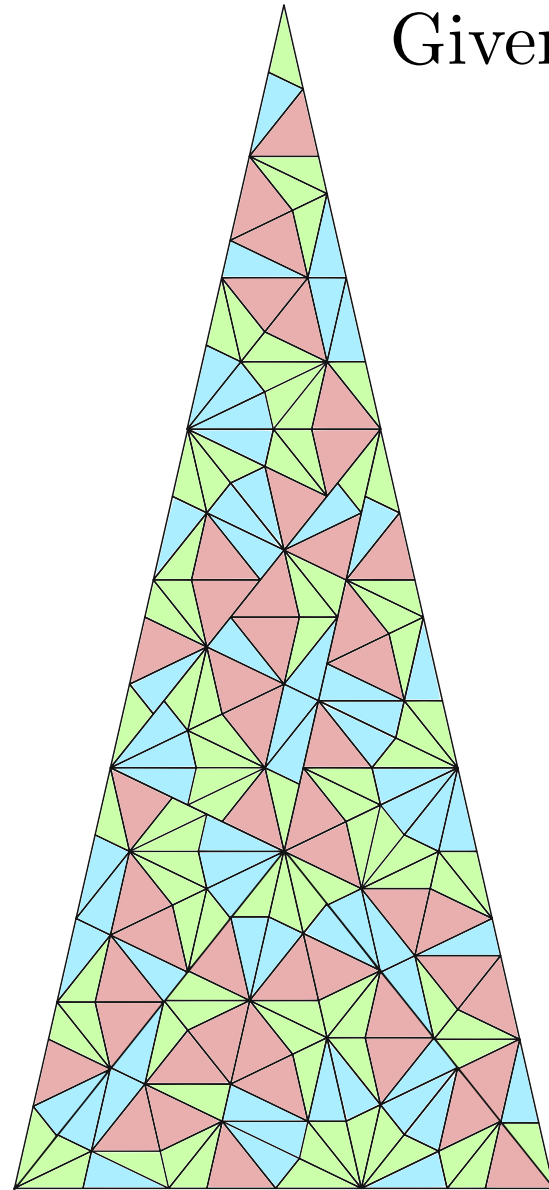


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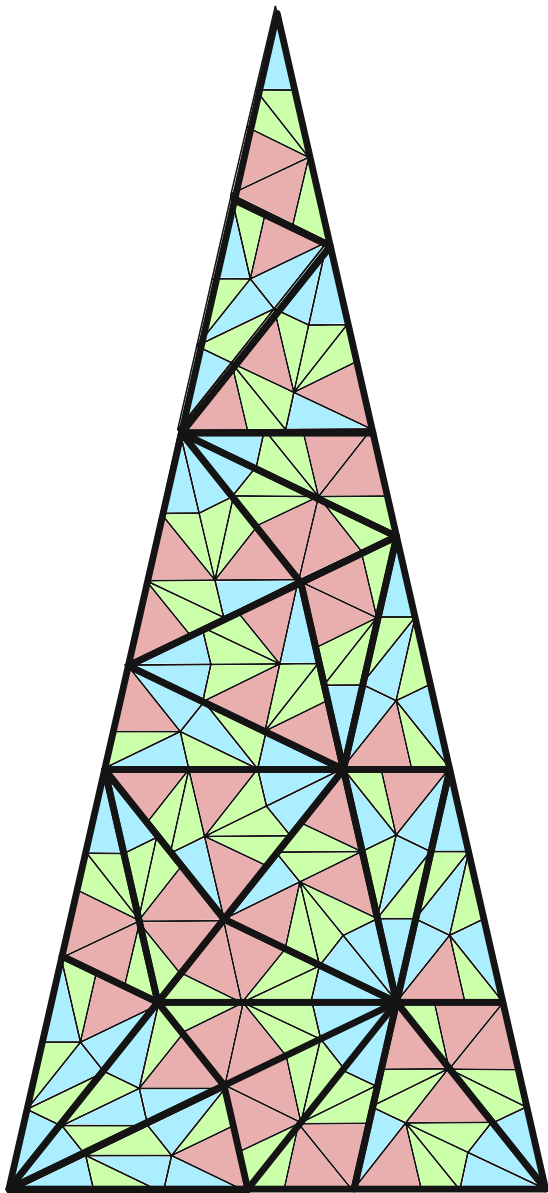
$x = 12\dots$



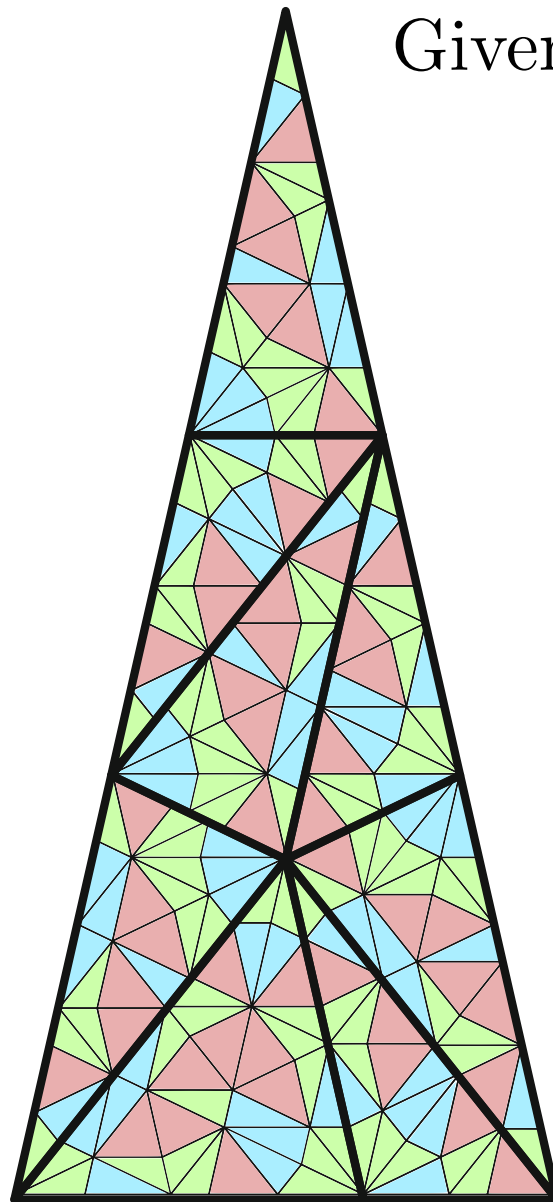
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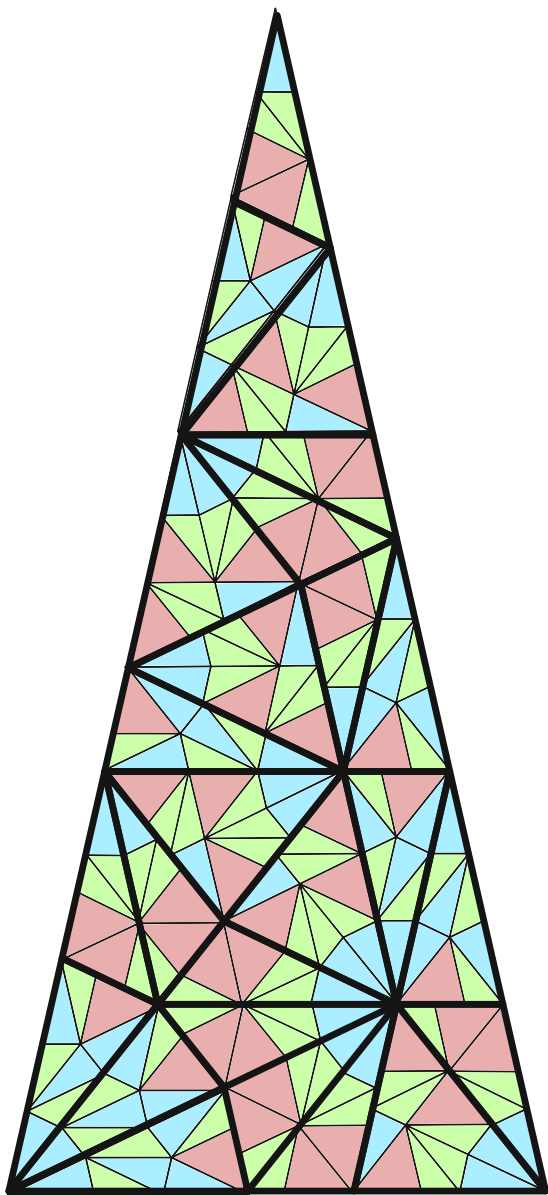


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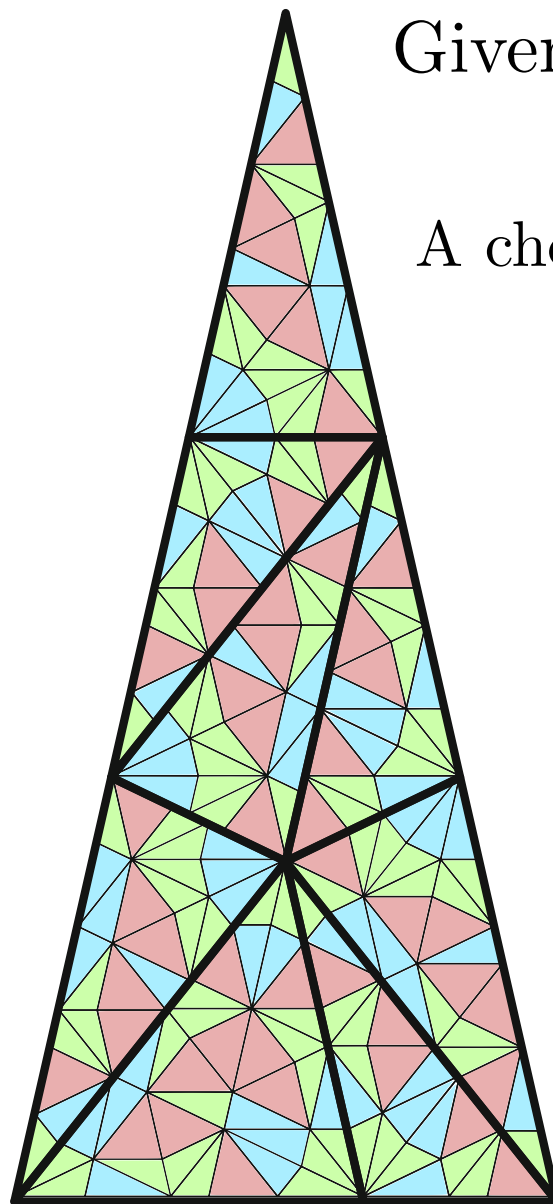


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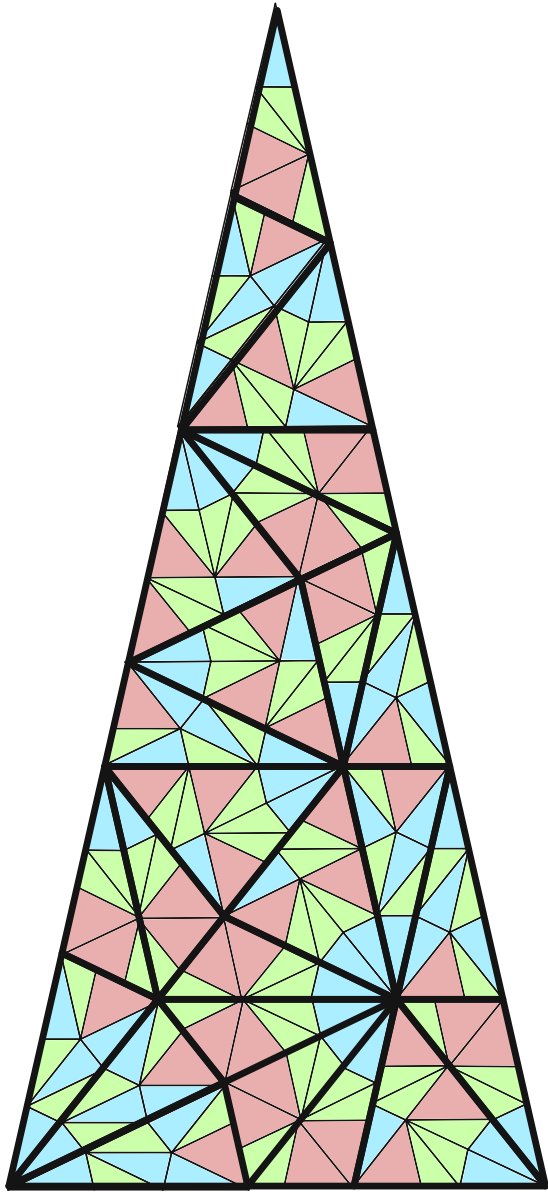


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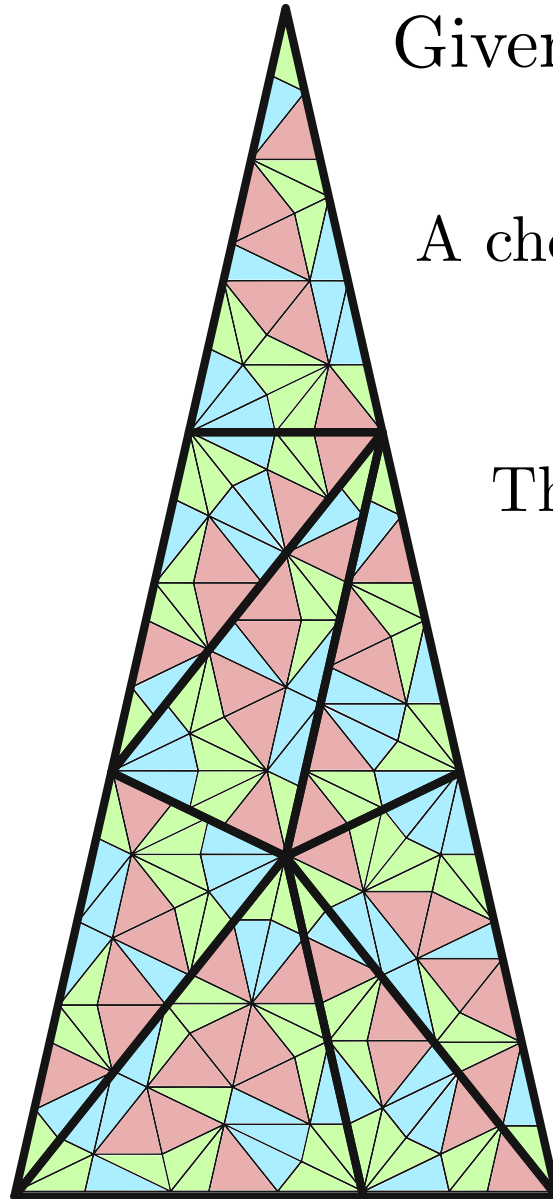
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A choice  $x \in \Sigma_2$  is a choice of hierarchical structure  
(Tower structure)

# RANDOM SUBSTITUTION TILINGS



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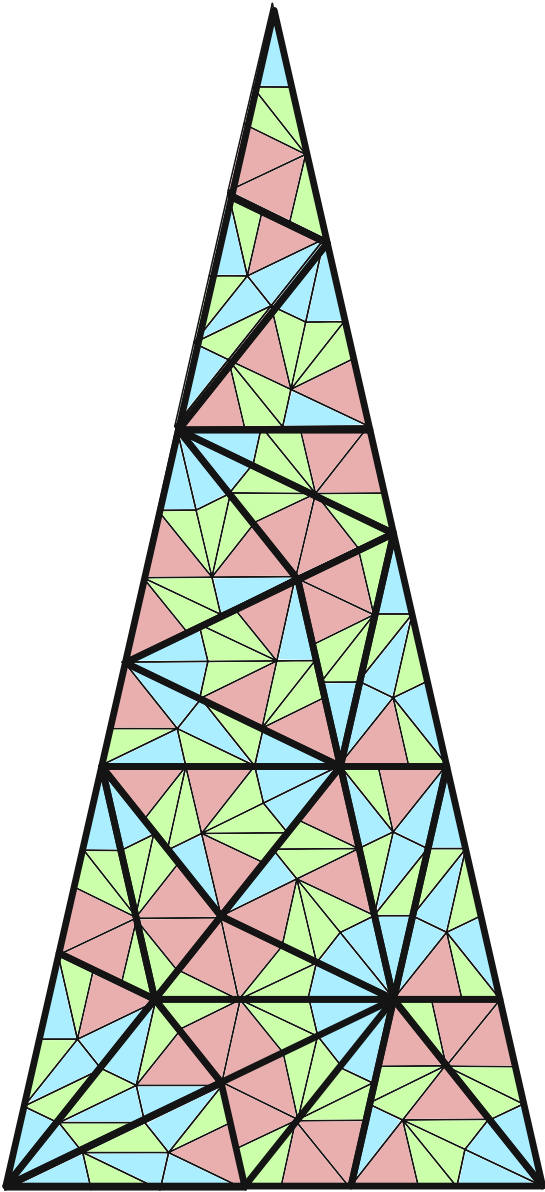
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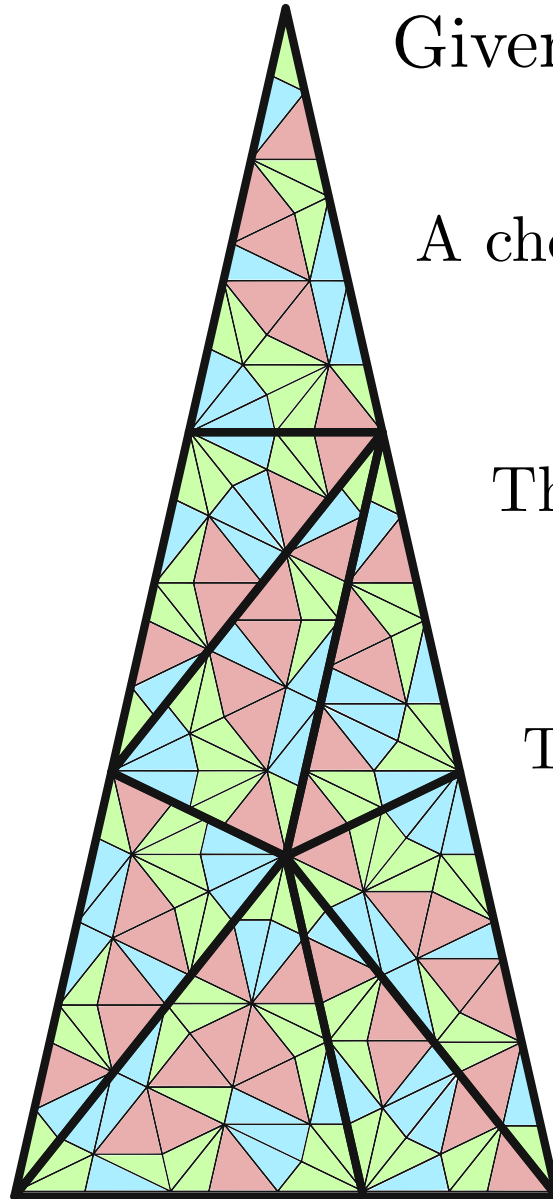
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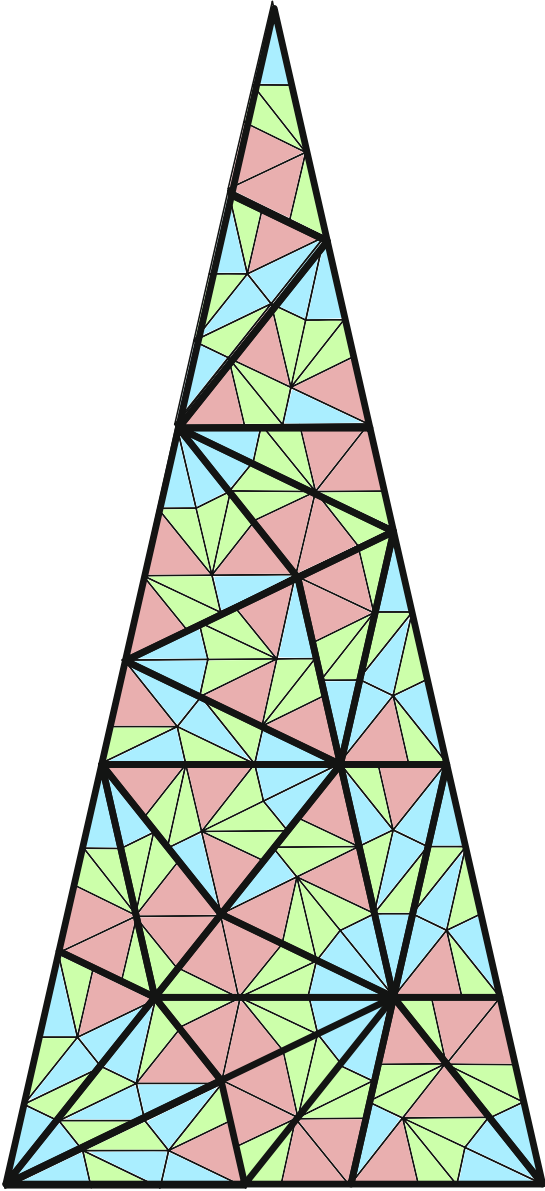
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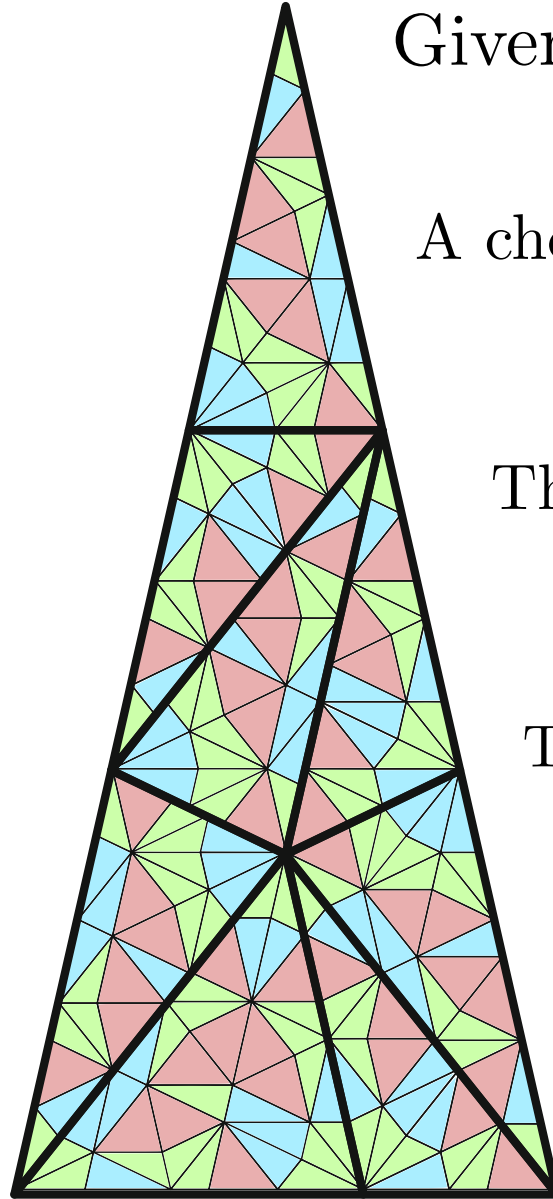
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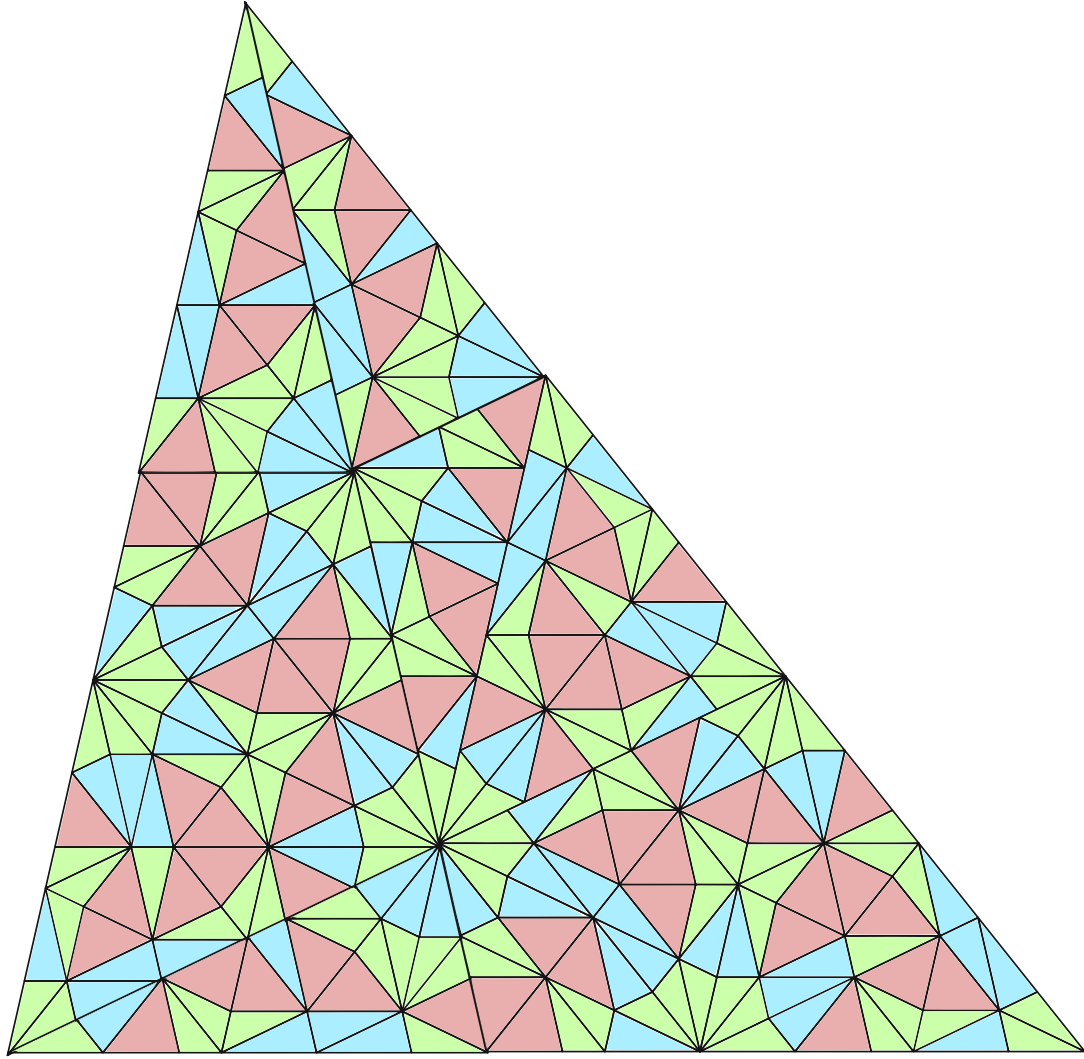
and induces an action on cohomology

$$\Phi_x^* : H^*(\Omega_{\sigma(x)}; \mathbb{R}) \rightarrow H^*(\Omega_x; \mathbb{R})$$

