

Traps, Patches, and Spots: Asymptotic Analysis of Localized Solutions to Some Diffusive Processes

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Special Workshop in Honor of Reinhard Illner

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Outline of the Talk

THREE SPECIFIC (SEEMINGLY UNRELATED) TOPICS:

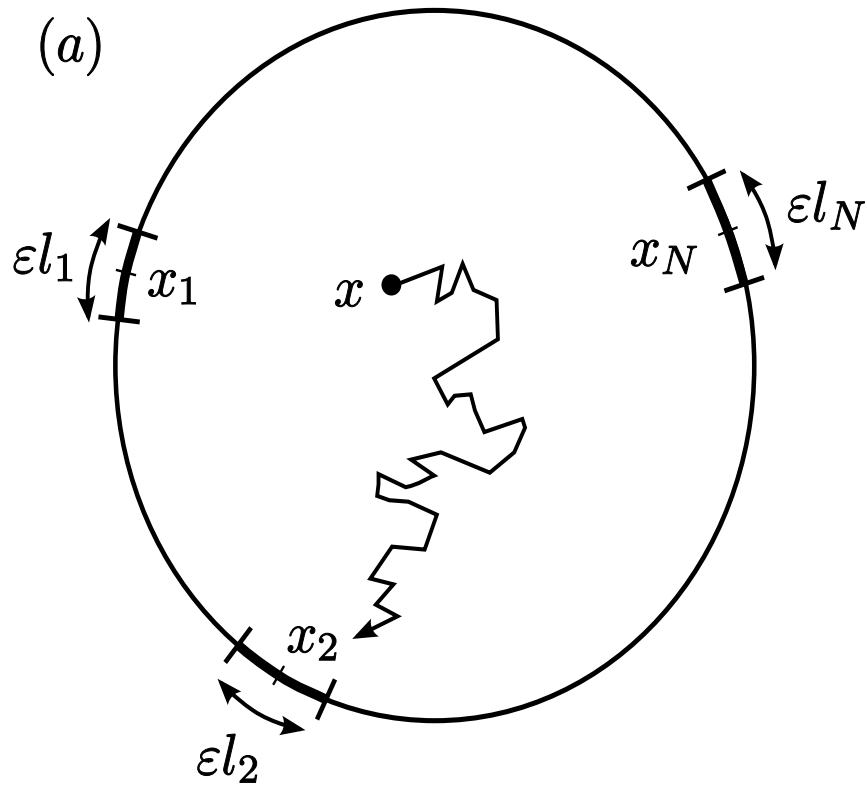
- **Part I (Patches):** The Mean First Passage Time (MFPT) for Diffusive Escape from a Sphere Through a Narrow Window on its Boundary.
- **Part II (Traps):** The MFPT for Diffusion on the Surface of a Sphere with Small Traps.
- **Part III (Spots):** The slow dynamics and equilibria of spot-type patterns for the singularly perturbed Brusselator RD model on the sphere.

COMMONALITIES:

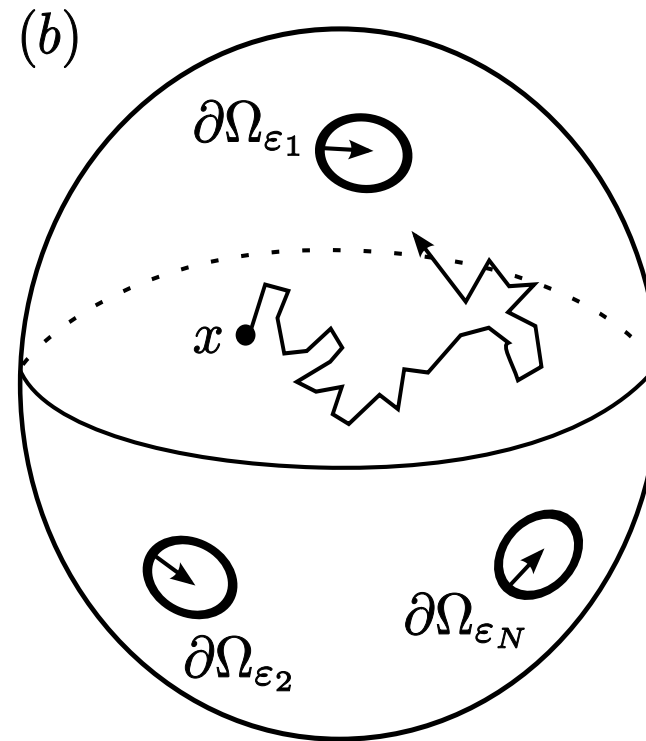
1. Asymptotic reduction to **discrete optimization problems** for interacting “particles” (Part I, II)
2. Reduction to DAE (differential algebraic ODE) system of “interacting particles” on the sphere (Part III)
3. All are related to **Fekete points**

Part I: Narrow Escape Problem in 3-D

Narrow Escape: Brownian motion with diffusivity D in Ω with $\partial\Omega$ insulated except for an (multi-connected) absorbing patch $\partial\Omega_a$ of measure $O(\varepsilon)$. Let $\partial\Omega_a \rightarrow x_j$ as $\varepsilon \rightarrow 0$ and $X(0) = x \in \Omega$ be initial point for Brownian motion.



Left: 2-D



Right: 3-D

Part I: Mathematical Formulation

The mean first passage time MFPT $v(x) = E[\tau | X(0) = x]$ for the narrow escape problem satisfies a Poisson problem with Dirichlet/Neumann boundary conditions (Z. Schuss (1980))

$$\Delta v = -\frac{1}{D}, \quad x \in \Omega,$$

$$\partial_n v = 0 \quad x \in \partial\Omega_r; \quad v = 0, \quad x \in \partial\Omega_a = \cup_{j=1}^N \partial\Omega_{\varepsilon_j}.$$

An eigenfunction expansion shows that the average MFPT \bar{v} satisfies

$$\bar{v} = \frac{1}{|\Omega|} \int_{\Omega} v \, dx \sim \frac{1}{D\lambda_1}, \quad \text{as } \varepsilon \rightarrow 0.$$

Here λ_1 is the principal eigenvalue of

$$\Delta u + \lambda u = 0, \quad x \in \Omega; \quad \int_{\Omega} u^2 \, dx = 1,$$

$$\partial_n u = 0 \quad x \in \partial\Omega_r, \quad u = 0, \quad x \in \partial\Omega_a = \cup_{j=1}^N \partial\Omega_{\varepsilon_j}.$$

Since $|\partial\Omega_a| = \mathcal{O}(\varepsilon)$, then $\bar{v} \rightarrow \infty$ and $\lambda_1 \rightarrow 0$ as $\varepsilon \rightarrow 0$.

Part I: Relevance to Biophysics

KEY GENERAL REFERENCES:

- Z. Schuss, A. Singer, D. Holcman, *The Narrow Escape Problem for Diffusion in Cellular Microdomains*, PNAS, **104**, No. 41, (2007), pp. 16098-16103.
- O. Bénichou, R. Voituriez, *Narrow Escape Time Problem: Time Needed for a Particle to Exit a Confining Domain Through a Small Window*, Phys. Rev. Lett, **100**, (2008), 168105.
- S. Condamin, et al., Nature, **450**, 77, (2007)
- S. Condamin, O. Bénichou, M. Moreau, Phys. Rev. E., **75**, (2007).

RELEVANCE OF NARROW ESCAPE TIME PROBLEM IN BIOLOGY:

- time needed for a reactive particle released from a specific site to activate a given protein on the cell membrane
- biochemical reactions in cellular microdomains (dendritic spines, synapses, microvesicles), consisting of a small number of particles that must exit the domain to initiate a biological function.
- determines reaction rate in Markov model of chemical reactions

Part I: Some Previous Results

- For a 3-D domain with smooth boundary (MJW, Keller, SIAP, 1993)

$$\lambda_1 \sim \frac{2\pi\varepsilon}{|\Omega|} \sum_{j=1}^N C_j .$$

Here C_j is the capacitance of the **electrified disk problem**

$$\begin{aligned} \Delta_y w &= 0, \quad y_3 \geq 0, \quad -\infty < y_1, y_2 < \infty; \quad w \sim C_j/|y|, \quad |y| \rightarrow \infty. \\ w &= 1, \quad y_3 = 0, \quad (y_1, y_2) \in \partial\Omega_j; \quad \partial_{y_3} w = 0, \quad y_3 = 0, \quad (y_1, y_2) \notin \partial\Omega_j. \end{aligned}$$

- For one circular trap of radius ε on the unit sphere Ω with $|\Omega| = 4\pi/3$,

$$\bar{v} \sim \frac{|\Omega|}{4\varepsilon D} \left[1 - \frac{\varepsilon}{\pi} \log \varepsilon + O(\varepsilon) \right],$$

Ref: A. Singer et al. J. Stat. Phys., **122**, No. 3, (2006).

- For arbitrary Ω with smooth $\partial\Omega$ and one circular trap at $x_0 \in \partial\Omega$

$$\bar{v} \sim \frac{|\Omega|}{4\varepsilon D} \left[1 - \frac{\varepsilon}{\pi} H \log \varepsilon + O(\varepsilon) \right].$$

Here H is the **mean curvature** of $\partial\Omega$ at $x_0 \in \partial\Omega$. Ref: A. Singer, Z. Schuss, D. Holcman, Phys. Rev. E., **78**, No. 5, 051111, (2009).

