

# Math 928, lecture 7, 28/1/2025

Last time: Calculus of variations

Methods for solving optimization problems with objective function

$$S(\gamma) = \int_a^b L(\gamma(t), \dot{\gamma}(t); t) dt$$

over functions  $\gamma: [a, b] \rightarrow \mathbb{E}^{dN}$ ,  $\gamma \in C^1$

$$L: \mathbb{E}^{dN} \times \mathbb{R}^{dN} \times \mathbb{R} \rightarrow \mathbb{R}, L \in C^1$$

Goals: Find critical pts. { Direct method:  
show  $S$  has min in some function space.

Indirect method: Find sufficient conditions for critical pts, solve for them

For our purposes don't need to differentiate  $S$  wrt  $\gamma$ , instead take directional derivatives in enough directions ("variational derivative")

Formal calculation: Suppose  $\gamma(t)$  minimal for all  $\delta$  pt.  $\gamma(t_0) = a$ ,  $\gamma(t_1) = b$ .

Idea: Consider  $S(r + \epsilon \eta) - S(r)$ ,  $\eta \in C_c^\infty(a, b)$   
 $\epsilon \rightarrow 0$

Then  $L(r(t) + \epsilon \eta(t), \dot{r}(t) + \epsilon \dot{\eta}(t); t) - L(r(t), \dot{r}(t); t)$   
 $= \epsilon \left\langle \frac{\partial L}{\partial q}, \eta(t) \right\rangle + \epsilon \left\langle \frac{\partial L}{\partial \dot{q}}, \dot{\eta}(t) \right\rangle + O(\epsilon^2)$   
evaluated at  $(r(t), \dot{r}(t); t)$ .

so

$$S(r + \epsilon \eta) - S(r) = \epsilon \int_{t_0}^{t_1} \left[ \left\langle \frac{\partial L}{\partial q}, \eta(t) \right\rangle + \left\langle \frac{\partial L}{\partial \dot{q}}, \dot{\eta}(t) \right\rangle \right] dt + O(\epsilon^2)$$
$$= \epsilon \int_{t_0}^{t_1} \left\langle \frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}, \eta(t) \right\rangle dt + O(\epsilon^2)$$

by parts  $\eta(t_0) = \eta(t_1) = 0$

If  $S(r)$  minimal, must have integral vanishes  
arbitrary choice of  $\eta \Rightarrow$

$$\frac{\partial L}{\partial q}(r(t), \dot{r}(t); t) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}}(r(t), \dot{r}(t); t) \right) = 0$$

"Euler-Lagrange Equation"

2<sup>nd</sup> order ODE. Typically has solutions

Remark: Solve ODE from initial conditions  
here we have boundary values.

## Formalization;

Lemma: (1) let  $f \in C(a, b)$ , suppose for all  $\eta \in C_c^\infty(a, b)$   
we have  $\int_a^b f \eta dt \geq 0$ . Then  $f \geq 0$ .  $\eta \geq 0$

(2) let  $f \in L^1(a, b)$ , same assumption then  $f \geq 0$  a.e.

Pf: (1) say  $f(s) < 0$ . Then have interval  $J \subset (a, b)$   
on which  $f \leq -\delta < 0$ . let  $\eta$  be positive supported in  $J$   
Then  $\int_a^b f \eta dt = \int_J f \eta \leq -\delta \int_J \eta dt < 0$ .

(2) let  $d\mu = f dt$  be the measure on  $[a, b]$   
with density  $f$  wrt Lebesgue.  $\mu(\eta) = \int_a^b f \eta dt$ .  
(Riesz Representation thm): since  $\mu(\eta) \geq 0$  if  $\eta \geq 0$ ,  
 $\mu$  is a positive measure  $\Rightarrow \frac{d\mu}{dt} = f \geq 0$ .  $\square$

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## Taste of "direct" arguments.

Def: Say  $L$  is "standard" if

$$L(q, \dot{q}; t) = \frac{1}{2} \langle M(q, t) \dot{q}, \dot{q} \rangle - U(q, t)$$

where  $M = M(q, t)$  is symmetric,  $M \geq \mu > 0$  for some  
constant,  $U$  "nice".

Fact: If  $M = \text{mass}$ ,  $U = \text{potential}$ , then Euler-Lagrange" Newton

Def: For nice enough  $\gamma: I \rightarrow \mathbb{R}^n$ , define

$$\|\gamma\|_{H^k}^2 = \sum_{i=0}^k \|\gamma^{(i)}\|_{L^2(I)}^2 \quad \leftarrow \text{Sobolev norm}$$

$$\underline{\| \gamma \|_{H^0}^2} = \|\gamma\|_{L^2}^2 = \int_I |\gamma(t)|^2 dt.$$

$H^k(I; \mathbb{R}^n) =$  completion of  $C_c^\infty(I; \mathbb{R}^n)$  wrt norm

$\Leftrightarrow \{ f \in L^2 \mid k^{\text{th}} \text{ distributional derivative also in } L^2 \}$

Ex: Equivalent norm is  $\sqrt{\|\gamma\|_{L^2}^2 + \|\gamma^{(k)}\|_{L^2}^2}$ .  
On  $\mathbb{R}$  equivalent to  $\|(1+|\cdot|)^k \hat{f}\|_2$ .

Ex:  $H^1 \cong \{ \gamma : \gamma \text{ is piecewise } C^1 \}$

Ex:  $H^k \subset C^{k-1}(I)$ , inclusion is compact.

