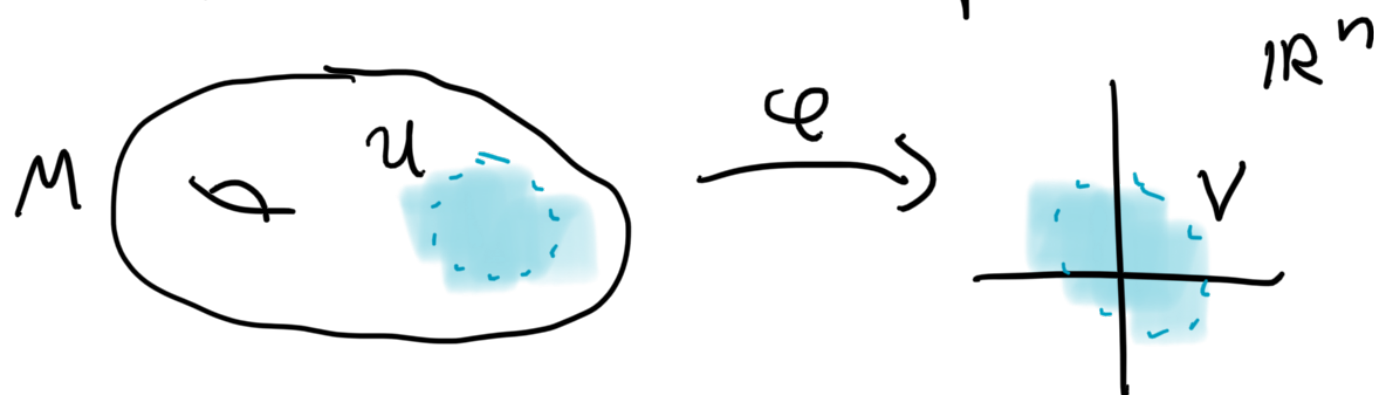


# Smooth Manifolds

Def: Topological manifold  $M$  of dim  $n$  is a paracompact Hausdorff space s.t. each pt has a nbhd homeomorphic to an open set in  $\mathbb{R}^n$ .

Coord chart:  $(U, \varphi)$  with  $U \subseteq M$  open and  $\varphi: U \rightarrow V \subseteq \mathbb{R}^n$  homeomorphism.

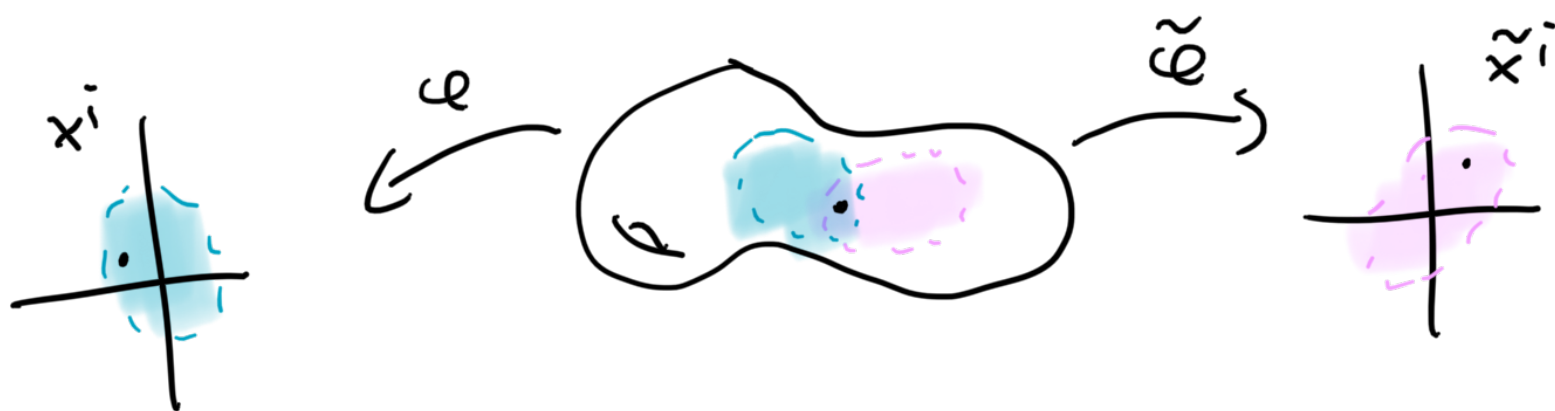


Atlas: Collection  $\mathcal{A}$  of coord charts covering  $M$ .

$$M = \bigcup_{\alpha \in \mathcal{A}} U_\alpha.$$

Coord transformation:  $(U, \varphi), (\tilde{U}, \tilde{\varphi})$

$\tilde{\varphi} \circ \varphi^{-1}$  is coord transformation.