Part I: Main Goals

Applications: Specific Scientific Questions:

- Obtain **explicit higher-order asymptotics** for $v(x)$ and \bar{v} as $\varepsilon \rightarrow 0$.
- Determine **whether there is a significant effect on \bar{v} of the spatial configuration $\{x_1, \dots, x_n\}$ of traps.**
- What is the effect on \bar{v} of **fragmentation** of the trap set?
- Develop **scaling laws for large N .**

Math: Connections to Approximation Theory: Let Ω be the unit sphere with N -circular absorbing patches on $\partial\Omega$ of a common radius. **Is minimizing \bar{v} equivalent to minimizing the Coulomb energy $\mathcal{H}_C(x_1, \dots, x_N)$ defined by**

$$\mathcal{H}_C(x_1, \dots, x_N) = \sum_{j=1}^N \sum_{k>j}^N \frac{1}{|x_j - x_k|}, \quad |x_j| = 1.$$

Such points are **Fekete points**. They correspond to finding the minimal energy configuration of “electrons” on the sphere. (References: J.J. Thomson, E. Saff, N. Sloane, A. Kuijlaars etc..)

Part I: The Surface Neumann G-Function

The surface Neumann G-function, G_s , is central to the analysis:

$$\Delta G_s = \frac{1}{|\Omega|}, \quad x \in \Omega; \quad \partial_r G_s = \delta(\cos \theta - \cos \theta_j) \delta(\phi - \phi_j), \quad x \in \partial\Omega,$$

Lemma: Let $\cos \gamma = x \cdot x_j$ and $\int_{\Omega} G_s dx = 0$. Then $G_s = G_s(x; x_j)$ is

$$G_s = \frac{1}{2\pi|x - x_j|} + \frac{1}{8\pi}(|x|^2 + 1) + \frac{1}{4\pi} \log \left[\frac{2}{1 - |x| \cos \gamma + |x - x_j|} \right] - \frac{7}{10\pi}.$$

Define the matrix \mathcal{G}_s using $R = -\frac{9}{20\pi}$ and $G_{sij} \equiv G_s(x_i; x_j)$ as

$$\mathcal{G}_s \equiv \begin{pmatrix} R & G_{s12} & \cdots & G_{s1N} \\ G_{s21} & R & \cdots & G_{s2N} \\ \vdots & \vdots & \ddots & \vdots \\ G_{sN1} & \cdots & G_{sN,N-1} & R \end{pmatrix},$$

Remark: As $x \rightarrow x_j$, G_s has a subdominant logarithmic singularity:

$$G_s(x; x_j) \sim \frac{1}{2\pi|x - x_j|} - \frac{1}{4\pi} \log |x - x_j| + R + o(1).$$

Part I: Main Result for \bar{v}

Principal Result: For $\varepsilon \rightarrow 0$, and for N circular traps of radii εa_j centered at x_j , for $j = 1, \dots, N$, the **averaged MFPT** \bar{v} satisfies

$$\bar{v} = \frac{|\Omega|}{2\pi\varepsilon DN\bar{c}} \left[1 + \varepsilon \log \left(\frac{2}{\varepsilon} \right) \frac{\sum_{j=1}^N c_j^2}{2N\bar{c}} + \frac{2\pi\varepsilon}{N\bar{c}} p_c(x_1, \dots, x_N) - \frac{\varepsilon}{N\bar{c}} \sum_{j=1}^N c_j \kappa_j + O(\varepsilon^2 \log \varepsilon) \right].$$

Here $c_j = 2a_j/\pi$ is the capacitance of the j^{th} circular absorbing window of radius εa_j , $\bar{c} \equiv N^{-1}(c_1 + \dots + c_N)$, $|\Omega| = 4\pi/3$, and κ_j and p_c are

$$\kappa_j = \frac{c_j}{2} \left[2 \log 2 - \frac{3}{2} + \log a_j \right]; \quad p_c(x_1, \dots, x_N) \equiv \mathcal{C}^t \mathcal{G}_s \mathcal{C}.$$

In the **quadratic form** for p_c , we label $\mathcal{C}^t = (c_1, \dots, c_N)$.

Remarks: 1) A similar result holds for non-circular traps. 2) **The logarithmic term** in ε arises from the subdominant singularity in G_s .

Part I: Main Result for \bar{v}

Corollary: (CWS): For N circular traps of a common radius ε (for which $c_j = 2/\pi$ and $a_j = 1$), then a three-term expansion is

$$\bar{v} = \frac{|\Omega|}{4\varepsilon DN} \left[1 + \frac{\varepsilon}{\pi} \log \left(\frac{2}{\varepsilon} \right) + \frac{\varepsilon}{\pi} \left(-\frac{9N}{5} + 2(N-2) \log 2 \right. \right. \\ \left. \left. + \frac{3}{2} + \frac{4}{N} \mathcal{H}(x_1, \dots, x_N) \right) + \mathcal{O}(\varepsilon^2 \log \varepsilon) \right],$$

with discrete energy $\mathcal{H}(x_1, \dots, x_N)$ given by

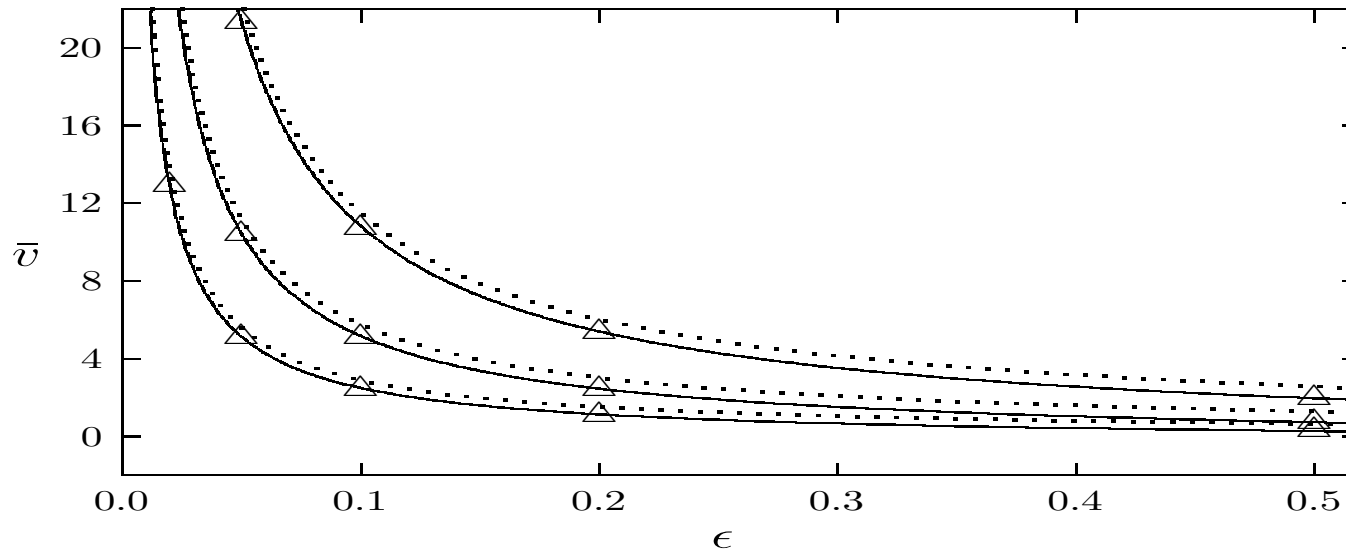
$$\mathcal{H}(x_1, \dots, x_N) = \sum_{i=1}^N \sum_{k>i}^N \left(\frac{1}{|x_i - x_k|} - \frac{1}{2} \log |x_i - x_k| - \frac{1}{2} \log (2 + |x_i - x_k|) \right).$$

- **Key point:** To minimize \bar{v} , we must minimize \mathcal{H} . This discrete energy generalizes the Coulombic or logarithmic energies of (classical) Fekete points. Extra term in \mathcal{H} involves surface diffusion.
- **Ref: [CWS]:** A. Chevaikov, M.J. Ward, R. Straube, *An Asymptotic Analysis of the Mean First Passage Time for Narrow Escape Problems: SIAM J. Multiscale Modeling and Simulation: Part II The Sphere*, 8, (2010), pp. 836–870.

Part I: Key Steps in Derivation

- Asymptotic expansion of global (outer) solution and local (inner) solutions near each trap.
- Tangential-normal coordinate system used near each trap.
- The Neumann G-function has a subdominant logarithmic singularity on the boundary (related to surface diffusion). This fact requires adding “**logarithmic switchback terms in ε** ” in the outer expansion (ubiquitous in Low Reynolds number flow problems)
- The **leading-order local solution is the tangent plane approximation** and yields electrified disk problem in a half-space, with capacitance C_j .
- **Key: Need corrections to the tangent plane approximation in the inner region, i.e. near the trap. This higher order correction term in the inner expansion satisfies a Poisson type problem.** The far-field behavior of this inhomogeneous problem is a monopole term and determines κ_j .
- Asymptotic matching and solvability conditions (Divergence theorem) determine v and \bar{v}

Part I: Numerical Validation of \bar{v}



Plot: \bar{v} vs. ϵ with $D = 1$ and either $N = 1, 2, 4$ equidistantly spaced circular windows of radius ϵ . **Solid:** 3-term expansion. **Dotted:** 2-term expansion.

Discrete: COMSOL. **Top:** $N = 1$. **Middle:** $N = 2$. **Bottom:** $N = 4$.

	$N = 1$			$N = 2$			$N = 4$		
ϵ	\bar{v}_2	\bar{v}_3	\bar{v}_n	\bar{v}_2	\bar{v}_3	\bar{v}_n	\bar{v}_2	\bar{v}_3	\bar{v}_n
0.02	53.89	53.33	52.81	26.95	26.42	26.12	13.47	13.11	12.99
0.05	22.17	21.61	21.35	11.09	10.56	10.43	5.54	5.18	5.12
0.10	11.47	10.91	10.78	5.74	5.21	5.14	2.87	2.51	2.47
0.20	6.00	5.44	5.36	3.00	2.47	2.44	1.50	1.14	1.13
0.50	2.56	1.99	1.96	1.28	0.75	0.70	0.64	0.28	0.30

Part I: Numerical Validation of \bar{v}

Remark: For $\varepsilon = 0.5$ and $N = 4$, traps occupy $\approx 20\%$ of the surface. Yet, the 3-term asymptotics for \bar{v} differs from COMSOL by only $\approx 7.5\%$.

