

## Chapter 1, Exercise 5

A set  $\Omega$  is said to be *pathwise connected* if any two points in  $\Omega$  can be joined by a (piecewise-smooth) curve contained entirely in  $\Omega$ . The purpose of this exercise is to prove that an *open* set  $\Omega$  is pathwise connected if and only if  $\Omega$  is connected.

### Part (a)

Suppose first that  $\Omega$  is open and pathwise connected, and that it can be written as  $\Omega = \Omega_1 \cup \Omega_2$  where  $\Omega_1$  and  $\Omega_2$  are disjoint, non-empty open sets. Choose two points  $w_1 \in \Omega_1$  and  $w_2 \in \Omega_2$  and let  $\gamma$  denote a curve in  $\Omega$  joining  $w_1$  to  $w_2$ . Consider a Parameterization  $z : [0, 1] \rightarrow \Omega$  of this curve with  $z(0) = w_1$  and  $z(1) = w_2$ , and let

$$t^* = \sup_{0 \leq t \leq 1} \{t : z(s) \in \Omega_1 \text{ for all } 0 \leq s < t\}.$$

Arrive at a contradiction by considering the point  $z(t^*)$

### Solution

As suggested, we consider the point  $z(t^*)$ . We ask the question: which of  $\Omega_1$  and  $\Omega_2$  contains this point? Evidently, this point is not in  $\Omega_1$ : if  $z(t^*)$  is in  $\Omega_1$ , then, because  $\Omega_1$  is open, there is an open ball  $B$  containing  $z(t^*)$ . Since  $z$  is continuous, it follows that  $z^{-1}(B)$  is open as a subset of  $[0, 1]$ . Thus (assuming  $t^* < 1$ )  $z^{-1}(\Omega_1)$  contains points to the right of  $t^*$ , which is impossible. If  $t^* = 1$ , then there is a sequence of points in  $\Omega_1$  that converges to  $z(1) \in \Omega_2$ , contradicting the assumption that  $\Omega_2$  is open.

If we assume instead that  $z(t^*) \in \Omega_2$ , we recognize that  $z(t) \in \Omega_2$  if and only if  $t > t^*$ . Thus  $t^*$  is the infimum of all values of  $t$  such that  $z(t) \in \Omega_2$ , and we can use the same argument as in the previous paragraph to conclude  $z(t^*) \notin \Omega_2$ . Since  $z(t^*) \in \Omega_1 \cup \Omega_2$ , this is a contradiction.

### 0.1 Part b

Conversely, suppose that  $\Omega$  is open and connected. Fix a point  $w \in \Omega$  and let  $\Omega_1 \subset \Omega$  denote the set of all points that can be joined to  $w$  by a curve contained in  $\Omega$ . Also, let  $\Omega_2 \subset \Omega$  denote the set of all points that cannot be joined to  $w$  by a curve in  $\Omega$ . Prove that both  $\Omega_1, \Omega_2$  are open, disjoint, and their union is  $\Omega$ . Finally, since  $\Omega_1$  is nonempty (why?) conclude that  $\Omega = \Omega_1$  as desired.

#### 0.1.1 Solution

Evidently  $\Omega_1 \cup \Omega_2 = \Omega$  and  $\Omega_1$  is disjoint from  $\Omega_2$ . The only thing that remains to be shown is that both  $\Omega_1$  and  $\Omega_2$  are open.

Let  $w_1 \in \Omega_1$ . Because  $\Omega$  is open,  $\Omega$  contains an open ball  $B$  centered at  $w_1$ . It is obvious that if  $w^* \in B$ , then there is a path  $z^*$  connecting  $w_1$  and  $w^*$ . Let  $z_1$  be a curve joining  $w$  to  $w_1$ . Then consider the curve defined by

$$z(t) = \begin{cases} z(2t) & \text{if } 0 \leq t < 1/2 \\ z(2t - 1) & \text{if } 1/2 \leq t \leq 1 \end{cases}$$

Then  $z$  is a continuous, piecewise smooth curve that connects  $w$  to  $w^*$ . It follows that  $B \subset \Omega_1$  and that  $\Omega_1$  is open.

