

Lecture 5. Complex Numbers and Euler's Formula

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Main purpose:

To introduce some basic knowledge of complex numbers to students so that they are prepared to handle complex-valued roots when solving the characteristic polynomials for eigenvalues of a matrix.

Eg: In high school, students learned that the roots of a quadratic equation $ax^2 + bx + c = 0$ ($a \neq 0$) are given by

$$x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

where the sign of the discriminant $\Delta = b^2 - 4ac$ determines the following three outcomes

$$\text{If } \begin{cases} \Delta > 0, & 2 \text{ real roots;} \\ \Delta = 0, & 1 \text{ (repeated) real root;} \\ \Delta < 0, & \text{no real root.} \end{cases}$$

When complex-valued roots are allowed as in the case when solving eigenvalues, however, a polynomial of degree n always has n roots (Gauss' Fundamental Theorem of Algebra), of which some or all of them can be identical (repeated). Thus, a quadratic equation always has 2 roots irrespective of the sign of Δ .

5.1 Definitions and basic concepts

The imaginary number i :

$$i \equiv \sqrt{-1} \quad \iff \quad i^2 = -1. \quad (1)$$

Every *imaginary number* is expressed as a real-valued multiple of i :

$$\sqrt{-9} = \sqrt{9}\sqrt{-1} = \sqrt{9}i = 3i.$$

A complex number:

$$z = a + bi, \quad (2)$$

where a , b are real, is the sum of a real and an imaginary number.

The real part of z : $Re\{z\} = a$ is a real number.

The imaginary part of z : $Im\{z\} = b$ is a also a real number.

A complex number represents a point (a, b) in a 2D space, called the complex plane. Thus, it can be regarded as a 2D vector expressed in form of a number/scalar. Therefore, there exists a one-to-one correspondence between a 2D vectors and a complex numbers.

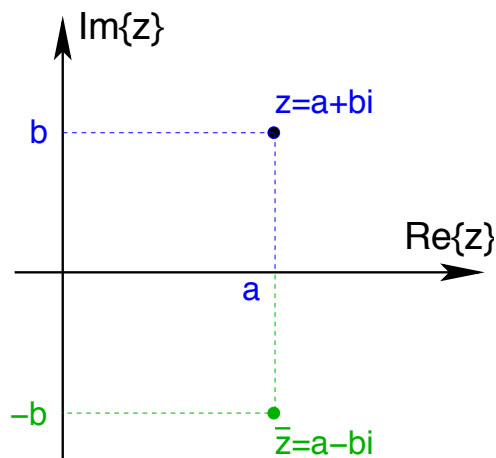


Figure 1: A complex number z and its conjugate \bar{z} in complex space. Horizontal axis contains all real numbers, vertical axis contains all imaginary numbers.

The complex conjugate:

$$\bar{z} = a - bi,$$

which is obtained by reversing the sign of $Im\{z\}$.

Notice that:

$$Re\{z\} = \frac{z + \bar{z}}{2} = a, \quad Im\{z\} = \frac{z - \bar{z}}{2i} = b.$$

Therefore, both $Re\{z\}$ and $Im\{z\}$ are linear combinations of z and \bar{z} .

5.2 Basic computations between complex numbers

Addition/subtraction:

If $z_1 = a_1 + b_1i$, $z_2 = a_2 + b_2i$ ($a_1, a_2, b_1, b_2 \in \mathbb{R}$), then

$$z_1 \pm z_2 = (a_1 + b_1i) \pm (a_2 + b_2i) = (a_1 \pm a_2) + (b_1 \pm b_2)i.$$

Or, real parts plus/minus real parts, imaginary parts plus/minus imaginary parts.

Multiplication by a real scalar α :

$$\alpha z_1 = \alpha a_1 + \alpha b_1i.$$

Multiplication between complex numbers:

$$z_1 z_2 = (a_1 + b_1i)(a_2 + b_2i) = a_1 a_2 + a_1 b_2i + a_2 b_1i + b_1 b_2 i^2 = (a_1 a_2 - b_1 b_2) + (a_1 b_2 + a_2 b_1)i.$$

All rules are identical to those of multiplication between real numbers, just remember that $i^2 = -1$.