Notation:  $\varphi(p) = (x^1, \dots, x^n) \in \mathbb{R}^n$ .

Write:  $\tilde{x}^i = f^i(x)$ ,  $f = \tilde{\varphi} \circ \varphi^{-1}$   
 $f: x(U \cap \tilde{U}) \rightarrow \tilde{x}(U \cap \tilde{U})$ .

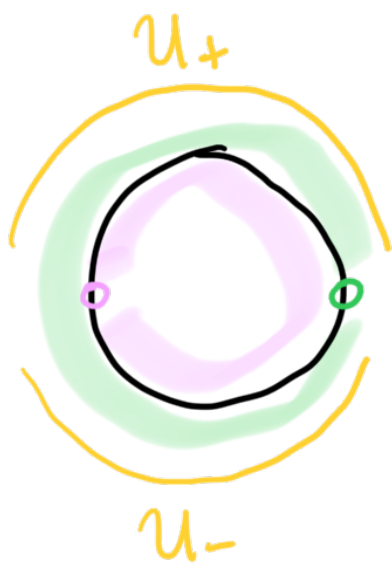
Def: Smooth mfd is topological mfd with a smooth structure (defined below).

Smooth Structure: Equivalence class of atlases st. coord transformations  $\tilde{x}^i = f^i(x)$  are smooth with smooth inverse.

Equiv relation:  $\mathcal{A} \sim \mathcal{A}'$  if  $\forall (U, \varphi) \in \mathcal{A}$   
 $(V, \psi) \in \mathcal{A}'$

$\Rightarrow \varphi \circ \psi^{-1}: \psi(U \cap V) \rightarrow \varphi(U \cap V)$   
 is smooth with smooth inverse.

ex)  $S^1 = \{ e^{i\theta} : \theta \in [0, 2\pi] \}$



$S^1 = U \cup V$

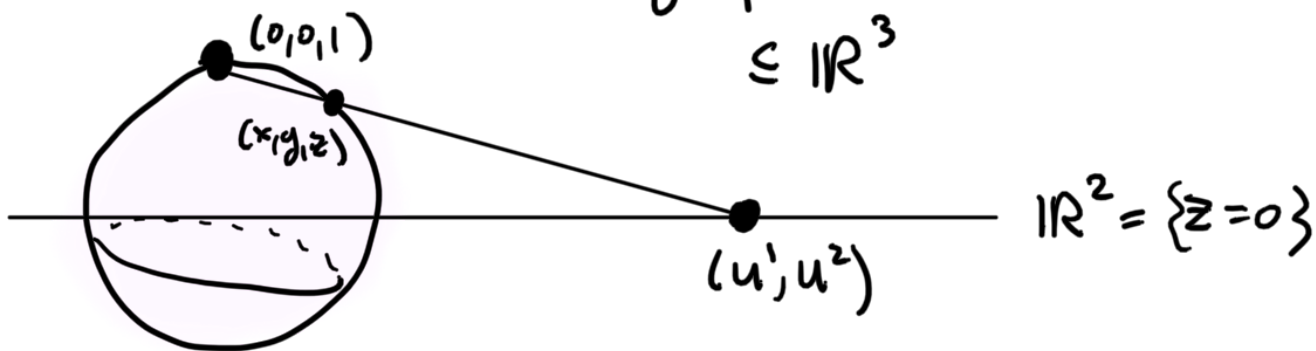
$U = \{ e^{i\theta} : \theta \in (0, 2\pi) \}$