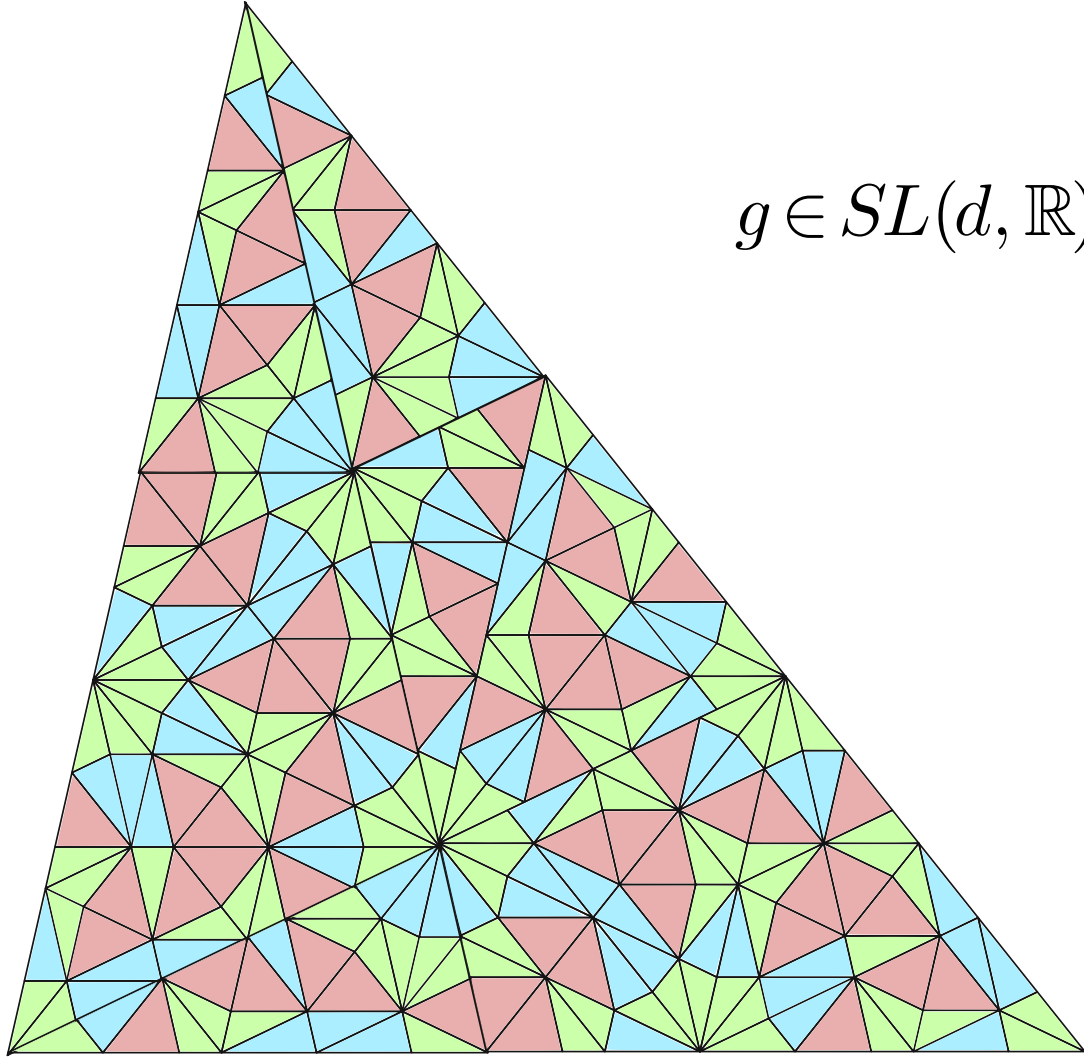
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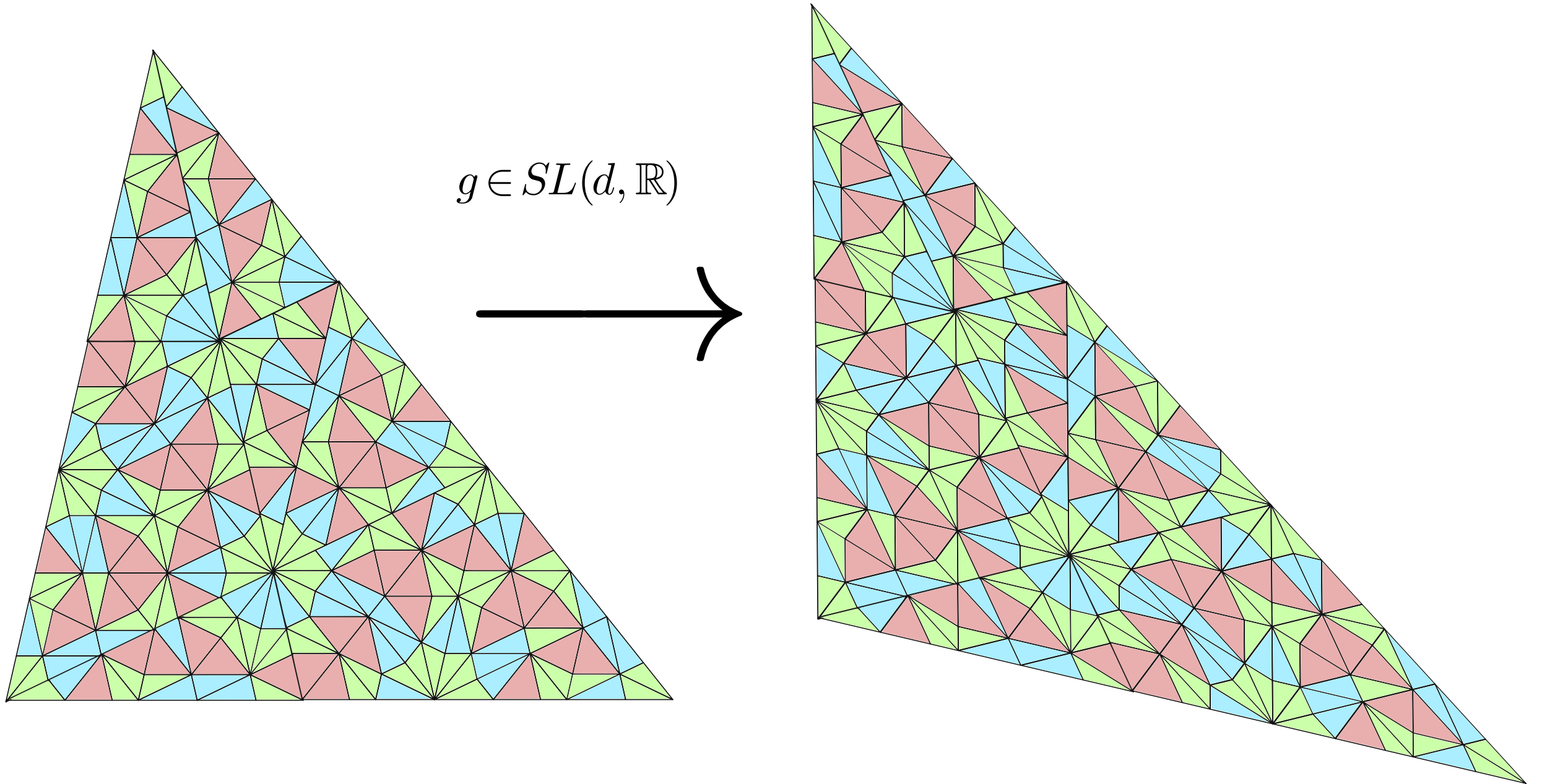


# DEFORMATIONS



$$g \in SL(d, \mathbb{R})$$

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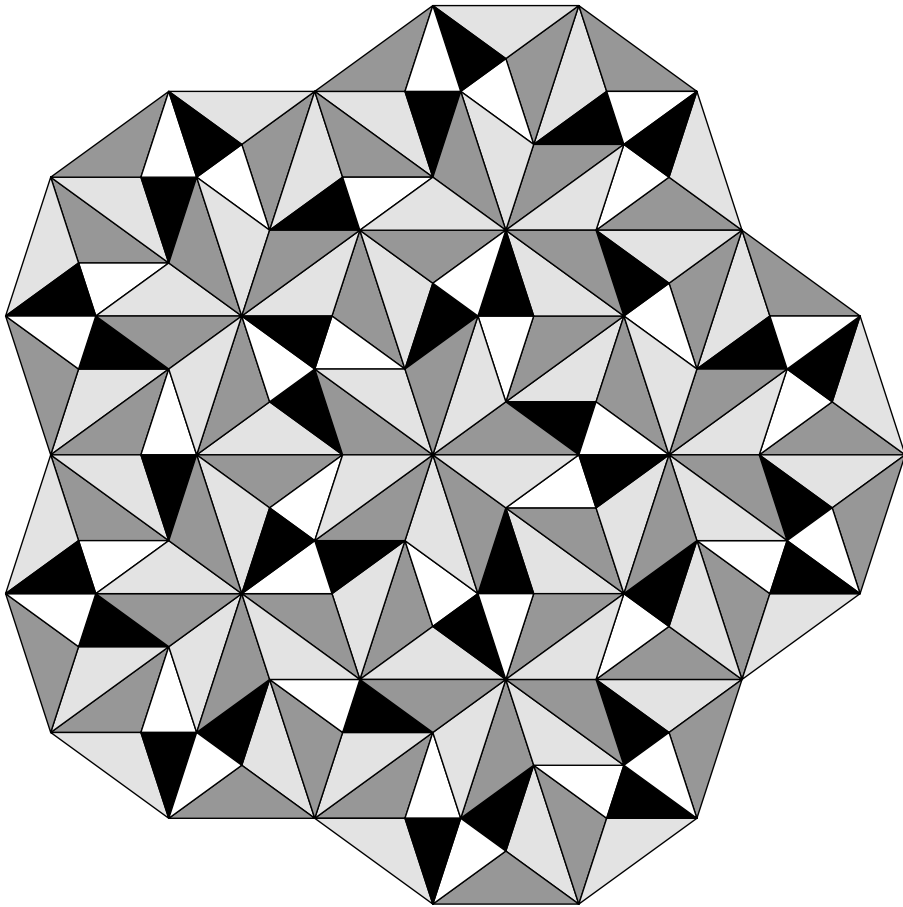
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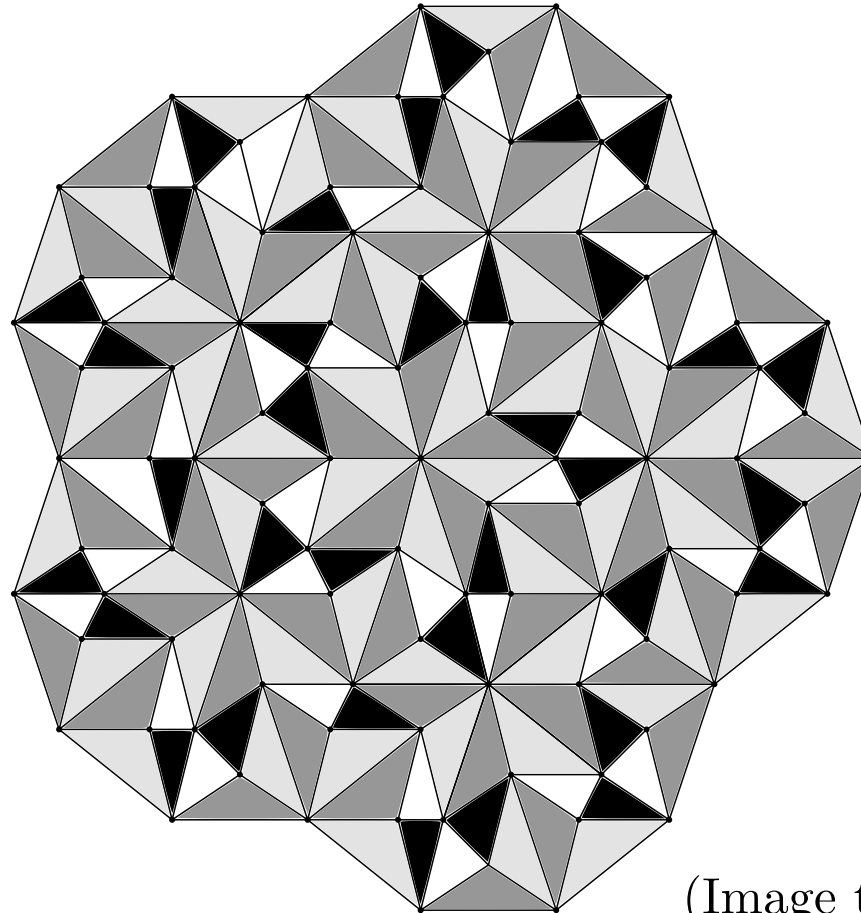
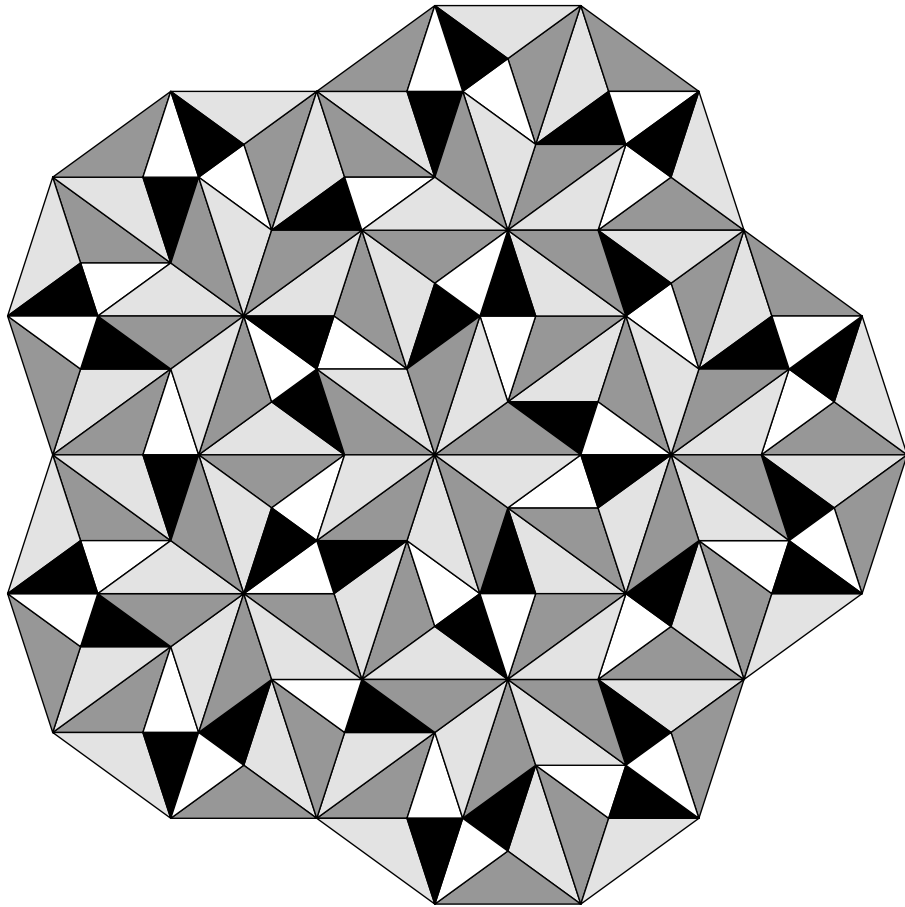
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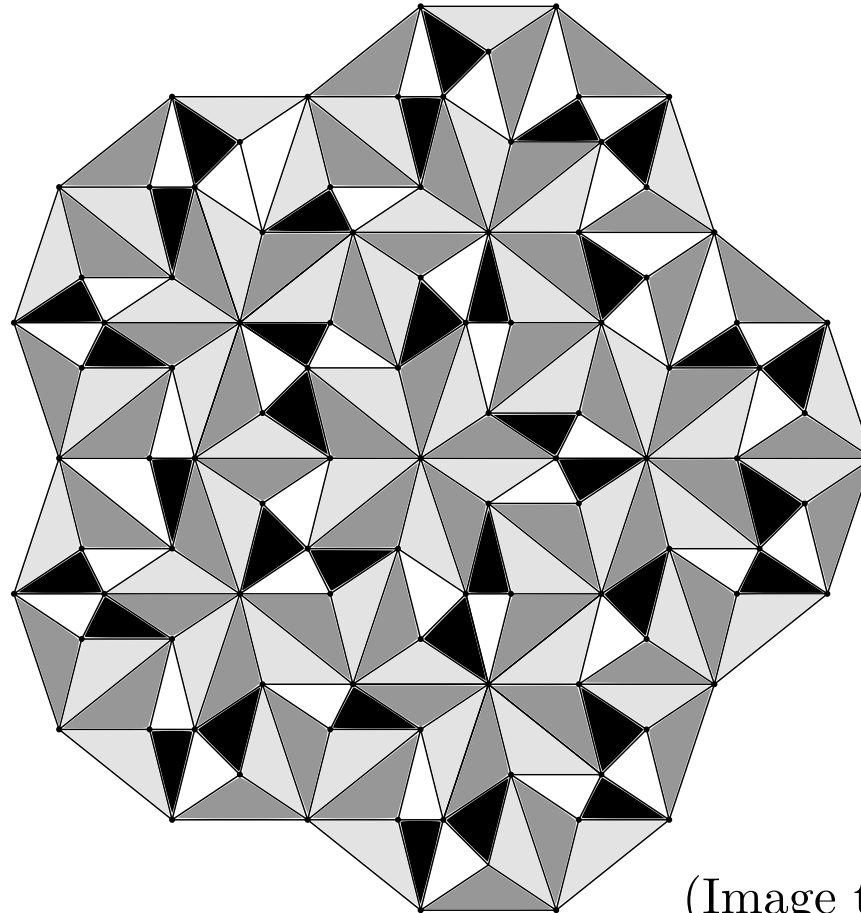
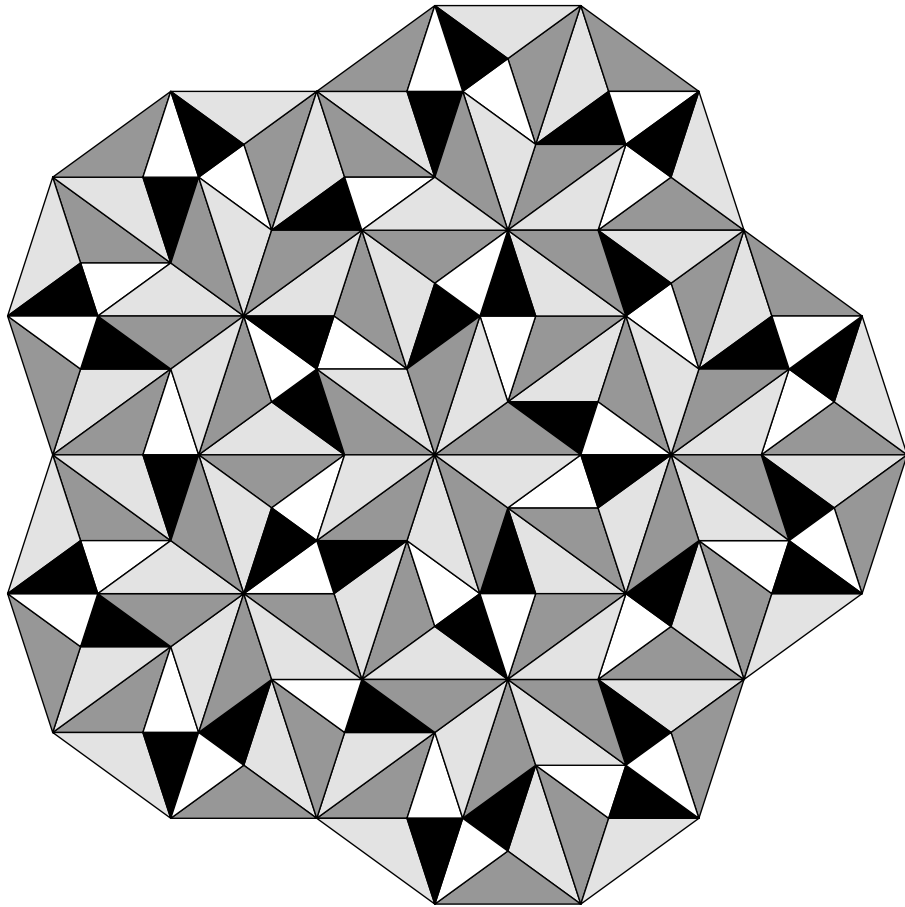


(Image taken from Clark-Sadun 2006)

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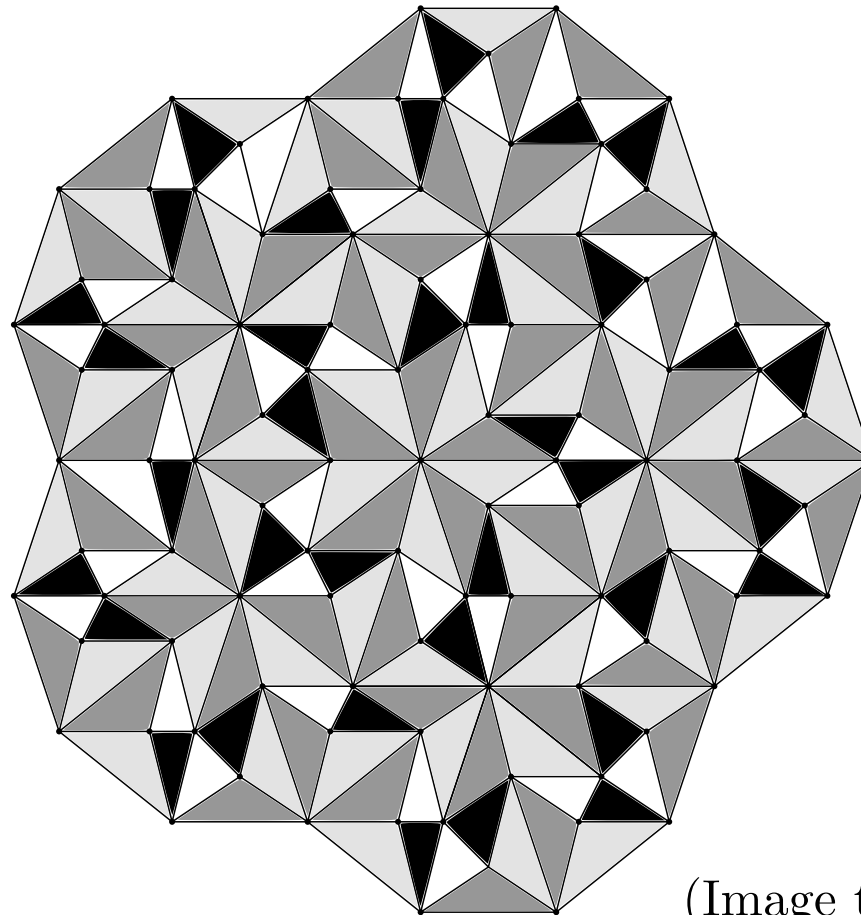
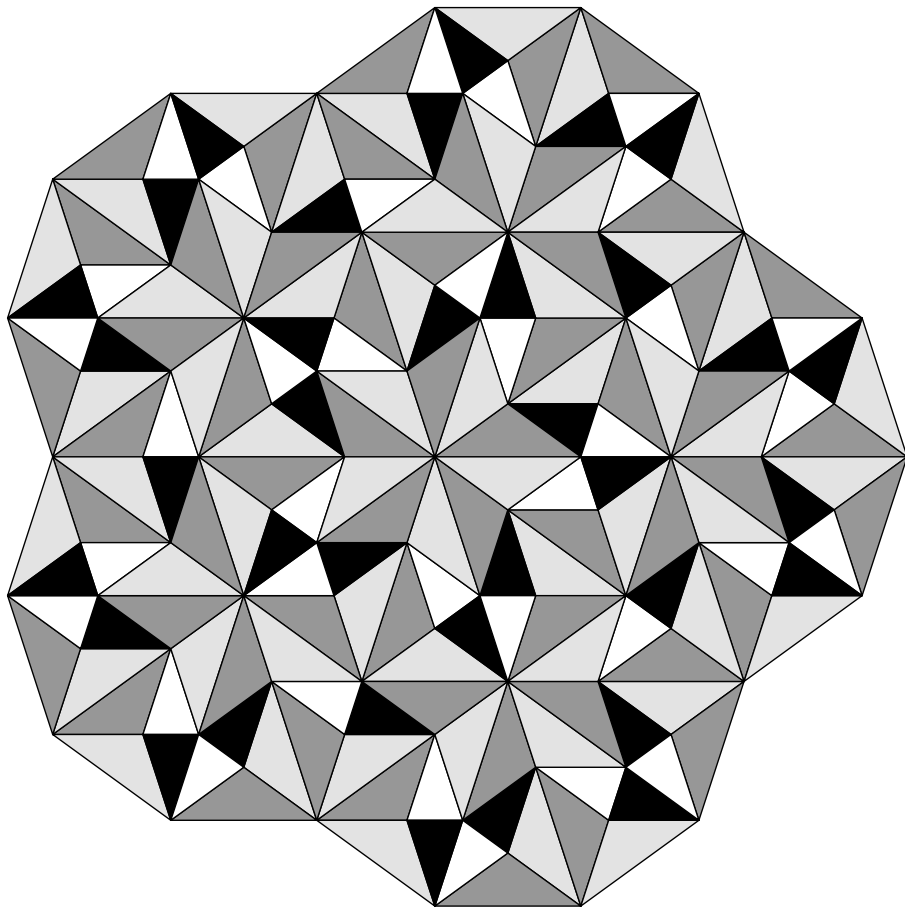
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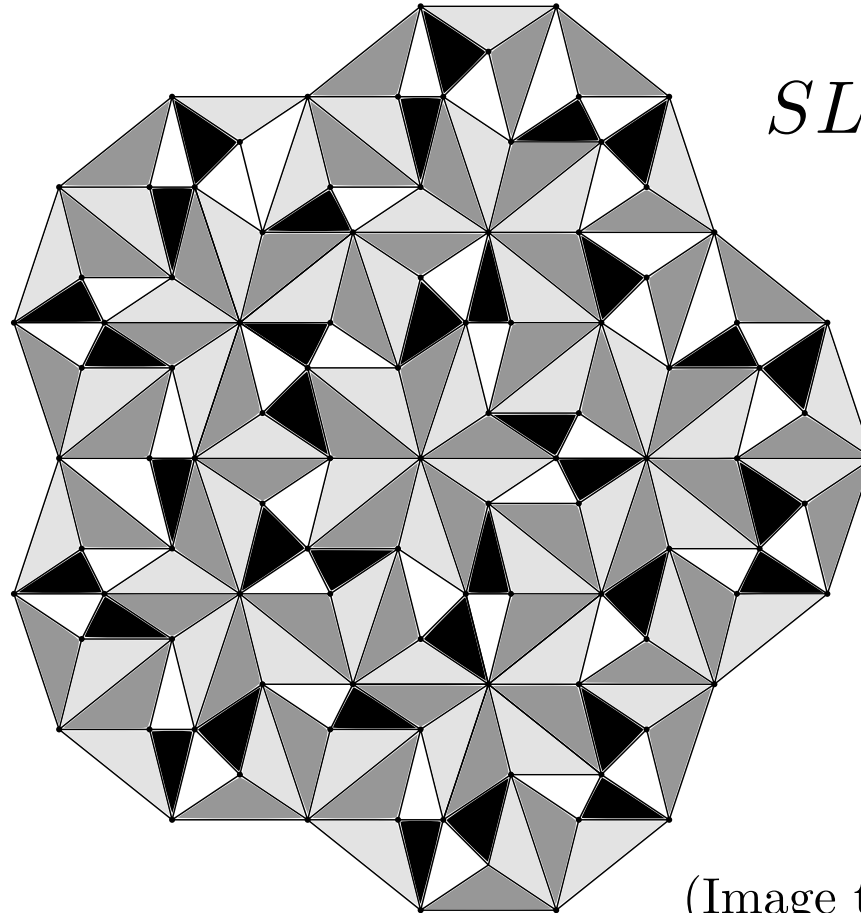
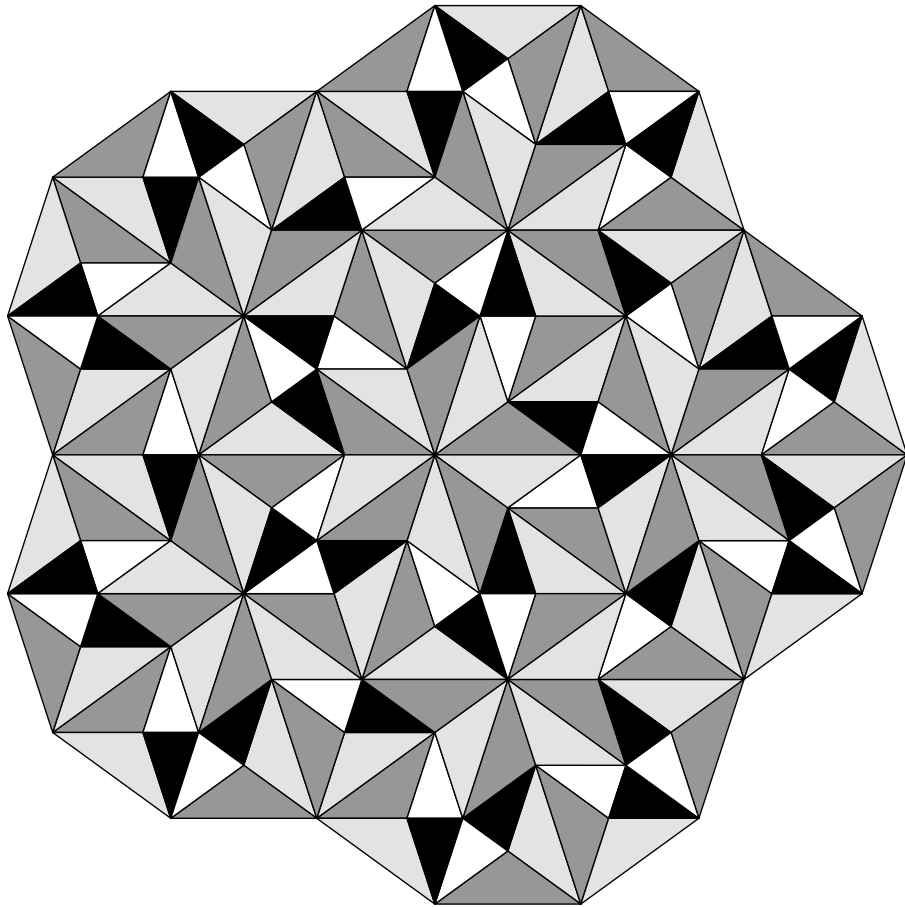
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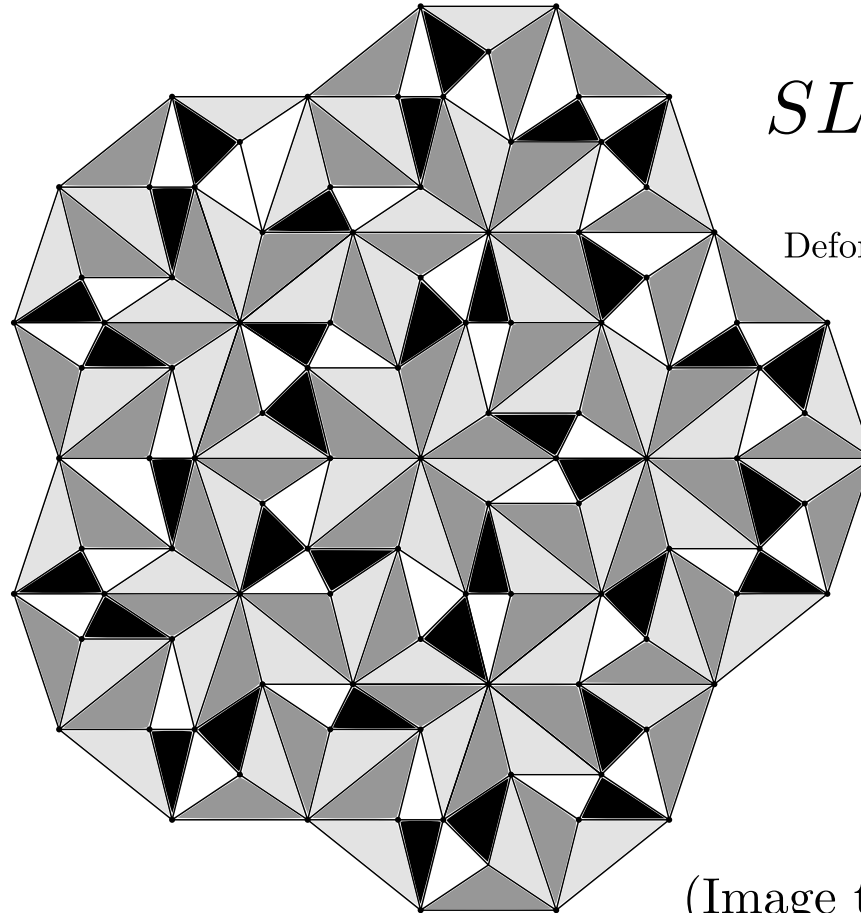
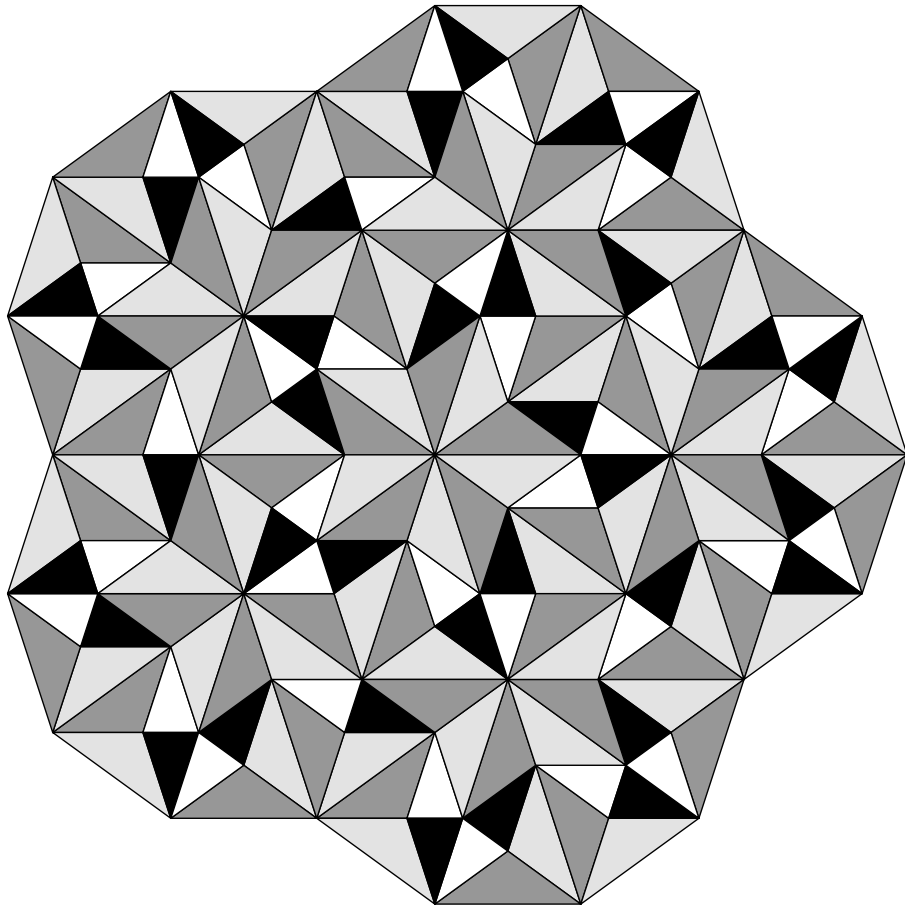
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Deformations give deformations of tiling spaces, changing the  $\mathbb{R}^d$  action and changing the geometry of return vectors.