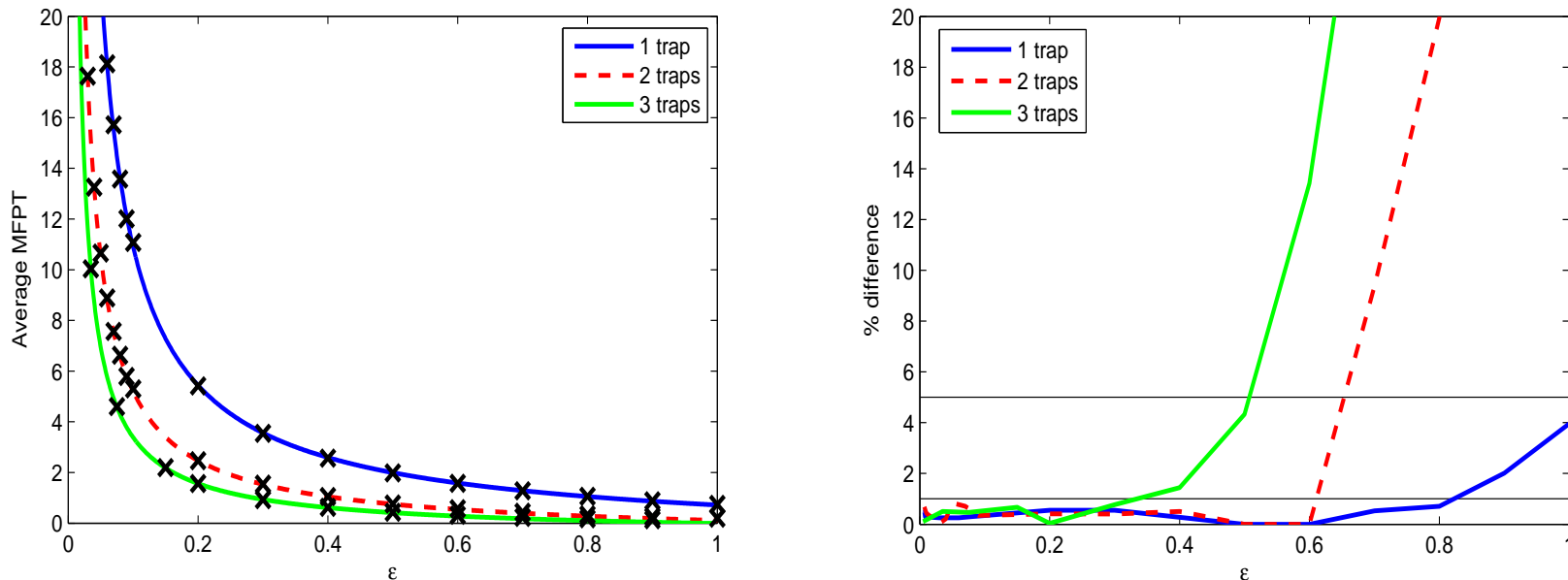
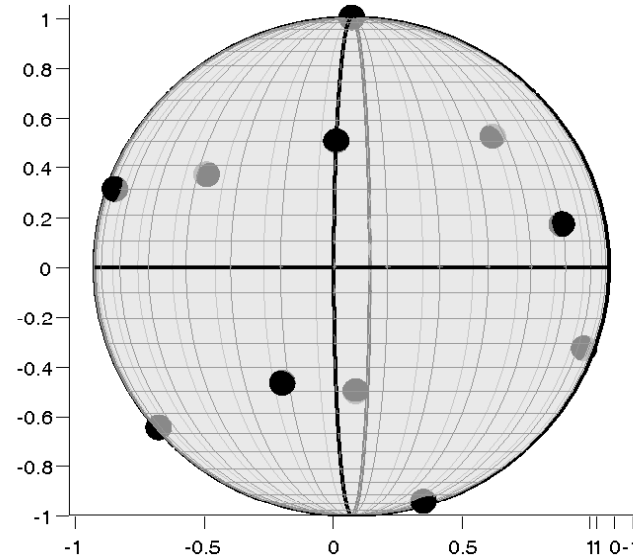
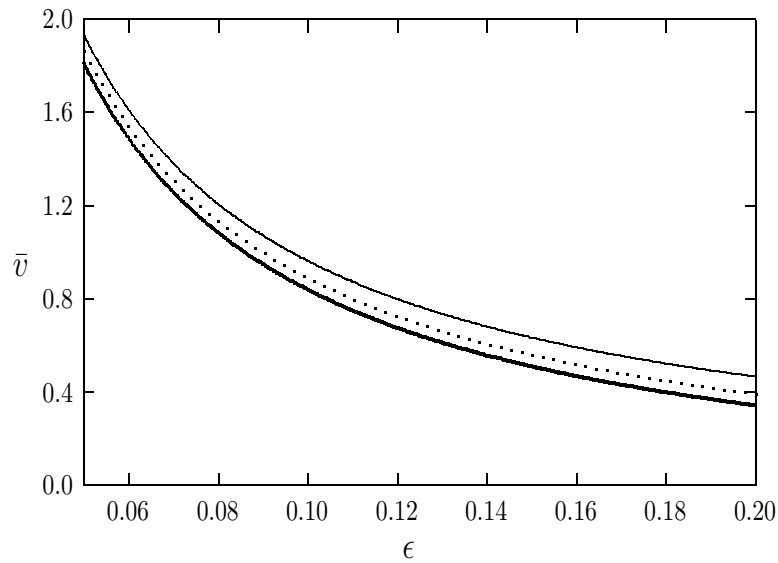


Fig: \bar{v} vs. trap radius ε for $D = 1$ for one, two, and three traps equally spaced on the equator: curves (asymptotics), crosses (full numerics).

- For one trap, we get only 1% error for a trap of radius $\varepsilon \lesssim 0.8$, i.e. $\varepsilon^2/4 \times 100 = 16\%$ percent surface trap area fraction.
- For 3 traps, 1% error when $\varepsilon \lesssim 0.3$, which is 6.8% percent surface trap area fraction.

Part I: Fragmentation/Location of Traps



Plot: $\bar{v}(\varepsilon)$ for $D = 1$, $N = 11$, and three trap configurations. **Heavy:** global minimum of \mathcal{H} (right figure). **Solid:** equidistant points on equator. **Dotted:** random.

- The effect of trap location is still rather significant.
- For $\varepsilon = 0.1907$, $N = 11$ traps occupy $\approx 10\%$ of surface area. **The optimal arrangement gives $\bar{v} \approx 0.368$. For a single large trap with a 10% surface area, $\bar{v} \approx 1.48$; a result 3 times larger. Thus, trap fragmentation effects are important.**

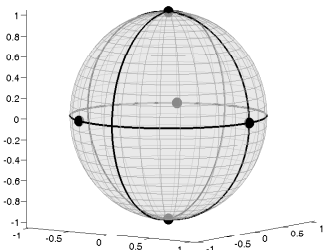
Part I: Discrete Optimization Problem I

Goal: Compare optimal energies and point arrangements of \mathcal{H} with those of classic Coulomb or Logarithmic energies

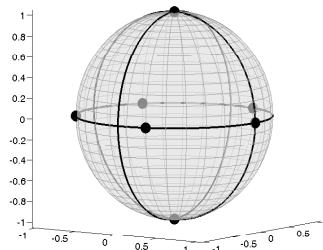
$$\mathcal{H}_C = \sum_{i=1}^N \sum_{j>i}^N \frac{1}{|x_i - x_j|}, \quad \mathcal{H}_L = - \sum_{i=1}^N \sum_{j>i}^N \log |x_i - x_j|.$$

Numerics: Extended Cutting Angle Method: Implemented for $N \leq 65$ in open software library GANSO by A. Cheviakov, R. Spiteri, S. Richards.

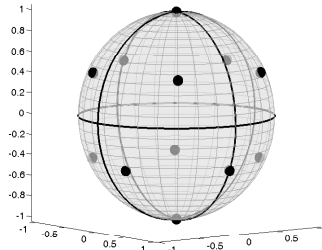
N=5



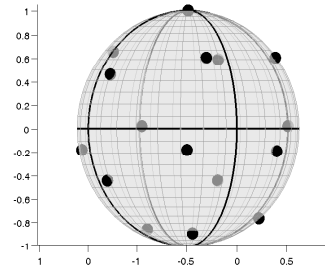
N=7



N=12



N=16



- Optimal \mathcal{H} grows more slowly with N than for other discrete energies.
- For $N = 2, \dots, 20$ optimal point arrangements coincide (proof?) Does agreement persist for large values of N ?