$V = \{ e^{i\varphi} : \varphi \in (-\pi, \pi) \}$

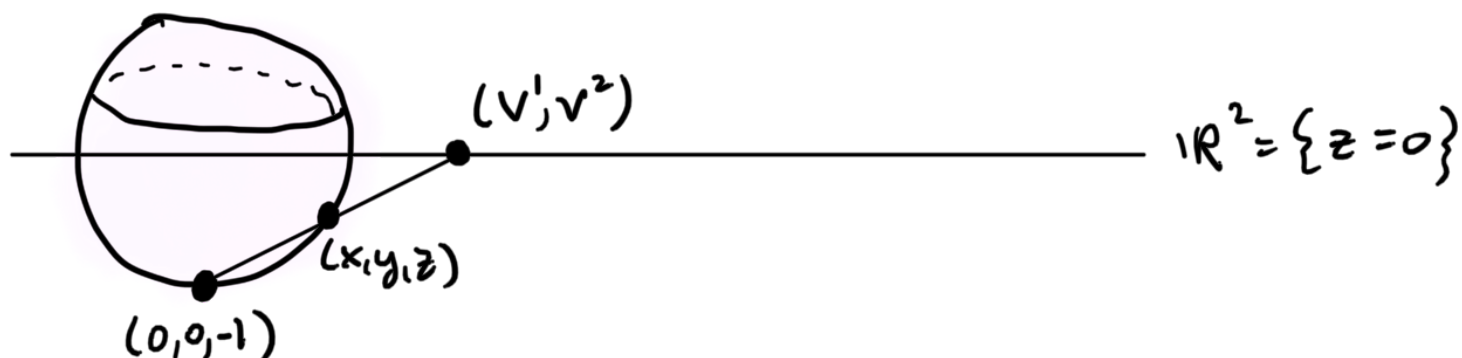
$U \cap V = U_+ \sqcup U_-$

Coord trans:  $\begin{cases} \varphi = \theta & \text{on } U_+ \\ \varphi = \theta - 2\pi & \text{on } U_- \end{cases}$

ex)  $S^2$  in stereographic coords



$(u^1, u^2) = \left( \frac{x}{1-z}, \frac{y}{1-z} \right)$



$(v^1, v^2) = \left( \frac{x}{1+z}, \frac{y}{1+z} \right)$

Exercise: coord trans is

$$(v^1, v^2) = \left( \frac{u^1}{(u^1)^2 + (u^2)^2}, \frac{u^2}{(u^1)^2 + (u^2)^2} \right)$$

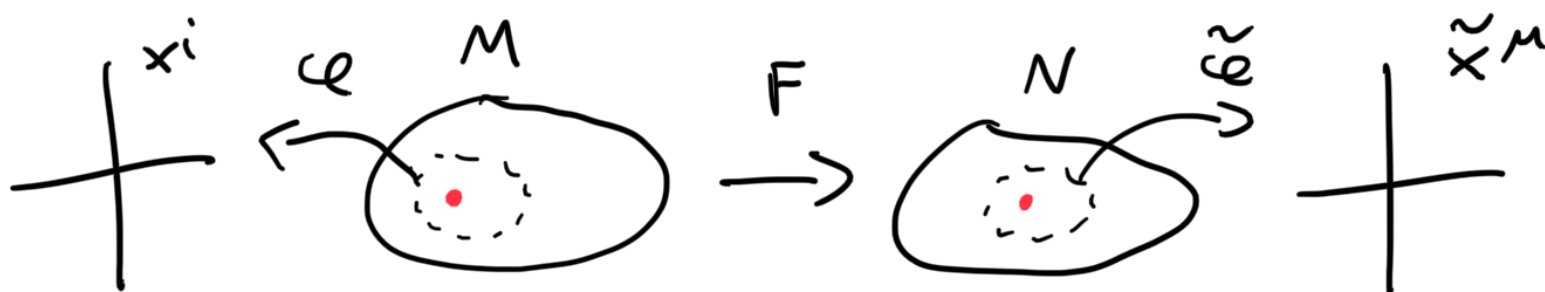
$$S^2 = U \cup V, \quad \begin{matrix} (u, u^i) \\ (v, v^i) \end{matrix} \quad \begin{matrix} U = S^2 \setminus (0, 0, 1) \\ V = S^2 \setminus (0, 0, -1) \end{matrix}$$

Def: Let  $F: M \rightarrow N$  be map between mfd.

