

Math 41, Lecture 6

Last time: $T \in \text{End}_F(V)$, $\dim_F V < \infty$.

Generalized eigenspaces $V_\lambda = \{v \in V \mid \exists k: (T-\lambda)^k v = 0\}$
min poly $m_T(x) \in F[x]$

Thm: (Spectral thm): Suppose m_T splits in F
(e.g. F algebraically closed). Then

$$V = \bigoplus_{\lambda} V_{\lambda}.$$

From this: (1) If $m_T(x) = \prod_{i=1}^r (x-\lambda_i)^{k_i}$

$$p_T(x) = \prod_{i=1}^r (x-\lambda_i)^{n_i}$$

then (1) $T|_{V_{\lambda_i} - \lambda_i}$ is nilpotent of deg k_i

$\Rightarrow$ (2) $p_T(T) = 0$ so $m_T \mid p_T$.

$\uparrow$

Thm (Cayley-Hamilton).

Today: Choosing a good basis for a nilpotent map

Let $N \in \text{End}_F(V)$ satisfy $N^k = 0$
(e.g. $N = \pi_{V_\lambda} - \lambda$, $V = V_\lambda$)

Observe. $\{0\} = \text{Ker}(N^0) \subset \text{Ker}(N)$
 $\subset \text{Ker}(N^2)$
 $\vdots$
 $\subset \text{Ker}(N^k)$

In fact these are distinct.

$$\text{If } \text{Ker}(N^{j+1}) = \text{Ker}(N^j)$$

$\Rightarrow$ on image of N^j , N is injective.

(if $N(N^j v) = 0$ then $N^j v = 0$).

Choose basis (size m_1) in $\text{Ker}(N^1)$

(1) Extend by m_2 vectors to get basis of $\text{Ker}(N^2)$

$\vdots$

(3) Extend by m_k vectors to get basis of $V =$
 $\text{Ker}(N^k)$

In this basis, matrix looks: block-matrix
blocks of size $m_i \times m_j$

if $N^j \underline{v} = \underline{0}$ then $N^{j-1}(N\underline{v}) = \underline{0}$

so N is a kind of shift here:

if $\underline{v} \in \text{basis}$ was chosen in j^{th} step, $N\underline{v}$
is combo of vectors from previous steps

$$\begin{pmatrix} 0_{m_1} & m_2 \times m_2 & m_1 \times m_3 & & \\ & 0_{m_2} & m_2 \times m_3 & & \\ & & 0_{m_3} & & \\ & & & \ddots & \\ & & & & \ddots & \\ & & & & & \ddots & \\ & & & & & & \ddots & \\ & & & & & & & \ddots & \\ & & & & & & & & \ddots & \\ & & & & & & & & & \ddots & \end{pmatrix}$$

zero below diagonal

zeros
on block-
diagonal

Idea: choose basis more carefully so N
shifts basis vectors, not just subspaces

Observe: need to choose vectors ^{not from $\ker(N^k)$}
s.t. $N^{k-1}v$ is in basis of $\ker N$

But $V \setminus \ker(N^{k-1})$ not a subspace, can't just choose a "basis" there

lemma: let N be nilpotent. let $B \subset V$ be a set of vectors such that: $N(B) \subset B \cup \{0\}$

then B is linearly indep iff $B \cap \ker(N)$ is.

Pf: let $\sum_{i=1}^r \alpha_i v_i = 0$ be a minimal dependence

in B . let m be maximal s.t. $N^m v_i \neq 0$

for some i ($\exists$ such m because N is nilpotent)

then $\sum_{i=1}^r \alpha_i (N^m v_i) = 0$

the $N^m v_i \neq 0$ (else we get shorter dependence)

All in $\ker(N)$ (if not, $N^{m+1} v_i \neq 0$ for some i .)

$\Rightarrow$ just got a dependence in $B \cap \ker(N)$.

Warning: We never showed the vectors $N^i \underline{v}_i$ are distinct, & they don't have to be

Correct lemma: Assume $N(B) \subset B \setminus \{0\}$
& N is injective on $B \setminus \text{Ker}(N)$.

