

# Jacobi Fields II

Def:

$$S_c(t) = \begin{cases} \frac{1}{\sqrt{c}} \sin \sqrt{c} t & c > 0 \\ t & c = 0 \\ \frac{1}{\sqrt{c}} \sinh \sqrt{c} t & c < 0 \end{cases}$$

- Lem:
- $(M, g)$  with constant sectional curv  $c$
  - $\gamma$  unit speed geodesic
  - $J(t)$  Jacobi field with  $\langle J(t), \dot{\gamma}(t) \rangle_g \equiv 0$  and  $J(0) = 0$ .

$$\Rightarrow |J(t)| = |S_c(t)| |D_t J(0)|.$$

Pf: const sec<sub>g</sub> means:

$$R(V, W)X = c(\langle W, X \rangle V - \langle V, X \rangle W)$$

Jacobi eqn:  $D_t^2 J + R(J, \dot{\gamma})\dot{\gamma} = 0$  becomes

$$D_t^2 J + cJ = 0.$$

Let  $E(t)$  be parallel transport of  $E(0) = D_t J(0)$   
 $D_t E \equiv 0$ .

Try  $J(t) = u(t) E(t)$ .

Get ODE:  $\ddot{u}(t) + cu(t) = 0$ .

$$u(0) = 0.$$

$$D_t J(0) = \underbrace{\dot{u}(0)}_{=1} E(0)$$

$u(t) = S_c(t)$  solves constraints.

$$\begin{aligned} \Rightarrow |J(t)| &= |S_c(t)| |E(t)| \\ &= |S_c(t)| |D_t J(0)| \quad \square \end{aligned}$$



parallel  $E$  preserves length  
 $\downarrow \partial_t |E|^2 = 2 \langle D_t E, E \rangle = 0$ .

Thm: •  $(M, g)$  with  $\text{sec}_g = c$ .

•  $p \in M$ ,  $(U, x^i)$  normal coords at  $p$ ,  $r = (\sum (x^i)^2)^{1/2}$

Then: on  $U \setminus \{p\}$ , metric appears as

$$g = dr^2 + s_c(r)^2 \hat{g}$$

with  $\hat{g} = \pi^* g_{S^{n-1}}$ ,  $\pi(x) = \frac{x}{|x|}$ ,  $\pi: \mathbb{R}^n \setminus \{0\} \rightarrow S^{n-1}$ .

Cor: Constant curvature metrics look the same.

(local uniqueness) (geometries with  $\text{sec}_g = c$  are locally isometric)

Recall model geometries:

(1)  $(S^n, g_{S^n})$ :  $\text{sec}_{g_{S^n}} = c > 0$

(2)  $(\mathbb{R}^n, g_{\text{Euc}})$ :  $\text{sec}_{g_{\text{Euc}}} = 0$

(3)  $(H^n, g_{\text{Hyp}})$ :  $\text{sec}_{g_{\text{Hyp}}} = c < 0$

Thm: (Killing-Hopf)

$(M, g)$  complete, simply connected,  $\text{sec}_g = \text{const}$ ,  $n \geq 2$ .

$\Rightarrow (M, g)$  isometric to either  $S^n, \mathbb{R}^n, H^n$ .

Will not prove: see Lee chap 12.

Proof of local uniqueness  $g = dr^2 + s_c^2 \hat{g}$ :

Note: Euclidean metric in polar coords

$$g_{\text{Euc}} = dr^2 + r^2 \hat{g} \leftarrow \text{metric on sphere}$$

Proved earlier (using Gauss lemma) that in normal coords:

$$g = dr^2 + g^T \leftarrow \text{metric on } \{r = \text{const}\}$$

Let  $w \in T_q M$ ,  $\delta_{ij} w^i q^j = 0$ ,  $b = r(q)$ .