Now, let  $w_2 \in \Omega_2$ . Because  $\Omega$  is open  $\Omega$  contains an open ball  $B$  centered at  $w_2$ . Let  $w^* \in B$ . If there were a curve  $z_2$  that connected  $w$  to  $w^*$ , then we could, as in the previous paragraph, find a curve connecting  $w$  to  $w_2$  by concatenating the path from  $w$  to  $w^*$  and the path from  $w^*$  to  $w_2$ . Thus  $w_2 \in \Omega_1$ , which is a contradiction.

Thus  $\Omega$  can be written as  $\Omega_1 \cup \Omega_2$  for disjoint open sets  $\Omega_1$  and  $\Omega_2$ . Since  $\Omega$  is connected, either  $\Omega_1 = \Omega$  or  $\Omega_2 = \Omega$ . But  $w \in \Omega_1$ , so  $\Omega_1$  is nonempty and therefore  $\Omega_1 = \Omega$ .

## Chapter 1, Exercise 7

The family of mappings introduced here plays an important role in complex analysis. These mappings, sometimes called Blaschke factors, will reappear in the various applications in later chapters.

### Part a

Let  $z, w$  be two complex numbers such that  $\bar{z}\omega \neq 1$ . Prove that

$$\left| \frac{w - z}{1 - \bar{w}z} \right| < 1 \text{ if } |z| < 1 \text{ and } |w| < 1$$

and also that

$$\left| \frac{w - z}{1 - \bar{w}z} \right| = 1 \text{ if } |z| = 1 \text{ or } |w| = 1.$$

[Hint: Why can we assume that  $z$  is real? It then suffices to prove that

$$(r - w)(r - \bar{w}) \leq (1 - rw)(1 - r\bar{w})$$

with equality for appropriate  $r$  and  $|w|$ .]

### Solution

Write  $z = re^{i\theta}$ . Then

$$\begin{aligned}\left| \frac{w - z}{1 - \bar{w}z} \right| &= \left| \frac{w - re^{i\theta}}{1 - \bar{w}re^{i\theta}} \right| \\ &= \left| e^{i\theta} \frac{we^{-i\theta} - r}{1 - we^{-i\theta}r} \right| \\ &= \left| \frac{we^{-i\theta} - r}{1 - we^{-i\theta}r} \right|.\end{aligned}$$

Letting  $w^* = we^{-i\theta}$  this becomes

$$\left| \frac{w^* - r}{1 - w^*r} \right|$$

so it is enough to consider the case in which  $z = r$  is a real number. Note further that replacing  $w$  by  $\bar{w}$  is equivalent to taking the complex conjugate of the entire fraction. So it is enough to show

$$\left( \frac{w - r}{1 - wr} \right) \left( \frac{\bar{w} - r}{1 - \bar{w}r} \right) \leq 1$$

or equivalently that

$$(w - r)(\bar{w} - r) \leq (1 - wr)(1 - \bar{w}r).$$

Suppose first that  $w$  and  $r$  both have absolute value less than 1. Let  $w = se^{i\theta}$ . Pull out  $e^{i\theta}$  and  $e^{-i\theta}$  from the first and second factor on the left turns the left side into  $(s - r)^2$ . Doing the same on the right side turns the expression to  $(1 - sr)^2$ . Since  $s, r < 1$ , we have that  $sr < \min(|s|, |r|) \leq \max(|s|, |r|) < 1$  so  $(s - r)^2$  is clearly smaller than  $(1 - sr)^2$  and we are done.

If  $s$  is instead equal to 1, then  $s - r = 1 - r = 1 - sr$ , and if  $r = 1$ , then  $s - r = s - 1 = -(1 - s) = -(1 - sr)$ , so we have equality in these cases.