Part I: Discrete Optimization Problem II

OPTIMAL ENERGIES: (Computations by R. Spiteri and A. Cheviakov)

N	\mathcal{H}	\mathcal{H}_C	\mathcal{H}_L
3	-1.067345	1.732051	-1.647918
4	-1.667180	3.674234	-2.942488
5	-2.087988	6.474691	-4.420507
6	-2.581006	9.985281	-6.238324
7	-2.763658	14.452978	-8.182476
8	-2.949577	19.675288	-10.428018
9	-2.976434	25.759987	-12.887753
10	-2.835735	32.716950	-15.563123
11	-2.456734	40.596450	-18.420480
12	-2.161284	49.165253	-21.606145
16	1.678405	92.911655	-36.106152
20	8.481790	150.881571	-54.011130
25	21.724913	243.812760	-80.997510
30	40.354439	359.603946	-113.089255
35	64.736711	498.569272	-150.192059
40	94.817831	660.675278	-192.337690
45	130.905316	846.188401	-239.453698
50	173.078675	1055.182315	-291.528601
55	221.463814	1287.772721	-348.541796
60	275.909417	1543.830401	-410.533163
65	336.769710	1823.667960	-477.426426

Scaling Law for Optimum Point

For $N \gg 1$, the optimal \mathcal{H} has the scaling law

$$\mathcal{H} \approx \mathcal{F}(N) \equiv \frac{N^2}{2} \log\left(\frac{e}{2}\right) + b_1 N^{3/2} + N(b_2 \log N + b_3) + b_4 N^{1/2} + b_5 \log N + b_6,$$

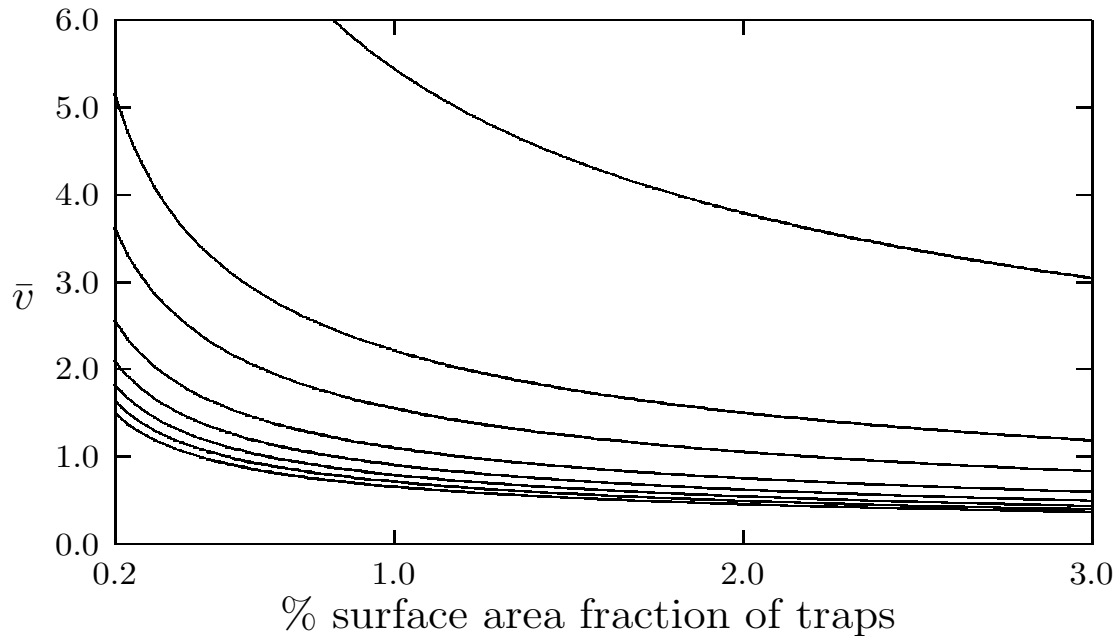
where a least-squares fit to the optimal energy yields

$$b_1 \approx -0.5668, \quad b_2 \approx 0.0628, \quad b_3 \approx -0.8420, \\ b_4 \approx 3.8894, \quad b_5 \approx -1.3512, \quad b_6 \approx -2.4523.$$

Scaling Law For \bar{v} : For $1 \ll N \ll 1/\varepsilon$, the optimal average MFPT \bar{v} , in terms of the trap surface area fraction $f = N\varepsilon^2/4$, satisfies

$$\bar{v} \sim \frac{|\Omega|}{8D\sqrt{fN}} \left[1 - \frac{\sqrt{f/N}}{\pi} \log\left(\frac{4f}{N}\right) + \frac{2\sqrt{fN}}{\pi} \left(\frac{1}{5} + \frac{4b_1}{\sqrt{N}} \right) \right].$$

Part I: Fragmentation of the Trap Set



Plot: averaged MFPT \bar{v} versus % trap area fraction for $N = 1, 5, 10, 20, 30, 40, 50, 60$ (top to bottom) at optimal trap locations.

- Fragmentation of traps on the sphere is a significant factor for small N .
- Only a minimal benefit by increasing N when N is already large.
- Q1: Derive a rigorous scaling law for optimal \mathcal{H} when $N \gg 1$.
- Q2: Does the limiting result from \mathcal{H} approach a homogenization theory result in the dilute trap area limit?

Part II: MFPT on the Sphere Surface

Consider Brownian motion on the **surface** of a sphere. The MFPT satisfies

$$\Delta_s v = -\frac{1}{D}, \quad x \in \Omega_\varepsilon \equiv \Omega \setminus \bigcup_{j=1}^N \Omega_{\varepsilon_j},$$
$$v = 0, \quad x \in \partial\Omega_{\varepsilon_j}; \quad \bar{v} \sim \frac{1}{|\Omega_\varepsilon|} \int_{\Omega_\varepsilon} v \, ds.$$

Here Ω is the unit sphere, Ω_{ε_j} are localized **non-overlapping circular traps** of radius $O(\varepsilon)$ on Ω centered at x_j with $|x_j| = 1$ for $j = 1, \dots, N$.

Eigenvalue Problem: The corresponding eigenvalue problem is

$$\Delta_s \psi + \lambda \psi = 0, \quad x \in \Omega_\varepsilon \equiv \Omega \setminus \bigcup_{j=1}^N \Omega_{\varepsilon_j},$$
$$\psi = 0, \quad x \in \partial\Omega_{\varepsilon_j}; \quad \int_{\Omega_\varepsilon} \psi^2 \, ds = 1.$$

- **Goal:** Calculate the **principal eigenvalue** λ_1 in the limit $\varepsilon \rightarrow 0$. **Note that $\bar{v} \sim 1/(D\lambda_1)$ as $\varepsilon \rightarrow 0$.** What is the effect of the trap locations?
- **Ref:** [CSW] D. Coombs, R. Straube, MJW, “*Diffusion on a Sphere with Traps...*”, SIAP 70(1), (2009), pp. 302–332.

Part II: Elliptic Fekete Points

Elliptic Fekete Points are points that globally minimize the logarithmic energy \mathcal{H}_L on the unit sphere

$$\mathcal{H}_L(x_1, \dots, x_N) = - \sum_{j=1}^N \sum_{k>j}^N \log |x_j - x_k|, \quad |x_j| = 1.$$

(References: Smale and Schub, Saff, Sloane, Kuijlaars, D. Boal, P. Palffy-Muhoray,...)

Key Question: Are elliptic Fekete points related to the configuration of traps that minimize the average MFPT \bar{v} for diffusion on the sphere?

Part II: MFPT Two-Term Asymptotics

An asymptotic analysis yields (Ref: [CSW]):

Principal Result: Consider N perfectly absorbing circular traps of a common radius $\varepsilon \ll 1$ centered at x_j , for $j = 1, \dots, N$ on S . Then, the asymptotics for the **MFPT** v in the “outer” region $|x - x_j| \gg O(\varepsilon)$ for $j = 1, \dots, N$ is

$$v(x) = -2\pi \sum_{j=1}^N A_j G(x; x_j) + \bar{v}, \quad \chi \equiv \frac{1}{4\pi} \int_S v ds,$$

where A_j for $j = 1, \dots, N$, with $\mu \equiv -1/\log \varepsilon$ is

$$A_j = \frac{2}{ND} \left[1 + \mu \sum_{\substack{i=1 \\ i \neq j}}^N \log |x_i - x_j| - \frac{2\mu}{N} p(x_1, \dots, x_N) + O(\mu^2) \right].$$

The **averaged MFPT** \bar{v} is given asymptotically by

$$\bar{v} = \frac{2}{ND\mu} + \frac{1}{D} \left[(2 \log 2 - 1) + \frac{4}{N^2} p(x_1, \dots, x_N) \right] + O(\mu).$$

Part II: MFPT Two-Term Asymptotics

Here the *discrete energy* $p(x_1, \dots, x_N)$ is the logarithmic energy

$$p(x_1, \dots, x_N) \equiv - \sum_{i=1}^N \sum_{j>i}^N \log |x_i - x_j|.$$

The Neumann Green function $G(x; x_0)$ that appears satisfies

$$\Delta_s G = \frac{1}{4\pi} - \delta(x - x_0), \quad x \in S; \quad \int_S G ds = 0$$

G is 2π periodic in ϕ and smooth at $\theta = 0, \pi$.

It is given analytically by

$$G(x; x_0) = -\frac{1}{2\pi} \log |x - x_0| + R, \quad R \equiv \frac{1}{4\pi} [2 \log 2 - 1].$$

Remark: G appears in various studies of the motion of fluid vortices on the surface S of a sphere (P. Newton, S. Boatto, etc..).