Let  $p \in M$ ,  $(u, x^i)$  coords near  $p$   
 $(\tilde{u}, \tilde{x}^M)$  coords near  $F(p)$ .

Near  $p$ ,  $F$  appears as:  $F^M(x^i) = \tilde{\varphi} \circ F \circ \varphi^{-1}$

$F$  is smooth if all such  $F^M(x^i)$  are smooth.



ex) Notion of smooth path  $\gamma: (-\epsilon, \epsilon) \rightarrow M$ .

Defn: Vector field: cover  $M^n$  by coord charts:  
 $M = \cup U_i$

A VF is defined by collection of smooth vector functions

$$V_u: U \rightarrow \mathbb{R}^n, \quad V_u = (V_u^1, \dots, V_u^n).$$

st. on overlaps  $V: U \rightarrow \mathbb{R}^n, \tilde{V}: \tilde{U} \rightarrow \mathbb{R}^n, U \cap \tilde{U} \neq \emptyset$

there holds:  $\tilde{V} = \frac{\partial \tilde{x}}{\partial x} V$  on  $U \cap \tilde{U}$  matrix notation

$\tilde{V}^i = \frac{\partial \tilde{x}^i}{\partial x^p} V^p$  on  $U \cap \tilde{U}$  index notation

e.g. 
$$\begin{pmatrix} \tilde{V}^1 \\ \tilde{V}^2 \end{pmatrix} = \begin{pmatrix} \frac{\partial \tilde{x}^1}{\partial x^1} & \frac{\partial \tilde{x}^1}{\partial x^2} \\ \frac{\partial \tilde{x}^2}{\partial x^1} & \frac{\partial \tilde{x}^2}{\partial x^2} \end{pmatrix} \begin{pmatrix} V^1 \\ V^2 \end{pmatrix}$$

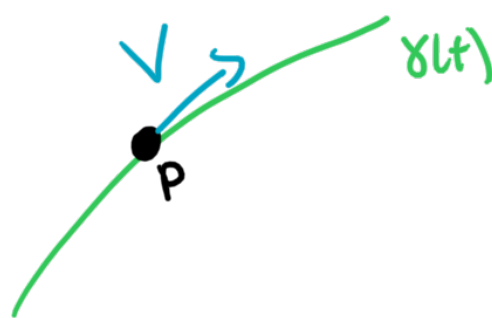
Notation:  $V = v^i \frac{\partial}{\partial x^i}$   $\leftrightarrow$   $V = \begin{pmatrix} v^1 \\ \vdots \\ v^n \end{pmatrix}$

↑ components      ↙ basis

Chain rule:  $v^p \frac{\partial}{\partial x^p} = v^p \frac{\partial \tilde{x}^i}{\partial x^p} \frac{\partial}{\partial \tilde{x}^i} = \tilde{v}^i \frac{\partial}{\partial \tilde{x}^i}$

If  $V$  is vector field,  $V(p) \in T_p M$  is tangent vector.  
 $p \in M,$

Motivation for defn: Let  $\gamma: (-\epsilon, \epsilon) \rightarrow M$  be smooth path,  $\gamma(0) = p$ .



$(U, x), (\tilde{U}, \tilde{x})$  coords near  $p$ .

Over  $U, \gamma = x^i(t)$ .

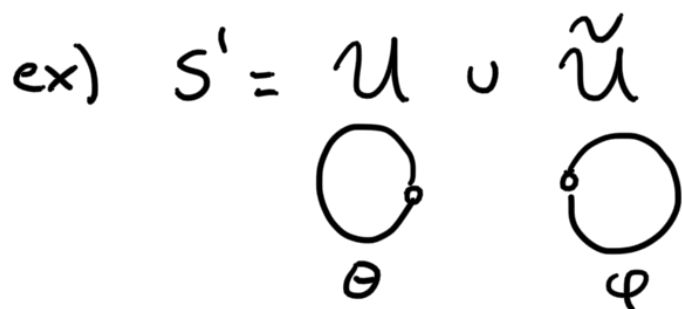
$V^i = \frac{dx^i}{dt}(0)$ . defines tangent vector