### Part b

Prove that for a fixed  $w$  in the unit disc  $\mathbb{D}$ , the mapping

$$F : z \mapsto \frac{w - z}{1 - wz}$$

satisfies the following conditions:

1.  $F$  maps the unit disc to itself (that is  $F : \mathbb{D} \rightarrow \mathbb{D}$ ), and is holomorphic
2.  $F$  interchanges 0 and  $w$ , namely  $F(0) = w$  and  $F(w) = 0$ .
3.  $|F(z)| = 1$  if  $|z| = 1$ .
4.  $F : \mathbb{D} \rightarrow \mathbb{D}$  is bijective. [Hint: Calculate  $F \circ F$ .]

### Solution

(i) and (iii) directly follow from part (a) of the problem except for the holomorphy, which is clear except when  $z\bar{w} = 1$ . This can only happen if  $|w| = 1$  and  $z = \frac{1}{\bar{w}}$ . It is seen that  $F$  has a removable singularity at  $z = \frac{1}{\bar{w}}$  with value  $w$ . (ii) follows by plugging in: the numerator is clearly 0 when  $z = w$ , and plugging in  $z = 0$  makes the numerator equal to  $w$  and the denominator equal to 1. All that remains to be seen is that  $F$  is bijective on  $\mathbb{D}$ . Consider  $F \circ F(z)$ . This is

$$\frac{w - \frac{w-z}{1-\bar{w}z}}{1 - \bar{w} \frac{w-z}{1-\bar{w}z}}.$$

We simplify this:

$$\begin{aligned} & \frac{w - \frac{w-z}{1-\bar{w}z}}{1 - \bar{w} \frac{w-z}{1-\bar{w}z}} \\ &= \frac{w - \frac{w-z}{1-\bar{w}z}}{1 - \frac{\bar{w}(w-z)}{1-\bar{w}z}} \\ &= \frac{w(1-\bar{w}z) - (w-z)}{1-\bar{w}z - \bar{w}(w-z)} \\ &= \frac{w - |w|^2z - w + z}{1-\bar{w}z - |w|^2 + \bar{w}z} \\ &= \frac{z(1-|w|^2)}{1-|w|^2} \\ &= z \end{aligned}$$

so the function  $F$  is an involution and therefore bijective on  $\mathbb{D}$ .

## Chapter 1, Exercise 13

Suppose that  $f$  is holomorphic in an open set  $\Omega$ . Prove that in any one of the following cases:

1.  $\operatorname{Re}(f)$  is constant;
2.  $\operatorname{Im}(f)$  is constant;
3.  $|f|$  is constant; one can conclude that  $f$  is constant.

### Solution

Suppose that  $\operatorname{Re}(f)$  is constant. Then  $f(x, y) = a + iv(x, y)$  for  $z = x + iy$ . Then we consider the PDEs from the Cauchy-Riemann equations:

$$0 = \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$$

So  $\frac{\partial v}{\partial y}$  is zero, and thus  $v$  depends only on  $x$  and

$$0 = \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

so  $\frac{\partial v}{\partial x}$  is zero and thus  $v$  depends only on  $y$ . Since  $v$  cannot depend on either  $x$  or  $y$ , it follows that  $v$  is constant.

The same argument works if  $\text{Im}(f)$  is constant. Alternatively, if  $\text{Im}(f)$  is constant, then  $\text{Re}(if)$  is constant and so  $if$ , and thus  $f$ , is constant.

Now suppose  $|f|$  is constant. Writing  $f(z) = u(x, y) + iv(x, y)$  for  $z = x + iy$ , we then have that  $u(x, y)^2 + v(x, y)^2$  is constant. In particular, this implies that  $\frac{\partial u}{\partial x} = -\frac{\partial v}{\partial x}$  and that  $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial y}$ . Thus we can again use the Cauchy-Riemann equations:

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = -\frac{\partial v}{\partial x}$$

and

$$\frac{\partial u}{\partial x} = -\frac{\partial u}{\partial y} = \frac{\partial v}{\partial x}$$

So we get  $\frac{\partial u}{\partial x}$  is equal to both  $\frac{\partial v}{\partial x}$  and  $-\frac{\partial v}{\partial x}$ , showing that both are equal to zero, and by the same logic as before,  $f$  is constant.