Part I: MFPT Two-Term Asymptotics

Corollary: For N identical perfectly absorbing traps of a common radius ε centered at x_j , for $j = 1, \dots, N$, on S , the principal eigenvalue has asymptotics, with $\mu \equiv -1/\log \varepsilon$

$$\lambda(\varepsilon) \sim \frac{\mu N}{2} + \mu^2 \left[-\frac{N^2}{4} (2 \log 2 - 1) - p(x_1, \dots, x_N) \right] + O(\mu^3).$$

- **Key Point:** $\lambda(\varepsilon)$ is maximized and \bar{v} minimized at the minimum point of p , i.e. at the elliptic Fekete points for the sphere.
- Can readily adapt the analysis to treat the case of N partially absorbing traps of different radii (see [CSW,2009]).
- For $N = 1$, v and λ_1 can be found from ODE problems, and we reproduce old results of Weaver (1983), Chao et. al. (1981), Biophys. J., and Lindeman and Laufenburger, Biophys. J. (1986)). In particular,

$$\lambda(\varepsilon) \sim \frac{\mu}{2} + \frac{\mu^2}{4} (1 - 2 \log 2) .$$

Part II: Summing the Logs

Can formulate a problem involving the Helmholtz Green function on the sphere that **sums the infinite logarithmic expansion for $\lambda(\varepsilon)$** . It reads as:

Principal Result: Consider N perfectly absorbing traps of a common radius ε for $j = 1, \dots, N$. Let $\nu(\varepsilon)$ be the smallest root of the transcendental equation

$$\text{Det}(I + 2\pi\mu\mathcal{G}_h) = 0, \quad \mu = -\frac{1}{\log \varepsilon}.$$

Here \mathcal{G}_h is the Helmholtz Green function matrix with matrix entries

$$\mathcal{G}_{hjj} = R_h(\nu); \quad \mathcal{G}_{hij} = -\frac{1}{4 \sin(\pi\nu)} P_\nu \left(\frac{|x_j - x_i|^2}{2} - 1 \right), \quad i \neq j.$$

Then, with an error of order $O(\varepsilon)$, we have $\lambda(\varepsilon) \sim \nu(\nu + 1)$.

● $P_\nu(z)$ is the Legendre function of the first kind, with regular part

$$R_h(\nu) \equiv -\frac{1}{4\pi} [-2 \log 2 + 2\gamma + 2\psi(\nu + 1) + \pi \cot(\pi\nu)],$$

where γ is Euler's constant and ψ is the Di-Gamma function.

Part I: Validation of Asymptotics

We validate our two-term and summing logs asymptotic theory by comparing with full numerical results

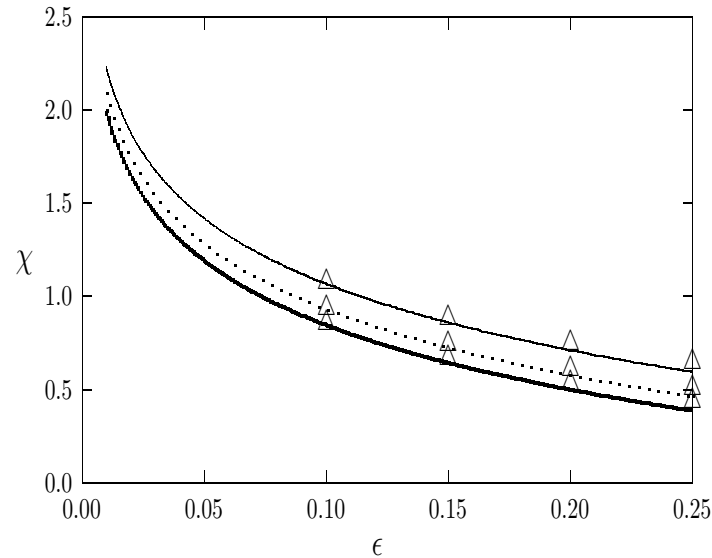
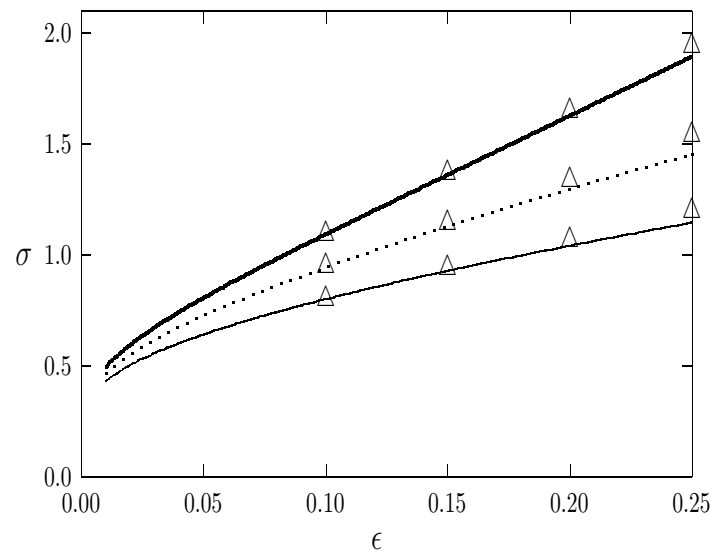
ε	5 random traps			2 antipodal traps		
	λ	λ^*	λ_2	λ	λ^*	λ_2
0.02	0.7918	0.7894	0.7701	0.2458	0.2451	0.2530
0.05	1.1003	1.0991	1.0581	0.3124	0.3121	0.3294
0.1	1.5501	1.5452	1.4641	0.3913	0.3903	0.4268
0.2	2.5380	2.4779	2.3278	0.5177	0.5110	0.6060

Legend: λ (COMSOL); λ^* (Summing Logs); λ_2 (2-term).

Note: For $\varepsilon = 0.2$ and $N = 5$, we get 5% trap area fraction. The agreement is still very good: 2.4% error (summing logs) and 8.3% error (2-term).

Part II: Effect of Trap Locations

EFFECT OF SPATIAL ARRANGEMENT OF $N = 4$ IDENTICAL TRAPS:



Note: $\epsilon = 0.1$ corresponds to 1% trap surface area fraction.

Fig: Results for $\lambda(\epsilon)$ (left) and $\bar{v}(\epsilon)$ (right) for three different 4-trap patterns with perfectly absorbing traps and a common radius ϵ . **Heavy solid:**

$(\theta_1, \phi_1) = (0, 0)$, $(\theta_2, \phi_2) = (\pi, 0)$, $(\theta_3, \phi_3) = (\pi/2, 0)$, $(\theta_4, \phi_4) = (\pi/2, \pi)$;

Solid: $(\theta_1, \phi_1) = (0, 0)$, $(\theta_2, \phi_2) = (\pi/3, 0)$, $(\theta_3, \phi_3) = (2\pi/3, 0)$,

$(\theta_4, \phi_4) = (\pi, 0)$; **Dotted:** $(\theta_1, \phi_1) = (0, 0)$, $(\theta_2, \phi_2) = (2\pi/3, 0)$,

$(\theta_3, \phi_3) = (\pi/2, \pi)$, $(\theta_4, \phi_4) = (\pi/3, \pi/2)$. **The marked points are computed from finite element package COMSOL.**

Part II: A Scaling Law

For $N \rightarrow \infty$, the optimal energy for the discrete variational problem associated with elliptic Fekete points gives

$$\max [-p(x_1, \dots, x_N)] \sim \frac{1}{4} \log \left(\frac{4}{e} \right) N^2 + \frac{1}{4} N \log N + l_1 N + l_2, \quad N \rightarrow \infty,$$

with $l_1 = 0.02642$ and $l_2 = 0.1382$.

Ref: E. A. Rakhmanov, E. B. Saff, Y. M. Zhou, (1994); B. Bergersen, D. Boal, P. Palffy-Muhoray, J. Phys. A: Math Gen., 27, No. 7, (1994).

This yields a **key scaling law for the minimum of the averaged MFPT:**

Principal Result: *For $N \gg 1$, and N circular disks of common radius ε , and with small trap area fraction $N(\pi\varepsilon^2) \ll 1$ with $|S| = 4\pi$, then*

$$\min \bar{v} \sim \frac{1}{ND} \left[-\log \left(\frac{\sum_{j=1}^N |\Omega_{\varepsilon_j}|}{|S|} \right) - 4l_1 - \log 4 + O(N^{-1}) \right].$$

Part II: Biophysical Application

Application: Estimate the averaged MFPT T for a surface-bound molecule to reach a molecular cluster on a spherical cell.

Physical Parameters: The diffusion coefficient of a typical surface molecule (e.g. LAT) is $D \approx 0.25\mu\text{m}^2/\text{s}$. Take $N = 100$ (traps) of common radius 10nm on a cell of radius $5\mu\text{m}$. This gives a 1% trap area fraction:

$$\varepsilon = 0.002, \quad N\pi\varepsilon^2/(4\pi) = 0.01.$$

Scaling Law: The scaling law gives an asymptotic lower bound on the averaged MFPT. For $N = 100$ traps, the bound is 7.7s, achieved at the elliptic Fekete points.

One Big Trap: As a comparison, for one big trap of the same area the averaged MFPT is 360s, which is very different.

Bounds: Therefore, for any other arrangement, $7.7\text{s} < T < 360\text{s}$.

Conclusion: Both the Spatial Distribution and Fragmentation Effect of Localized Traps are Rather Significant even at Small Trap Area Fraction

Part III: Spot Patterns in RD Systems

Spatially localized solutions can occur for singularly perturbed RD models

$$u_t = \varepsilon^2 \Delta u + f(u, v); \quad \tau v_t = D \Delta v + g(u, v), \quad x \in \Omega \in \mathbb{R}^2.$$

Assume semi-strong interactions for which $\varepsilon \ll 1$ and $D = \mathcal{O}(1)$.

Key: Since $\varepsilon \ll 1$, v can be localized in space as a spot pattern, i.e. concentration at a discrete set of points.

Some Well-Known RD systems:

- **Gray-Scott Model:** (Pearson, Science 1993, Muratov scaling (1996))

$$f(u, v) = -u + Avu^2, \quad g(u, v) = (1 - v) - vu^2.$$

- **Schnakenburg Model:** $f(u, v) = -u + vu^2$ and $g(u, v) = a - vu^2$.

- **GM Model:** $f(u, v) = -u + u^2/u$ and $g(u, v) = -v + u^2$.

- **Brusselator Model:** $f(u, v) = E - (B + 1)u + u^2v$, $g(u, v) = Bu - u^2v$.