Lemma: (Poincaré inequality) let  $u: I \rightarrow \mathbb{R}^n$  be diff

with  $u(t_0) = u(t_1) = 0$ . Then

$$\int_{t_0}^{t_1} |u|^2 dt \leq 2 \left( \frac{t_1 - t_0}{2} \right)^2 \int_{t_0}^{t_1} |u'|^2 dt$$

Pf: wlog  $I = [-\Delta, \Delta]$ . Then

$$\int_{-\Delta}^{\Delta} |u|^2 dt = [t|u|^2]_{-\Delta}^{\Delta} - 2 \int_{-\Delta}^{\Delta} t u u' dt$$

$$\leq 2\Delta \cdot \left( \int_{-a}^0 |u|^2 dt \right)^{1/2} \left( \int_{-a}^0 |\dot{u}|^2 dt \right)^{1/2}. \quad \square$$

lemma: (Coercivity) Suppose  $U(q) \leq A + C|q|^2$

$$\forall \epsilon > 0 \exists \delta > 0 \text{ st. } \int_{t_0}^{t_0+\delta} U(q, t) dt \leq B + \epsilon \int_{t_0}^{t_0+\delta} |q|^2 dt$$

Pf: let  $\bar{q}$  linearly interpolate  $q(t_0) = a, q(t_1) = b$

let  $u = q - \bar{q}$ . Then

$$\dot{u} = \dot{q} - \dot{\bar{q}} = \dot{q} - \frac{b-a}{\delta}$$

$$\text{so } |\dot{u}|^2 \leq 2|\dot{q}|^2 + 2\frac{(b-a)^2}{\delta^2}$$

$$\text{so } U(q) \leq A + C|q|^2 \leq A + 2C|\bar{q}|^2 + 2C|u|^2$$

$$\text{so } \int_{t_0}^{t_0+\delta} U(q) dt \leq A\delta + 2C\delta(|a|^2 + |b|^2) + C\delta^2 \int_{t_0}^{t_0+\delta} |\dot{u}|^2 dt$$

$$\leq A\delta + 2C\delta(|a|^2 + |b|^2) + 2C\delta(a-b)^2 + 2C\delta^2 \int_{t_0}^{t_0+\delta} |\dot{q}|^2 dt.$$

Take  $\delta$  small so that  $2C\delta^2 < \epsilon$ .  $\square$

Corollary: If  $\epsilon < \nu$ , (1)  $S(\tau)$  bounded below

(2)  $S_\epsilon$  level sets bounded in  $H^1$ .

(if  $S(\tau) \leq \tau, \|\tau\|_{H^1} \leq f(\tau)$ )

Hamilton's Principle: Solutions to Newton's equations  
are critical pts of the action.

(if  $\delta$  small enough set "least action")

$$\frac{1}{2} \langle M \underline{v}(t+dt), \underline{v}(t+dt) \rangle \approx \frac{1}{2} \langle M \underline{v}, \underline{v} \rangle + \frac{1}{2} \langle M \underline{v}, \underline{a} \cdot dt \rangle$$

to 1<sup>st</sup> order

$$+ \frac{1}{2} \langle M \underline{a} dt, \underline{v} \rangle + \frac{1}{2} \langle M \underline{a}, \underline{a} \rangle (dt)^2$$

$$\underline{v}(t+dt) \approx \underline{v}(t) + \underline{a}(t) dt$$

$$\approx \frac{1}{2} \langle M \underline{v}, \underline{v} \rangle + (\frac{1}{2} \langle M \underline{a}, \underline{v} \rangle + \frac{1}{2} \langle M \underline{v}, \underline{a} \rangle) dt$$

$$\approx \frac{1}{2} \langle M \underline{v}, \underline{v} \rangle + \langle M \underline{a}, \underline{v} \rangle dt$$

$$\frac{d(\tau)}{dt} = \langle M \underline{a}, \underline{v} \rangle = \langle \vec{F}, \underline{v} \rangle$$

(if  $\ddot{y} = f$  then  $(\dot{y})^2 = 2\dot{y}\ddot{y} = 2\dot{y}f$ )

say  $f = f(y)$  then

$$\dot{y}\ddot{y} = f(y)\dot{y}$$

$$\frac{d}{dt}(\frac{1}{2}\dot{y}^2) \quad \frac{d}{dt}u(y) \quad \text{if } \frac{dy}{dt} = f$$

Leibnitz rule  $(fg)' = f'g + fg'$

$$\langle f(x+\Delta x), g(x+\Delta x) \rangle \approx \dots$$

$$f(\underline{v}) = \underline{v}^T A \underline{v} \quad \text{A matrix}$$

$$f(\underline{v} + \underline{\delta}) = (\underline{v} + \underline{\delta})^T A (\underline{v} + \underline{\delta}) = \underline{v}^T A \underline{v} + \underline{\delta}^T A \underline{v} + \underline{v}^T A \underline{\delta} + \underline{\delta}^T A \underline{\delta}$$

$$= \underline{v}^T A \underline{v} + \underline{v}^T A^T \underline{d} + \underline{v}^T A \underline{d} + o(|\delta|^2)$$

to 1<sup>st</sup> order

$$= f(\underline{v}) + (\underline{v}^T (A + A^T)) \cdot \underline{d} + o(|\delta|^2)$$