Need to show:  $\langle w, \frac{\partial}{\partial r} \rangle_{g_{\text{EUC}}} = 0$

$$g(w, w) = S_c(b)^2 \hat{g}(w, w)$$

$\hat{g} \leftarrow |w|_g^2$

To compute  $|w|_g^2$ , reach it by Jacobi field.

$$\gamma(t) = \left( \frac{q^1}{b}, \dots, \frac{q^n}{b} \right) t \quad \text{unit geo normal coords}$$

$$\gamma_s(t) = \left( t \left( \frac{q^1 + s w^1}{b} \right), \dots, t \left( \frac{q^n + s w^n}{b} \right) \right)$$

$\text{variation of geos}$

$$J(t) = \frac{d}{ds} \Big|_{s=0} \gamma_s$$

$$= \left( \frac{t}{b} w^1, \dots, \frac{t}{b} w^n \right) \quad \text{Jacobi field with } J(b) = w.$$

Note:  $\langle \dot{\gamma}, J \rangle(t) \equiv 0$

prev lemma

$$\Rightarrow |J(t)| = |S_c(t)| |D_t J(0)|.$$

$$\Rightarrow |w|_g^2 = |J(b)|_g^2$$

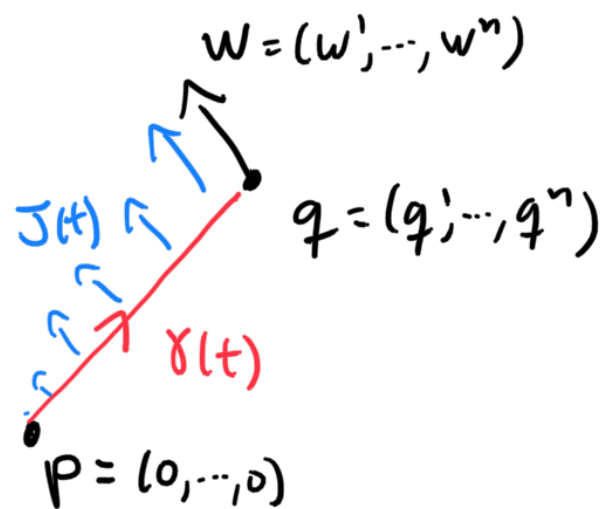
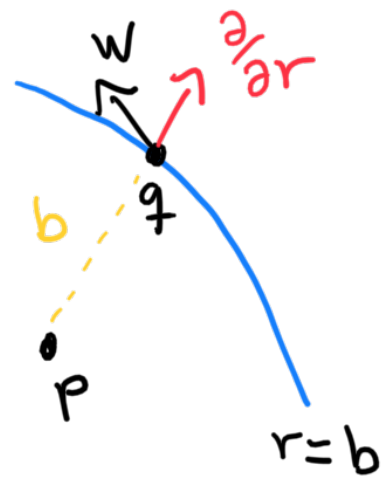
$$= (S_c(b))^2 |D_t J(0)|_g^2$$

$$= S_c(b)^2 \left| \left( \frac{w^1}{b}, \dots, \frac{w^n}{b} \right) \right|_g^2$$

$$= S_c(b)^2 |w|_{\hat{g}}^2 \quad \square$$

Polarization argument:

for  $g_1 = g_2$  just need  $|v|_{g_1} = |v|_{g_2} \quad \forall v$



Since Gauss lemma

$$g_{ij} \left( \frac{q^j}{b} t \right) \frac{q^i}{b} t \frac{w^j}{b} = \delta_{ij} \frac{q^i}{b} t \frac{w^j}{b} = 0 \leftarrow \delta_{ij} q^i w^j = 0.$$

$g(0) = \delta_{ij}$   
 $\Gamma(0) = 0$   
normal coords

NB:  $w = \dot{\gamma}(0)$ ,  $\gamma(t)$  on  $\{r=b\}$   
 $\pi_* w = \frac{d}{dt} \pi \circ \gamma = \frac{w}{b}$ ,  $\pi(x) = \frac{x}{|x|}$   
 $\hat{g}(w, w) = |\pi_* w|_{g_{\text{EUC}}}^2$

## Second Variation Formula

Let  $\gamma(t): [a, b] \rightarrow (M, g)$  be unit speed geodesic.