Over  $\tilde{U}$ :

$\tilde{V}^i = \frac{d\tilde{x}^i}{dt}(0) = \frac{\partial \tilde{x}^i}{\partial x^p} \frac{dx^p}{dt}(0) = \frac{\partial \tilde{x}^i}{\partial x^p} V^p$

Conversely, every  $V \in T_p M$  comes from  $V = \dot{\gamma}(0)$ .  
 e.g. in local coords

$\gamma(t) = \begin{pmatrix} p^1 \\ \vdots \\ p^n \end{pmatrix} + t \begin{pmatrix} v^1 \\ \vdots \\ v^n \end{pmatrix}$



$\mathcal{Q} = \begin{cases} \theta \\ \theta - 2\pi \end{cases}$

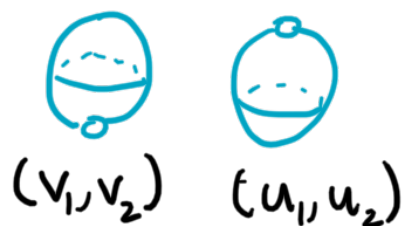
Can define  $V$  vector field:  $\{(U, v=1), (\tilde{U}, \tilde{v}=1)\}$

$1 = \frac{\partial \mathcal{Q}}{\partial \theta} \cdot 1$

✓ other notation:  
 $V = \frac{\partial}{\partial \theta} = \frac{\partial}{\partial \phi}$



ex)  $S^2 = \mathcal{U} \cup \tilde{\mathcal{U}}$



$$(v_1, v_2) = \frac{1}{u_1^2 + u_2^2} (u_1, u_2)$$

Can define  $X$  vector field on  $\tilde{\mathcal{U}}$ :  $\tilde{X} = \frac{\partial}{\partial u_1}$ .

How to extend to  $\mathcal{U}$ ?

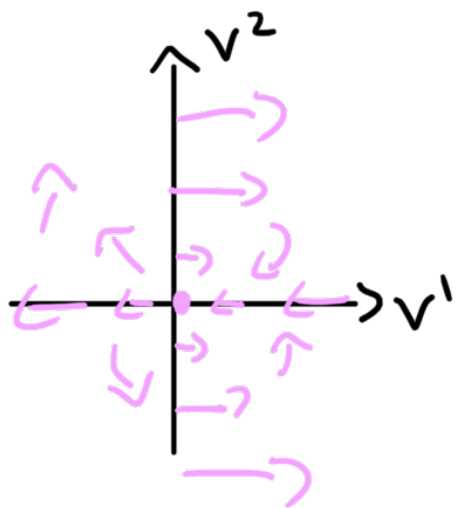
i.e.  $\tilde{X} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ .

Exercise:

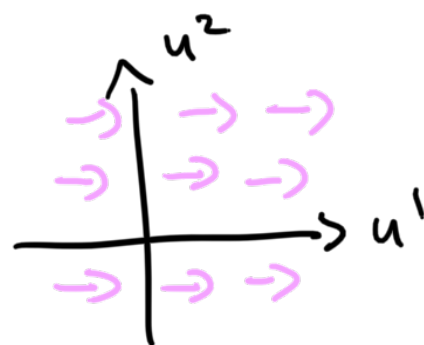
$$\frac{\partial v}{\partial u} = \begin{pmatrix} v_2^2 - v_1^2 & -2v_1v_2 \\ -2v_1v_2 & v_1^2 - v_2^2 \end{pmatrix}$$

$$\begin{bmatrix} \frac{\partial v}{\partial u} \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} v_2^2 - v_1^2 \\ -2v_1v_2 \end{pmatrix} = X. \quad X = \frac{\partial v}{\partial u} \tilde{X}$$

$X$  is defined by:  $\left\{ \left( \mathcal{U}, \begin{pmatrix} v_2^2 - v_1^2 \\ -2v_1v_2 \end{pmatrix} \right), \left( \tilde{\mathcal{U}}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right) \right\}$



only zero at North pole



project through North pole