

Riemann Curvature

Let ∇ be Levi-Civita connection on TM.

Christoffel symbols Γ_{ij}^k . John Lee conventions

$$R_{ijk}^l = \partial_i \Gamma_{jk}^l - \partial_j \Gamma_{ik}^l + \Gamma_{ip}^l \Gamma_{jk}^p - \Gamma_{jp}^l \Gamma_{ik}^p$$

Special case of $E \rightarrow M$, $\nabla = d + A$ with $E = TM$,

$$A_i^k{}_j = \Gamma_{ij}^k, \quad F_{ij}^p{}_q = R_{ijq}^p. \quad \leftarrow \text{difference in conventions to match Lee's book}$$

Riemann curv
 \leftarrow tensor

$$R = R_{ijk}^l \in \Omega^2(\text{End } TM)$$

2-form indices End TM indices

More notation: for $x, y, z \in \Gamma(TM)$,

plug into 2-form \leftarrow act by endomorphism

$$R(x, y)z = \nabla_x \nabla_y z - \nabla_y \nabla_x z - \nabla_{[x, y]} z,$$

$$R(\partial_i, \partial_j)\partial_k = R_{ijk}^l \partial_l.$$

Consistency check:

$$R(\partial_i, \partial_j)\partial_k = \nabla_{\partial_i} \nabla_{\partial_j} \partial_k - \nabla_{\partial_j} \nabla_{\partial_i} \partial_k$$

$$= \nabla_{\partial_i} (\Gamma_{jk}^n \partial_n) - (i \leftrightarrow j)$$

$$= \partial_i \Gamma_{jk}^n \partial_n + \Gamma_{jk}^n \Gamma_{in}^r \partial_r - (i \leftrightarrow j)$$

$$= (\partial_i \Gamma_{jk}^l + \Gamma_{ip}^l \Gamma_{jk}^p - (i \leftrightarrow j)) \partial_l \quad \checkmark$$

$$= R_{ijk}^l \partial_l$$

Second covariant derivatives:

$$V = V^k \partial_k$$

$$\nabla_{\partial_i} V = (\nabla_i V^k) \partial_k$$

$$\nabla_i V^k = \partial_i V^k + \Gamma_{ij}^k V^j$$

Lee's book: $V^k /_{/p} = \nabla_p V^k$

Then $T_i^k := \nabla_i V^k$ defines $T \in \Gamma(TM \otimes T^*M)$.

$$\nabla_j T_i^k = \partial_j T_i^k + \Gamma_{jp}^k T_i^p - T_p^k \Gamma_{ji}^p \quad \text{covariant derivative}$$

Write: $\nabla_j \nabla_i V^k := \nabla_j T_i^k$

Lee's book:

$$V^k /_{/ij} = \nabla_j \nabla_i V^k$$



$$\nabla_{\partial_i} \nabla_{\partial_j} V \neq (\nabla_i \nabla_j V^k) \partial_k$$

In these notes

∇_{∂_i} acts on vectors: $\nabla_{\partial_i} V = (\nabla_i V^k) \partial_k$

∇_i acts on components of tensors:

$$\nabla_i V^k = \partial_i V^k + \Gamma_{ij}^k V^j$$

$$\nabla_{\partial_i} \nabla_{\partial_j} V = \nabla_{\partial_i} (\nabla_j V^k \partial_k)$$

$$= \partial_i (\nabla_j V^k) \partial_k + \nabla_j V^k \nabla_{\partial_i} \partial_k$$

$$= (\partial_i (\nabla_j V^k) + \Gamma_{il}^k \nabla_j V^l) \partial_k$$

vs:

$$\nabla_i \nabla_j V^k = \partial_i (\nabla_j V^k) - \underbrace{\Gamma_{ij}^l \nabla_l V^k}_{\text{new term}} + \Gamma_{il}^k \nabla_j V^l$$

new term

However, it is nevertheless true that

$$\nabla_i \nabla_j V^k - \nabla_j \nabla_i V^k = R_{ijp}^k V^p$$

check: $[\nabla_i, \nabla_j] V^k$

$$\begin{aligned}
&= \nabla_i \nabla_j V^k - \underbrace{(i\ j)}_{\text{switch}} \\
&= \partial_i \nabla_j V^k + \Gamma_{ip}^k \nabla_j V^p - \nabla_p V^k \underbrace{\Gamma_{ij}^p}_{\text{sym}} - \underbrace{(i\ j)}_{\text{antisym}} \\
&= \partial_i (\cancel{\partial_j V^k} + \Gamma_{jp}^k V^p) + \Gamma_{ip}^k (\partial_j V^p + \Gamma_{jl}^p V^l) - (i\ j) \\
&= \partial_i \Gamma_{jl}^k V^l + \underbrace{\Gamma_{jp}^k \partial_i V^p + \Gamma_{ip}^k \partial_j V^p + \Gamma_{ip}^k \Gamma_{jl}^p V^l}_{\text{sym in } (i, j)} - (i\ j) \\
&= (\partial_i \Gamma_{jl}^k + \Gamma_{ip}^k \Gamma_{jl}^p - (i\ j)) V^l \quad \checkmark
\end{aligned}$$