Length/magnitude of a complex number $z = a + bi$

$$|z| = \sqrt{z\bar{z}} = \sqrt{(a + bi)(a - bi)} = \sqrt{a^2 + b^2},$$

which is identical to the length of a 2D vector (a, b) .

Division between complex numbers:

$$\frac{z_1}{z_2} = \frac{z_1\bar{z}_2}{z_2\bar{z}_2} = \frac{(a_1 + b_1i)(a_2 - b_2i)}{|z_2|^2} = \frac{(a_1a_2 + b_1b_2) + (a_2b_1 - a_1b_2)i}{a_2^2 + b_2^2}.$$

Eg 5.2.1 Given that $z_1 = 3 + 4i$, $z_2 = 1 - 2i$, calculate

1. $z_1 - z_2$;
2. $\frac{z_1}{2}$;
3. $|z_1|$;
4. $\frac{z_2}{z_1}$.

Ans:

1. $z_1 - z_2 = (3 - 1) + (4 - (-2))i = 2 + 6i$;
2. $\frac{z_1}{2} = \frac{3}{2} + \frac{4}{2}i = 1.5 + 2i$;
3. $|z_1| = \sqrt{z_1\bar{z}_1} = \sqrt{3^2 + 4^2} = \sqrt{25} = 5$;
4. $\frac{z_2}{z_1} = \frac{z_2\bar{z}_1}{z_1\bar{z}_1} = \frac{(1-2i)(3-4i)}{5^2} = \frac{-5-10i}{25} = -\frac{1}{5} - \frac{2}{5}i$.

5.3 Complex-valued exponential and Euler's formula

Euler's formula:

$$e^{it} = \cos t + i \sin t. \tag{3}$$

Based on this formula and that $e^{-it} = \cos(-t) + i \sin(-t) = \cos t - i \sin t$:

$$\cos t = \frac{e^{it} + e^{-it}}{2}, \quad \sin t = \frac{e^{it} - e^{-it}}{2i}. \tag{4}$$

Why? Here is a way to gain insight into this formula.

Recall the Taylor series of e^t :

$$e^t = \sum_{n=0}^{\infty} \frac{t^n}{n!}.$$

Suppose that this series holds when the exponent is imaginary.

$$\begin{aligned} e^{it} &= \sum_{n=0}^{\infty} \frac{(it)^n}{n!} = \sum_{n \text{ even}}^{\infty} \frac{(it)^n}{n!} + \sum_{n \text{ odd}}^{\infty} \frac{(it)^n}{n!} = \sum_{m=0}^{\infty} \frac{(it)^{2m}}{(2m)!} + \sum_{m=0}^{\infty} \frac{(it)^{2m+1}}{(2m+1)!} \\ &= \sum_{m=0}^{\infty} \frac{i^{2m} t^{2m}}{(2m)!} + \sum_{m=0}^{\infty} \frac{i^{2m+1} t^{2m+1}}{(2m+1)!} = \sum_{m=0}^{\infty} \frac{(i^2)^m t^{2m}}{(2m)!} + \sum_{m=0}^{\infty} \frac{i(i^2)^m t^{2m+1}}{(2m+1)!} \end{aligned}$$

$$= \sum_{m=0}^{\infty} \frac{(-1)^m t^{2m}}{(2m)!} + i \sum_{m=0}^{\infty} \frac{(-1)^m t^{2m+1}}{(2m+1)!} = \cos t + i \sin t.$$

Remarks:

- Sine and cosine functions are actually linear combinations of exponential functions with imaginary exponents.
- Similarly, hyperbolic sine and cosine functions are linear combinations of exponential functions with real exponents.

$$\sinh(t) = \frac{e^t - e^{-t}}{2}, \quad \cosh(t) = \frac{e^t + e^{-t}}{2}.$$

5.4 Polar representation of complex numbers

For any complex number $z = x + iy$ ($\neq 0$), its length and angle w.r.t. the horizontal axis are both uniquely defined.

