

Math 535, lecture 9

27/1/2023

Last time:

M smooth manifold

① **sheaf of smooth functions**: map $U \rightarrow C^\infty(U)$
for open sets $U \subset M$. Can restrict $f \in C^\infty(U)$
to open subsets $V \subset U$

② **sheaf of smooth vector fields**: map $U \rightarrow D_{\text{vec}}(C^\infty(U))$
can restrict $X \in D_{C^\infty(U)}$ to $V \subset U$.

In both cases, (1) an element $\begin{cases} f \in C^\infty(U) \\ X \in D_{C^\infty(U)} \end{cases}$ is
determined
by restrictions to open cover of U .

(2) a system of elements on open cover
of U defines an element on U
iff restrictions to $V_i \cap V_j$ are consistent.

In local co-ordinates (i.e. on patch $\varphi: U \rightarrow \mathbb{R}^n$)

(1) $C^\infty(U) \cong C^\infty(\varphi(U))$ via composition with φ .

(2) $D_{C^\infty(U)} = \left\{ \sum_{i=1}^n a_i(x) \frac{\partial}{\partial x^i} \mid a_i \in C^\infty(\varphi(U)) \right\}$.

\Rightarrow Tangent & cotangent spaces of N at p

$$T_p^*M = T_p/M^2 \quad \begin{matrix} T_p \subset C^\infty(M) \\ \ker(\delta_p) \end{matrix}$$

$T_p M =$ "derivations" $C^\infty(U) \rightarrow \mathbb{R}$:

"local derivation" $\partial(fg)(p) = \partial f \cdot g(p) + f(p) \cdot \partial g$.

spaces are in perfect pairing:

in local coordinates T_p^*N represented by linear forms

$$dx^i$$

$$T_p M \quad " \quad " \quad \frac{\partial}{\partial x^i}.$$

Today: Derivations

lemma: Let M, N be smooth manifolds, $f \in C^\infty(N, M)$
 let $p \in M$. For each $v \in T_p M$, $v(f \circ \varphi)$ is a local
 derivation at $\varphi(p)$ on $C^\infty(U)$, map $d\varphi_p : T_p M \rightarrow T_{\varphi(p)} N$
 given by $v \mapsto (f \mapsto v(f \circ \varphi))$ is linear.

Def: $d\varphi_p$ is called the **derivative** or **differential** of φ at p

Ex: for local co-ordinates this is the usual Jacobian matrix

Pf: composition with φ is an algebra hom
 $C^\infty(N) \rightarrow C^\infty(M)$

so $(\nu, f) \mapsto \nu(f \circ \varphi)$ is bilinear. Also

$$\begin{aligned}\nu((f \circ g) \circ \varphi) &= \nu(f \circ \varphi \cdot (g \circ \varphi)) = \nu(f \circ \varphi) \cdot \nu(g \circ \varphi)(p) \\ &\quad + (f \circ \varphi)(p) \cdot \nu(g \circ \varphi) \\ &= \nu(f \circ \varphi) \cdot \nu(g \circ \varphi(p)) + f(\varphi(p)) \cdot \nu(g \circ \varphi).\end{aligned}$$

Prop: (1) $d\varphi: T_N \rightarrow T_M$ is smooth

(2) Chain rule holds (=construction is functorial)

$$d(\varphi \circ \psi)_p = d\varphi_{\psi(p)} \circ d\psi_p.$$

Thm: (Inverse & Implicit function theorems)

- (1) Suppose $d\varphi_p$ is injective. Then $\varphi|_U$ is injective for some nbd U of p .
- (2) " " " surjective. Then φ is an open map in a nbd of p

(3) If $d\varphi_p$ is a isom then find U of p , V of $\varphi(p)$
s.t. $\varphi|_U : U \rightarrow V$ is a diffeomorphism.

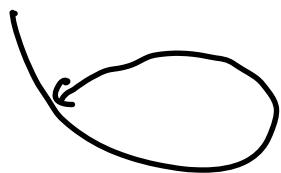
(4) Suppose $d\varphi_p$ is surjective. The level set
 $P = \varphi^{-1}(\varphi(p))$ is (near p) a
submanifold.

Def: A smooth map $\varphi : M \rightarrow N$ is an

- (1) immersion if $d\varphi_p$ is injective for all p
- \Downarrow
- (2) local embedding if for all $p \in N$ find U
s.t. $\varphi|_U$ is a diffeo onto its image

(3) An embedding if it's an immersion which
is a homeomorphism onto its image

Example:



Def: A parametrized submanifold of N
is a pair (M, f) where M is a manifold,
 $f : M \rightarrow N$ is an injective immersion

Two parametrizations are **equivalent** if conjugate by a diffeo of the source manifolds

A **submanifold** is an equivalence class

if $f: M_1 \rightarrow N$ is an injective immersion

If $\psi: M_2 \rightarrow M_1$ is a diffeo.

then $f \circ \psi: M_2 \rightarrow N$ is an injective immersion

usually write $M \cap N$ for a submanifold.

Therefore $p \in M$, $T_p M \subset T_p N$.

Def: let $\gamma: [a, b] \rightarrow N$ be a smooth curve
its **derivative** is $\dot{\gamma}(t) = d\gamma\left(\frac{d}{dt}\right)_t \in T_{\gamma(t)} N$

Say γ is an **integral curve** of $X \in D_N$ if
 $\dot{\gamma}(t) = X_{\gamma(t)}$.

Thm: (Picard) For any X , any $p \in N$ there
is an integral curve of X with $\gamma(0) = p$ defined
in some nbd of 0, unique when defined.

Def: A **distribution** on N is a smooth choice of a subspace $V_p \subset T_p N$ of $\dim k$ for each p .

\Rightarrow

Cover N with nbd's, on each choose k vector fields $\{X_i\}_{i=1}^k \subset \mathcal{D}_U$ s.t. $\{X_i(p)\}_{i=1}^k$ are indep in $T_p N$ for each $p \in U$

Call a submanifold (M^k, f) **tangent** to a distribution V if $df(T_p M) = V_{f(p)}$ for all $p \in M$

Observation: If $X, Y \in \mathcal{D}(N)$ are sections of V (i.e. $X(p), Y(p) \in V_p$ for all p) can think of X, Y as vector fields on M . Then $[X, Y]$ is a vector field on M , hence tangent to V .

Thm (Frobenius) (1) Through each $p \in N$ there is a unique submanifold tangent to V .

(2) The distribution is **integrable**: if X, Y sections of V so is $[X, Y]$