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$$2\alpha_\mu \leq d_f^-(\lambda).$$

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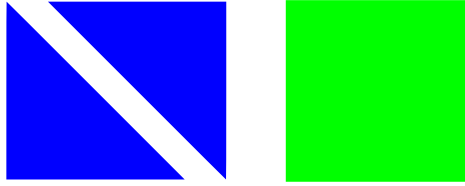
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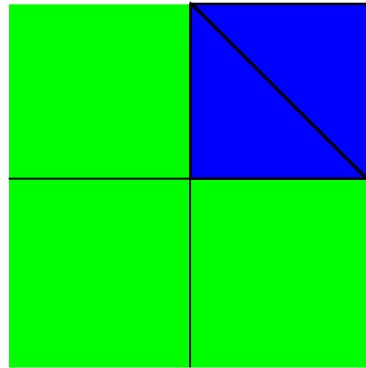
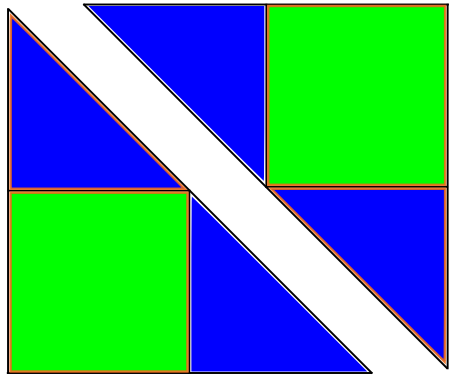
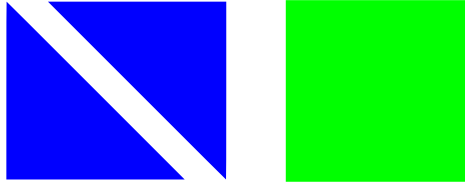
▀ Estimate Hausdorff dimension of bad deformation parameters and show that it is codimension  $\dim(E_x^+) - d$  in space of parameters  $\mathcal{M}_x$  (following Bufetov-Solomyak)

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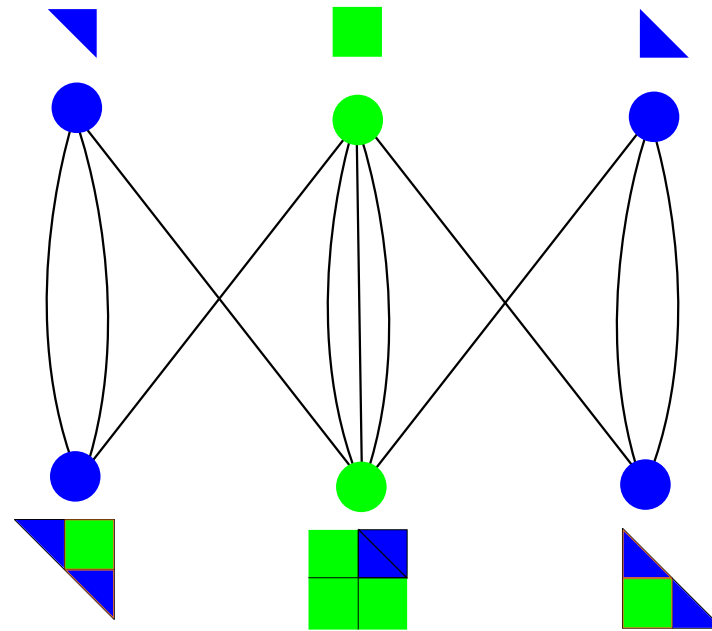
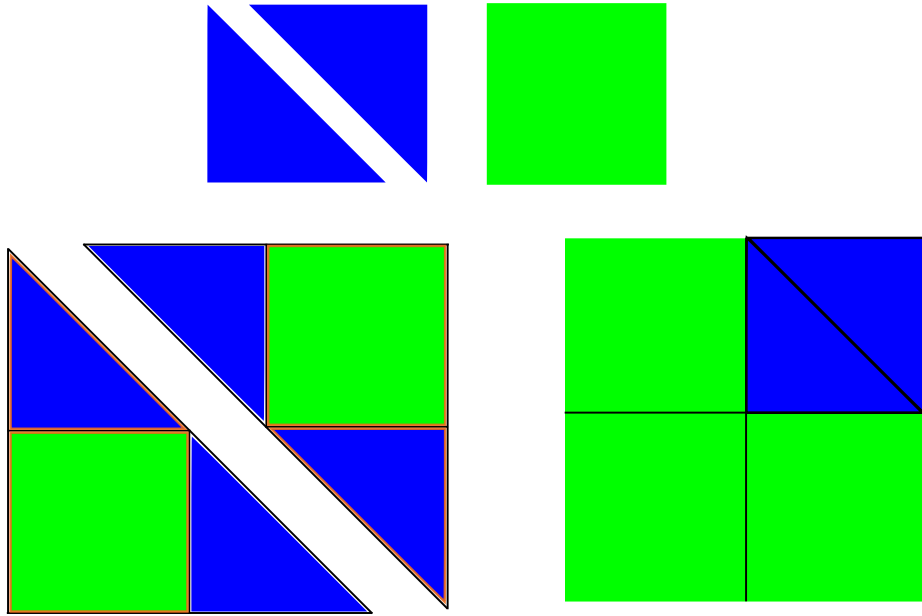
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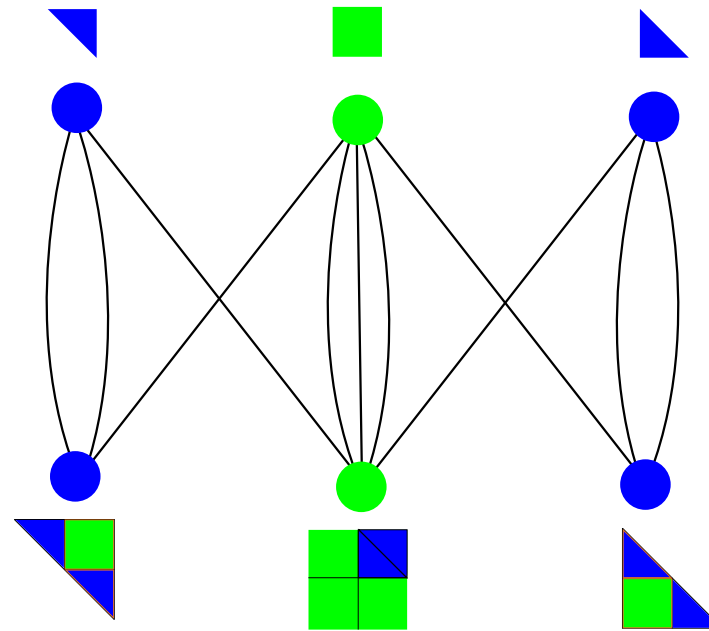
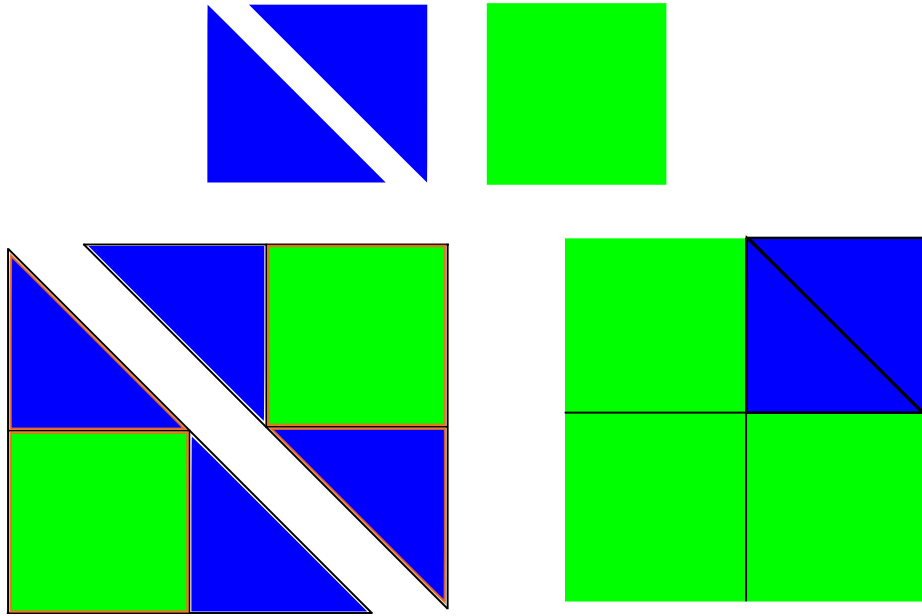


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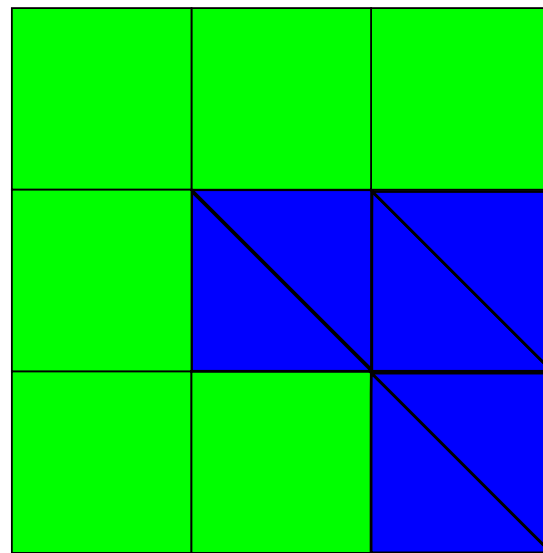
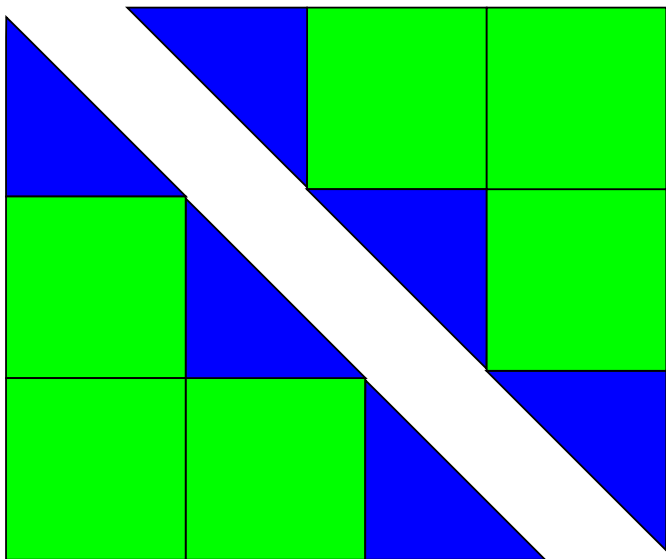
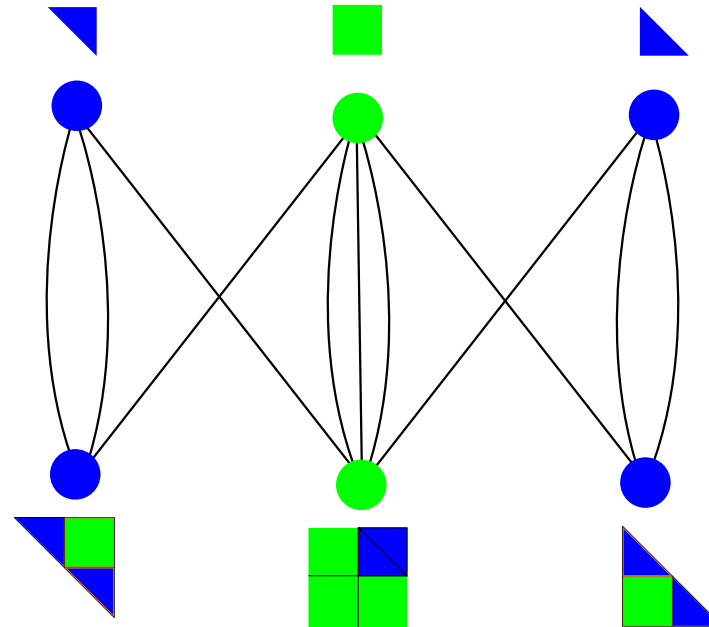
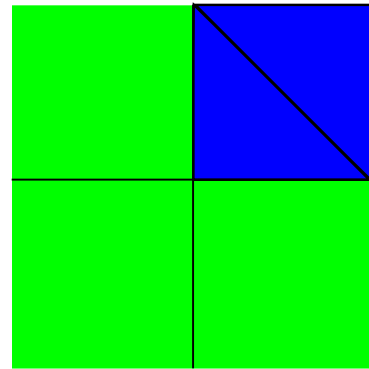
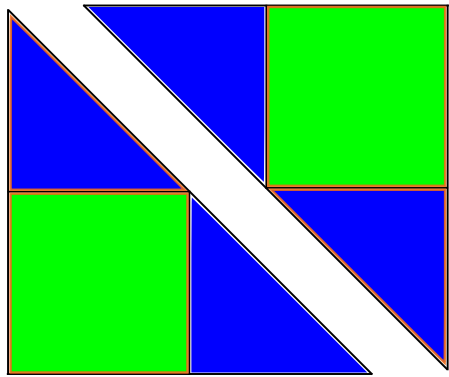
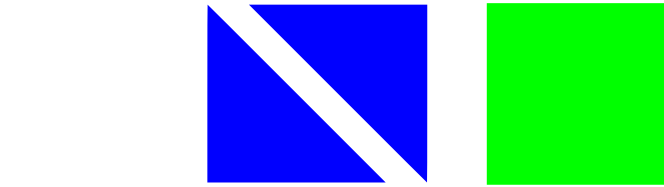
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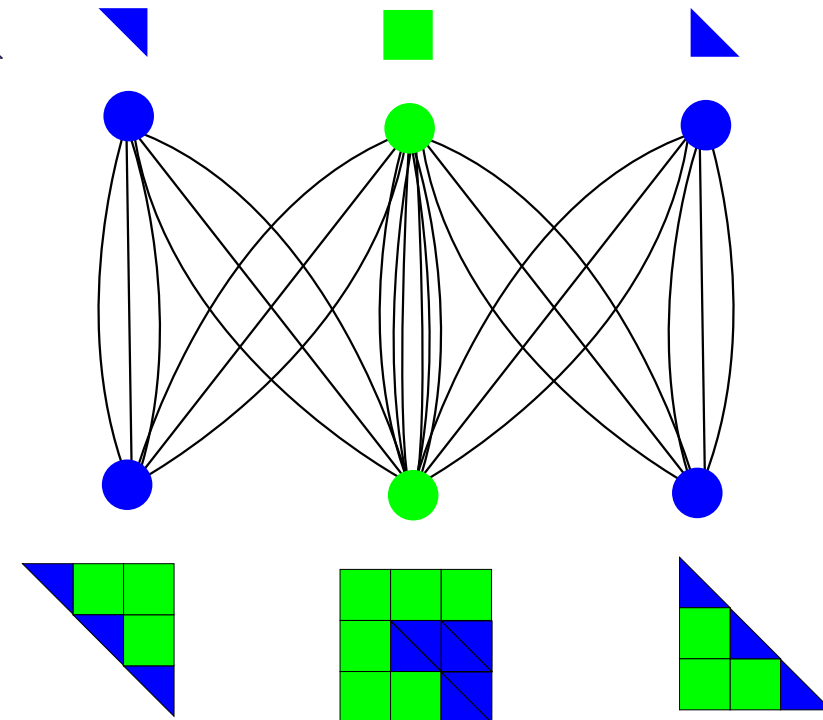
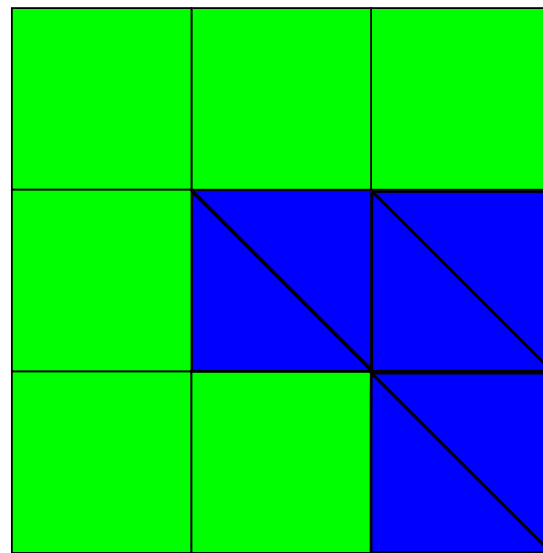
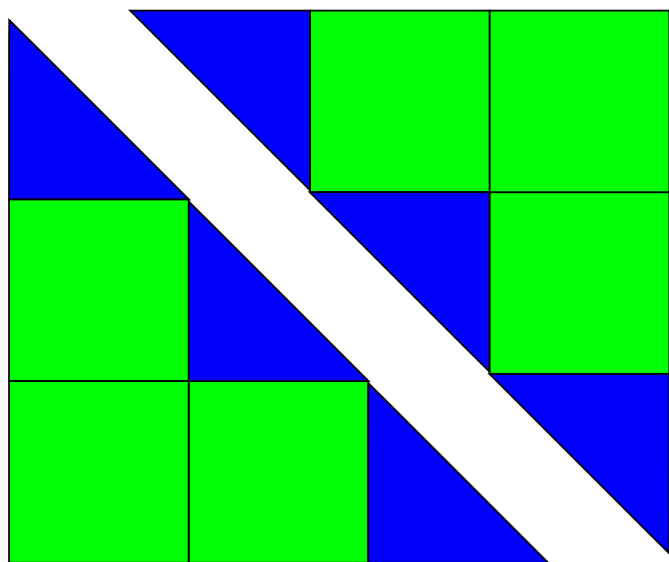
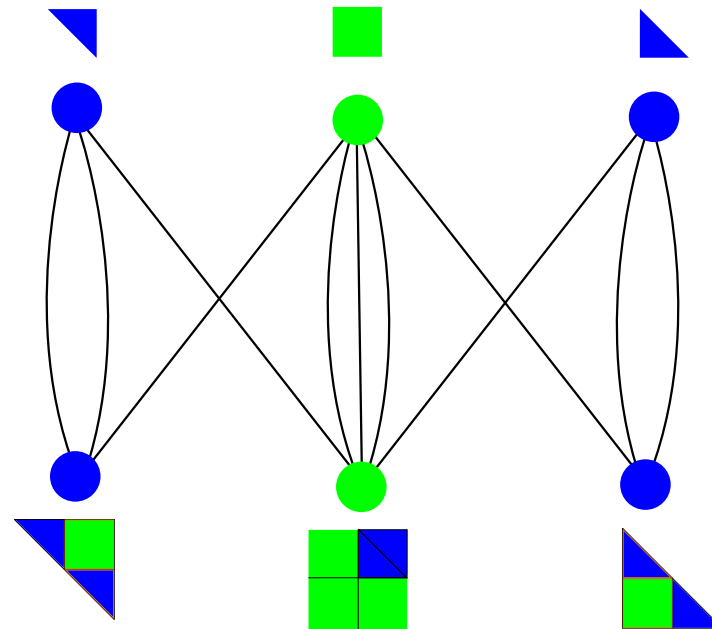
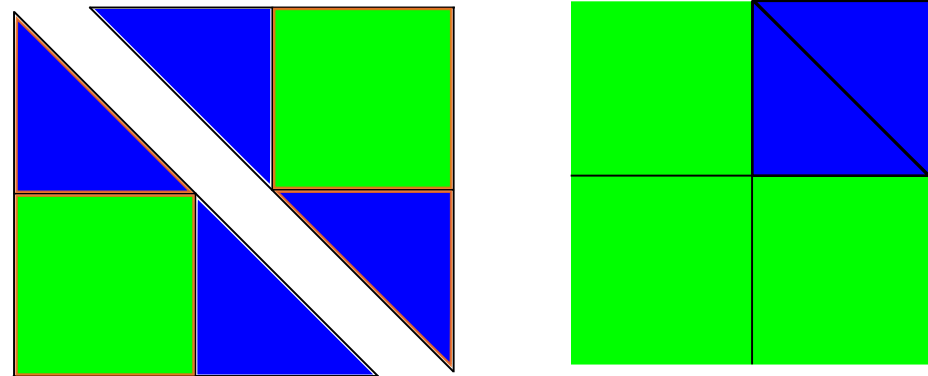
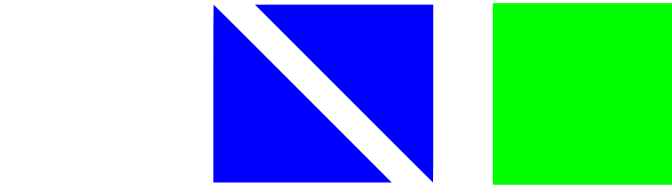
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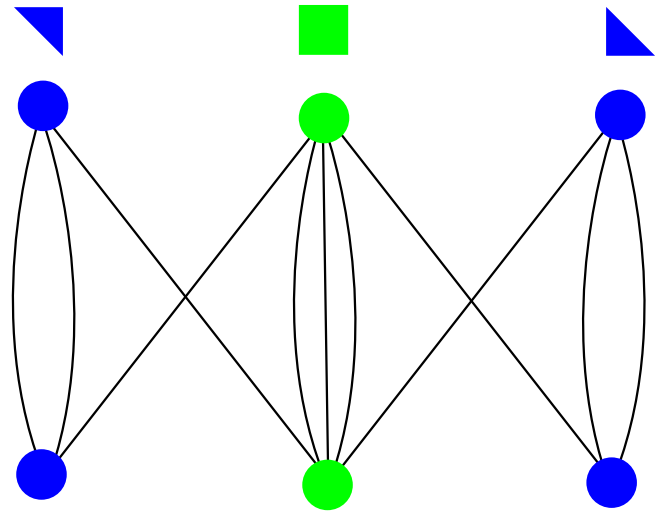
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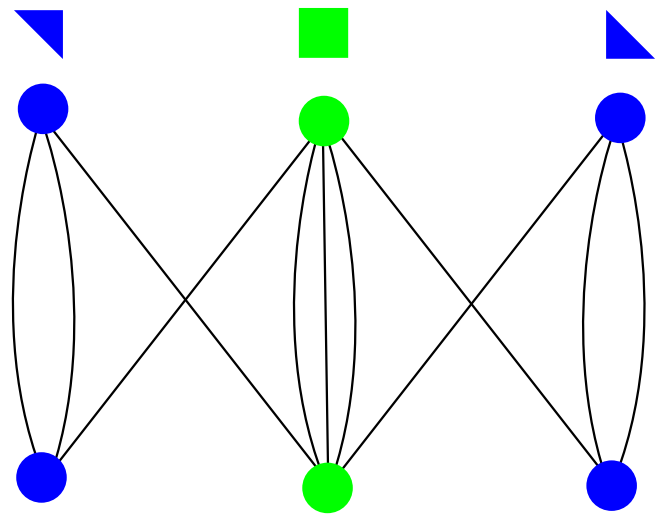
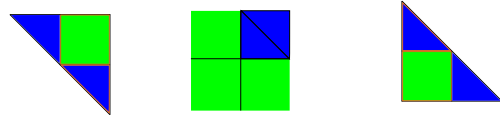




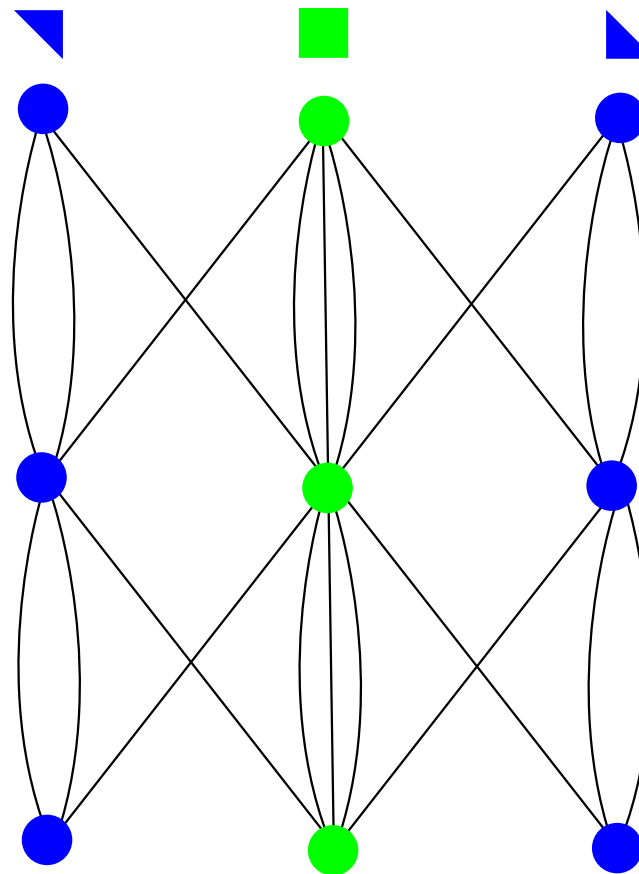
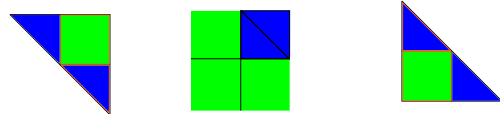
# SUBSTITUTION RULES



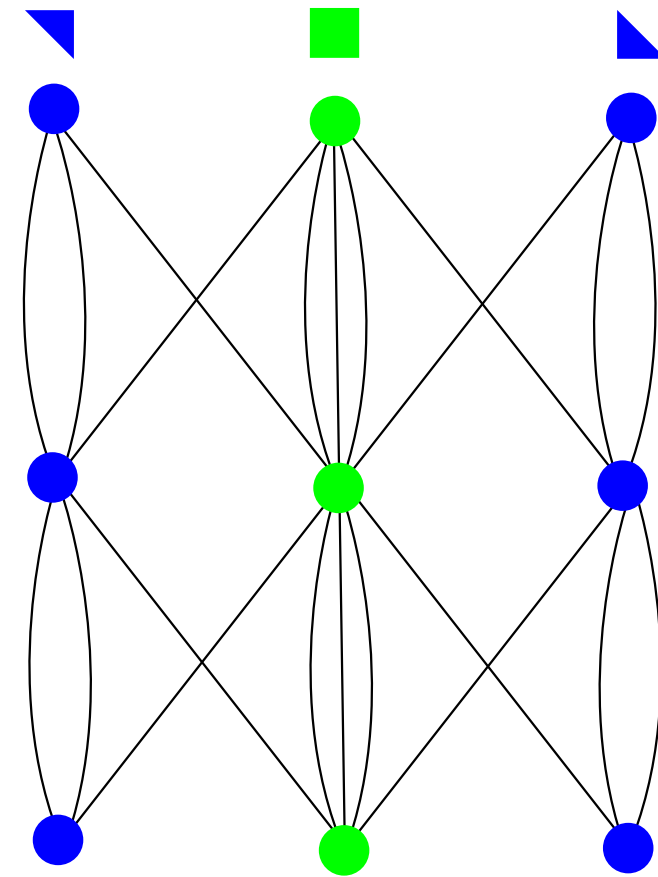
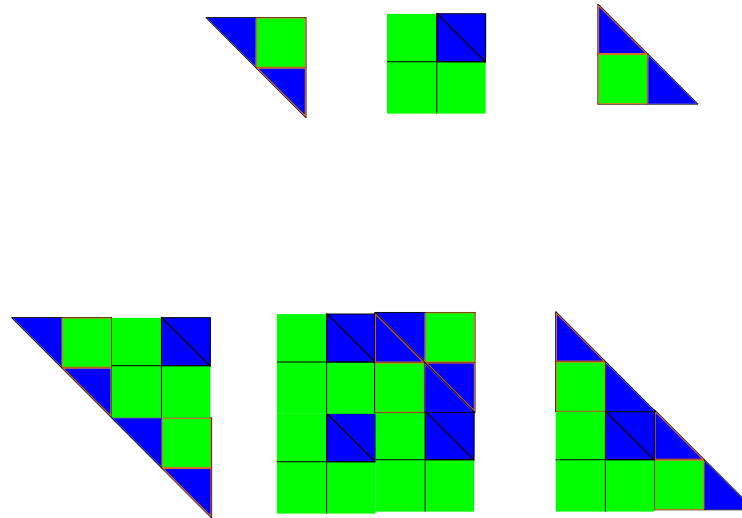
# SUBSTITUTION RULES