Def: $R_{ijpe} = g_{ek} R_{ijp}^k$

$$\begin{aligned}
R_m(x, y, z, w) &= \langle R(x, y)z, w \rangle_g \\
&= R_{ijpe} x^i y^j z^p w^e.
\end{aligned}$$

Remark: Given $p \in M$, can choose coords s.t.
 $g_{ij}(p) = \delta_{ij}$ identity.

Indeed: if $G = [g_{ij}(p)]$, take square root of matrix:

$$G = Q^T Q \Rightarrow \text{new coords } \tilde{x}^i = Q^i_j x^j$$

$$g_{ij} \mapsto \frac{\partial x^p}{\partial \tilde{x}^i} g_{pq} \frac{\partial x^q}{\partial \tilde{x}^j}$$

$$g_{ij}(p) \mapsto (Q^{-1})^T G Q^{-1} = I.$$

Q: Can we find coords s.t.
 $g_{ij}(x) \equiv \delta_{ij}$ in a nbhd of p ?

Thm: $Rm(g) \equiv 0 \iff \forall p \in M, \exists$ local coords (U, x^i)
s.t. $g_{ij} \equiv \delta_{ij}$ in U .

Pf: (\Leftarrow) trivial

(\Rightarrow) We proved earlier that
 $F \equiv 0 \implies \exists$ ON frame $\{e_a\}$ on U
with $\nabla e_a = 0$.

Since torsion = 0,
 $[e_a, e_b] = \nabla_{e_a} e_b - \nabla_{e_b} e_a = 0$.

By integrability thm, \exists coords x^i near p with
 $\frac{\partial}{\partial x^i} = e_i$.

$$g_{ij} = g(\partial_i, \partial_j) = g(e_i, e_j) = \delta_{ij}. \quad \square$$

Local Expression:

• Let $a \in M$. Suppose (x^i) are local coords s.t.

$$g_{ij}(a) = \delta_{ij}, \quad \partial_k g_{ij}(a) = 0 \quad (\text{e.g. take normal coords at } p)$$

$$\begin{aligned} \Rightarrow R_{ijpl}(a) &= g_{lk} \partial_i \Gamma_{jp}^k - g_{lk} \partial_j \Gamma_{ip}^k \\ &= \frac{1}{2} \partial_i (-\partial_l g_{jp} + \partial_j g_{lp} + \partial_p g_{jl}) - (ij) \end{aligned}$$

Recall: $\Gamma_{jp}^k = \frac{1}{2} g^{kq} (-\partial_q g_{jp} + \partial_j g_{qp} + \partial_p g_{jq})$

$$R_{ijpl}(a) = \frac{1}{2} (-\partial_i \partial_l g_{jp} + \partial_i \partial_p g_{jl} + \partial_j \partial_l g_{ip} - \partial_j \partial_p g_{il}) \quad (*)$$

Symmetries:

- $R_{ijpl} = -R_{jip l}$
- $R_{ijpl} = -R_{ijlp}$
- $R_{ijpl} = R_{plij}$
- $R_{ijpl} + R_{pijl} + R_{jpi l} = 0$

Check: directly in normal coords (U, x^i) (*)

For arbitrary coords (V, \tilde{x}^i) , transition fun $\frac{\partial x^a}{\partial \tilde{x}^i}$,

$$(R_V)_{ijpl} = \frac{\partial x^a}{\partial \tilde{x}^i} \frac{\partial x^b}{\partial \tilde{x}^j} \frac{\partial x^c}{\partial \tilde{x}^p} \frac{\partial x^d}{\partial \tilde{x}^l} (R_U)_{abcd}$$

if symmetry here,
then symmetry
for $(R_V)_{ijkl}$.