Difficulties: No variational structure; Patterns are “far-from- equilibrium”.
Turing and weakly nonlinear theories are not applicable.

Part III: Brusselator on the Unit Sphere

$$\partial_T U = \varepsilon_0^2 \Delta_S U + \hat{E} - (B + 1)U + U^2 V, \quad \partial_T V = D \Delta_S V + BU - U^2 V.$$

where $\varepsilon_0^2 \equiv D_U/L^2$, $D \equiv D_V/L^2$, and L is the radius of the sphere. Here Δ_S is the surface Laplacian for the unit sphere.

Asymptotic Limit: where $\varepsilon_0 \ll 1$ and $\hat{E} = \mathcal{O}(\varepsilon_0)$.

Introduce new variables:

$$T = \frac{t}{B + 1}, \quad U = \frac{\sqrt{(B + 1)D}}{\varepsilon_0} u, \quad V = \frac{B}{\sqrt{(B + 1)D}} \varepsilon_0 v.$$

This yields **non-dimensional Brusselator Model:**

$$u_t = \varepsilon^2 \Delta_S u + \varepsilon^2 E - u + f u^2 v, \quad \tau v_t = \Delta_S v + \varepsilon^{-2} (u - u^2 v).$$

with

$$\varepsilon \equiv \frac{\varepsilon_0}{\sqrt{B + 1}}, \quad \tau \equiv \frac{(B + 1)}{D}, \quad f \equiv \frac{B}{B + 1}, \quad E \equiv \frac{\hat{E}}{\sqrt{(B + 1)D}\varepsilon_0}.$$

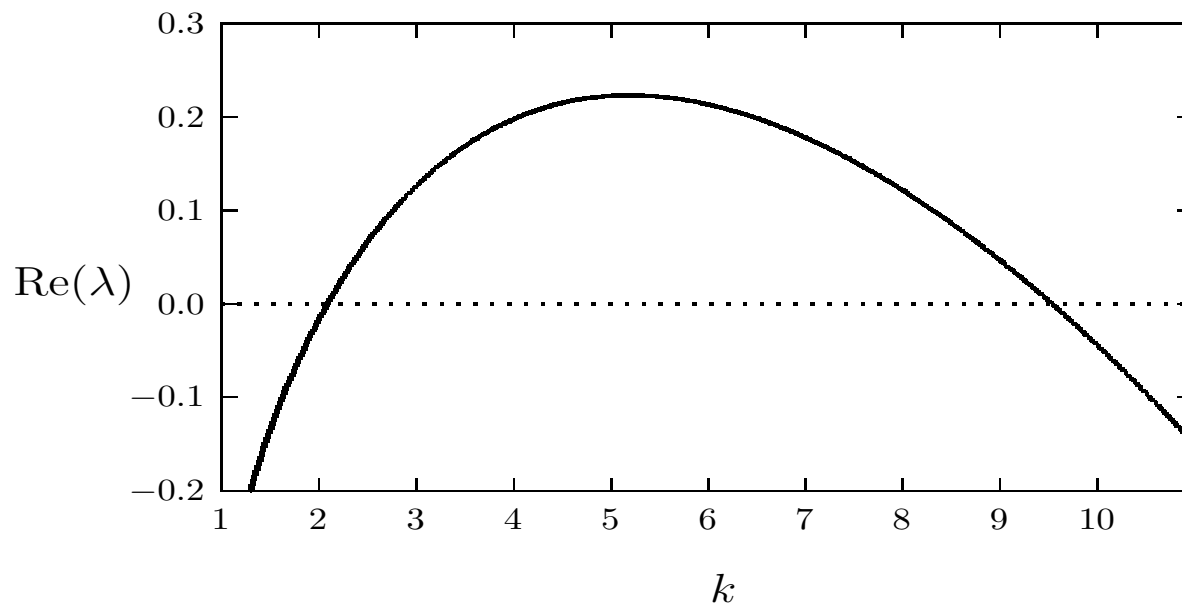
Part III: Turing Stability Analysis

The **spatially uniform state** is $u_e = \varepsilon^2 \mathbb{E} / (1 - f)$ and $v_e = (1 - f) / (\varepsilon^2 \mathbb{E})$.

Turing-Type stability analysis: Introduce perturbation of the uniform state:

$$(u, v) = (u_e, v_e) + e^{\lambda t} Y_l^m(\theta, \phi)(\hat{u}, \hat{v}), \quad k^2 \equiv l(l + 1), \quad |m| \leq l.$$

For $\varepsilon \rightarrow 0$ and $f > 1/2$, the (wide) instability band where $\text{Re}(\lambda) > 0$ is $0 < k_{\text{low}} < k < k_{\text{up}} \sim \sqrt{2f - 1} / \varepsilon$.



Plot: $\text{Re}(\lambda)$ versus k for $f = 0.8$, $\varepsilon = 0.075$, and $\mathbb{E} = 2.5$.

Part III: Turing/Weakly Nonlinear Theory

Key: For $\varepsilon \ll 1$, any spherical harmonic $Y_l^m(\theta, \phi)$ with integers l and m satisfying $4.45 \leq l(l+1) \leq 91.6$ and $|m| \leq l$ is unstable. This gives $l = 2, \dots, 9$.

Fundamental Difficulty: The linear stability problem with $f > 1/2$ and $\varepsilon \ll 1$ is highly degenerate with many unstable modes of comparable growth rate.

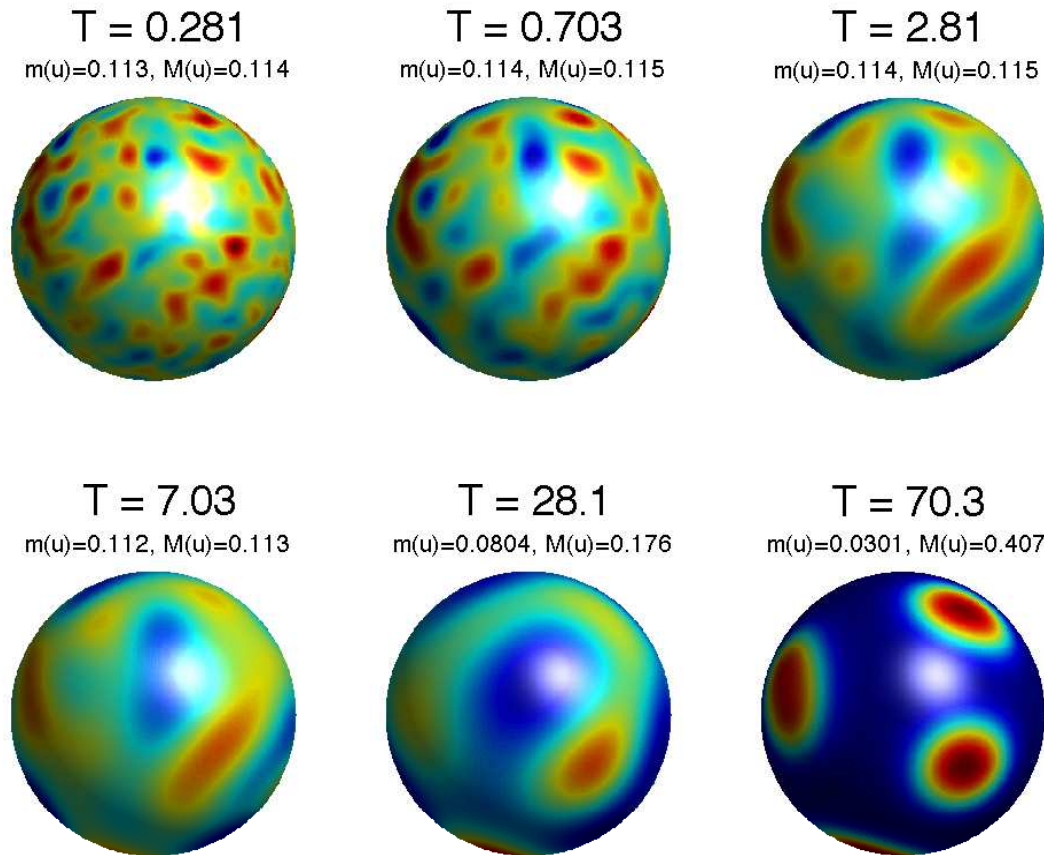
Weakly Nonlinear Analysis: For $\varepsilon = \mathcal{O}(1)$ tune parameters to onset of instability. However, due to degeneracy of spherical harmonics, eigenspace of zero-eigenvalue crossing is large. This leads to large set of coupled nonlinear normal form ODE amplitude equations via equivariant bifurcation theory. Weakly nonlinear patterns are unstable (subcritical), but re-stabilize at a saddle node point after including cubic terms. (Chossat, Melbourne, Archive Rat. Mech. Anal. 1990; Callahan, Physica D, 2004; P. Matthews, Nonlinearity 2003, Phys. Rev. E. 2003).

Key Difficulty:

- Due to mode degeneracy, linear and weakly nonlinear analysis is of only limited use in predicting pattern development.

Part III: Brusselator Patterns (Numerics)

Set: $f = 0.8$, $\varepsilon = 0.075$, $E = 6$. Initial data is uniform state with 2% random pert.



Numerics: “Closest Point Algorithms to Compute PDE’s on Surfaces”, by S. Ruuth (SFU) , C. McDonald (Oxford).

Initial Transient: very complicated due to interaction of many unstable modes, but leads to 8 localized spots.