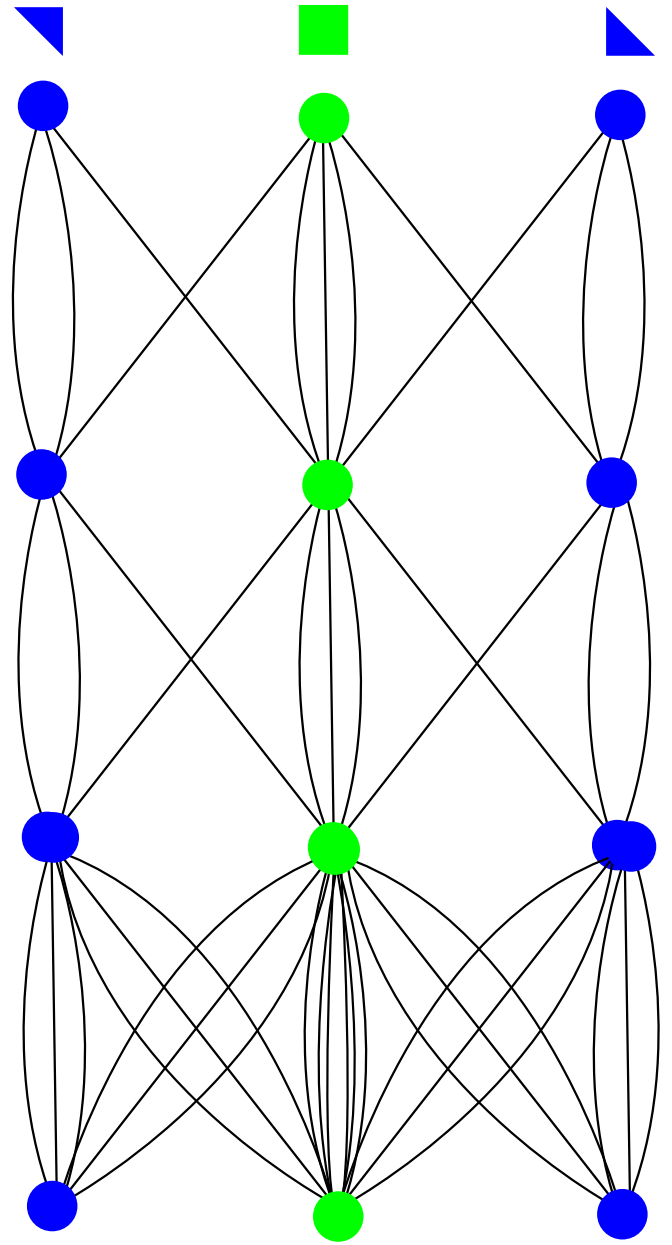
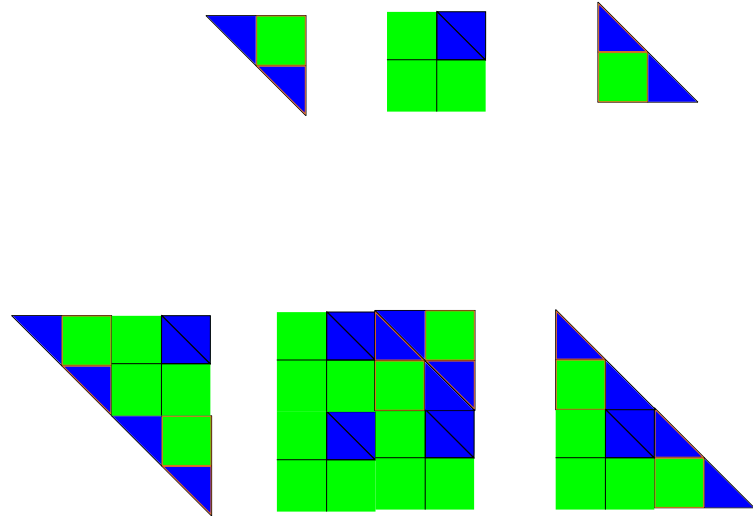
# SUBSTITUTION RULES



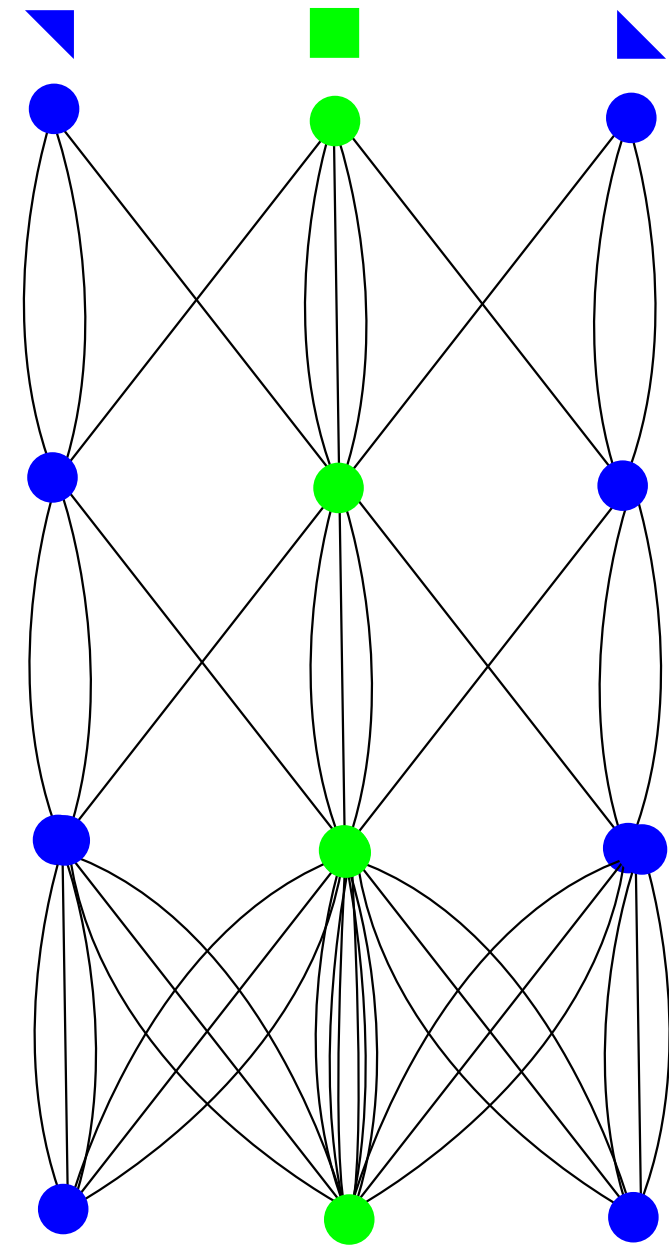
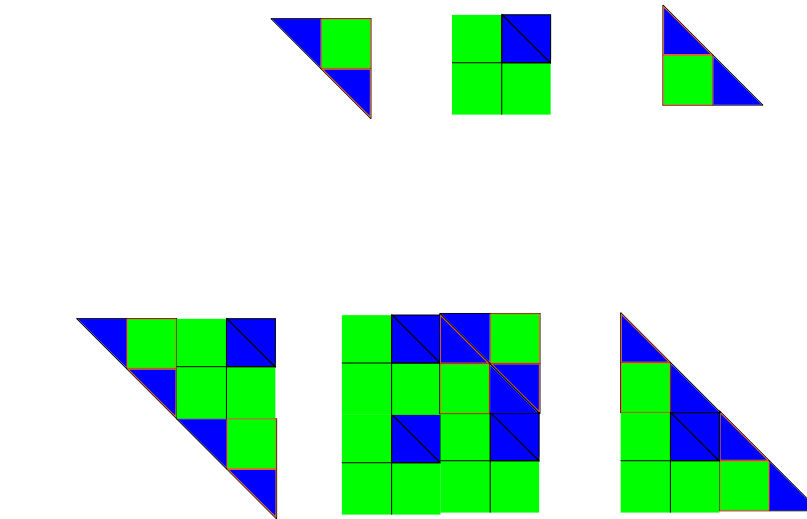
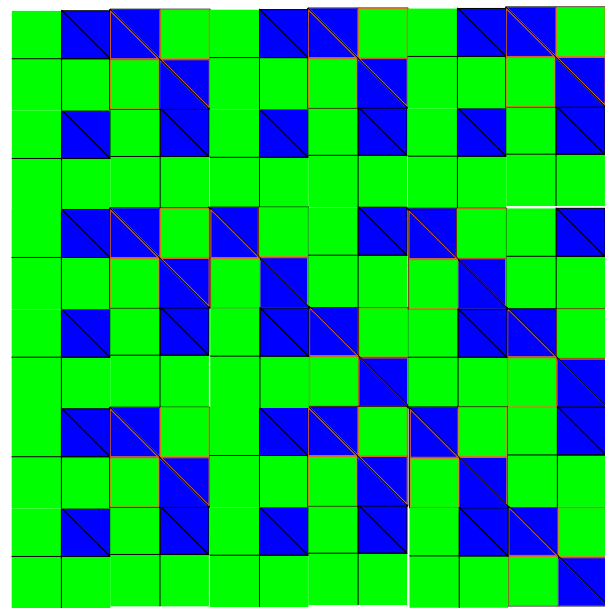
# SUBSTITUTION RULES



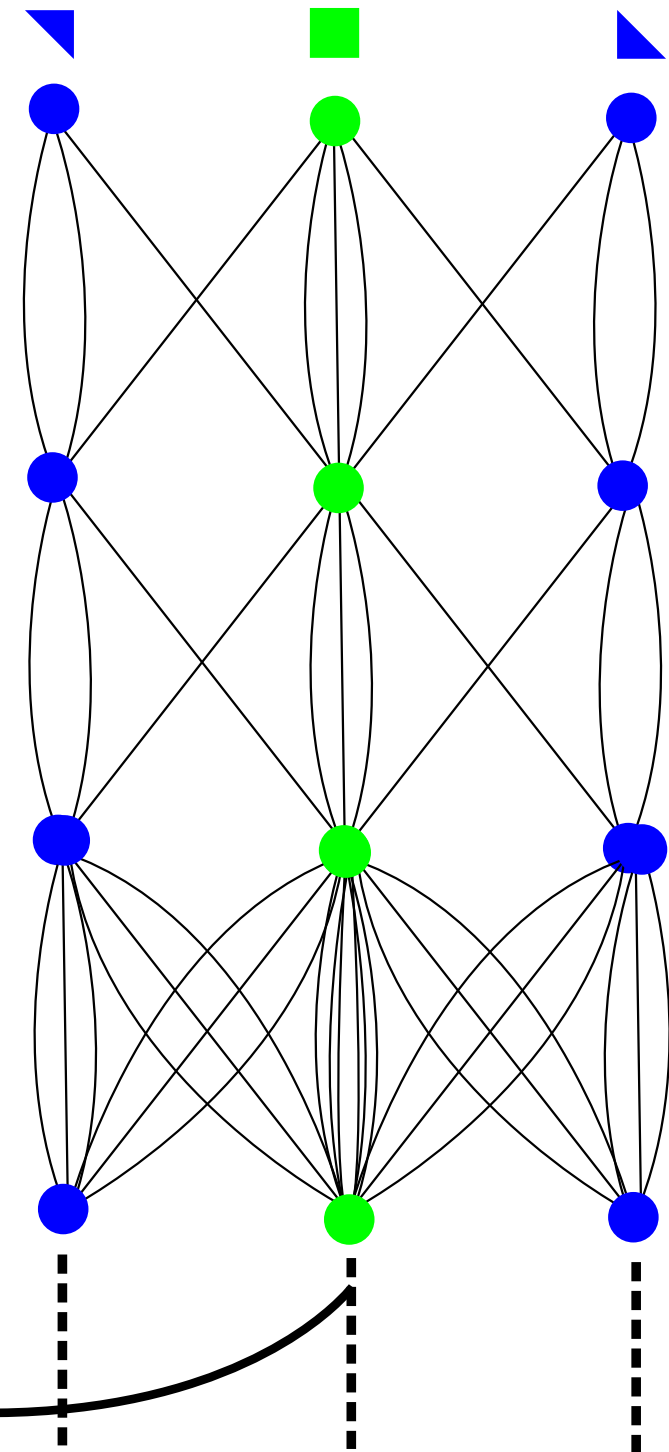
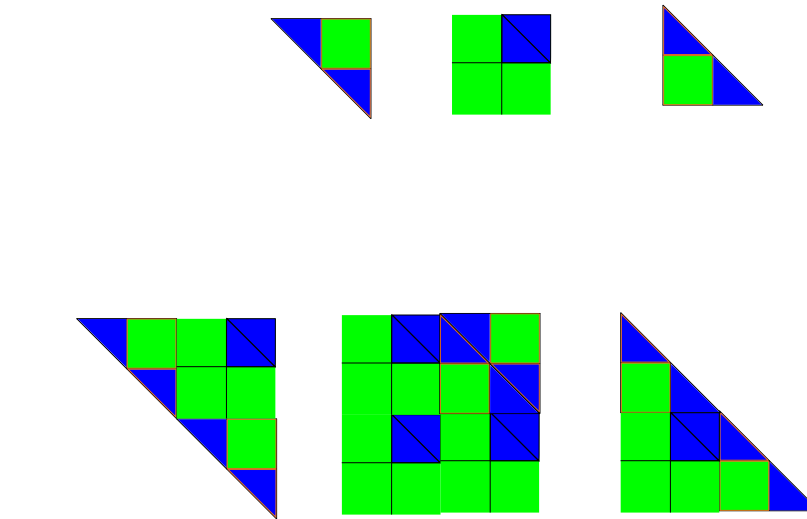
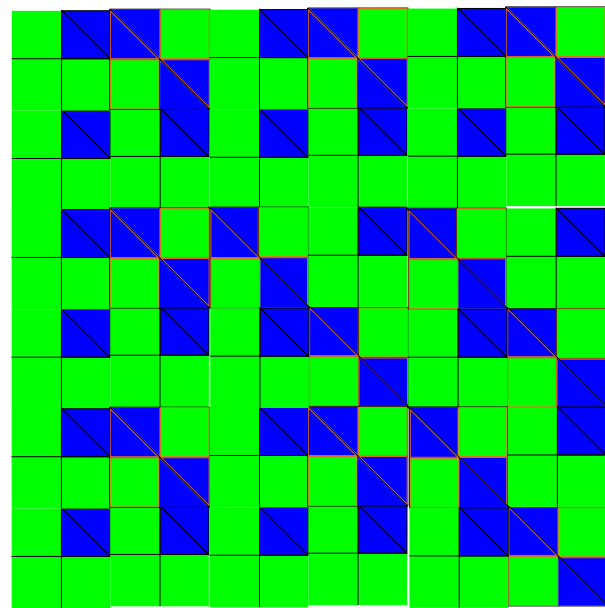
# SUBSTITUTION RULES



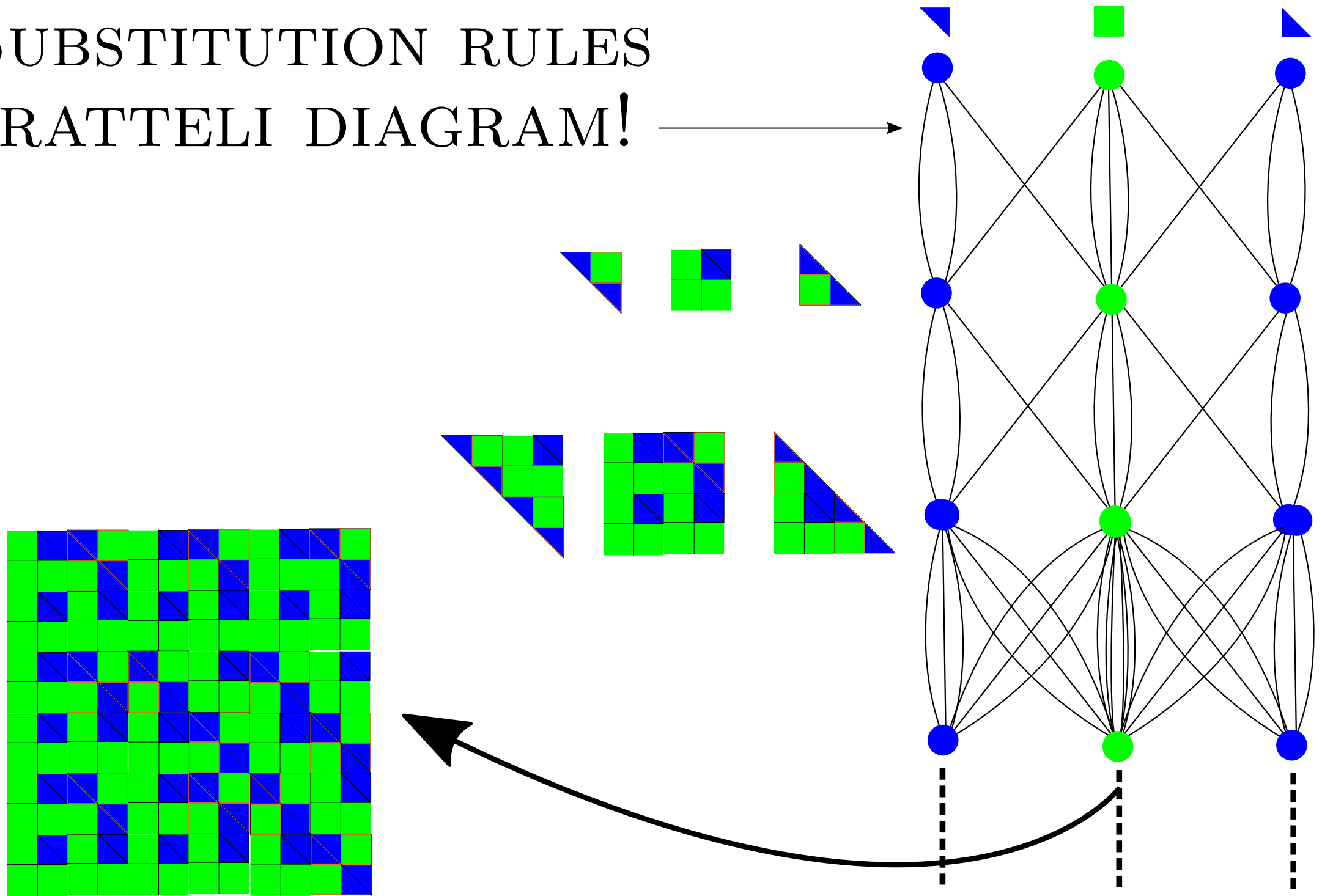
# SUBSTITUTION RULES



# SUBSTITUTION RULES



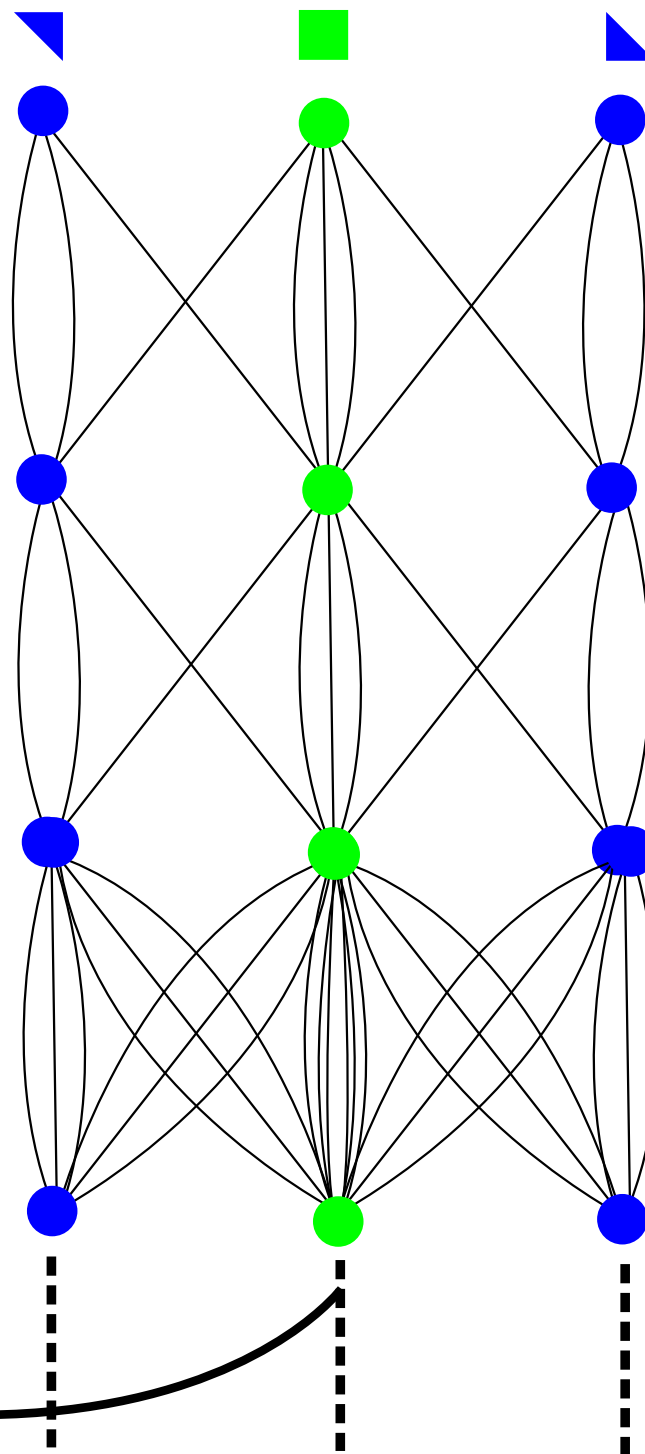
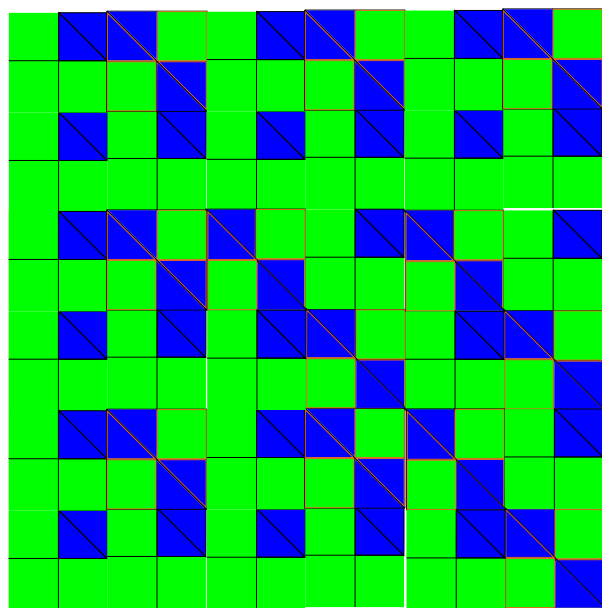
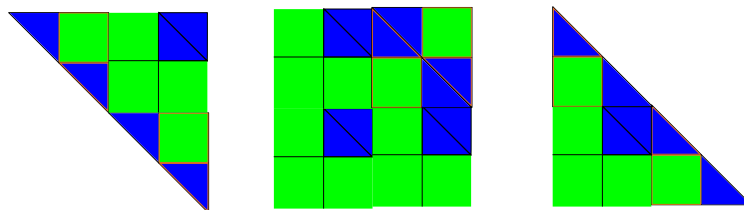
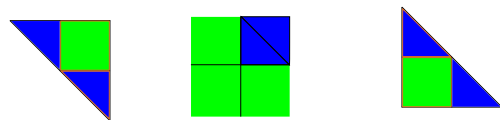
# SUBSTITUTION RULES BRATTELI DIAGRAM!





# SUBSTITUTION RULES BRATTELI DIAGRAM!

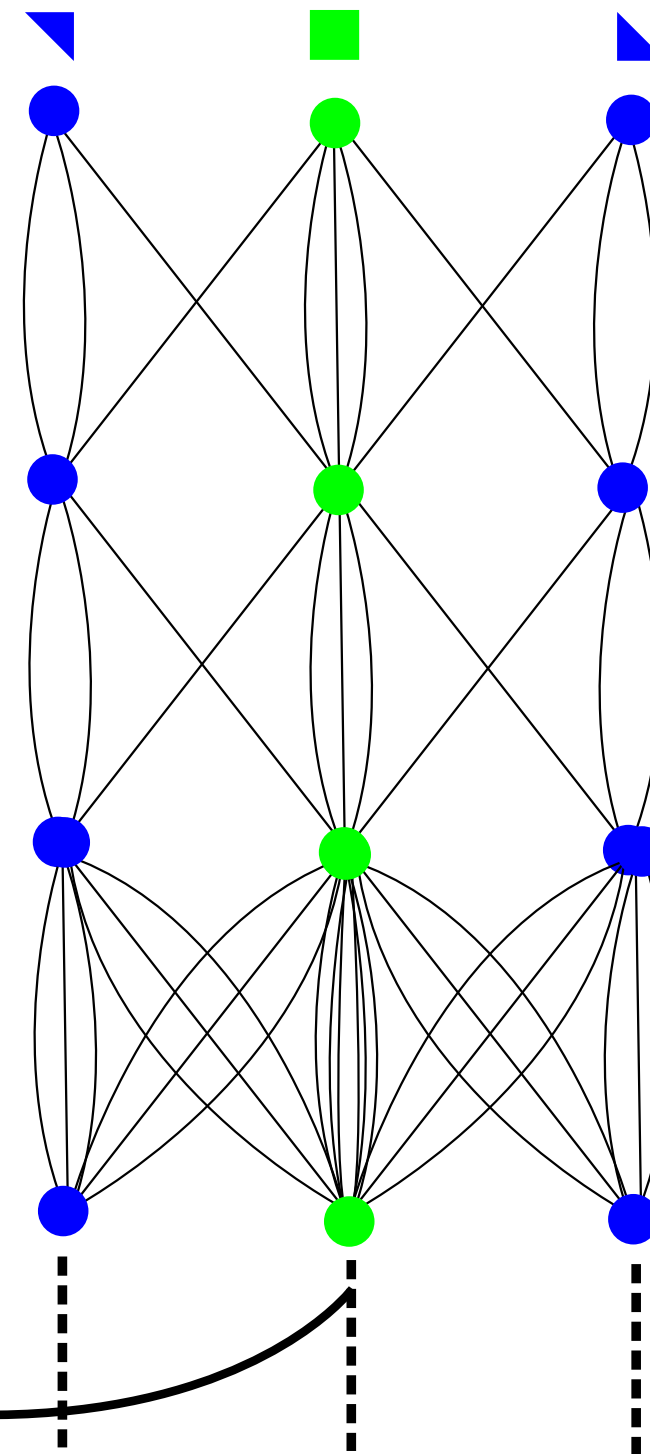
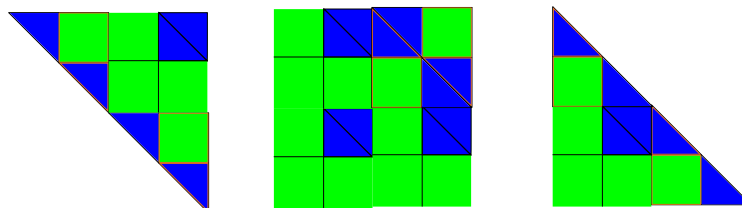
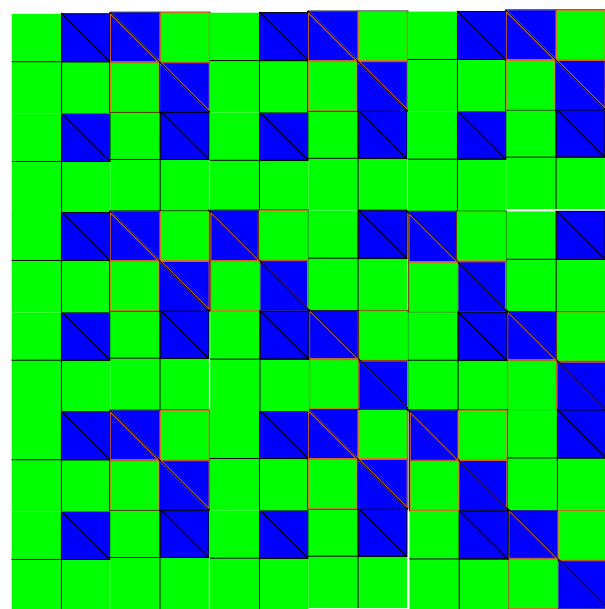
Vertices correspond to large patches of a tiling



# SUBSTITUTION RULES BRATTELI DIAGRAM!

Vertices correspond to large patches of a tiling

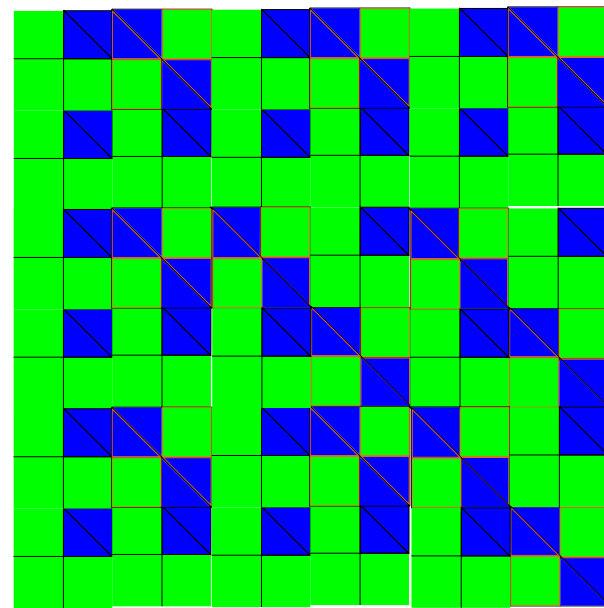
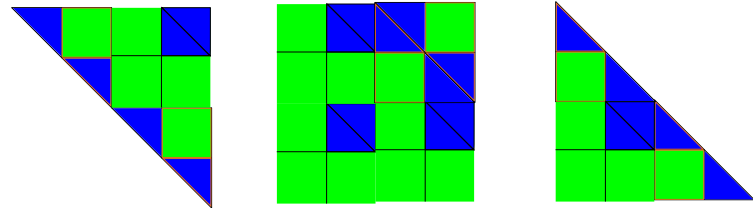
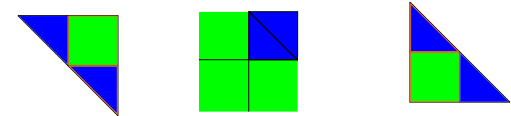
# of tiles in a patch corresponding to a vertex =  
# of paths which reach that vertex



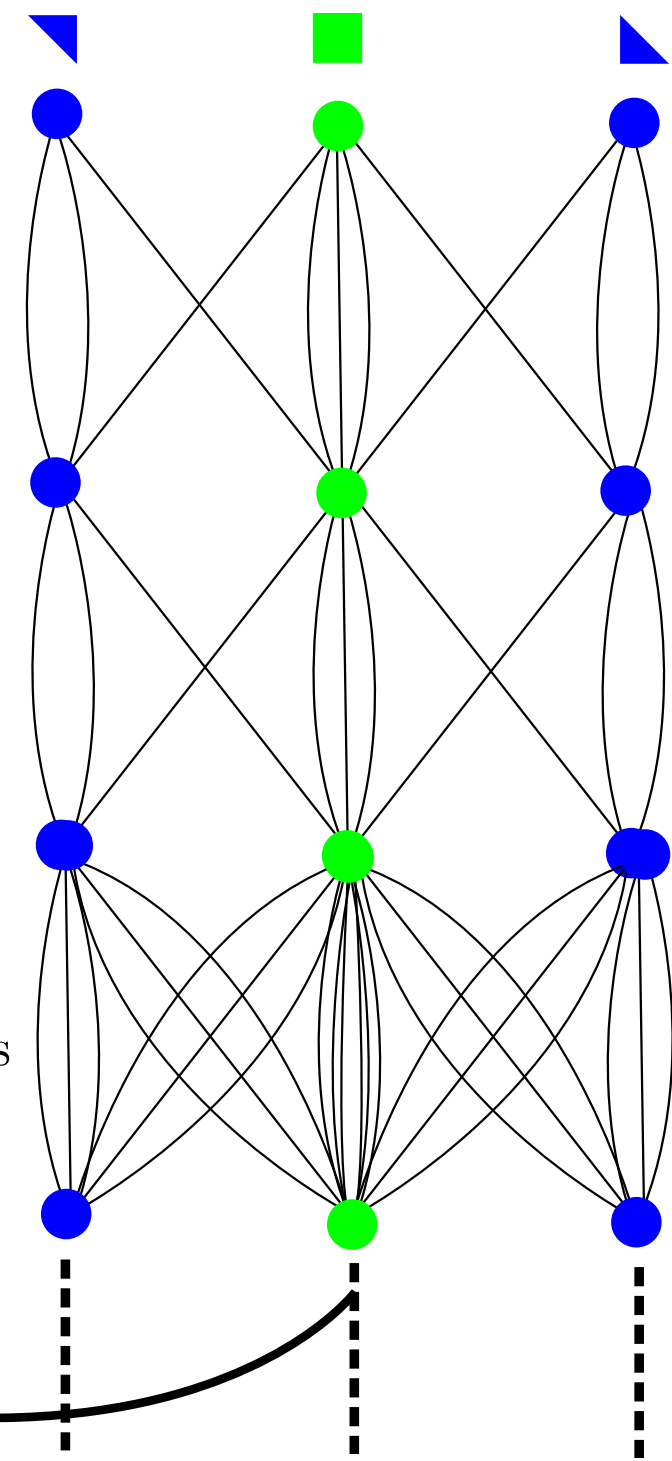
# SUBSTITUTION RULES BRATTELI DIAGRAM!