This transformation rule follows from:

$$[\nabla_i, \nabla_j] V^k = R_{ijp}{}^k V^p$$

indices here transform correctly \Rightarrow indices on $R_{ijp}{}^k$ transform correctly

$$[\nabla_i, \nabla_j] V^k \mapsto \frac{\partial x^a}{\partial \tilde{x}^i} \frac{\partial x^b}{\partial \tilde{x}^j} \frac{\partial \tilde{x}^k}{\partial x^c} [\nabla_a, \nabla_b] V^c$$

Bianchi identity:

$$\nabla_m R_{ijpl} + \nabla_l R_{ijmp} + \nabla_p R_{ijlm} = 0.$$

Claim: this is equiv to $d_A F = 0$ in general formalism $\nabla = d + A$ on bundle $E \rightarrow M$.

$$d_A F = \frac{1}{2} \nabla_\kappa F_{ij}^\alpha{}_\beta dx^\kappa \wedge dx^i \wedge dx^j. \quad (*)$$

Earlier, used $d_\nabla F = dF + A \wedge F - F \wedge A$.

For tensor, should use:

$$\begin{aligned} \nabla_\kappa F_{ij}^\alpha{}_\beta &= \partial_\kappa F_{ij}^\alpha{}_\beta - \underbrace{\Gamma_{\kappa i}^\rho}_{\text{sym}} F_{\rho j}^\alpha{}_\beta - \underbrace{\Gamma_{\kappa j}^\rho}_{\text{sym}} F_{i\rho}^\alpha{}_\beta \\ &\quad + A_\kappa^\alpha{}_\gamma F_{ij}^\gamma{}_\beta - F_{ij}^\alpha{}_\gamma A_\kappa^\gamma{}_\beta. \end{aligned} \quad (**)$$

Sub **(**)** into **(*)**:

$$d_A F = \frac{1}{2} (\partial_\kappa F_{ij}^\alpha{}_\beta - 0 - 0 + A_\kappa^\alpha{}_\gamma F_{ij}^\gamma{}_\beta - F_{ij}^\alpha{}_\gamma A_\kappa^\gamma{}_\beta) dx^\kappa \wedge dx^i \wedge dx^j$$

$\Rightarrow d_A F = dF + A \wedge F - F \wedge A$ consistent with **(**)**

$$\text{Bianchi } \Rightarrow 0 = \frac{1}{2} \nabla_\kappa F_{ij}^\alpha{}_\beta dx^\kappa \wedge dx^i \wedge dx^j$$

$$0 = \frac{1}{3!} (\nabla_\kappa F_{ij}^\alpha{}_\beta + \nabla_j F_{\kappa i}^\alpha{}_\beta + \nabla_i F_{j\kappa}^\alpha{}_\beta) dx^\kappa \wedge dx^i \wedge dx^j.$$

If $F_{ij}{}^q{}_\rho = R_{ij\rho}{}^q$, using $\nabla_\kappa g_{ij} = 0$ then:

$$0 = \nabla_\kappa R_{ij\rho}{}^q + \nabla_j R_{\kappa i\rho}{}^q + \nabla_i R_{j\kappa\rho}{}^q$$

$$\Rightarrow 0 = \nabla_\kappa R_{\rho l i j} + \nabla_j R_{\rho l \kappa i} + \nabla_i R_{\rho l j \kappa}. \quad \checkmark$$

Defn: Ricci curvature

$$R_{ij} = R^p{}_{ij}{}^p$$

basically just 1 way (up to sign) to contract without getting zero

Defn: Scalar curvature

$$S = g^{ij} R_{ij}$$

Note: $R_{ij} = R_{ji}$, also $R_{ij} = R_{ip}{}^p{}_j = -R_{ip}{}^p{}_j$.

Exercise: In spherical coords, metric on sphere of radius $a > 0$ appears as

$$g = a^2 \sin^2 \varphi d\theta \otimes d\theta + a^2 d\varphi \otimes d\varphi$$



Compute:

$$\Gamma_{ij}^\theta = \begin{bmatrix} 0 & \cos \varphi / \sin \varphi \\ \cos \varphi / \sin \varphi & 0 \end{bmatrix}$$

$$\Gamma_{ij}^\varphi = \begin{bmatrix} -\sin \varphi \cos \varphi & 0 \\ 0 & 0 \end{bmatrix}$$

$R_{\theta\varphi\varphi\theta} = a^2 \sin^2 \varphi$ (others determined by symmetry of curvature in 2D)

$$R_{ij} = \begin{bmatrix} \sin^2 \varphi & 0 \\ 0 & 1 \end{bmatrix}, \quad \text{note: } R_{ij} = a^{-1} g_{ij} \quad (\text{Einstein metric})$$

$$S = 2/a \quad \text{constant, positive scalar curvature}$$

Sectional curvature:

- $\Pi \subseteq T_p M$ 2D subspace, $\Pi = \text{span}(V, W)$

$$\text{Sec}(\Pi) = \text{Sec}(V, W) = \frac{R(V, W, W, V)}{(|V|^2|W|^2 - \langle V, W \rangle^2)}$$

obs: If $\text{Sec} \equiv c$, then:

$$Rm(X, Y, Z, W) = c (g(X, W)g(Y, Z) - g(X, Z)g(Y, W))$$

Indeed: Let $T = (\text{LHS}) - (\text{RHS})$.