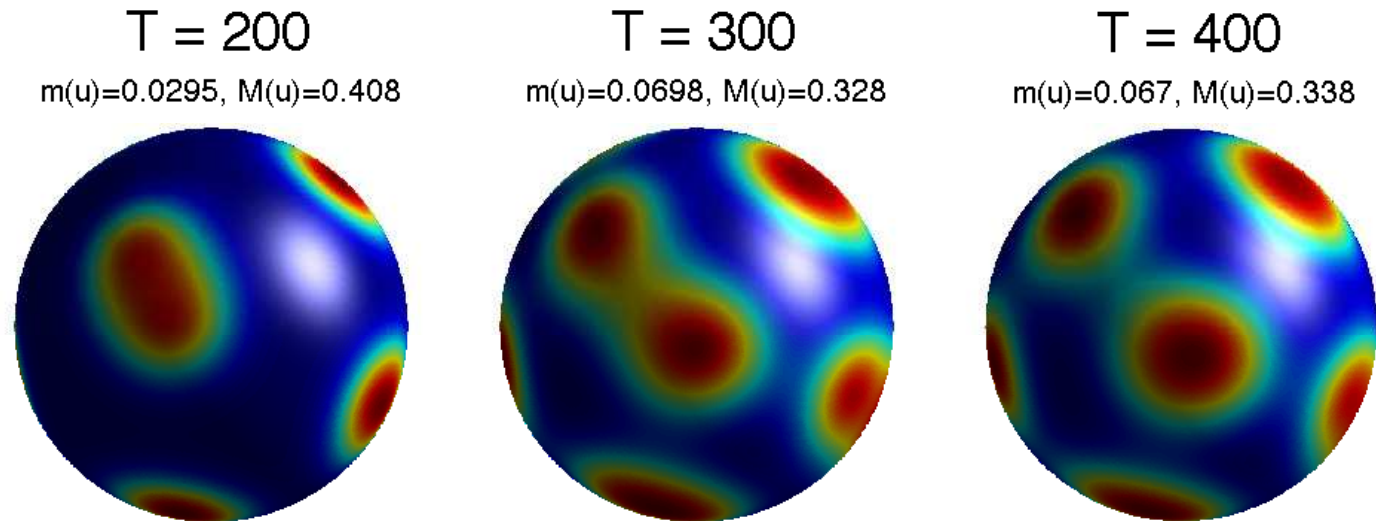
Part III: Challenges and Questions

- **Challenge:** Develop a mathematical theory to analyze the existence, stability, and dynamics, of localized “far-from equilibrium” spot patterns.
- **Question 1:** Do such localized patterns undergo secondary instabilities on longer time-scales? (competition, self-replication, etc.)
- **Question 2:** Can one derive a reduced dynamical system for the locations of the spots? Any similarities to Eulerian point vortices?
- **Question 3:** Are steady-state spot patterns related to elliptic Fekete points?

Ref 1 (Quasi-Equilibria and Stability): I. Rozada, S. Ruuth, M.J. Ward, *The Stability of Localized Spot Patterns for the Brusselator on the Sphere*, SIADS, 13(1), (2014), pp. 564–627.

Ref 2 (Slow Dynamics): P. Trinh, M.J. Ward, *Slow Spot Dynamics for Reaction-Diffusion Systems on the Sphere*, submitted Nov. 2014, Nonlinearity, (39 pages).

Part II: Self-Replication Instability



Plot: Solution at later times for $f = 0.8$, $\varepsilon = 0.075$. For $t \leq 70$ we take $E = 6$. and then slowly increase E as $E = \min(6 + 0.05(t - 70), 9)$. Spot self-replication occurs over a rather long time-scale due to dynamically-triggered bifurcation.

Spot self-replication (Another Example): Take $f = 0.7$, $\varepsilon = 0.06$, and $E = 5.0$ for $0 < t < 50$. Increase the fuel E as $E = 5.0 + \sigma(t - 50)$ with $\sigma = 0.05$ for $t \geq 50$. Roughly simultaneous spot splitting occurs. ([Movie](#))

Part II: Quasi-Equilibria

Principal Result: For $\varepsilon \rightarrow 0$, the quasi-equilibrium solution is given by an outer solution, valid away from the spots, and *inner core solutions* near each of the spots centered at $\mathbf{x} = \mathbf{x}_j$ for $j = 1, \dots, N$:

$$u_{\text{qe}} \sim \varepsilon^2 \mathbf{E} + \sum_{i=1}^N U_{i,0} \left(\frac{|\mathbf{x} - \mathbf{x}_i|}{\varepsilon} \right), \quad v_{\text{qe}} \sim \sum_{i=1}^N S_i L_i(\mathbf{x}) + \bar{v},$$

where $L_i(\mathbf{x}) \equiv \log |\mathbf{x} - \mathbf{x}_i|$, and \bar{v} is a constant. The leading-order radially symmetric inner core solution, $U_{i,0}$, is defined on the tangent plane to the sphere near the spot at $\mathbf{x} = \mathbf{x}_i$. The spot strengths, S_i for $i = 1, \dots, N$, satisfy the *nonlinear algebraic system*

$$\mathcal{N}(\mathbf{S}) \equiv \left[\mathbf{I} - \nu(\mathbf{I} - \mathcal{E}_0)\mathcal{G} \right] \mathbf{S} + \nu(\mathbf{I} - \mathcal{E}_0)\chi(\mathbf{S}) - \frac{2\mathbf{E}}{N} \mathbf{e} = \mathbf{0}.$$

Here \mathbf{I} is the identity, $(\mathcal{E}_0)_{ij} = \frac{1}{N}$, $(\mathbf{S})_i = S_i$, $(\chi(\mathbf{S}))_i = \chi(S_i)$, $(\mathbf{e})_i = 1$, and $\nu = -1/\log \varepsilon$. The values of $\chi(S_i)$ are found by numerically solving a *core problem*. The *Green's matrix* \mathcal{G} is a key quantity:

$$(\mathcal{G})_{ij} = \log |\mathbf{x}_i - \mathbf{x}_j| \equiv L_i(\mathbf{x}_j), \quad i \neq j; \quad (\mathcal{G})_{ii} = 0.$$

Part III: Slow Spot Dynamics

Principal Result: *Let $\varepsilon \rightarrow 0$. Provided that there are no $\mathcal{O}(1)$ time-scale instabilities of the quasi-equilibrium spot pattern, the spot locations, $\mathbf{x}_j(\sigma)$ for $j = 1, \dots, N$, with $\sigma = \varepsilon^2 t$, satisfy the ODE-DAE system*

$$\frac{d\mathbf{x}_j}{d\sigma} = \frac{2}{\mathcal{A}_j} (\mathbf{I} - \mathcal{Q}_j) \sum_{\substack{i=1 \\ i \neq j}}^N \frac{S_i \mathbf{x}_i}{|\mathbf{x}_i - \mathbf{x}_j|^2}, \quad \mathcal{Q}_j \equiv \mathbf{x}_j \mathbf{x}_j^T, \quad j = 1, \dots, N.$$

coupled to the nonlinear algebraic constraint (NAS)

$$\mathcal{N}(\mathbf{S}) \equiv \left[\mathbf{I} - \nu(\mathbf{I} - \mathcal{E}_0)\mathcal{G} \right] \mathbf{S} + \nu(\mathbf{I} - \mathcal{E}_0)\chi(\mathbf{S}) - \frac{2\mathbf{E}}{N} \mathbf{e} = \mathbf{0}.$$

Here $\mathcal{A}_j = \mathcal{A}(S_j; f) < 0$ is defined via an integral.

Remarks:

- The matrix $\mathbf{I} - \mathcal{Q}_j$ projects onto the unit sphere.
- If \mathbf{x}_j is a solution then so is $\mathcal{R}\mathbf{x}_j$ where \mathcal{R} is an orthogonal matrix.

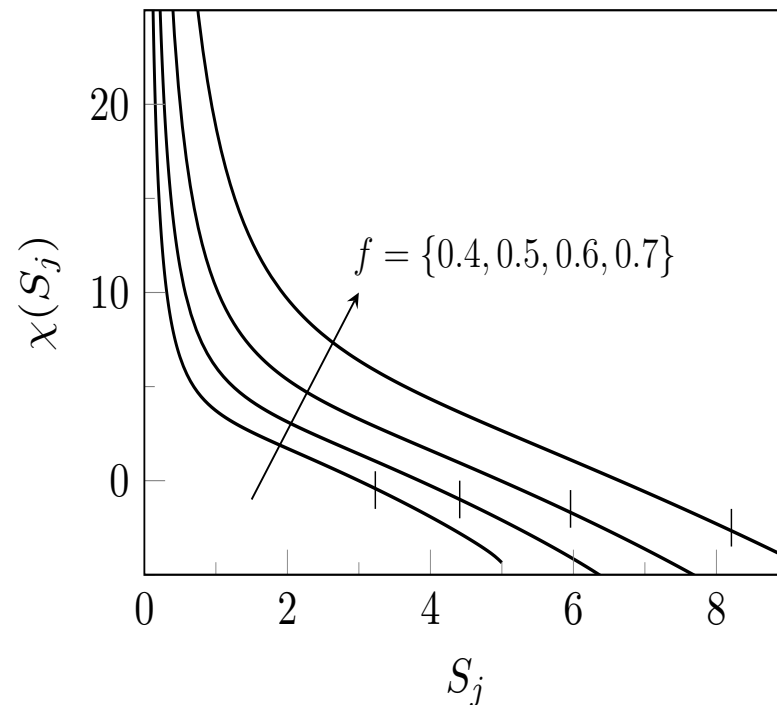
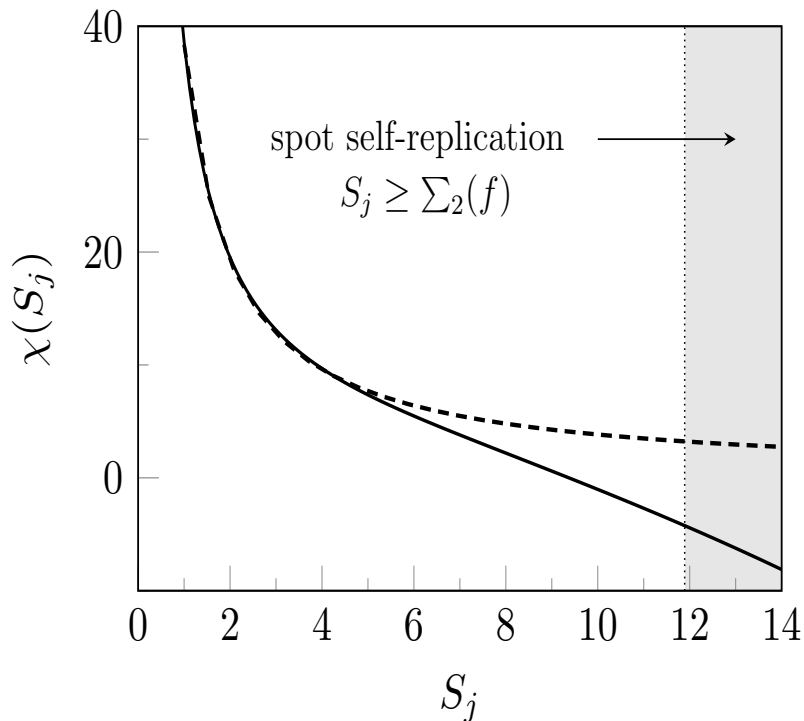
Part III: The Core Problem