Vertices correspond to large patches of a tiling

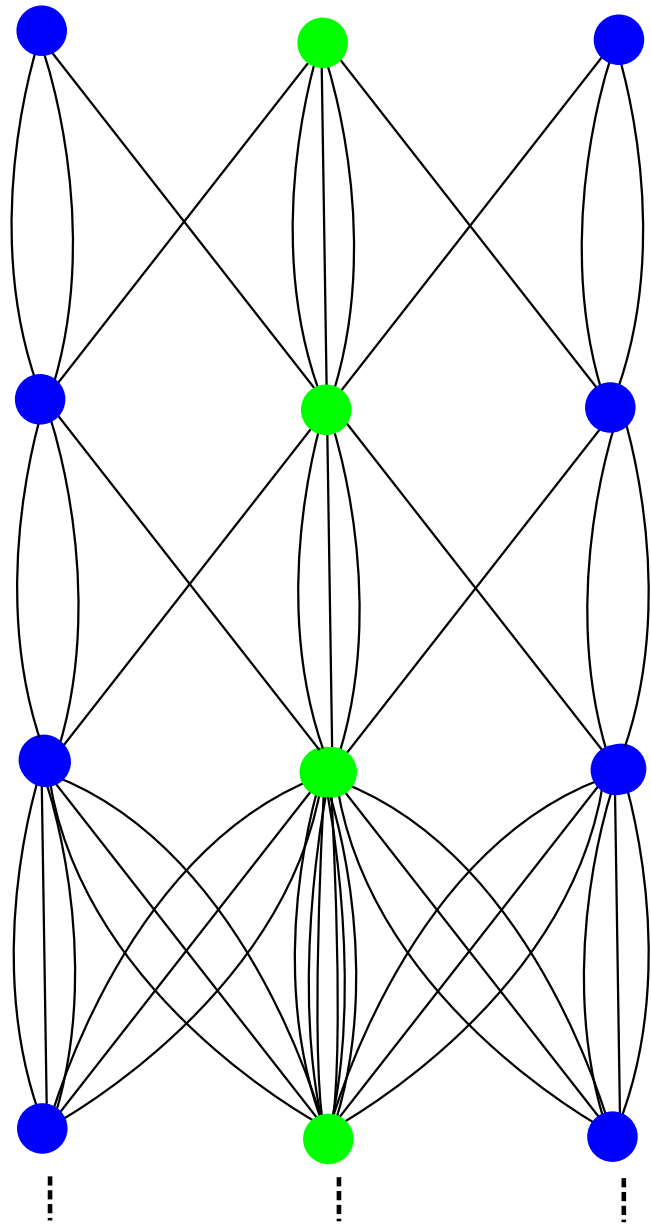
# of tiles in a patch corresponding to a vertex =  
# of paths which reach that vertex



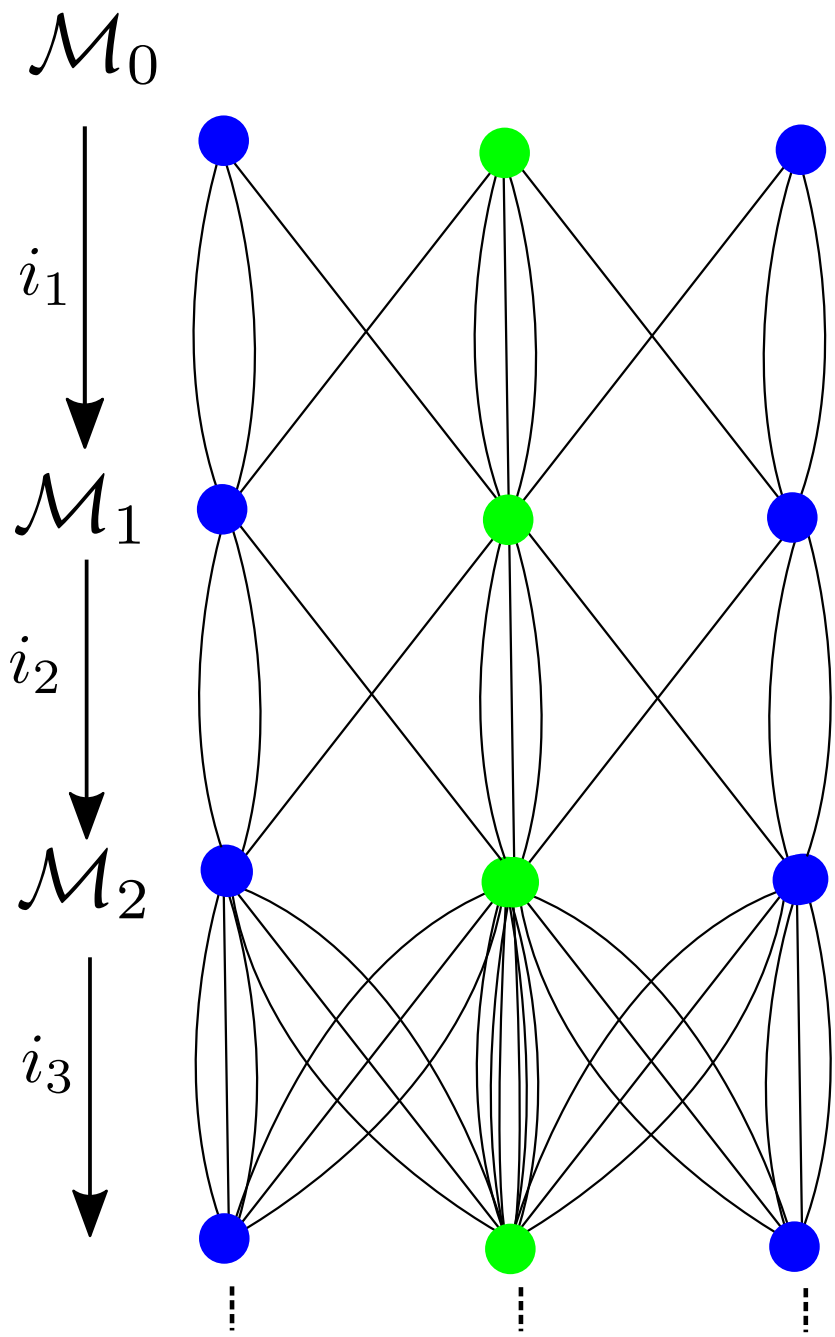
Tilings are obtained by taking limits of larger and larger patches.



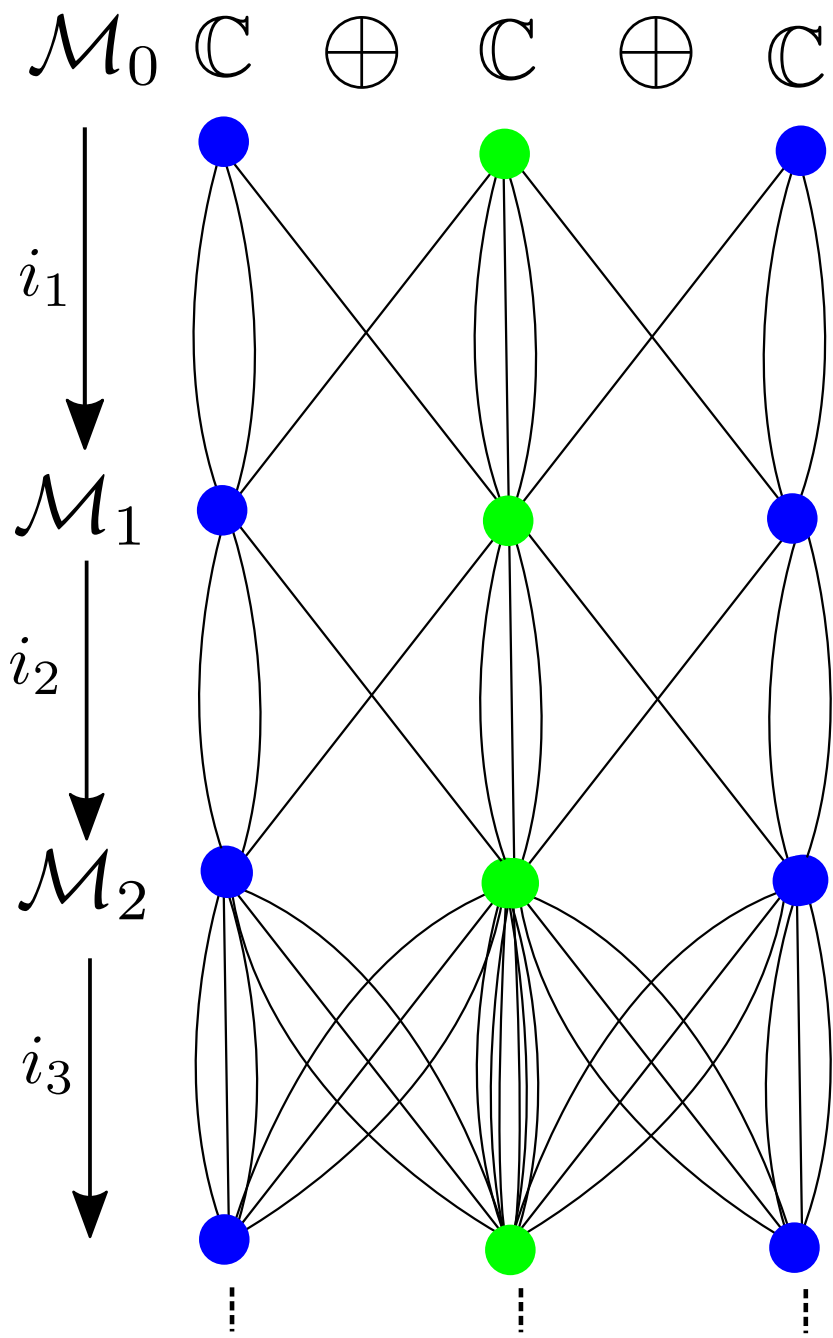
# BRATTELI DIAGRAM!



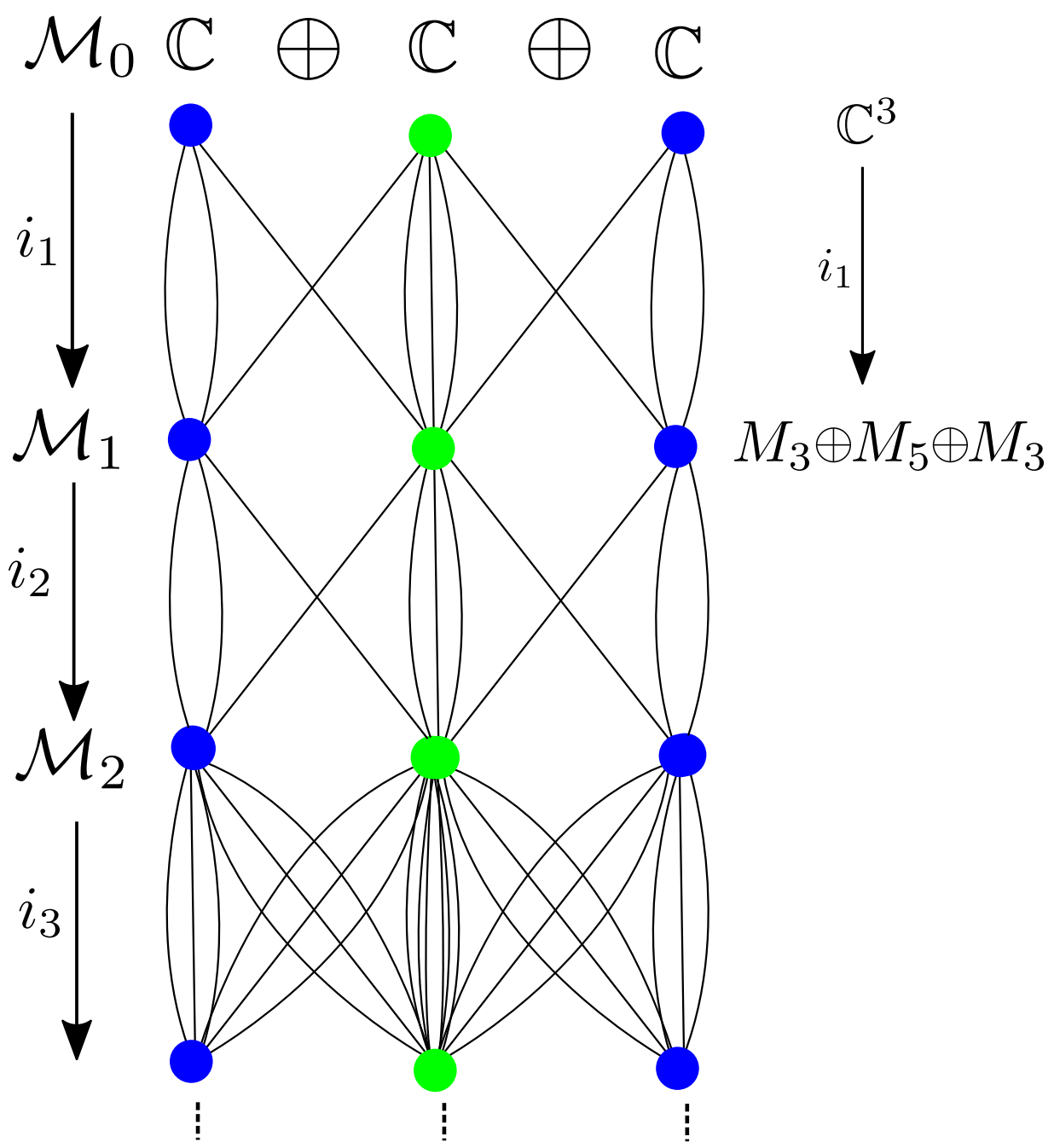
# BRATTELI DIAGRAM!



# BRATTELI DIAGRAM!

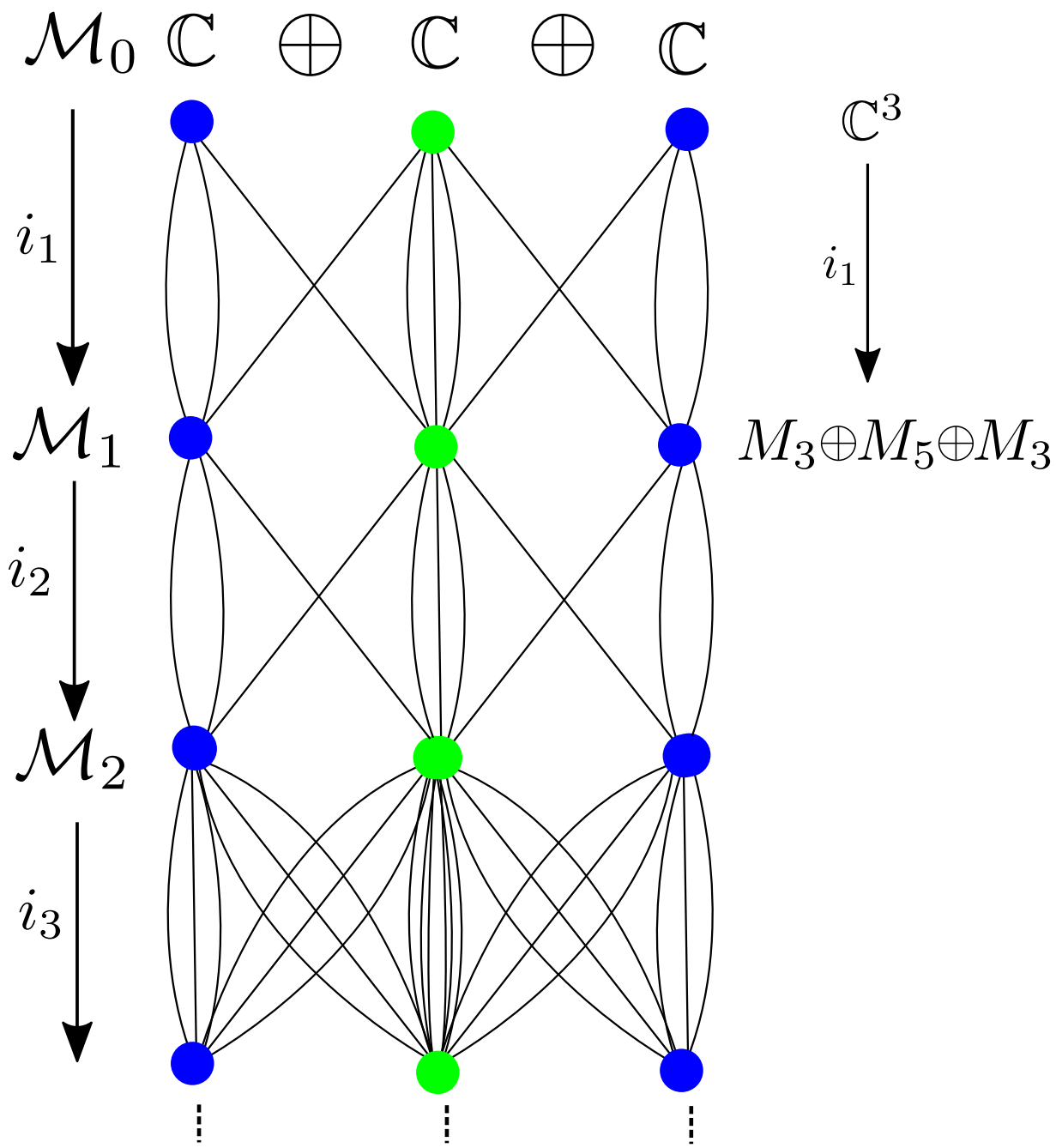


# BRATTELI DIAGRAM!



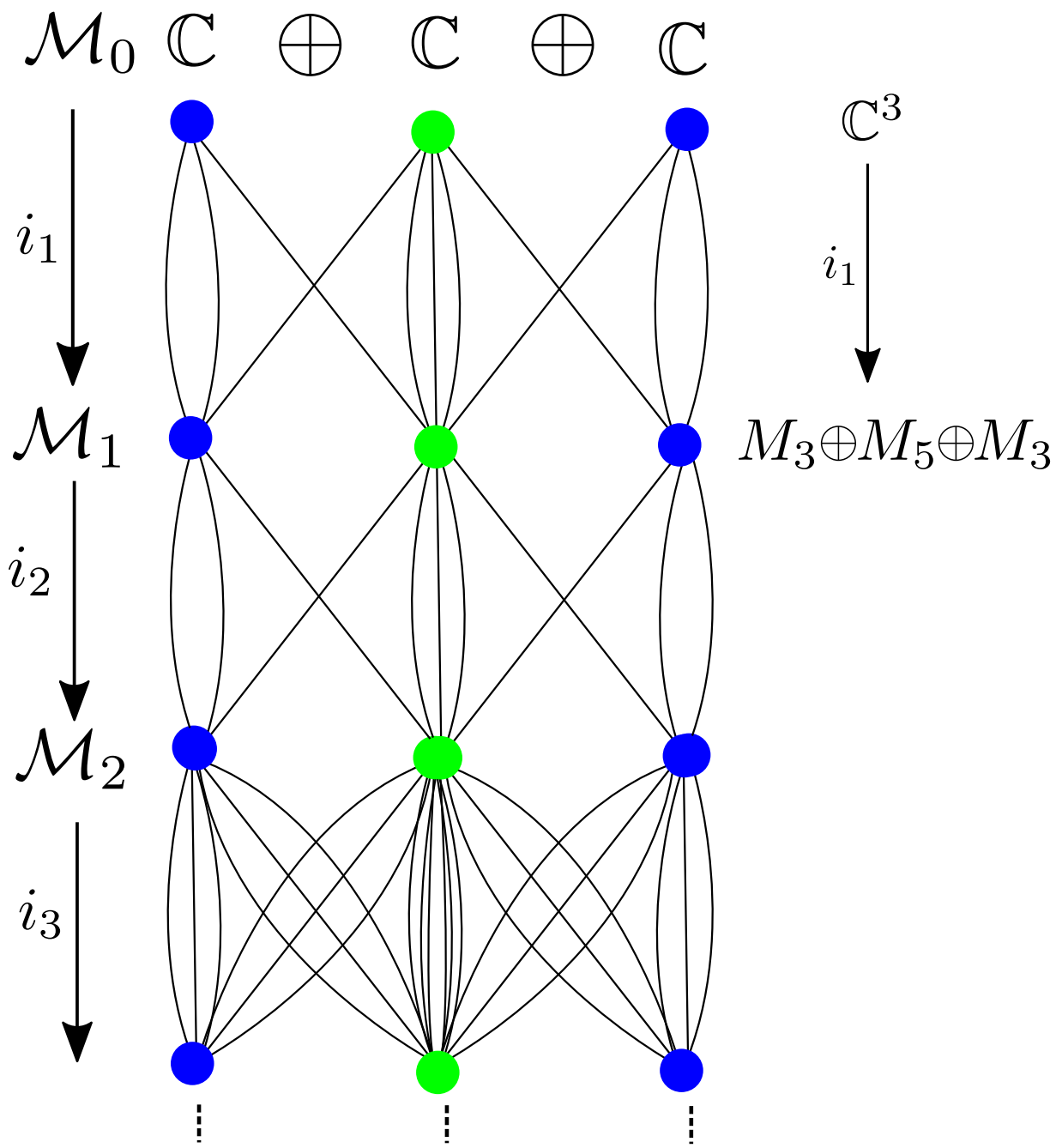
# BRATTELI DIAGRAM!

$$(a, b, c) \in \mathbb{C}^3$$





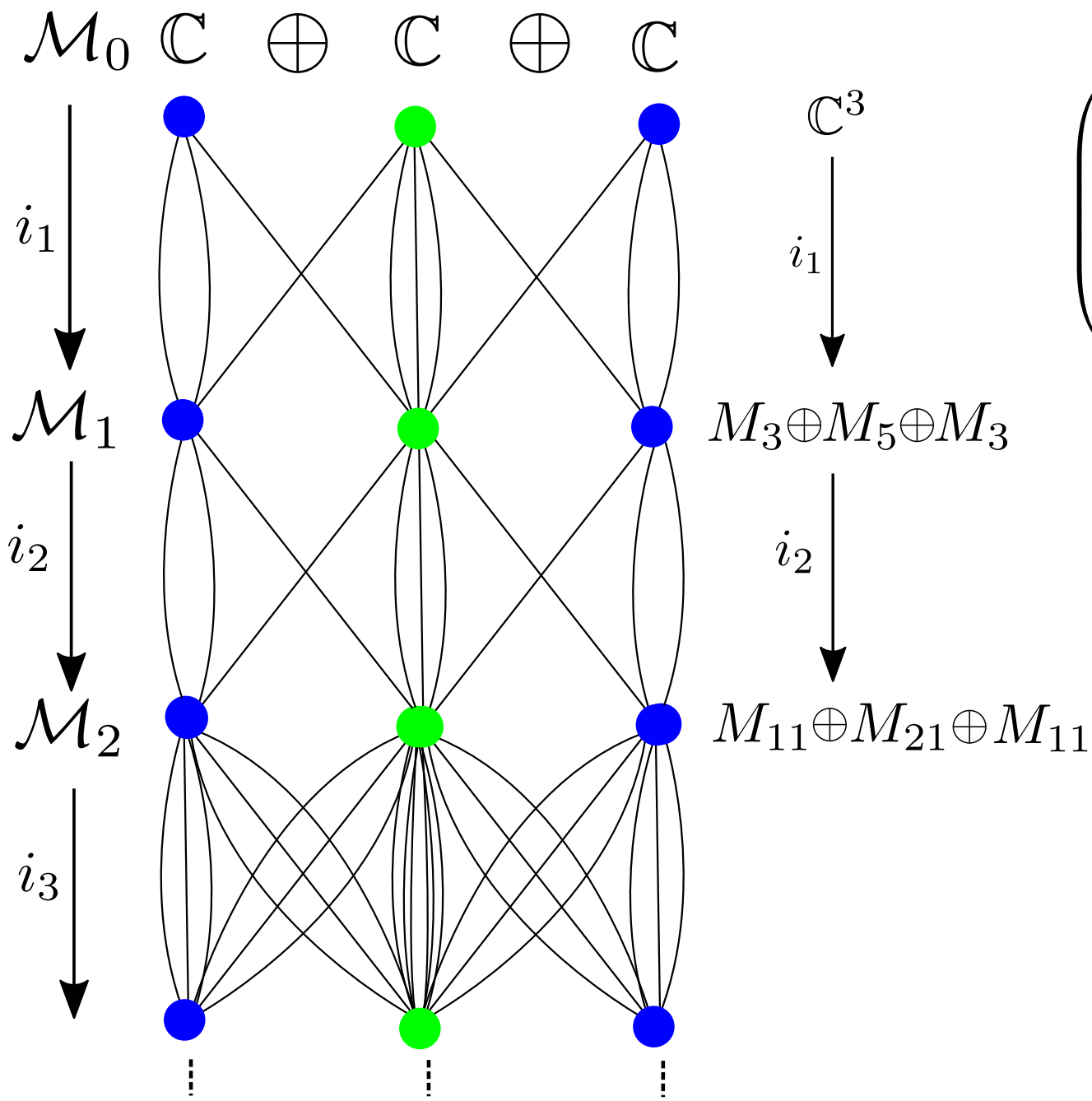
# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