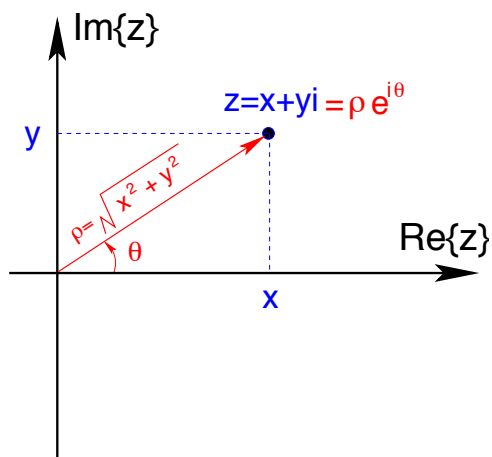


Figure 2: A complex number $z = x + iy$ can be expressed in the polar form $z = \rho e^{i\theta}$, where $\rho = \sqrt{x^2 + y^2}$ is its length and θ the angle between the vector and the horizontal axis. The fact $x = \rho \cos \theta$, $y = \rho \sin \theta$ are consistent with Euler's formula $e^{i\theta} = \cos \theta + i \sin \theta$.

One can convert a complex number from one form to the other by using the Euler's formula:

$$\begin{aligned} z = x + iy &\Leftrightarrow z = \rho e^{i\theta}, & \text{where} \\ x = \rho \cos \theta, \quad y = \rho \sin \theta; & \quad \rho = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1} \frac{y}{x}; \end{aligned}$$

where we often restrict $0 \leq \theta \leq 2\pi$ or $-\pi \leq \theta \leq \pi$. Otherwise, the conversion from Cartesian to polar coordinates is not unique, θ can differ by an integer multiple of 2π .

Eg 5.4.1 Convert the following complex numbers from one form to the other.

1. $z = 3i$;

2. $z = 1$;

3. $z = 1 + i\sqrt{3}$;

4. $z = -2 - 2i$;

5. $z = e^{-i\frac{\pi}{6}}$;

6. $z = 5e^{i\frac{\pi}{4}}$;

7. $z = -5e^{-i\frac{\pi}{3}}$.

Ans:

1. $z = 3i = 3e^{i\frac{\pi}{2}}$;

2. $z = 1 = e^{i0} = 1$, (for a positive real number, there is no change!);

3. $z = 1 + i\sqrt{3} = \sqrt{1^2 + (\sqrt{3})^2} e^{i \tan^{-1} \frac{\sqrt{3}}{1}} = 2e^{i\frac{\pi}{3}}$;

4. $z = -2 - 2i = \sqrt{(-2)^2 + (-2)^2} e^{i \tan^{-1}(\frac{-2}{-2})} = 2\sqrt{2}e^{i\frac{5\pi}{4}} = 2\sqrt{2}e^{-i\frac{3\pi}{4}}$;

5. $z = e^{-i\frac{\pi}{6}} = \cos(-\frac{\pi}{6}) + i \sin(-\frac{\pi}{6}) = \frac{\sqrt{3}}{2} - i\frac{1}{2}$;

6. $z = 6e^{i\frac{\pi}{4}} = 6 \cos \frac{\pi}{4} + i6 \sin \frac{\pi}{4} = 3\sqrt{2} + 3\sqrt{2}i = 3\sqrt{2}(1 + i)$;

7. $z = -4e^{-i\frac{\pi}{3}} = (-4) \left[\cos(-\frac{\pi}{3}) + i \sin(-\frac{\pi}{3}) \right] = (-4) \left[\frac{1}{2} - i\frac{\sqrt{2}}{2} \right] = -2 + 2\sqrt{2}i$.

Remark: It is important to know that the collection of all complex numbers of the form $z = e^{i\theta}$ form a circle of radius one (unit circle) in the complex plane centered at the origin. In other words, the equation for a unit circle centered at the origin in complex plane is $z = e^{i\theta}$ (see figure).