Example: $\underline{v}$ be such that $N^k \underline{v} = 0$, $N^{k-1} \underline{v} \neq 0$

consider $B = \{ \underline{v}, N\underline{v}, N^2\underline{v}, \dots, N^{k-1}\underline{v} \}$

indeed N shifts these vectors: $N(N^j \underline{v}) = N^{j+1} \underline{v}$.

injective:

each $N^j \underline{v} \in \text{Ker}(N^{k-j}) \setminus \text{Ker}(N^{k-j-1})$

so N injective here

$B \cap \text{Ker}(N) = \{ N^{k-1} \underline{v} \}$ indep (vector is $\neq 0$)

Then $\text{Span}(B)$ is N -inv't, matrix of $N|_{\text{Span}(B)}$ wrt B is

(reverse order) $A = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 1 \end{pmatrix}$ $a_{ij} = \begin{cases} 1 & j = i+1 \\ 0 & j \neq i+1 \end{cases}$

matrix has 1s on the diagonal above main
0 elsewhere

Def: We call such a matrix a **Jordan block**
(also such a subspace).

Thm: $N \in \text{End}_F(V)$ nilp $\Rightarrow V$ is a direct sum
of Jordan blocks; (2) number of blocks of
each size only depends on N .

Example: $A = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} (123) \in M_3(\mathbb{Q})$

$$\begin{aligned} A^2 &= \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} [(123) \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}] (123) \\ &= \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} (0) (123) = 0 \end{aligned}$$

so A is nilpotent of deg 2

$$\text{Im}(A) = \text{Span}\left\{\begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}\right\} \subset \text{Ker}(A) \quad (A^2 = 0)$$

note: $A \begin{pmatrix} 3 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$. (solve linear equations)

then $\left\{\begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \\ 0 \end{pmatrix}\right\}$ is a Jordan block for A .

$$\dim \ker(A) = 3 - \dim \operatorname{Im}(A) = 2,$$

$$\text{choose } \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \in \ker(A) \text{ indep of } \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

Then $\left\{ \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \right\}$ is a Jordan block,

let $B = \left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \right\}$ then the matrix of A wrt B is

$$\text{block of size 2} \rightarrow \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

block of size 1

can't have block of size 3 $\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$
(that's nilp of deg 3)

can't have 3 blocks of size 1: $A \neq 0$

Proof of thm: Say N is nilp of deg d .

for $0 \leq k \leq d$ set $W_k = \ker(N^k) \cap \ker(N)$

so $W_0 = W = \ker(N) \supset W_1 \supset W_2 \supset \dots \supset W_d = \{0\}$.

Choose basis C of W consistent with this
 decomp: choose basis $C_{d-1} \subset W_{d-1}$,
 extend to basis $C_{d-1} \cup C_{d-2} \subset W_{d-2}$

$\vdots$
 so $C_k \subset W_k$ s.t. $\bigcup_{k' \geq k} C_{k'}$ set basis of W_k

let $C = \bigcup_k C_k = \{v_i\}_{i \in I}$ define k_i s.t.
 $v_i \in C_{k_i}$.

Now each $v_i \in \mathcal{N}^{k_i} \cap W$, so $\exists u_i \in V$
 s.t. $N^{k_i} u_i = v_i$.

For $i \in I$, $0 \leq j \leq k_i$ set $v_{i,j} = N^{k_i-j} u_i$

so $v_{i,0} = v_i$, $N v_{i,1} = v_{i,0}$, $N v_{i,2} = v_{i,1}$, ...

$\therefore v_{i,k} = u_i$

In general: $N v_{i,j} = \begin{cases} 0 & j=0 \\ v_{i,j-1} & j \neq 0 \end{cases}$

clear $\{v_{i,j}\}_{j=0}^{k_i}$ is a Jordan block,

$B = \bigcup_{i \in K} \{v_{ij}\}_{j=0}^{k_i} \Leftrightarrow$ direct sum of Jordan blocks

B is indep by lemma. $N(B) \subset B \cup \{0\}$
 By N -invariant, N does not mix blocks, within each block it's the example above.