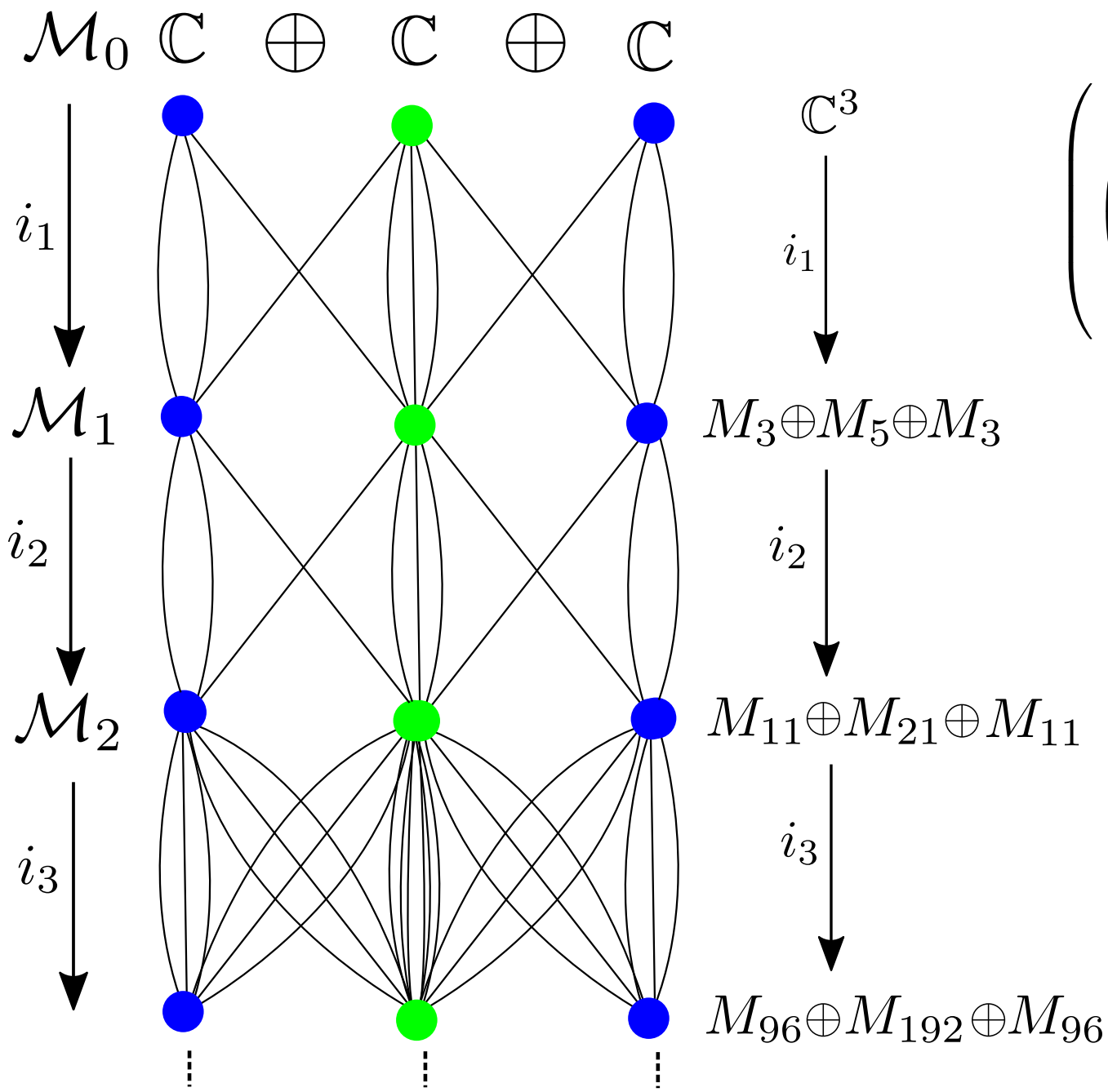
# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

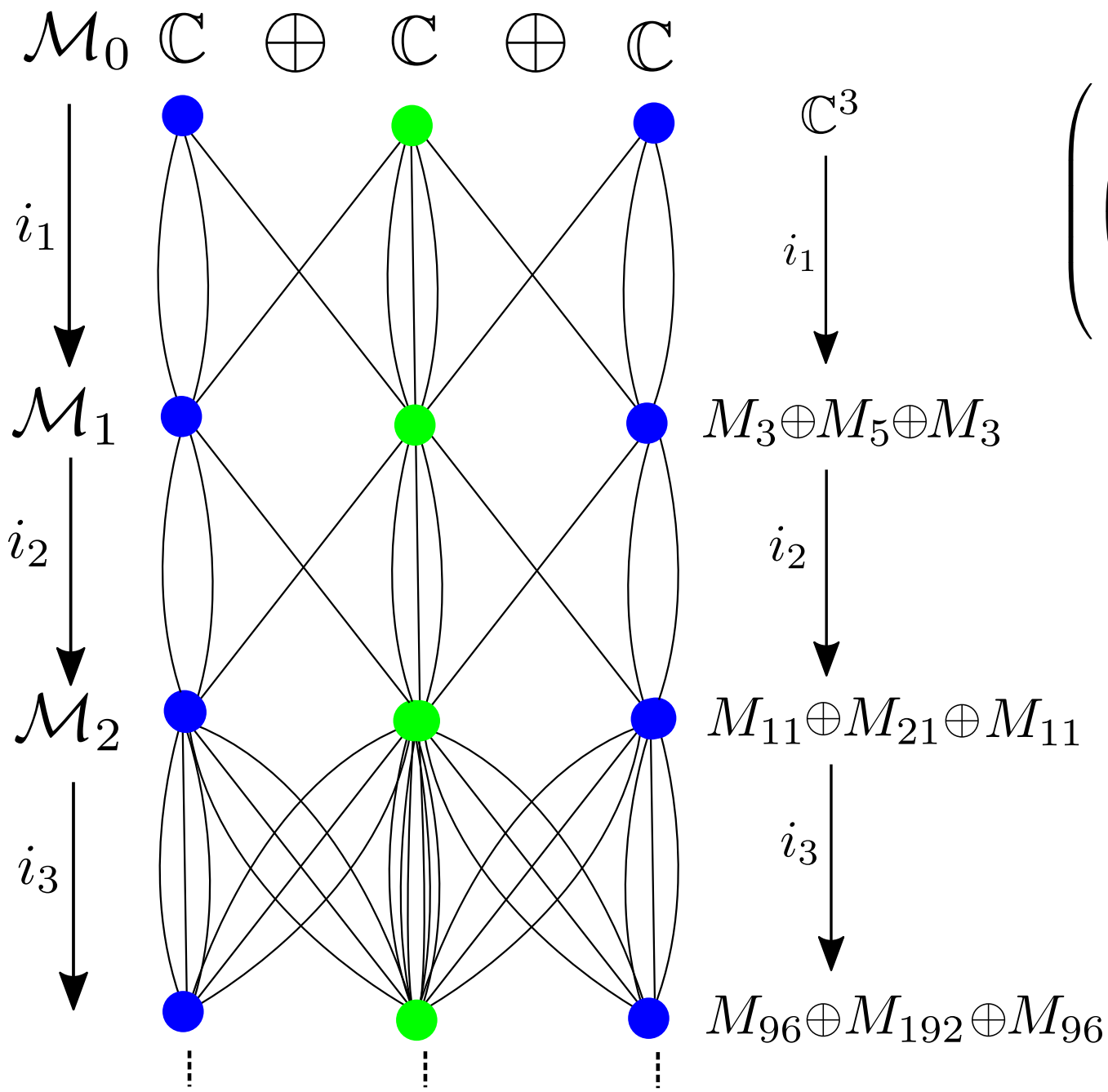
# BRATTELI DIAGRAM!



$(a, b, c) \in \mathbb{C}^3$

$$\begin{matrix}
 & & i_1 \downarrow & & \\
 & & \downarrow & & \\
 \left( \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{pmatrix} \right), & & \left( \begin{pmatrix} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{pmatrix} \right), & & \left( \begin{pmatrix} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{pmatrix} \right)
 \end{matrix}$$

# BRATTELI DIAGRAM!

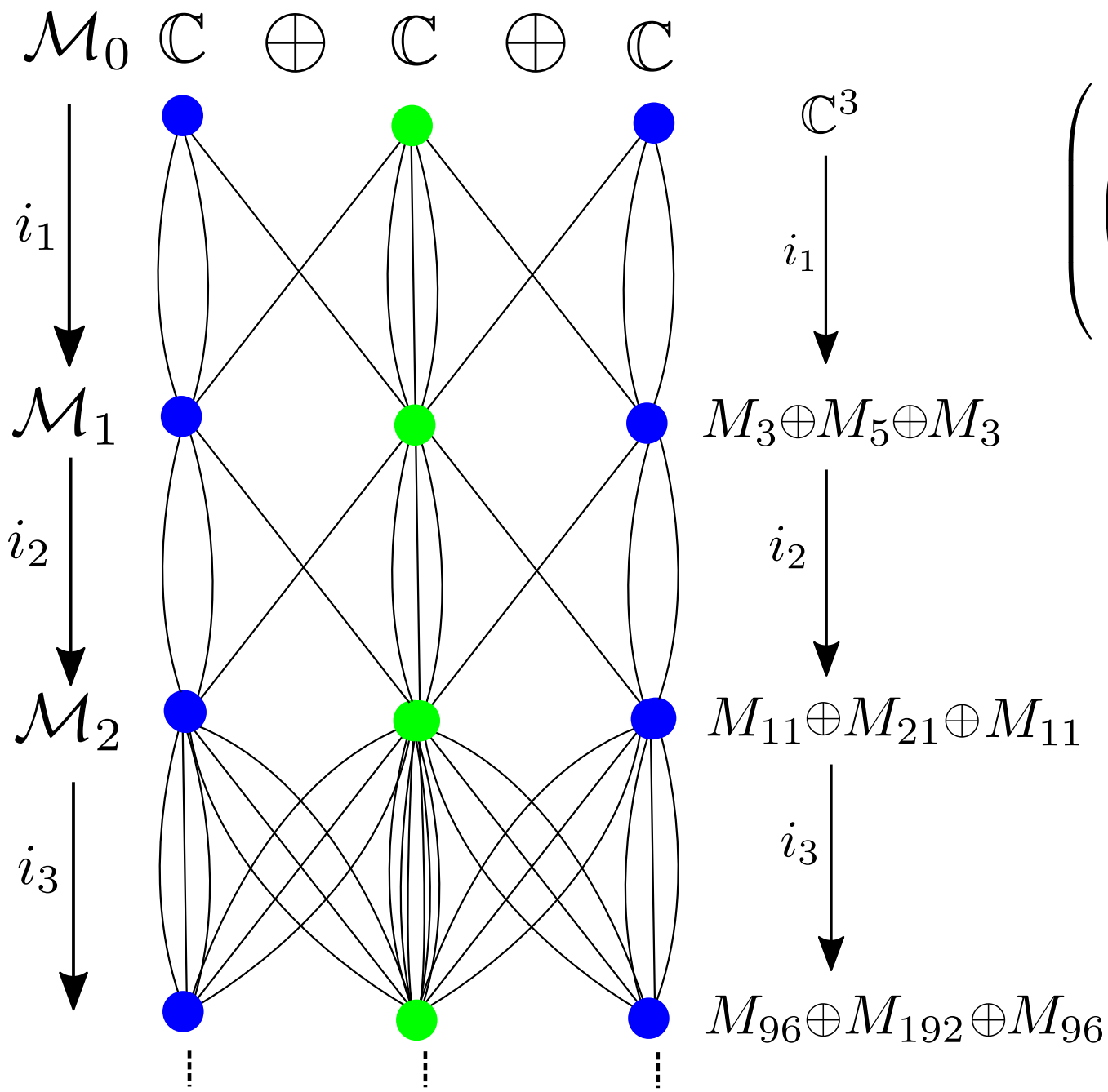


$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

$$LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

# BRATTELI DIAGRAM!

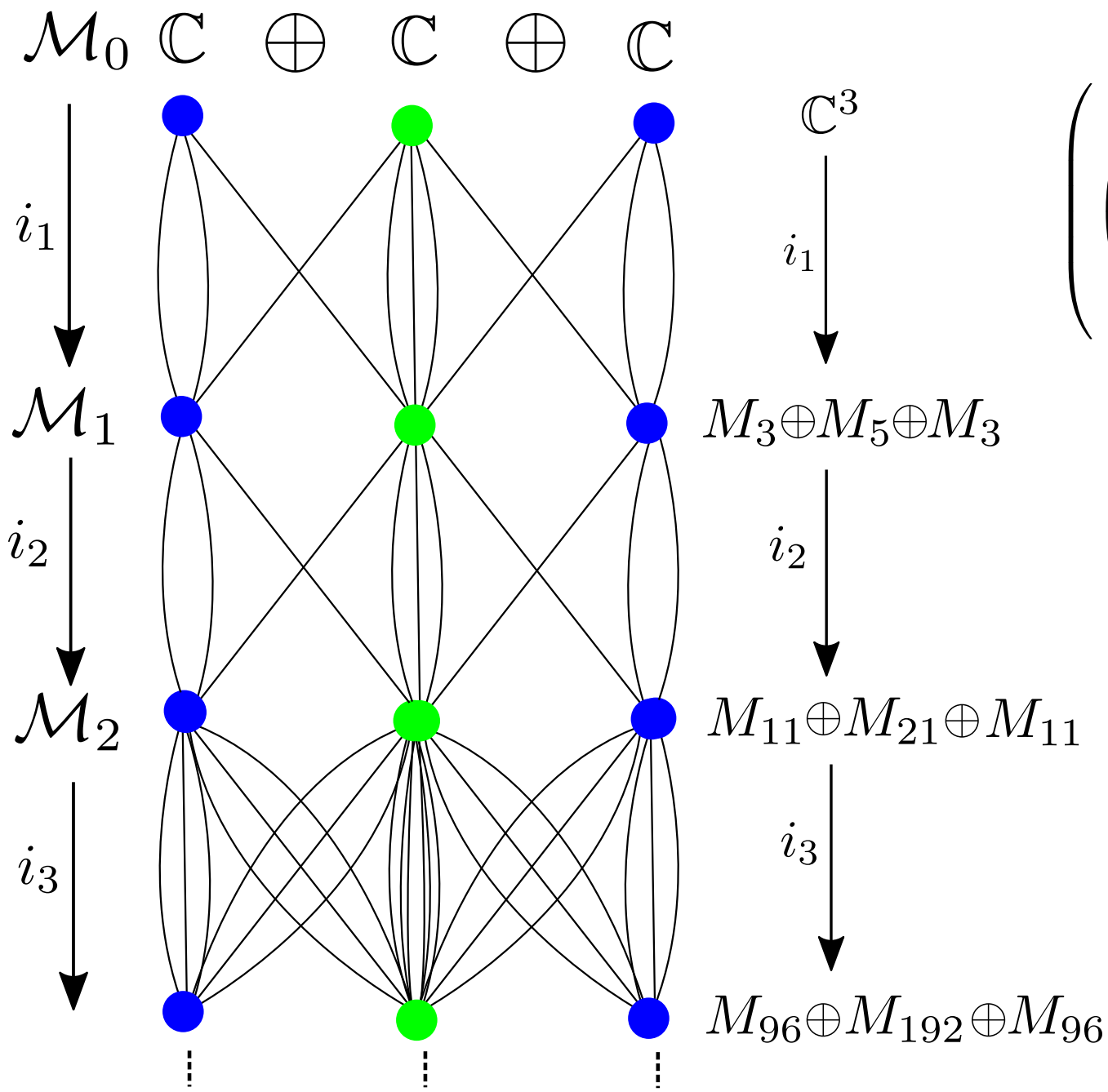


$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

$$\text{Locally finite algebra } LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

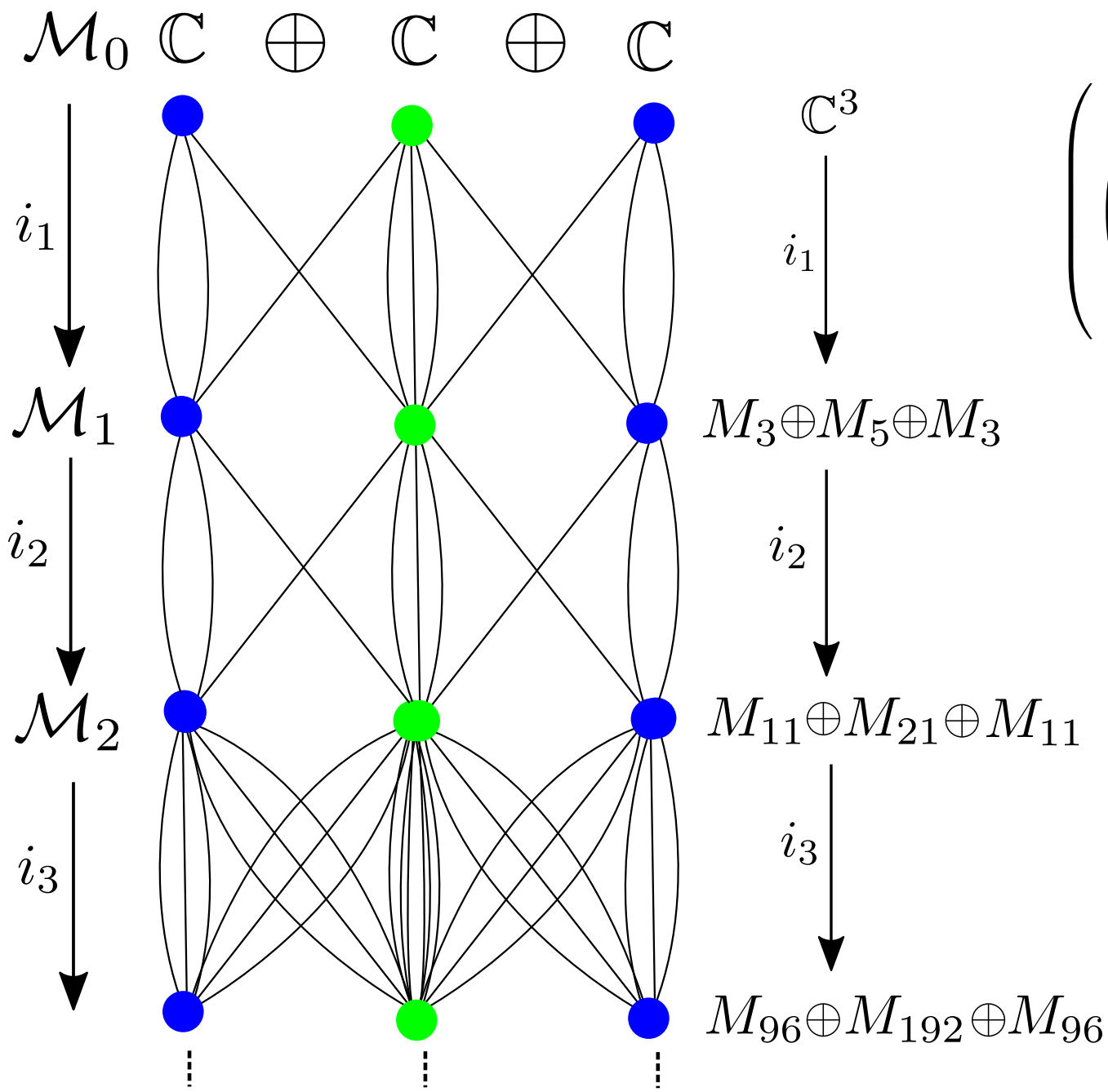
$$i_1 \downarrow \left( \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{pmatrix}, \begin{pmatrix} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{pmatrix}, \begin{pmatrix} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{pmatrix} \right)$$

$$LF(B) = \lim_{\longrightarrow} (\mathcal{M}_k, i_k)$$

Locally finite algebra

If  $\mathcal{M}_k = \bigoplus_{i=1}^{\ell} M_{n_i}$  then  $\mathcal{M}_k^* = \text{Tr}(\mathcal{M}_k) \cong \mathbb{C}^{\ell}$

# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

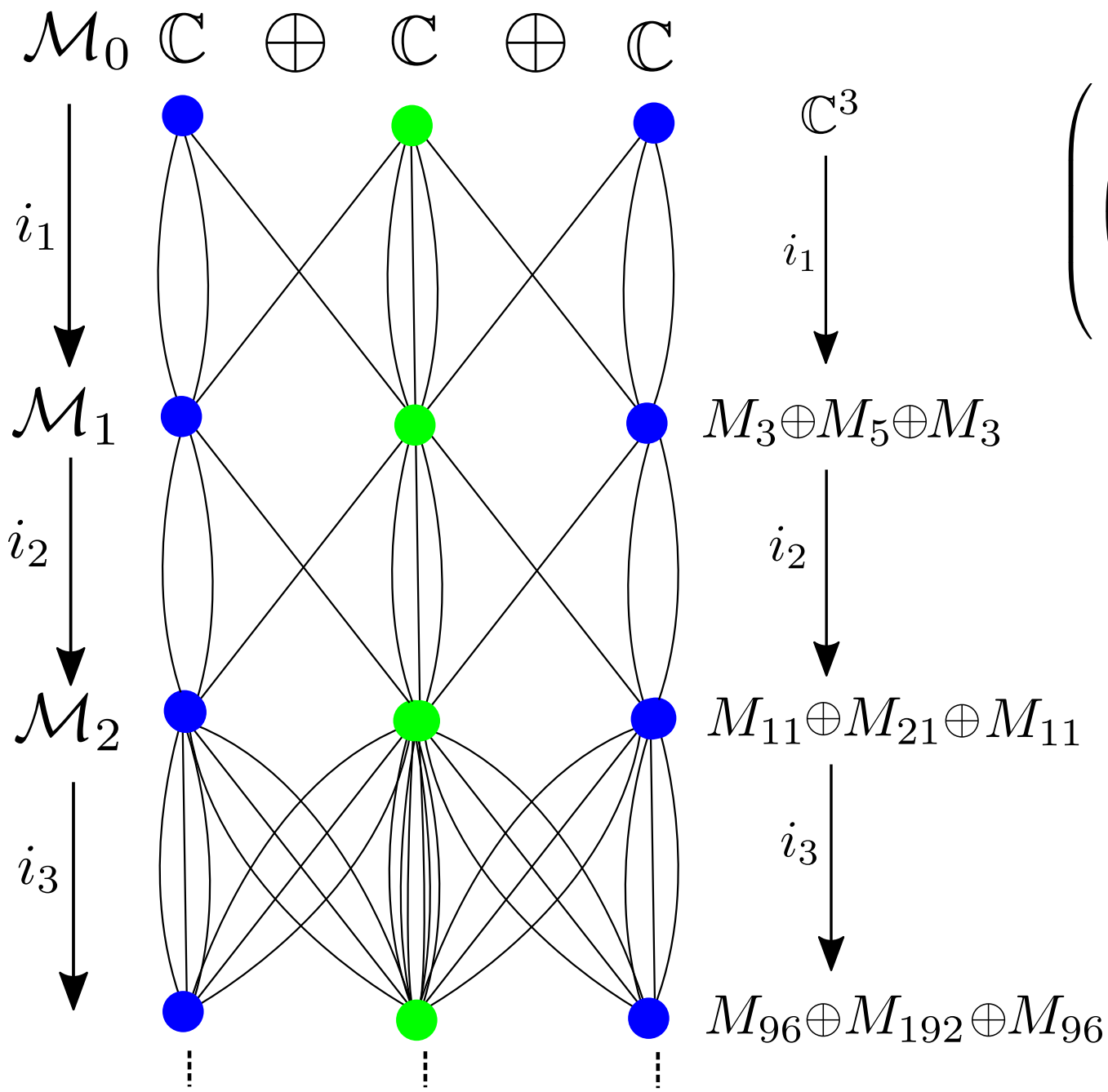
$$LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

Locally finite algebra

$$\text{If } \mathcal{M}_k = \bigoplus_{i=1}^{\ell} M_{n_i} \text{ then } \mathcal{M}_k^* = \text{Tr}(\mathcal{M}_k) \cong \mathbb{C}^{\ell}$$

Trace space

# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$\begin{array}{c}
 i_1 \downarrow \\
 \left( \begin{array}{c} \left( \begin{array}{ccc} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{array} \right), \left( \begin{array}{ccccc} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{array} \right), \left( \begin{array}{ccc} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{array} \right) \end{array} \right)
 \end{array}$$

$$LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

Locally finite algebra

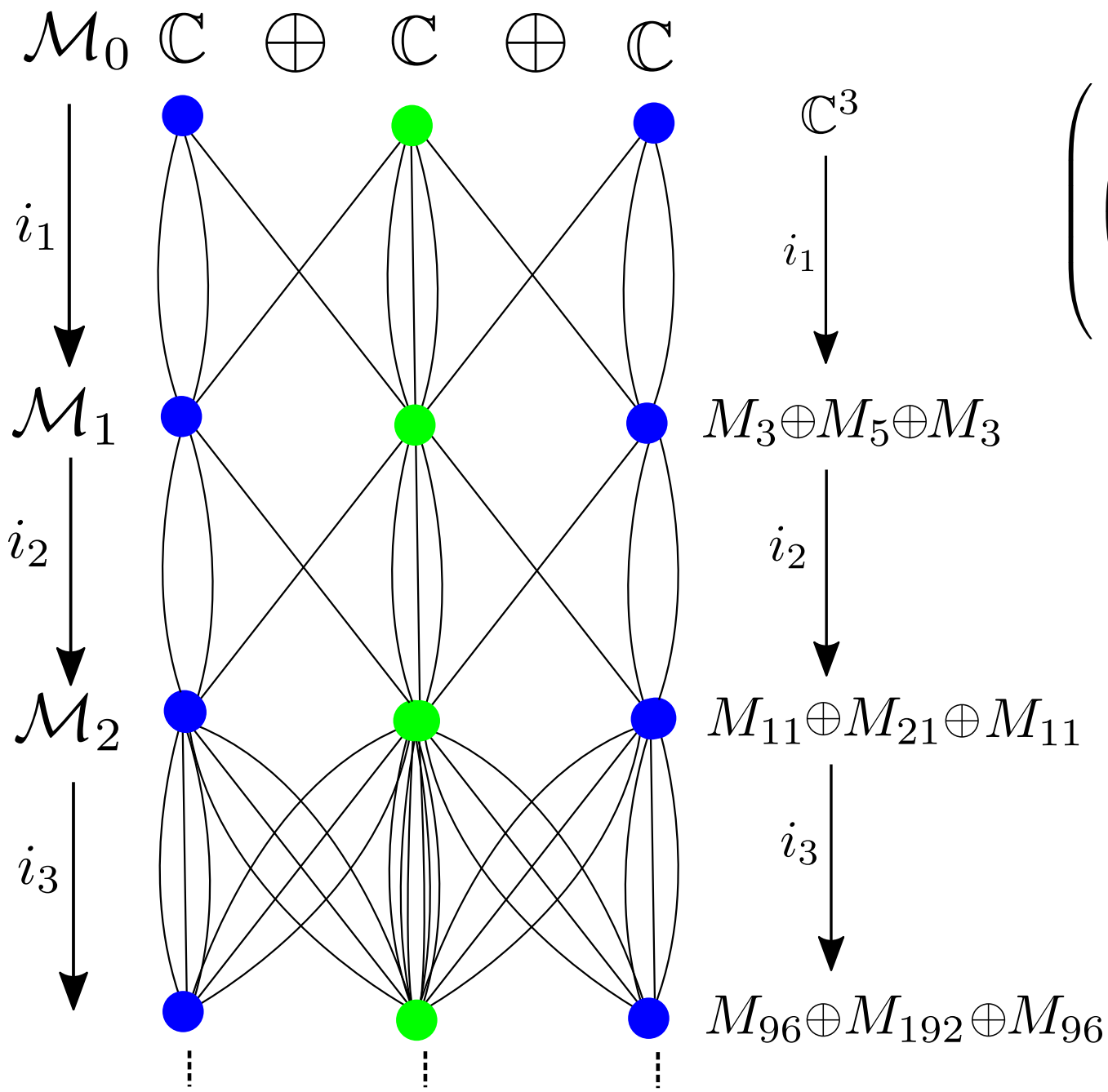
$$\text{If } \mathcal{M}_k = \bigoplus_{i=1}^{\ell} M_{n_i} \text{ then } \mathcal{M}_k^* = \text{Tr}(\mathcal{M}_k) \cong \mathbb{C}^{\ell}$$

Trace space

$$LF(B)^* = \text{Tr}(B) = \varprojlim (\text{Tr}(\mathcal{M}_k), i_k^*)$$



# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$i_1 \downarrow \left( \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{pmatrix}, \begin{pmatrix} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{pmatrix}, \begin{pmatrix} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{pmatrix} \right)$$

$$LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

Locally finite algebra

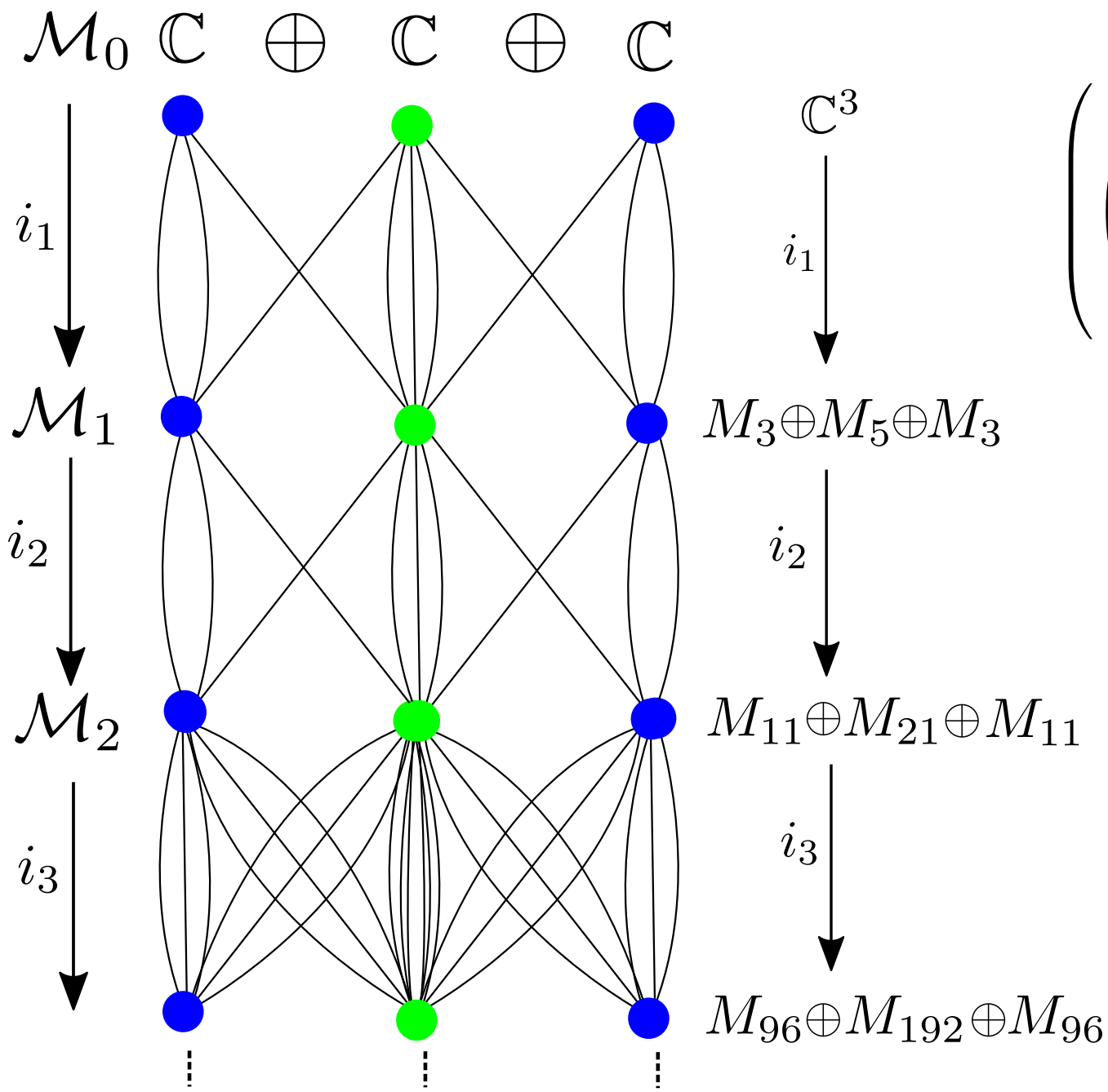
$$\text{If } \mathcal{M}_k = \bigoplus_{i=1}^{\ell} M_{n_i} \text{ then } \mathcal{M}_k^* = \text{Tr}(\mathcal{M}_k) \cong \mathbb{C}^{\ell}$$