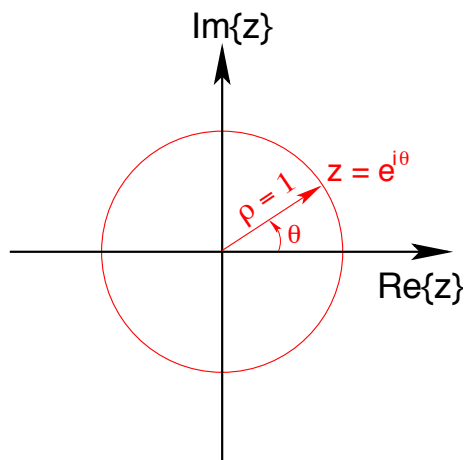


Figure 3: The collection of all complex numbers of the form $z = e^{i\theta}$ form a unit circle centered at the origin in the complex plane.

Remark: Rotation of a vector represented by a complex number $z = \rho e^{i\theta}$ counter-clockwise by angle ϕ is achieved by multiplying $e^{i\phi}$ to it:

$$e^{i\phi} z = e^{i\phi} \rho e^{i\theta} = \rho e^{i(\theta+\phi)}.$$

Remark: The product between $z_1 = \rho_1 e^{i\theta_1}$ and $z_2 = \rho_2 e^{i\theta_2}$ yields

$$z_1 z_2 = \rho_1 e^{i\theta_1} \rho_2 e^{i\theta_2} = (\rho_1 \rho_2) e^{i(\theta_1 + \theta_2)}$$

which is a vector of length $\rho_1 \rho_2$ and an angle $\theta_1 + \theta_2$.

Eg 5.4.2 Find all roots of $\sqrt[3]{1}$, complex and real.

Ans:

$$1 = e^0 = e^{i(0)} = e^{(2\pi n)i}, \quad \text{for any integer } n.$$

Therefore,

$$\sqrt[3]{1} = 1^{\frac{1}{3}} = \left(e^{(2\pi n)i} \right)^{\frac{1}{3}} = e^{\frac{2\pi n}{3}i}, \quad \text{for any integer } n.$$

Often, the angle θ for a complex number expressed in form of $e^{\theta i}$ is restricted in the range $0 \leq \theta < 2\pi$.

If so, $\sqrt[3]{1}$ has only three roots in this range: $\sqrt[3]{1} = 1$, $e^{\frac{2\pi}{3}i}$, $e^{\frac{4\pi}{3}i}$.

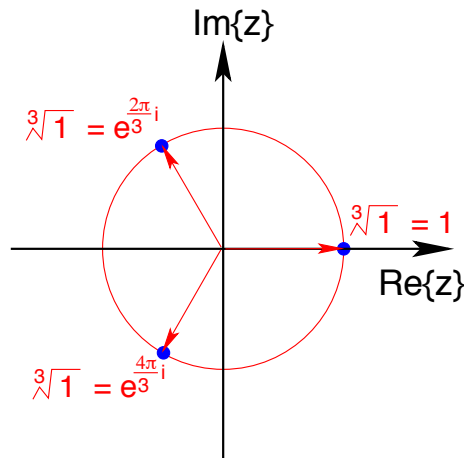


Figure 4: The cubic roots of number 1 in complex plane.

5.5 Polynomials of degree n must have n roots!

Eg 5.5.1 Find all roots of $z^2 + 2z + 10 = 0$.

Ans: Notice that

$$z^2 + 2z + 10 = z^2 + 2z + 1 + 9 = (z + 1)^2 + 9 = 0.$$

There is no real root! But there are two complex-valued roots forming a pair of complex conjugates.

$$(z+1)^2 + 9 = 0 \Rightarrow (z+1)^2 = -9 \Rightarrow z+1 = \pm\sqrt{-9} \Rightarrow z = -1 \pm 3i.$$

Final remarks:

(a) Any polynomial of degree n can always be factored into the product of n terms in which z_i , ($i = 1, \dots, n$) are the n roots.

$$P_n(z) = a_n z^n + a_{n-1} z^{n-1} + \dots + a_1 z + a_0 = a_n (z - z_n)(z - z_{n-1}) \cdots (z - z_1).$$

(b) Complex roots of a polynomial always occur as a pair of complex conjugates: $z_{\pm} = a \pm bi$.