On the tangent plane near the j -th spot, we look for a locally radially symmetric **core solution** satisfying

$$\Delta_\rho U_{j0} - U_{j0} + f U_{j0}^2 V_{j0} = 0, \quad \Delta_\rho V_{j0} + U_{j0} - U_{j0}^2 V_{j0} = 0,$$

$$U'_{j0}(0) = V'_{j0}(0) = 0; \quad U_{j0} \rightarrow 0, \quad V_{j0} \sim S_j \log \rho + \chi(S_j) + o(1) \text{ as } \rho \rightarrow \infty.$$

This problem determines $\chi(S_j)$.



Part III: The Spot Strengths I

Common Source Strength Patterns: If the pattern $\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ of spots are such that $\mathcal{G}\mathbf{e} = \kappa_1\mathbf{e}$ then,

$$S_1 = S_2 = \dots = S_N = S_c \equiv \frac{2E}{N}.$$

This property holds for spots equi-distantly placed on a ring, for all platonic solids, any two-spot pattern, and for twisted cuboids.

Q1: Determine all spatial configurations of spots for which this holds. Any relation to Elliptic Fekete Points?

A Key Link: If we set $S_j = S_c$ for all j in the dynamics, then **stable equilibria of the dynamics are local minima of the discrete logarithmic energy**

$$\mathcal{H}_L(x_1, \dots, x_N) \equiv - \sum_{i=1}^N \sum_{j>i}^N \log |\mathbf{x}_i - \mathbf{x}_j|, \quad |x_j| = 1, \quad j = 1, \dots, N.$$

Proof: Use Lagrange multipliers and project to the sphere.

Part III: The Spot Strengths II

Elliptic Fekete points lead to a \mathcal{G} matrix for which \mathbf{e} is nearly an eigenvector. **Q: Is there an asymptotic equipartition of the discrete logarithmic energy for large N ?**

Number of points N	$\ \xi - \mathbf{e}\ _2$
8	$6.0301e - 16$
10	0.0216
20	0.0050
100	0.0029
120	0.0015

Table: Distance $\|\dots\|_2$ between an eigenvector ξ of \mathcal{G} and \mathbf{e} , both normalized, for different elliptic Fekete point configurations. **A random distribution of 100 points on the sphere has a norm difference of 0.2512.**

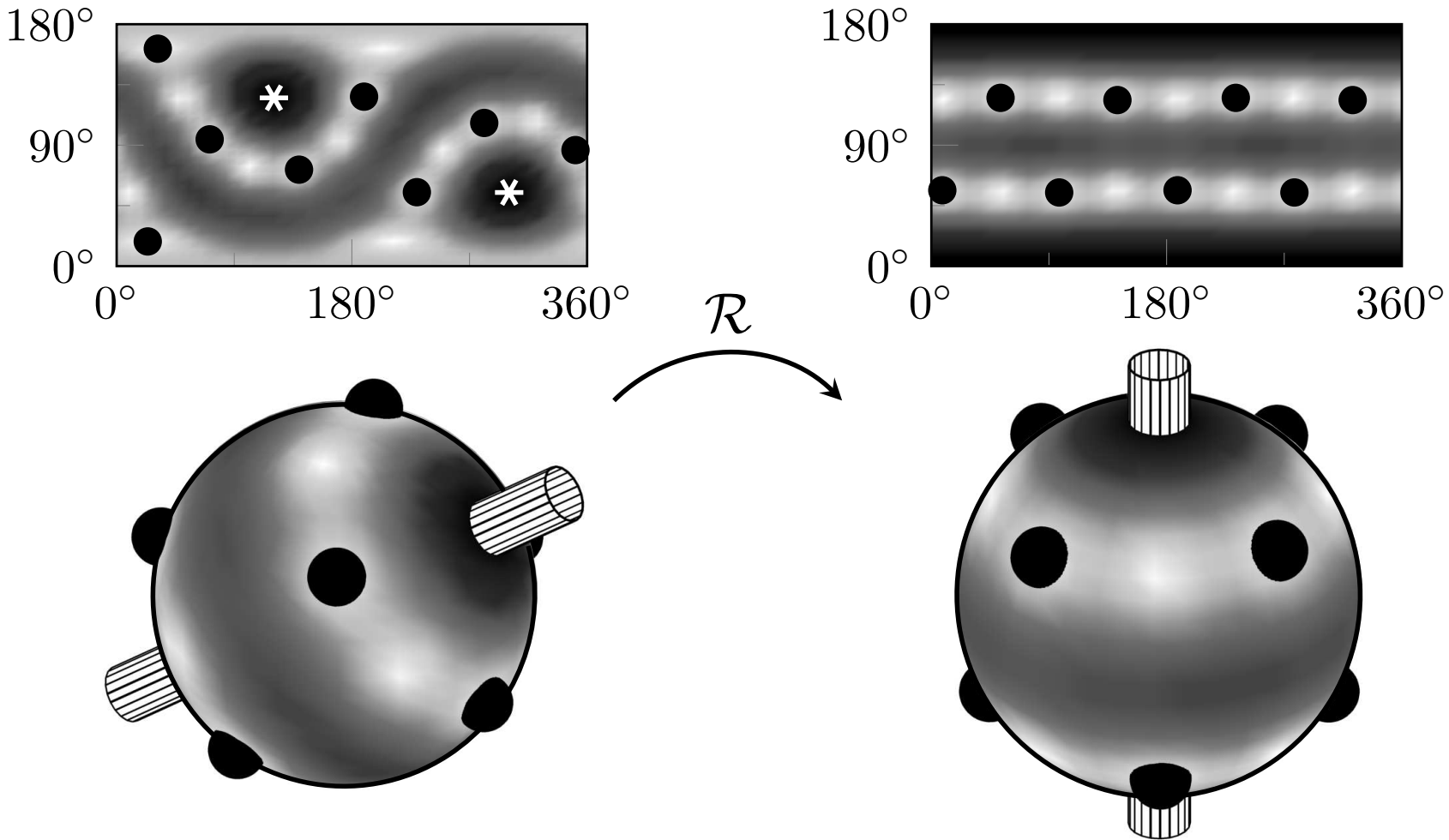
Part III: Steady-State Spot Patterns

For $N = 2, \dots, 8$, for 50 randomly generated initial spot configurations we solved the ODE-DAE system to detect stable steady-states with large basins of attraction:

Results:

- **N=2:** two antipodal spots ($S_1 = S_2$)
- **N=3:** Three equally-spaced spots on a equator ($S_1 = S_2 = S_3$).
- **N=4:** Spots at vertices of a tetrahedron ($S_j = S_c$ for $j = 1, \dots, 4$).
- **N=5,6,7:** Two antipodal spots, with $N - 2$ spots equally-spaced on the mid-plane. Two source strengths S_p and S_c .
- **N=8** Pattern is a 45° twisted cuboid consisting of two parallel planes, each containing four equally-spaced spots. The spots on the two planes are 45° phase-shifted. The ratio of the distance between neighboring spots on a ring to the perpendicular distance between the planes is approximately 0.967. This yields that the planes are at latitudes $\theta \approx 55.6^\circ$ and $\theta \approx 124.4^\circ$. ($S_j = S_c$ for $j = 1, \dots, 8$). This is the elliptic Fekete point pattern for 8 particles.

Eight-Spot Pattern



Left: The shading on the sphere and top (ϕ, θ) plane indicate with two asterisks a better location to place the polar axis of the sphere (marked by a cylinder). (Right) After an orthogonal transformation, \mathcal{R} , the rotated sphere in the (new) $(\bar{\phi}, \bar{\theta})$ -plane shows two rings of four spots.

Final Remarks

- After an asymptotic reduction, all three problems lead to reduced problems involving **discrete interacting particles**.
- For the 3-D narrow escape problem, we have derived a new discrete energy. Study rigorously the asymptotics for large N for globally minimum energy states.
- For spot dynamics, use symmetry group analysis combined with ODE dynamics to classify the steady-state patterns for $N > 8$. **In contrast to weakly nonlinear theory, this ODE-DAE dynamics gives a new approach for analyzing RD patterns on the sphere.**
- Set $S_j = S_c$ for $j = 1, \dots, N$. **Does the ODE system provide a more tractable way to compute elliptic Fekete points?**