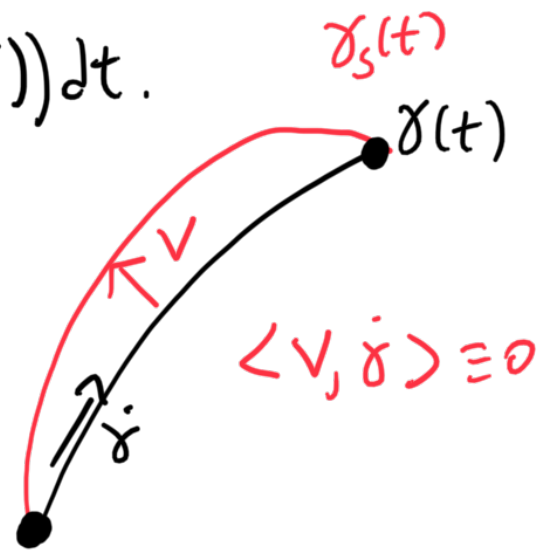
Let  $\gamma_s(t)$  be a family of curves for  $t \in [a, b]$   
with  $\gamma_0 = \gamma$ .  
 $s \in (-\epsilon, \epsilon)$ .

Let  $V = \frac{d}{ds} \Big|_{s=0} \gamma_s$  and assume  $\langle V, \dot{\gamma}_0 \rangle_g(t) \equiv 0$ .

Assume  $\gamma_s(a) = p, \gamma_s(b) = q \quad \forall s$ .

Then:

$$\frac{d^2}{ds^2} \Big|_{s=0} L_g(\gamma_s) = \int_a^b (|D_t V|^2 + R_m(V, \dot{\gamma}, V, \dot{\gamma})) dt.$$



Proof:

Recall:  $\gamma = \gamma_s(t)$

$$\dot{\gamma} = \frac{d}{dt} \gamma_s, \quad V = \frac{d}{ds} \gamma_s$$

$$D_t X^k = \partial_t X^k + \dot{\gamma}^i \Gamma_{il}^k X^l$$

$$D_s X^k = \partial_s X^k + V^i \Gamma_{il}^k X^l$$

$$\Rightarrow \frac{d}{ds} |\dot{\gamma}|^2 = 2 \langle D_s \dot{\gamma}, \dot{\gamma} \rangle$$

$$\stackrel{(*)}{=} 2 \langle D_t V, \dot{\gamma} \rangle$$

$$D_s \dot{\gamma} = D_t V$$

since  $\Gamma_{il}^k = \Gamma_{li}^k$

Next, recall:  $[\nabla_i, \nabla_j] w^l = R_{ijp}^l w^p$

$$[D_s, D_t] w^l = V^i \dot{\gamma}^j R_{ijp}^l w^p$$



$$\begin{aligned} \Rightarrow \frac{d^2}{ds^2} \langle \dot{\gamma}, \dot{\gamma} \rangle &= 2 \langle D_s D_t V, \dot{\gamma} \rangle + 2 \langle D_t V, D_s \dot{\gamma} \rangle \\ &= 2 \langle D_t D_s V, \dot{\gamma} \rangle \\ &\quad + 2 g_{\ell k} V^i \dot{\gamma}^j \dot{\gamma}^k R_{ijp}{}^\ell V^p \dot{\gamma}^k \\ &\quad + 2 |D_t V|^2 \end{aligned}$$

$$\frac{d^2}{ds^2} \langle \dot{\gamma}, \dot{\gamma} \rangle \stackrel{(**)}{=} 2 \frac{d}{dt} \langle D_s V, \dot{\gamma} \rangle + 2 |D_t V|^2 + 2 R(V, \dot{\gamma}, V, \dot{\gamma}).$$

$$\frac{d}{ds} \int_a^b |\dot{\gamma}| = \int_a^b \frac{1}{2} |\dot{\gamma}| \frac{d}{ds} \langle \dot{\gamma}, \dot{\gamma} \rangle$$

$\begin{matrix} V \swarrow \searrow \dot{\gamma} \\ \langle V, \dot{\gamma} \rangle = 0 \end{matrix}$   
 $= 0$  since  $\frac{d}{dt} \langle V, \dot{\gamma} \rangle$

$$\begin{aligned} \frac{d^2}{ds^2} \int_a^b |\dot{\gamma}| &\stackrel{(*)}{=} \int_a^b -|\dot{\gamma}|^{-3/2} \langle D_t V, \dot{\gamma} \rangle^2 \\ &+ \int_a^b \frac{1}{|\dot{\gamma}|} \left( \frac{d}{dt} \langle D_s V, \dot{\gamma} \rangle + |D_t V|^2 + R(V, \dot{\gamma}, V, \dot{\gamma}) \right) \end{aligned}$$