Claim: For each k , $\text{Span}_F(B) \supset \text{Ker}(N^k)$
 (for $k=d$, $N^d=0$, $\text{Span}_F(B) \supset V$)

Pf: clear for $k=0$. Suppose $\text{Span}_F(B) \supset \text{Ker}(N^k)$
 Let $v \in \text{Ker}(N^{k+1})$. Then $N^k v \in \text{Ker}(N) \cap \text{Im}(N^k) = W_k$.

$$\begin{aligned} \text{so } N^k v &= \sum_{i: k_i \geq k} \alpha_i v_i && \text{for some } \alpha_i \\ &= \sum_{i: k_i \geq k} \alpha_i N^k u_i \end{aligned}$$

$$\Rightarrow N^k \left(v - \sum_{i: k_i \geq k} \alpha_i u_i \right) = 0$$

$$\text{so } \underline{v} = \sum_{i: k_i \geq k} \alpha_i \underline{v}_i \in \ker(N^k) \subset \text{Span}_{\mathbb{F}}(B)$$

by induction hypothesis.

$$\text{also } \underline{v}_i \in B \quad \underline{v}_i = \underline{v}_{ijk_i} \in B$$

so $\underline{v} \in \text{Span}_{\mathbb{F}}(B)$ and we are done. $\square$

Def A Jordan basis is a basis $\{\underline{v}_{ij}\}_{0 \leq j \leq k_i}$

$$\text{s.t. } N \underline{v}_{ij} = \begin{cases} \underline{v}_{i,j-1} & j \geq 1 \\ \underline{0} & j = 0 \end{cases}$$

lemma: A Jordan basis has exactly

$$\dim_{\mathbb{F}} W_{k-1} - \dim_{\mathbb{F}} W_k$$

blocks of size k .

$\Leftrightarrow$ up to permuting blocks, the **Jordan form** (= matrix of N in basis) is **unique**.

Pfs In Jordan basis, $\text{Ker } N = \text{Span} \{v_{i,0}\}$

$\{v_{i,j} : \begin{matrix} j \leq k_i - k \\ k_i \geq k \end{matrix}\}_{CB}$ is a basis for $\text{Im}(N^k)$

$$\Rightarrow \text{Im}(N^k) \cap \text{Ker}(N) = \text{Span}_F \{v_{i,0} \mid k_i \geq k\}.$$

Return to case of general $T \in \text{End}_F(V)$

Theorem: Suppose m_T splits in F .

Then $\exists$ basis $\{v_{\lambda,i,j} \mid \begin{matrix} \lambda \in \text{Spec}_F(T) \\ i \in I_\lambda, 0 \leq j \leq k(\lambda,i) \end{matrix}\}$

such that

$$(T - \lambda) v_{\lambda,i,j} = \begin{cases} v_{\lambda,i,j-1} & j \geq 1 \\ 0 & j = 0 \end{cases}$$

$\Leftrightarrow$

$$T v_{\lambda,i,j} = \lambda v_{\lambda,i,j} + \begin{cases} v_{\lambda,i,j-1} & j \geq 1 \\ 0 & j = 0 \end{cases}$$

Furthermore, if we write $W_\lambda = \text{Ker}(T - \lambda)$,

i s.t. $k(\lambda,i) = k$ is

$$\dim_F((T - \lambda)^{k'} V_\lambda \cap W_\lambda) = \dim_F((T - \lambda)^k V_\lambda \cap W_\lambda).$$

PF: Apply the previous thm to $\mathcal{M}_{V_\lambda} - \lambda$.

Cor: The algebraic ^{multiplicity} of λ is $\dim V_\lambda$.

The geometric mult. is # λ -blocks.

Example: $A_1 = I + A$ (A from above)

this has char poly $(x-1)^3$, min poly $(x-1)^2$,
back in previous example, with Jordan form

$$\left(\begin{pmatrix} 1 & 1 \\ & 1 \end{pmatrix} \right)_{(1)}$$

if $A_2 = 2I + A$, get Jordan form

$$\left(\begin{pmatrix} 2 & 1 \\ & 2 \end{pmatrix} \right)_{(2)}$$

Block-diag matrix, each block
has $\text{ev. } \lambda$ on diag, 1st right above
0 else where.