Trace space

$$LF(B)^* = \text{Tr}(B) = \varprojlim (\text{Tr}(\mathcal{M}_k), i_k^*)$$

( =  $K_0(AF(B))^*$  )

# BRATTELI DIAGRAM!



$$(a, b, c) \in \mathbb{C}^3$$

$$i_1 \downarrow \left( \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & a \end{pmatrix}, \begin{pmatrix} c & 0 & 0 & 0 & 0 \\ 0 & b & 0 & 0 & 0 \\ 0 & 0 & a & 0 & 0 \\ 0 & 0 & 0 & b & 0 \\ 0 & 0 & 0 & 0 & b \end{pmatrix}, \begin{pmatrix} b & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & c \end{pmatrix} \right)$$

$$LF(B) = \varinjlim (\mathcal{M}_k, i_k)$$

Locally finite algebra

$$\text{If } \mathcal{M}_k = \bigoplus_{i=1}^{\ell} M_{n_i} \text{ then } \mathcal{M}_k^* = \text{Tr}(\mathcal{M}_k) \cong \mathbb{C}^{\ell}$$

Trace space

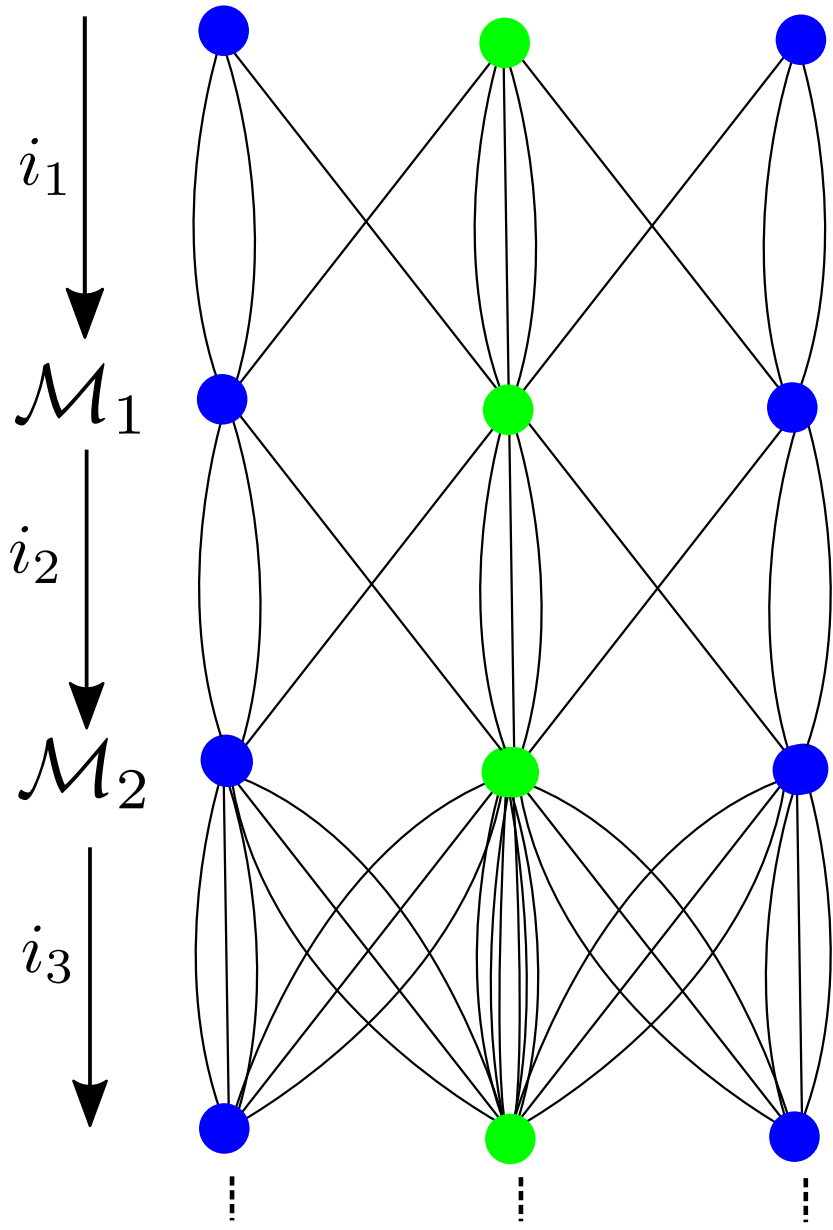
$$LF(B)^* = \text{Tr}(B) = \varprojlim (\text{Tr}(\mathcal{M}_k), i_k^*)$$

( =  $K_0(AF(B))^*$  )

The maps  $i_k^*$  are given by the adjacency (i.e. substitution) matrix

# BRATTELI DIAGRAM!

$\mathcal{M}_0 \quad \mathbb{C} \quad \oplus \quad \mathbb{C} \quad \oplus \quad \mathbb{C}$

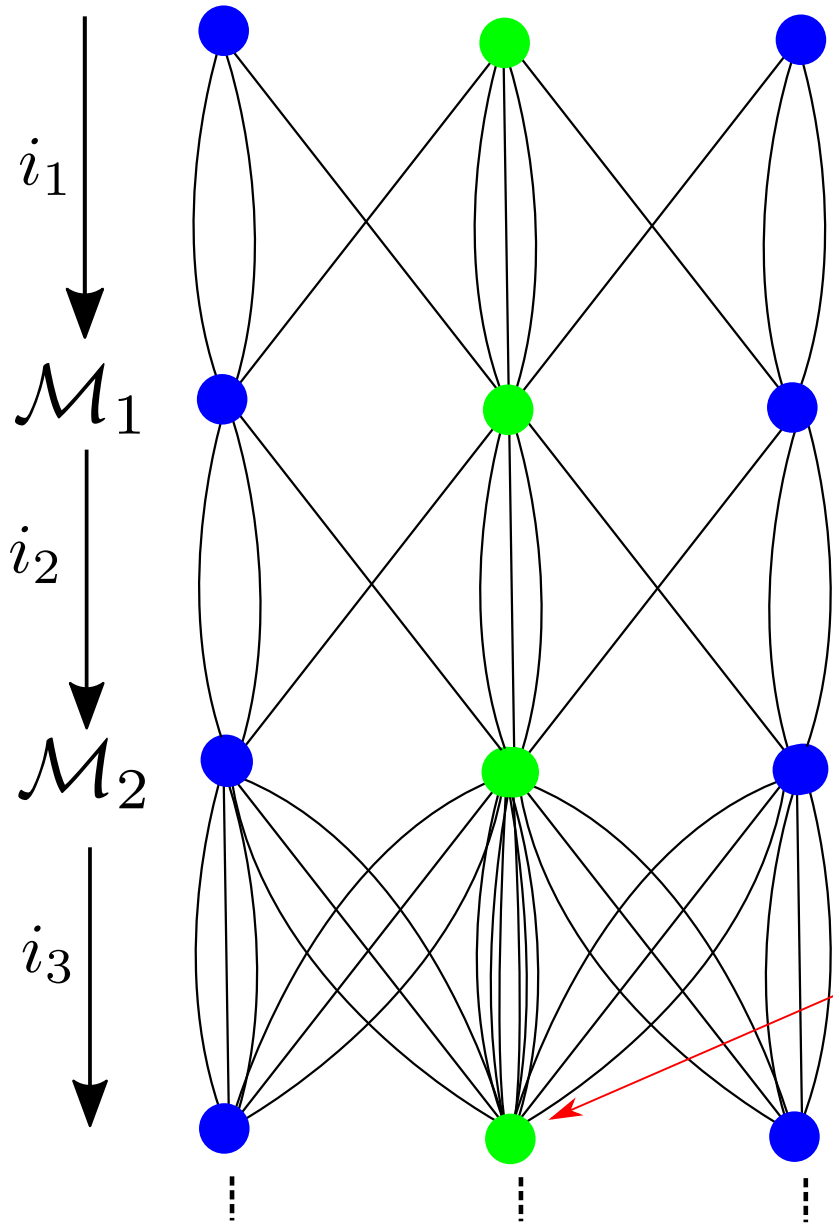


$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$

$$\left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix} \right)$$

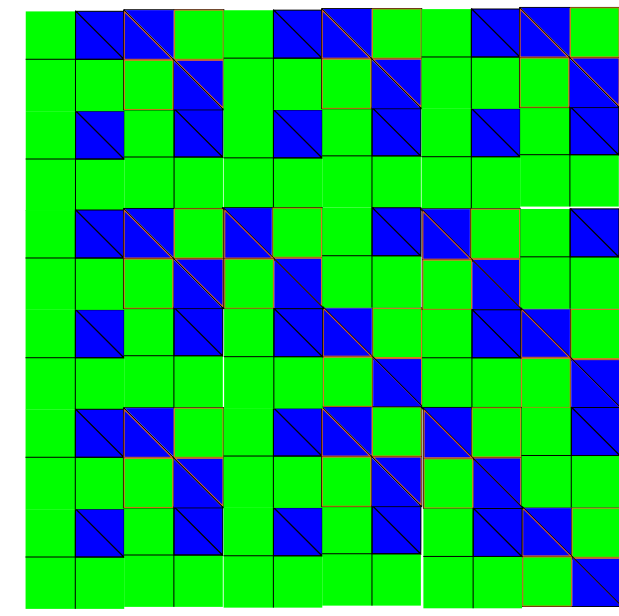
# BRATTELI DIAGRAM!

$\mathcal{M}_0 \quad \mathbb{C} \quad \oplus \quad \mathbb{C} \quad \oplus \quad \mathbb{C}$



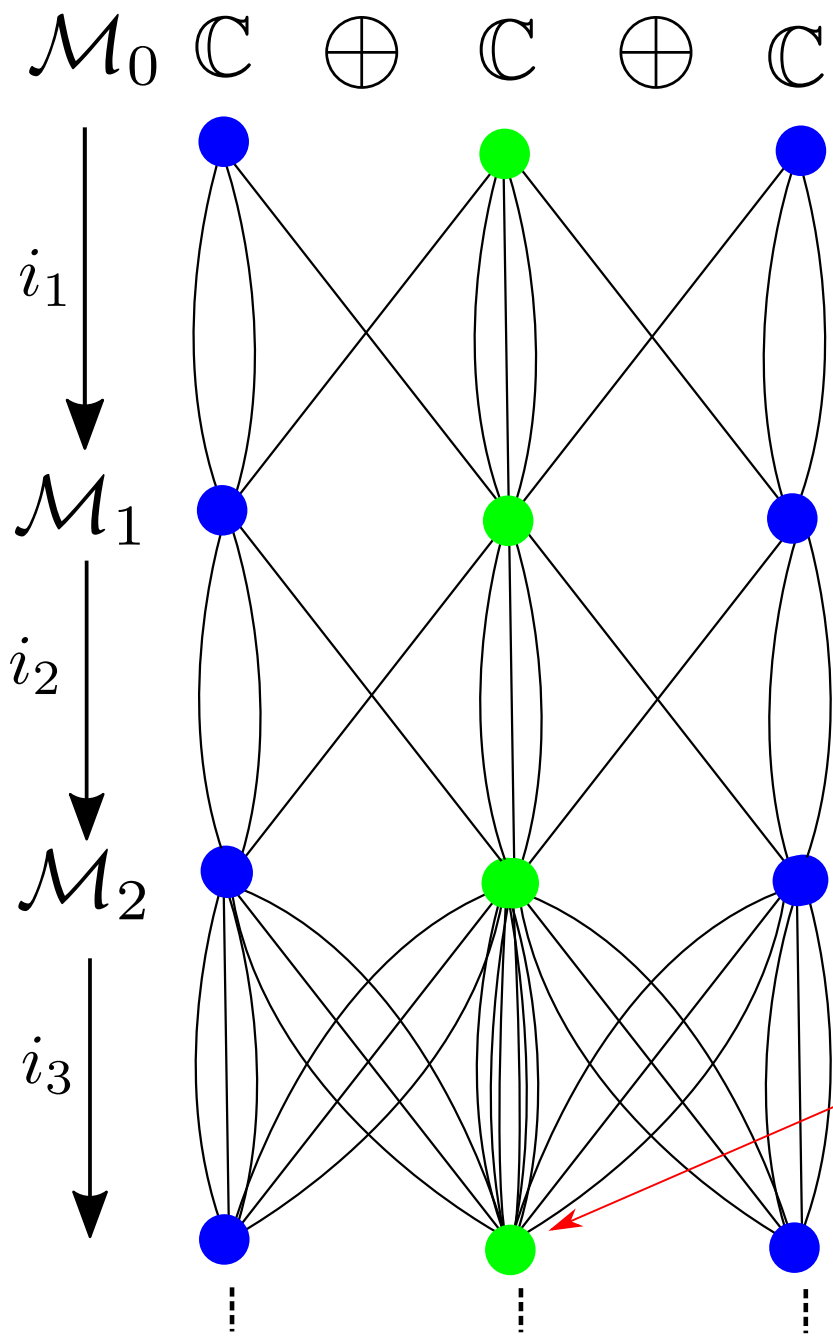
$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$

$$\left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix} \right)$$



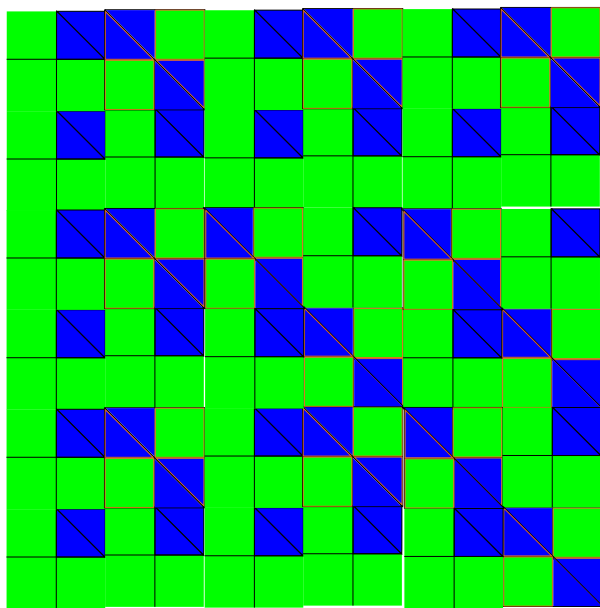
# BRATTELI DIAGRAM!

$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$



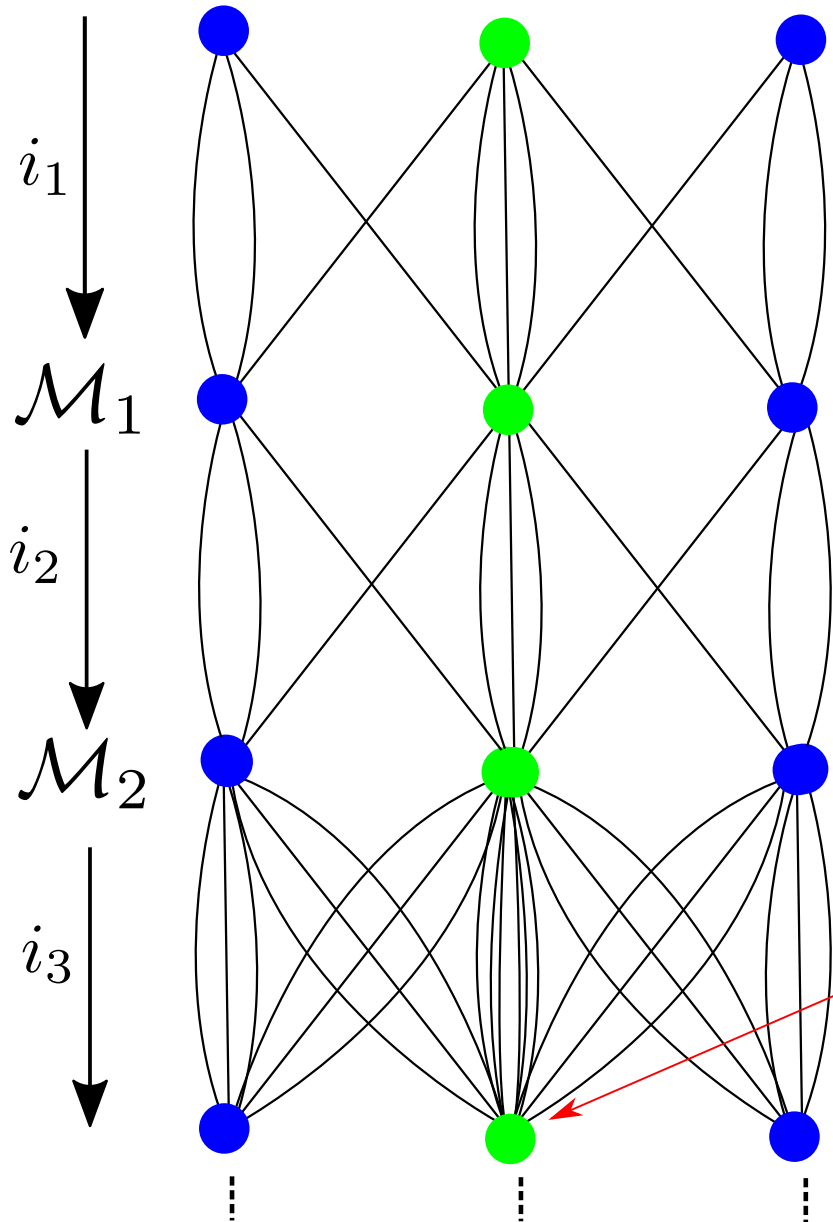
$$\left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleleft \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleleft \end{pmatrix} \right)$$

How many  $\blacksquare$  do I see in ?



# BRATTELI DIAGRAM!

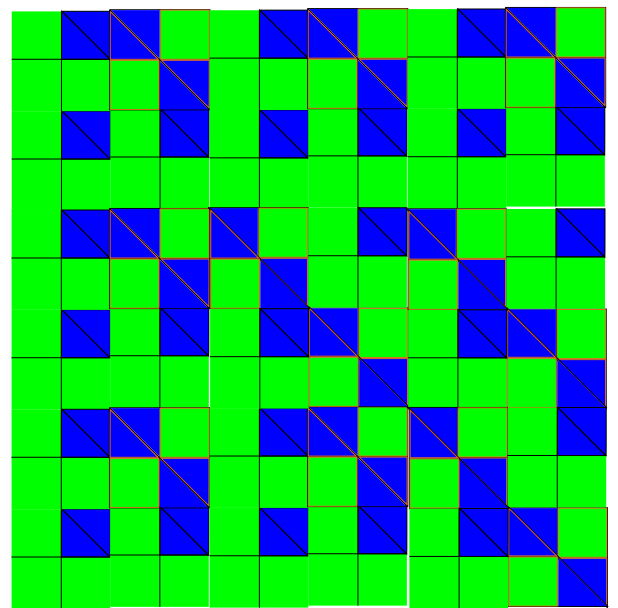
$\mathcal{M}_0 \quad \mathbb{C} \quad \oplus \quad \mathbb{C} \quad \oplus \quad \mathbb{C}$



$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$

$$i_1 \downarrow \left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix} \right)$$

How many  $\blacksquare$  do I see in ?

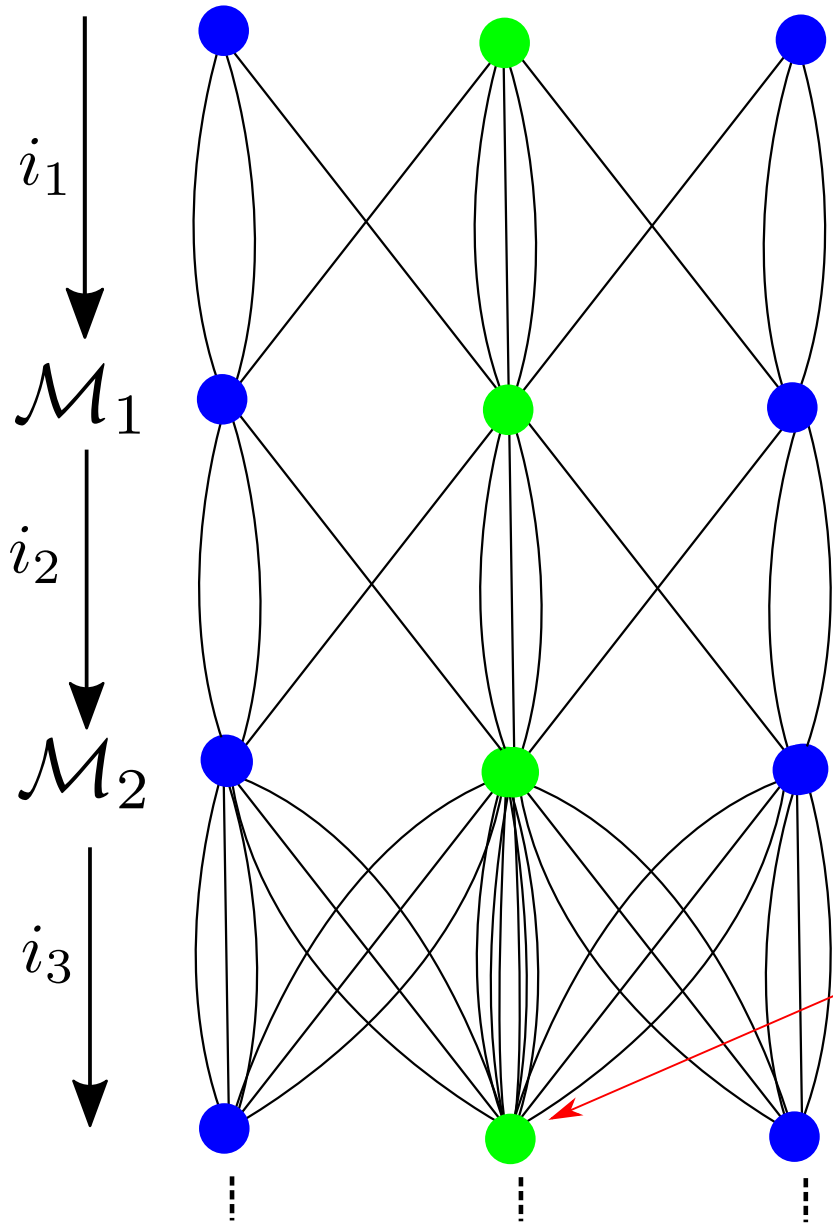


$$\tau_2^3 \in \text{Tr}(\mathcal{M}_3) = \mathbb{C}^3$$

# BRATTELI DIAGRAM!

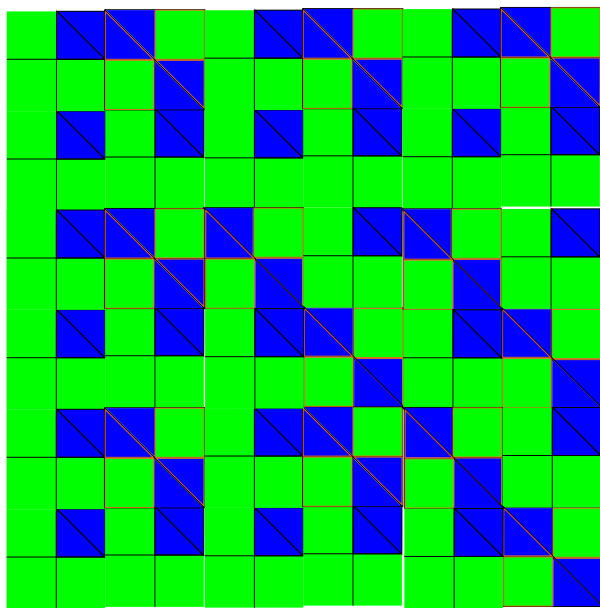
$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$

$\mathcal{M}_0 \quad \mathbb{C} \quad \oplus \quad \mathbb{C} \quad \oplus \quad \mathbb{C}$



$$\left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix} \right)$$

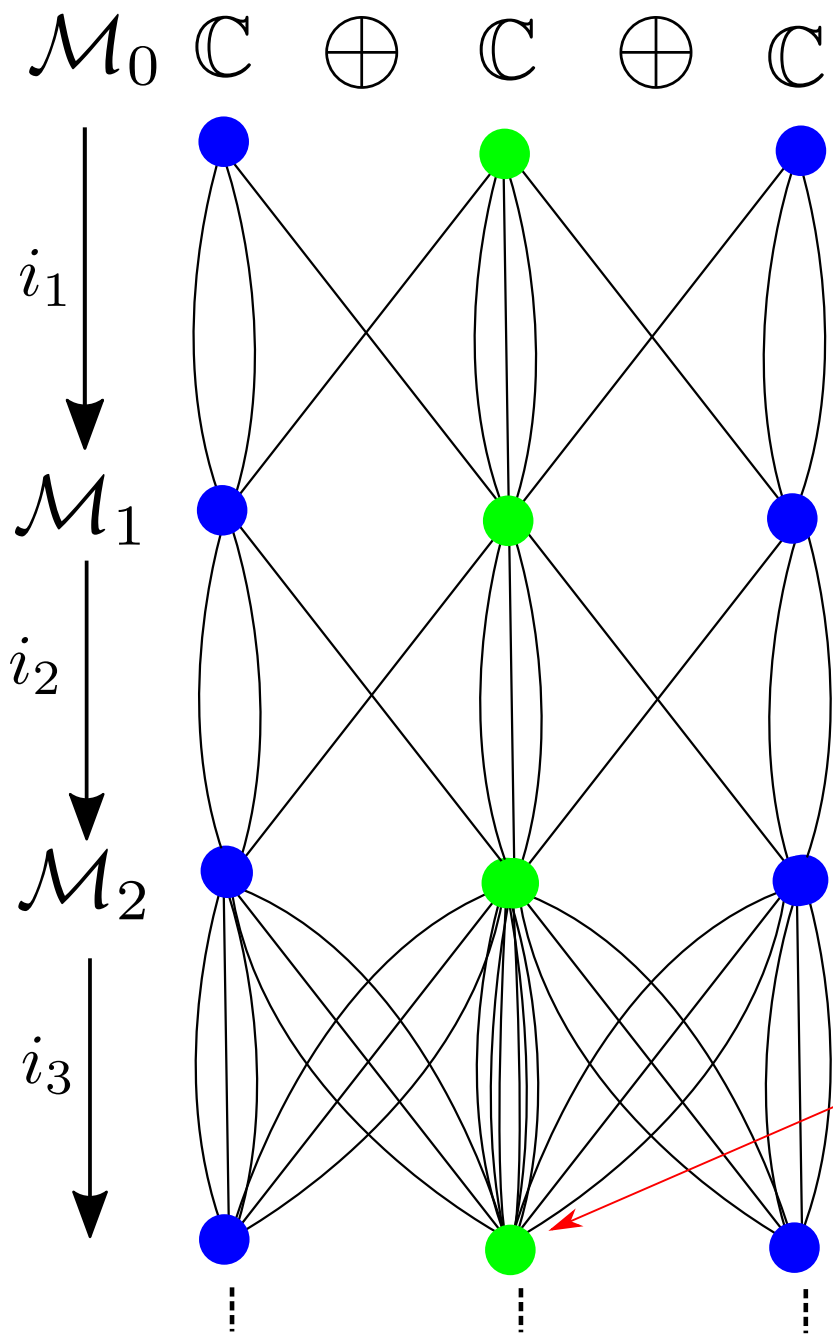
How many  $\blacksquare$  do I see in ?



$$\tau_2^3 \in \text{Tr}(\mathcal{M}_3) = \mathbb{C}^3$$

(canonical trace on second summand  $M_{192}$ )

# BRATTELI DIAGRAM!

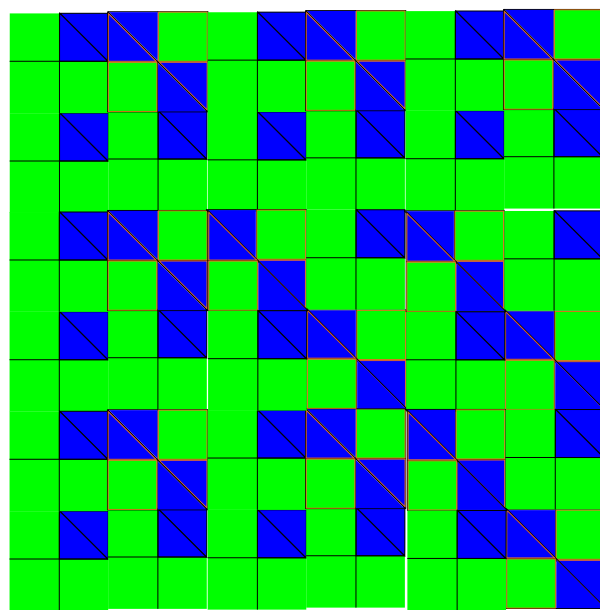


$$(\blacktriangleleft, \blacksquare, \blacktriangleright) \in \mathbb{C}^3$$

$$i_1 \downarrow$$

$$\left( \begin{pmatrix} \blacktriangleleft & 0 & 0 \\ 0 & \blacksquare & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix}, \begin{pmatrix} \blacktriangleleft & 0 & 0 & 0 & 0 \\ 0 & \blacksquare & 0 & 0 & 0 \\ 0 & 0 & \blacktriangleleft & 0 & 0 \\ 0 & 0 & 0 & \blacksquare & 0 \\ 0 & 0 & 0 & 0 & \blacksquare \end{pmatrix}, \begin{pmatrix} \blacksquare & 0 & 0 \\ 0 & \blacktriangleleft & 0 \\ 0 & 0 & \blacktriangleright \end{pmatrix} \right)$$

