

Problem Set 1: Riemann Curvature

Problem 1. Let (M, g) be a Riemannian manifold.

(a) Let (U, x^i) and $(\tilde{U}, \tilde{x}^i)$ be two coordinate charts with non-empty overlap. In coordinates x^i , denote the metric by g_{ij} . In coordinates $\tilde{x}^i$, denote the metric by $\tilde{g}_{ij}$. Write down the relation between g_{ij} and $\tilde{g}_{ij}$.

(b) Let Γ_{ij}^k denote the Christoffel symbols in coordinates x^i . Let $\tilde{\Gamma}_{ij}^k$ denote the Christoffel symbols in coordinates $\tilde{x}^i$. Show that

$$\tilde{\Gamma}_{ij}^k = \frac{\partial \tilde{x}^k}{\partial x^p} \Gamma_{rs}^p \frac{\partial x^r}{\partial \tilde{x}^i} \frac{\partial x^s}{\partial \tilde{x}^j} - \frac{\partial x^r}{\partial \tilde{x}^i} \frac{\partial x^s}{\partial \tilde{x}^j} \frac{\partial^2 \tilde{x}^k}{\partial x^r \partial x^s}.$$

We see that Christoffel symbols do not transform like a section of a vector bundle due to the additional second term.

(c) You can use this to show that the Levi-Civita connection is a well-defined connection. This means that if $V = V^i \partial_i$ is a vector field, then

$$W^i{}_k := \nabla_k V^i, \quad \nabla_k V^i = \frac{\partial}{\partial x^k} V^i + \Gamma_{kp}^i V^p$$

defines a section $\nabla V := W \in \Gamma(M, TM \otimes T^*M)$. For ∇V to define a section, it must satisfy

$$\tilde{\nabla}_\mu \tilde{V}^\nu = \frac{\partial x^a}{\partial \tilde{x}^\mu} \frac{\partial \tilde{x}^\nu}{\partial x^b} \nabla_a V^b$$

on overlaps of (U, x^i) and $(\tilde{U}, \tilde{x}^\mu)$. Here

$$\tilde{\nabla}_\mu \tilde{V}^\nu = \frac{\partial}{\partial \tilde{x}^\mu} \tilde{V}^\nu + \tilde{\Gamma}_{\mu\rho}^\nu \tilde{V}^\rho$$

is the expression for the connection over the coordinate chart $\tilde{U}$, and

$$\tilde{V}^\mu = \frac{\partial \tilde{x}^\mu}{\partial x^i} V^i$$

is the representation of the vector field over the chart $\tilde{U}$.

Problem 2. Compute the Riemann curvature, Ricci curvature, and scalar curvature of the Poincaré metric

$$g_{ij} = \frac{1}{y^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

on the upper half-plane $H = \{(x, y) \in \mathbb{R}^2 : y > 0\}$.

Problem 3. Compute the Riemann curvature, Ricci curvature, and scalar curvature of $\mathbb{S}^2$ with the metric induced by Euclidean space in spherical coordinates

$$f(\theta, \phi) = (\cos \theta \sin \phi, \sin \theta \sin \phi, \cos \phi).$$

Problem 4. Let (M, g) be a Riemannian manifold of dimension $n = 2$. Suppose that there is a coordinate system where the metric g can locally be written as

$$g_{ij} = e^{f(x,y)} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Show that

$$R_{ij} = -\frac{(f_{xx} + f_{yy})}{2} \delta_{ij}.$$

Problem 5. Equip the punctured sphere $S^2 \setminus \{N, S\}$ with spherical coordinates so that the metric appears as

$$g = d\varphi d\varphi + \sin^2 \varphi d\theta d\theta.$$

Show that the change of coordinates

$$u = \log \tan \frac{\varphi}{2}, \quad v = \theta$$

makes the metric conformal to the flat cylinder $\mathbb{R} \times S^1$.

Problem 6. The tangent bundle TS^2 of the 2-sphere $S^2 \subset \mathbb{R}^3$ can be described by

$$TS^2 = \{(x, v) \in S^2 \times \mathbb{R}^3 : \langle v, x \rangle = 0\}.$$

Here $\langle \cdot, \cdot \rangle$ is the Euclidean inner product in $\mathbb{R}^3$. A vector field on S^2 is a map

$$V : S^2 \rightarrow \mathbb{R}^3,$$

such that $\langle V(x), x \rangle = 0$. We can define a covariant derivative by

$$\nabla V = dV - \langle dV, x \rangle x.$$

We showed in lectures that ∇ is the Levi-Civita connection on (S^2, g) , where g is the metric induced on S^2 by the Euclidean metric in $\mathbb{R}^3$. Show that the Riemann curvature acts by

$$R(V, W)Z = \langle Z, W \rangle V - \langle Z, V \rangle W,$$

where V, W, Z are tangent vectors at x , meaning $\langle V, x \rangle = 0$.