$= \langle D_t V, \dot{\gamma} \rangle + \langle V, D_t \dot{\gamma} \rangle$

Use:  $|\dot{\gamma}| = 1,$

$$\frac{d^2}{ds^2} \int_a^b |\dot{\gamma}| = \int_a^b \langle D_s V, \dot{\gamma} \rangle + \int_a^b |D_t V|^2 + R(V, \dot{\gamma}, V, \dot{\gamma}).$$

$= 0$  since

$$D_s V = 0 \text{ @ } a, b$$

$$V(a) = 0, \frac{d}{ds} \Big|_{s=0} V = 0$$

$$\dot{\gamma}_s(a) = p \quad \forall s$$

□

Denote:  $I(V, W) = \int_a^b (\langle D_t V, D_t W \rangle + R(V, \dot{\gamma}, W, \dot{\gamma})) dt$   
 for  $V, W$  vector fields  
 along  $\gamma(t)$ .

Thm: Let  $\gamma(t)$  be unit speed geodesic from  $p$  to  $q$ .

Suppose  $\gamma$  has an interior conjugate pt.

Then  $\gamma(t)$  is not length minimizing.

← from defn of conj pt

Pf: Write  $\gamma: [a, b] \rightarrow M$ , and  $J(t)$  a normal Jacobi field with  $J(a) = 0, J(c) = 0, a < c < b$ .

Goal: construct  $X^{\text{normal}}$  vector field along  $\gamma$  s.t.

$I(X, X) < 0$ . Then family

$\gamma_s(t) = \gamma(t) + sX$  is s.t.

2<sup>nd</sup> var formula

$\frac{d^2}{ds^2} \Big|_{s=0} L(\gamma_s) \stackrel{K}{=} I(X, X) < 0 \Rightarrow$  contradicts that  $\gamma$  is minimizer of length.

Consider:  $V(t) = \begin{cases} J(t) & a \leq t \leq c \\ 0 & c \leq t \leq b \end{cases}$

normal: if  $\langle J, \dot{\gamma} \rangle = 0 \Rightarrow \langle D_t J, \dot{\gamma} \rangle = 0$

$W(t) =$  normal VF s.t.:  $W(c) = -D_t J(c)$ .

$W(a) = 0$

$W(b) = 0$

$X_\epsilon(t) = V + \epsilon W$ .

Then:  $I(X_\epsilon, X_\epsilon) = I(V, V) + 2\epsilon I(V, W) + \epsilon^2 I(W, W)$ .

①  $I(V, V) = \int_a^c \langle D_t J, D_t J \rangle + R(J, \dot{\gamma}, J, \dot{\gamma})$

$$= \int_a^c \langle D_t J, J \rangle - \int_a^c \langle \underbrace{D_t^2 J + R(J, \dot{\gamma})\dot{\gamma}}_{=0 \text{ Jacobi field eqn}}, J \rangle$$

conjugate pts

$$= 0.$$

$$\textcircled{2} I(v, w) = \int_a^c \langle D_t J, w \rangle - \int_a^c \langle \underbrace{D_t^2 J + R(J, \dot{\gamma})\dot{\gamma}}_{=0}, w \rangle$$

$$= -|D_t J(c)|^2 \quad \begin{array}{l} w(c) = -D_t J(c) \\ w(a) = 0 \end{array}$$

$$\Rightarrow I(X_\varepsilon, X_\varepsilon) = \varepsilon \left[ -2|D_t J(c)|^2 + \varepsilon I(w, w) \right]$$

$< 0$  for  $\varepsilon$  small.

$|D_t J(c)| \neq 0$  because if  $J(c) = 0$   
 $D_t J(c) = 0$   
 then backwards uniqueness  
 of ODE  $\Rightarrow J \equiv 0$ . □