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(canonical trace on second summand  $M_{192}$ )

$$\tau_2^3(i_3 \circ i_2 \circ i_1((0, 1, 0))) = i_1^* i_2^* i_3^* \tau_2^3((0, 1, 0))$$



LET'S DO THE TWIST

$$\int e^{-2\pi i \langle \lambda, t \rangle} g_i \circ \varphi_t(\mathcal{T}) dt$$

LET'S DO THE TWIST  $f_i = \sum \delta_p * h_i$

where  $p$  is in the center of mass of tiles of type  $i$

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$$\sum_{\ell=1}^{\tau_v(e_i)} \int_{t_i} e^{-2\pi i \langle \lambda, t - \tau_\ell \rangle} h_i(t) dt$$

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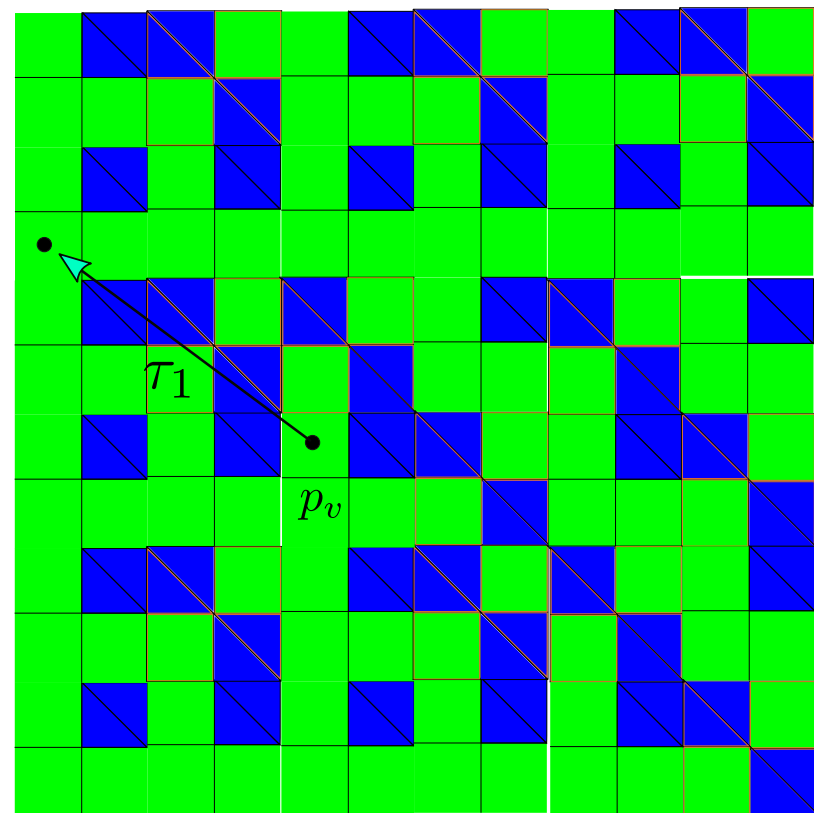
$$\begin{aligned} \int_{\mathcal{P}(v)} e^{-2\pi i \langle \lambda, t \rangle} g_i \circ \varphi_t(\mathcal{T}) dt &= \int_{\substack{\text{tiles in } \mathcal{P}(v) \\ \text{of type } i}} e^{-2\pi i \langle \lambda, t \rangle} g_i \circ \varphi_t(\mathcal{T}) dt = \\ &= \sum_{\ell=1}^{\tau_v(e_i)} \int_{t_i} e^{-2\pi i \langle \lambda, t - \tau_\ell \rangle} h_i(t) dt = \sum_{\ell=1}^{\tau_v(e_i)} e^{2\pi i \langle \lambda, \tau_\ell \rangle} \int_{t_i} e^{-2\pi i \langle \lambda, t \rangle} h_i(t) dt \\ &= \sum_{\ell=1}^{\tau_v(e_i)} e^{2\pi i \langle \lambda, \tau_\ell \rangle} \hat{h}_i(\lambda) = \hat{h}_i(\lambda) \sum_{\ell=1}^{\tau_v(e_i)} e^{2\pi i \langle \lambda, \tau_\ell \rangle} \end{aligned}$$

LET'S DO THE TWIST

$$\left| \int_{\mathcal{P}(v)} e^{-2\pi i \langle \lambda, t \rangle} g_i \circ \varphi_t(\mathcal{T}) dt \right| \leq |\hat{h}_i(\lambda)| \left| \sum_{\ell=1}^{\tau_v(e_i)} e^{2\pi i \langle \lambda, \tau_\ell \rangle} \right|$$

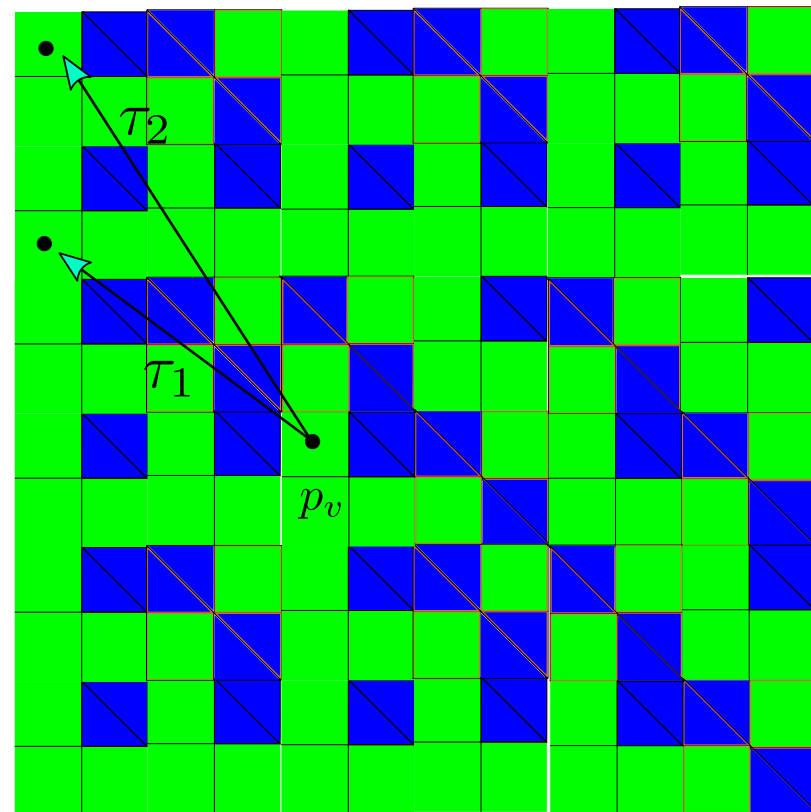
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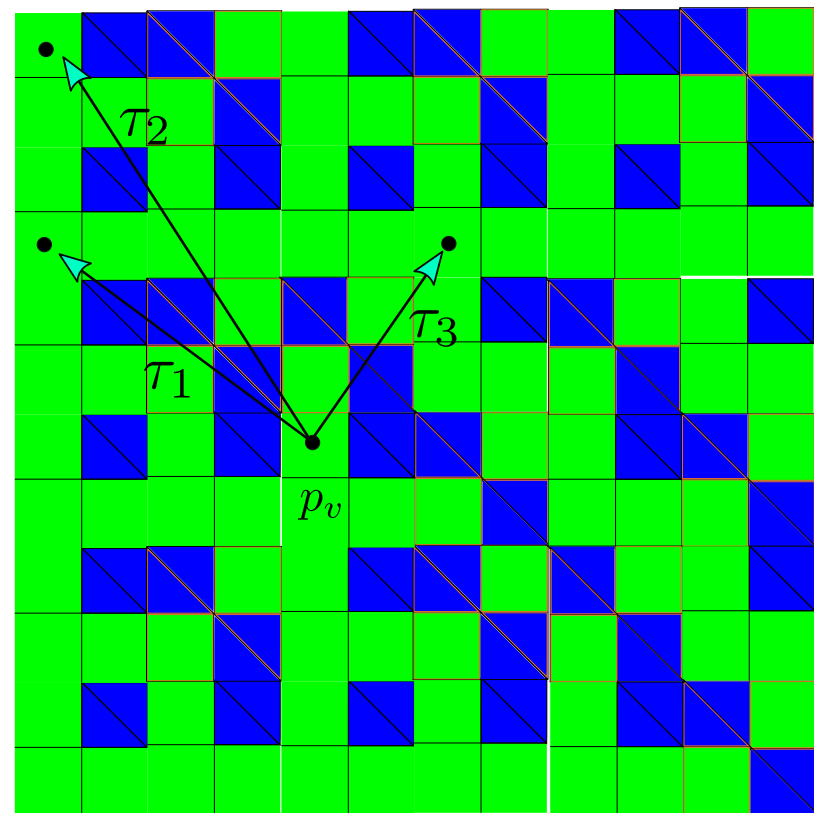
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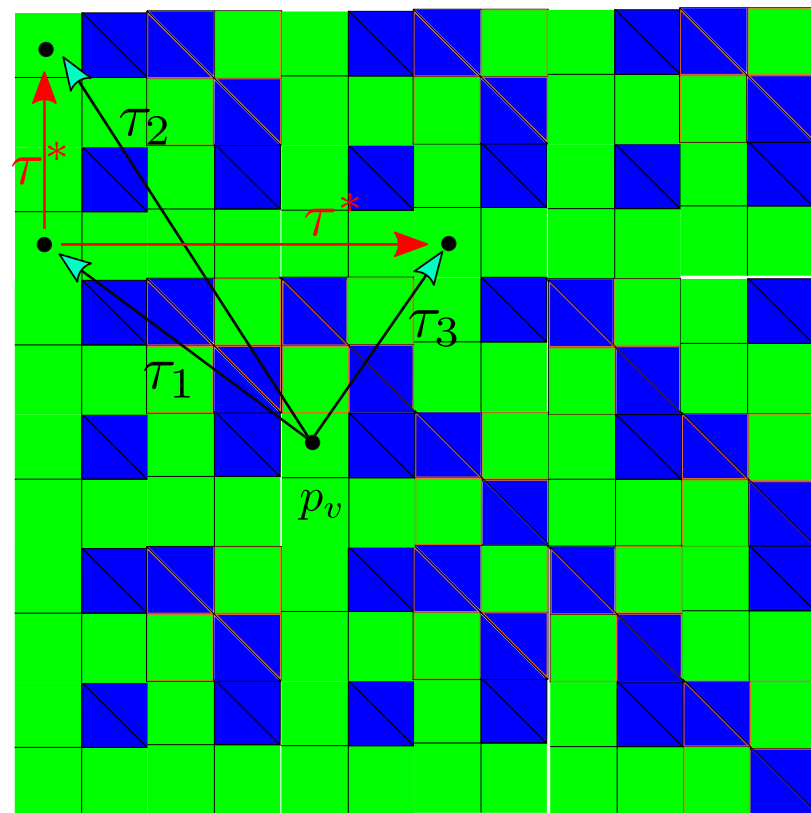




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$\tau^*$  is a return vector  
between tiles of type  $i$

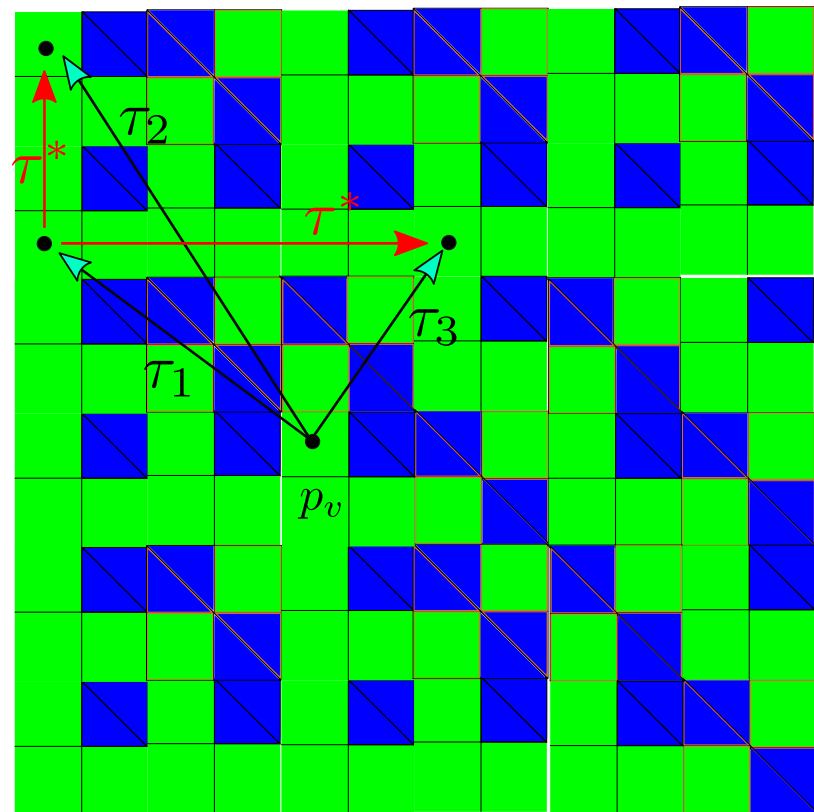


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$$\leq |\hat{h}_i(\lambda)| \left| \tau_v(e_i) - 2 + \left| 1 + e^{2\pi i \langle \lambda, \tau^* \rangle} \right| \right|$$



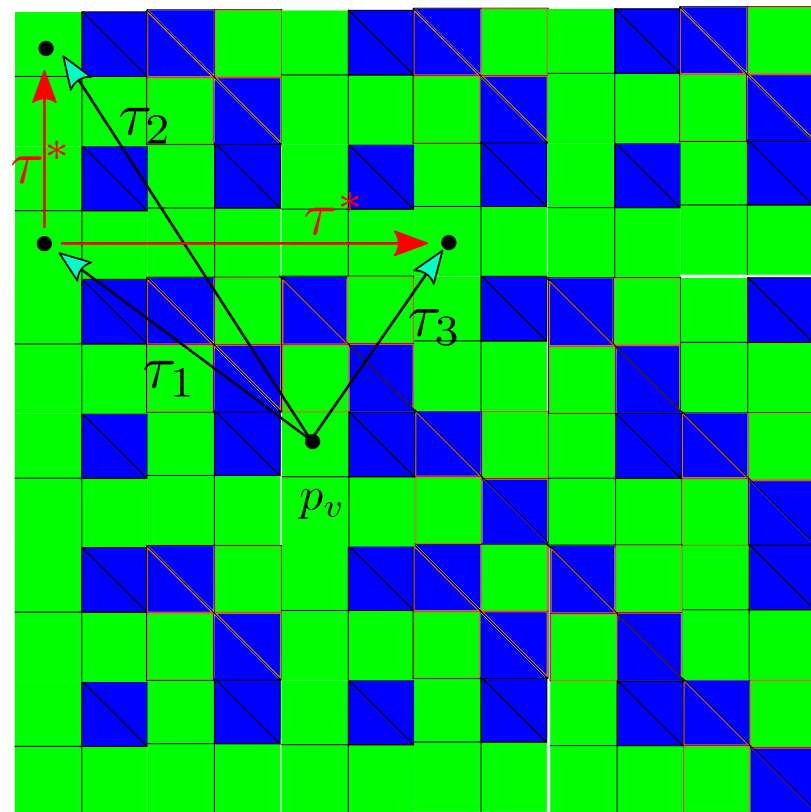
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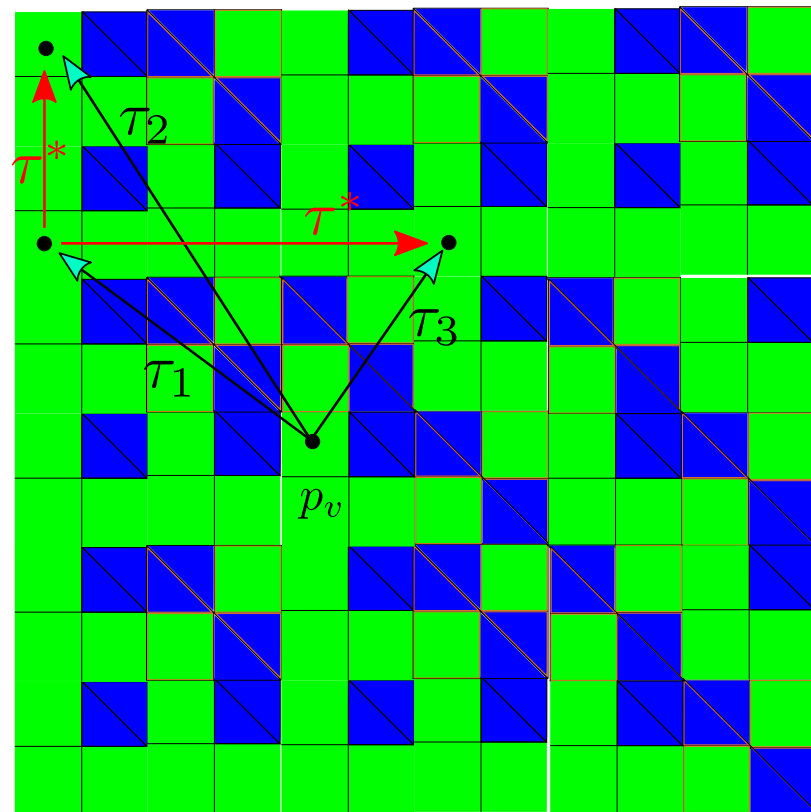
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$$\leq |\hat{h}_i(\lambda)| \left( \tau_v(e_i) - \frac{1}{2} \|\langle \lambda, \tau^* \rangle\|_{\mathbb{R}/\mathbb{Z}}^2 \right)$$



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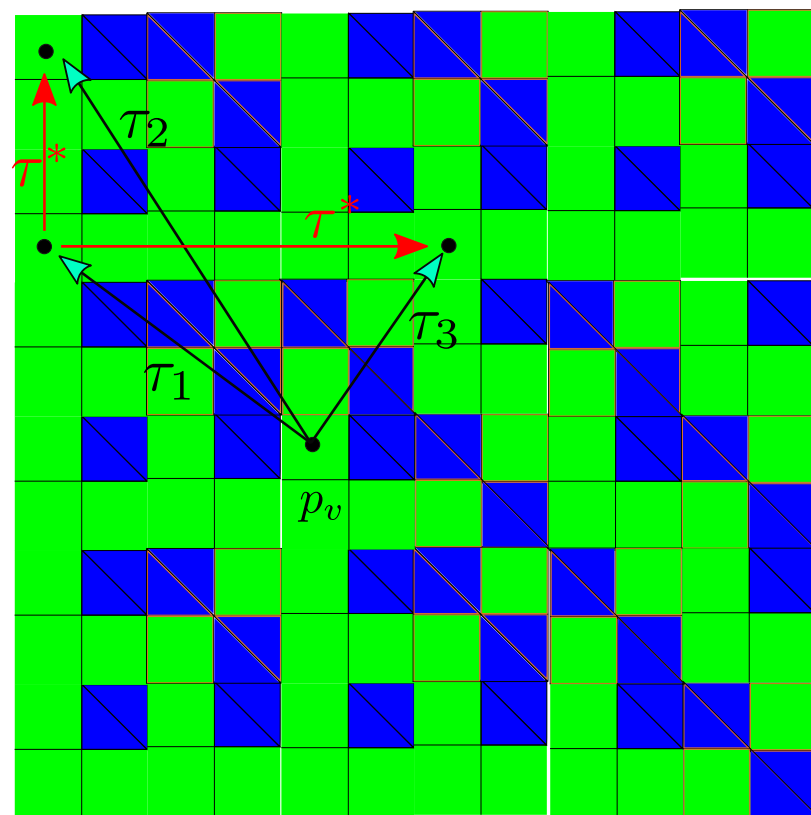
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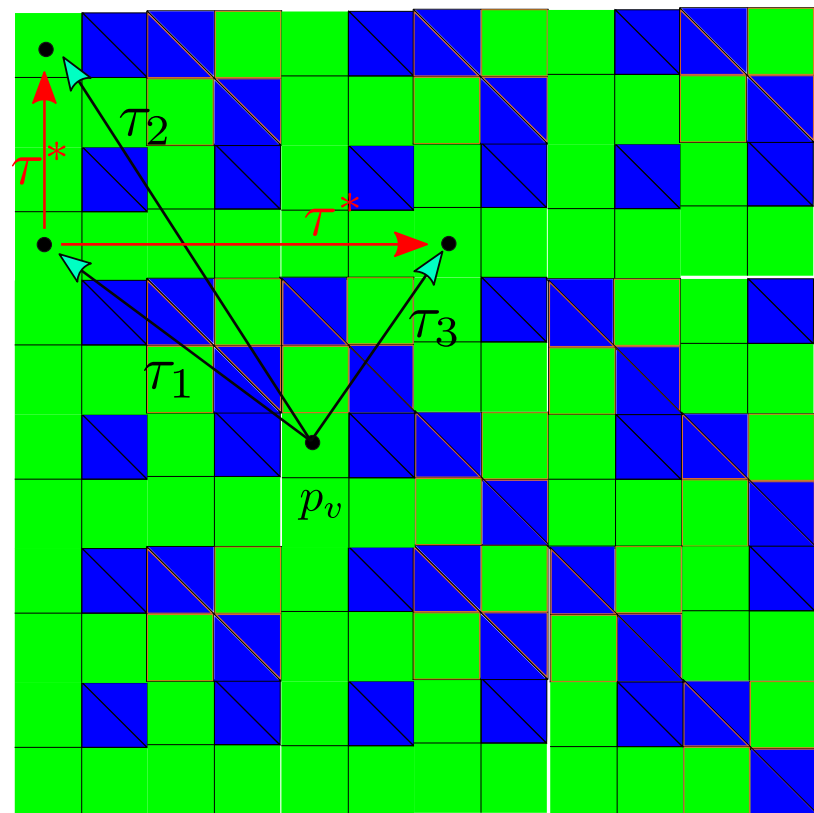
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↑  
growth controlled by  
the trace cocycle  
(cocycle on  $H^d(\Omega_x; \mathbb{R})$ )



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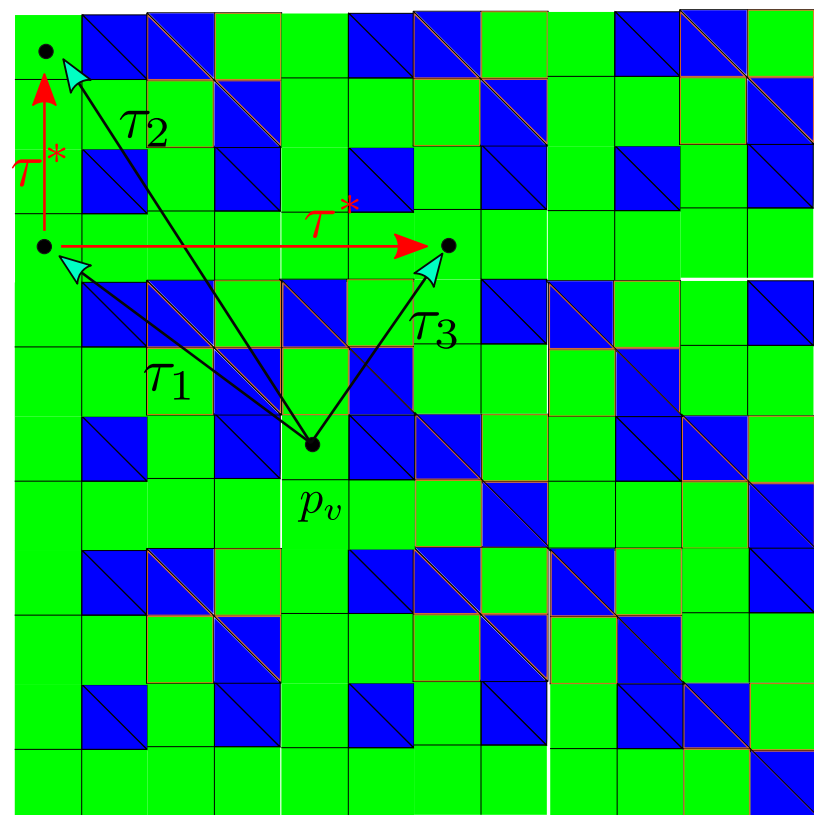
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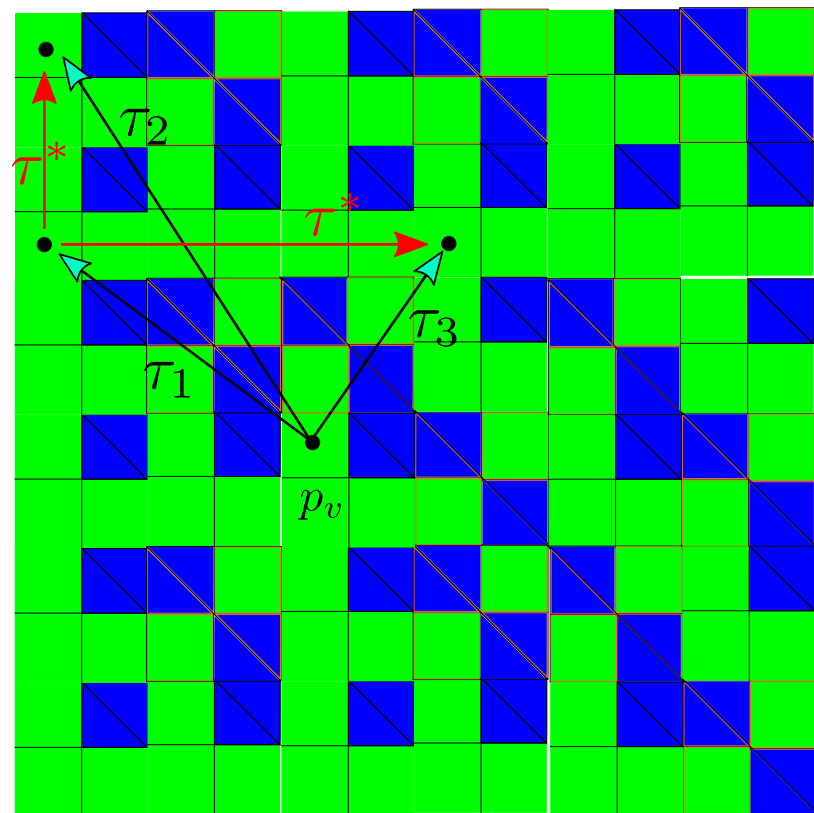
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When  $d = 1$  there is one cocycle to care about.





# LET'S DO THE TWIST

$$\left| \int_{\mathcal{P}(v)} e^{-2\pi i \langle \lambda, t \rangle} g_i \circ \varphi_t(\mathcal{T}) dt \right| \leq |\hat{h}_i(\lambda)| \left| \sum_{\ell=1}^{\tau_v(e_i)} e^{2\pi i \langle \lambda, \tau_\ell \rangle} \right|$$

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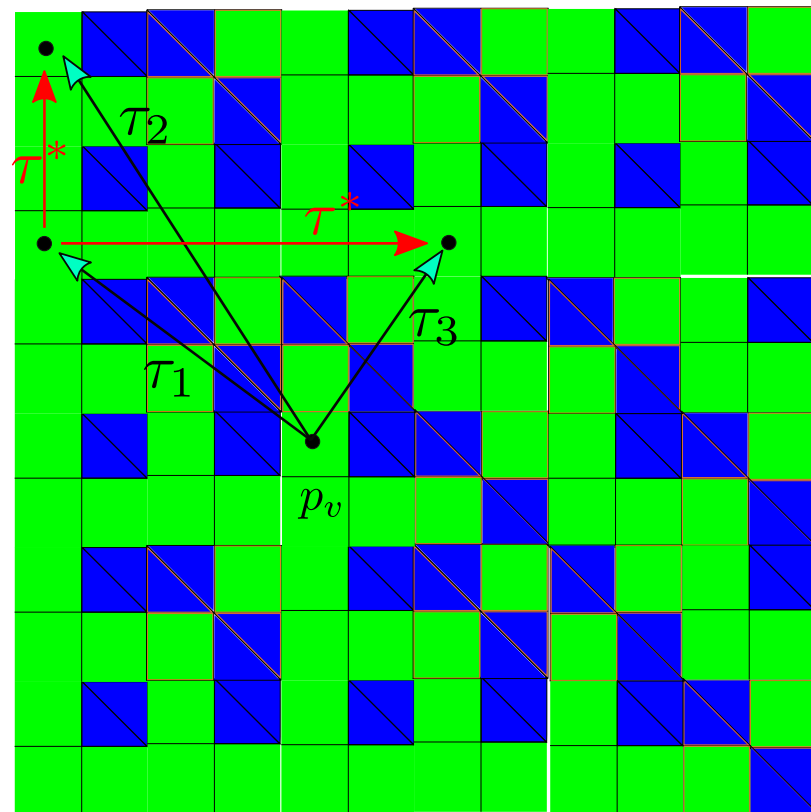
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↑  
growth controlled by  
the return vector cocycle  
(cocycle on  $H^1(\Omega_x; \mathbb{R})$ )

When  $d = 1$  there is one cocycle to care about.  
When  $d > 1$  these are different!



# LET'S DO THE TWIST

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growth controlled by  
the trace cocycle  
(cocycle on  $H^d(\Omega_x; \mathbb{R})$ )

↑  
growth controlled by  
the return vector cocycle  
(cocycle on  $H^1(\Omega_x; \mathbb{R})$ )

When  $d = 1$  there is one cocycle to care about.  
When  $d > 1$  these are different!

Need to stay away from lattice points under the renormalization dynamics (cocycle dynamics). Use the Erdos-Kahane method (B-S) to estimate the dimension of set of deformation parameters which does not stay away from lattice points. This set has codimension at most  $\dim(E_x^+) - d$ , which is why if you have  $d + 1$  positive exponents the bad set is small.