$\Rightarrow T(X, Y, Y, X) \equiv 0$ + T satisfies symmetries of Riemann curv tensor.

$$0 = T(X+W, Y, Y, X+W)$$

$$= T(X, Y, Y, W) + T(W, Y, Y, X) \quad \text{Sym of Rm}$$

$$\Rightarrow 0 = T(X, Y, Y, W)$$

$$0 = T(X, Y+Z, Y+Z, W)$$

$$0 = T(X, Y, Z, W) + T(X, Z, Y, W) \quad *$$

Bianchi:

$$0 = T(X, Y, Z, W) + T(Z, X, Y, W) + T(Y, Z, X, W)$$

$$0 \stackrel{*}{=} T(X, Y, Z, W) - T(X, Z, Y, W) - T(Y, X, Z, W)$$

$$0 = 3T(X, Y, Z, W) \quad \checkmark$$

Note: Same argument shows: if $\text{Sec}_{g_1} = \text{Sec}_{g_2}$, then $Rm_{g_1} = Rm_{g_2}$.

Commutator Formulas:

We noted earlier that

$$[\nabla_i, \nabla_j] V^k = R_{ijp}{}^k V^p. \quad V \in \Gamma(TM)$$

This implies

$$[\nabla_i, \nabla_j] \alpha_k = R_{ijp}{}^k \alpha_p. \quad \alpha \in \Omega^1(M)$$

Indeed:

$$\begin{aligned} [\nabla_i, \nabla_j] \alpha_k &= [\nabla_i, \nabla_j] g_{kp} \alpha^p \\ &= g_{kp} [\nabla_i, \nabla_j] \alpha^p \\ &= R_{ij}{}^l{}_k \alpha_l. \end{aligned}$$

Note: For $f \in C^\infty(M, \mathbb{R})$, can define the Hessian of f :

$$\nabla_i \nabla_j f = \partial_i \partial_j f - \Gamma_{ij}{}^l \partial_l f. \quad \text{Note } \nabla_i \nabla_j f = \nabla_j \nabla_i f.$$

The Laplace operator is $\Delta f = \nabla^p \nabla_p f$, or:

$$\Delta = g^{pq} \nabla_p \nabla_q.$$

Can apply Δ on functions: $\Delta: C^\infty(M, \mathbb{R}) \rightarrow C^\infty(M, \mathbb{R})$

Can also apply Δ on tensors

$$\text{ex) } \Delta \nabla_i f = g^{pq} \nabla_p \nabla_q \nabla_i f$$

$$\alpha_i = \nabla_i f \\ \Delta \alpha_i := (\Delta \alpha)_i$$

apply Δ
to 1-form

$$\alpha_i = \nabla_i f.$$

$$= g^{pq} \nabla_p \nabla_i \nabla_q f$$

$$= g^{pq} \nabla_i \nabla_p \nabla_q f + g^{pq} R_{pi}{}^l{}_q \nabla_l f$$

$$= \nabla_i \Delta f + R_{il} \nabla^l f$$

$$\Delta: \Omega^1(M) \rightarrow \Omega^1(M)$$

This type of calculation is used in "Bochner formulas".

More examples of commuting covariant derivatives:

$$\text{ex) } [\nabla_i, \nabla_j] W^k_l = R_{ijp}^k W^p_l + R_{ij}^p{}_l W^k_p$$

$$\text{ex) } \nabla_i \nabla_j \nabla_k V^l \quad \text{commute } \nabla_i \nabla_j \nabla_k.$$

$$\begin{aligned} \nabla_i \nabla_j \nabla_k V^l &= \nabla_i (\nabla_k \nabla_j V^l + R_{j k p}^l V^p) \\ &= \nabla_i \nabla_k \nabla_j V^l + \nabla_i (R_{j k p}^l V^p) \\ &= \nabla_k \nabla_i \nabla_j V^l + R_{i k}^p{}_j \nabla_p V^l \\ &\quad + R_{i k p}^l \nabla_j V^p + \nabla_i (R_{j k p}^l V^p). \end{aligned}$$