Problem 7. Let (M, g) be a Riemannian manifold. Recall the local expression for the Laplacian on functions:

$$\Delta f = g^{ij} \partial_i \partial_j f - g^{ij} \Gamma_{ij}^k \partial_k f.$$

Let (U, x^i) be a local coordinate chart. Suppose $\Delta x^i = 0$ for all i . Such coordinates are called harmonic coordinates, or the harmonic gauge condition. Fix i, j , let $g_{ij} = g(\partial_{x^i}, \partial_{x^j})$, and view $g_{ij}(x)$ as a local function on U . Show that in these coordinates

$$\Delta g_{ij} = -2R_{ij} + \mathcal{O}(g, \partial g).$$

This is why the Ricci tensor can be viewed as the “Laplacian of the metric”. This expression was used by Choquet-Bruhat to apply PDE theory to the initial value problem in general relativity. This is also why the Ricci flow $\partial_t g = -2\text{Ric}(g)$ can be understood as a heat flow for the metric tensor. One way to prove this is to first show the Bochner formula

$$\Delta \langle \nabla f, \nabla h \rangle = 2 \langle \nabla^2 f, \nabla^2 h \rangle + \langle \nabla f, \nabla \Delta h \rangle + \langle \nabla \Delta f, \nabla h \rangle + 2R^{pq} \partial_q f \partial_p h.$$

and then apply it to $f = x^i$, $h = x^j$.

Problem 8. Let G be a Lie group with identity I . Denote for $g \in G$, denote the left action by

$$L_g : G \rightarrow G, \quad L_g h = gh.$$

Given a basis $e_1|_I, \dots, e_n|_I \in T_I G$, we obtain a global frame of vector fields $(L_g)_* e_1|_I, \dots, (L_g)_* e_n|_I$, which we denote by $e_1, \dots, e_n$ for simplicity. The structure constants of this frame are given by

$$[e_i, e_j] = c^k_{ij} e_k.$$

In terms of the structure constants, the Jacobi identity $[V, [W, X]] + [W, [X, V]] + [X, [V, W]] = 0$ is

$$c^p_{ir} c^q_{jk} + c^p_{kr} c^q_{ij} + c^p_{jr} c^q_{ki} = 0$$

for all indices p, q, i, r, j, k .

(a) Show that

$$de^k = \frac{1}{2} c^k_{ij} e^j \wedge e^i,$$

where $\{e^i\}$ is the dual frame to $\{e_i\}$.

(b) We define a metric on the Lie group G by

$$g(e_i, e_j) = \delta_{ij}.$$

Recall that the Levi-Civita connection ∇ is defined by

$$\begin{aligned} 2g(\nabla_X Y, Z) &= Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) + g(Z, [X, Y]) \\ &\quad + g(Y, [Z, X]) + g(X, [Z, Y]). \end{aligned}$$

Compute the connection coefficients $A_i^k{}_j$, defined by

$$\nabla_{e_i} e_j = A_i^k{}_j e_k.$$

The connection form is $A = A_i^k{}_j e^i$.

(c) Further suppose that G is such that the structure constants are totally skew-symmetric. This means that in addition to the usual antisymmetry $c^k_{ij} = -c^k_{ji}$, we also have

$$c^k_{ij} = -c^i_{kj}.$$

Compute the components $F_{ij}{}^p{}_q$ of the curvature form $F = dA + A \wedge A$.

$$F = \frac{1}{2} F_{ij}{}^p{}_q e^i \wedge e^j.$$

Use the Jacobi identity to simplify your answer.

(d) The Lie group $SO(3)$ admits a global frame of vector fields $\{e_i\}_{i=1}^3$ which satisfies

$$[e_i, e_j] = \epsilon_{ijk} e_k,$$

where ϵ_{ijk} is the Levi-Civita symbol. Show that $SO(3)$ admits an Einstein metric. This is a metric which satisfies the curvature condition

$$R_{ij} = \lambda g_{ij},$$

where λ is a constant.
